

Instituto Federal Goiano - Campus Ceres Bacharelado em Sistemas de Informação Prof. Me. Ronneesley Moura Teles

Adallberto Lucena Moura
Andrey Silva Ribeiro
Anny Karoliny Moraes Ribeiro
Brener Gomes de Jesus
Davi Ildeu de Faria
Eduardo de Oliveira Silva
Gleyson Israel Alves
Gusttavo Nunes Gomes
Ianka Talita Bastos de Assis
Ígor Justino Rodrigues

# $Algoritmo\ Viola-Jones$

# Sumário

1	O artigo	2
2	Funcionamento do algoritmo	2
3	Vantagem	2
4	Desvantagem	2
5	Implementação Viola-Jones em Python	3
	5.1 Porquê a implementação em Python?	3
	5.2 IntegralImage.py	3
	5.3 HaarLikeFeature.py	4
	5.4 AdaBoost.py	6
	5.5 Utils.py	9
	5.6 example.py	11
6	Referências Bibliográfica	13

# Algoritmo Viola-Jones

### 1 O artigo

Em 2001, Paul Viola e Michael Jones, dois pesquisadores de Cambridge publicaram uma artigo entitulado: "Rapid Object Detection using a Boosted Cascade of Simple Features" que demonstrava um novo método de detecção de faces. O artigo se diferencia e se paltava em 3 pontos importantes.

A primeira foi uma nova maneira de se representar uma imagem, a "imagem integral" (*Integral Image*, em inglês), que permitiu os detectores usados por eles, computarem a imagem de maneira mais rápida.

A segunda foi o algoritmo de aprendizado baseado no *AdaBoost*, que selecionava um número pequeno de características visuais críticas de um conjunto maior e com seus classificadores, extremamente eficientes.

O terceiro aspecto importante, foi o método de combinar e incrementar classificadores em "cascata", o que permitia regiões do fundo da foto de serem rapidamente descatadas, disponibilizando maior processamento computacional em posições com maior possíbilidade de ser o objeto no qual se está procurando, como um rosto.

Os autores aprofundaram seus métodos de como construiram esse algoritmo, de como funcionavam as equações e apresentaram os resultados encontrados e compararam com algoritmos similares da época, e como os algoritmos "Rowley-Baluja-Kanade", "Schneiderman-Kanade" e "Roth-Yang-Ahuja".

Devido sua implementação seguir uma abordagem diferente para construção de um sistema de detecção de face, aproximadamente 15 vezes mais rápida que os métodos anteriores, o algoritmo *Viola-Jones* revolucionou esse campo da computação se tornando uma referência.

## 2 Funcionamento do algoritmo

## 3 Vantagem

- 15 vezes mais rápido que o algoritmo "Rowley-Baluja-Kanade" no processamento da imagem.
- 600 vezes se comparado ao "Schneiderman-Kanade".

## 4 Desvantagem

- A detecção de faces, só é possível se o rosto estiver na posição frontal.
- A base de dados usada, precisa de faces em diferentes condições incluindo: iluminação, brilho, escala, pose e variações de câmera.
- Nível de detecção na literatura 80% (FAUX,2012)
- É um algoritmo de detecção de face e não de reconhecimento facial.

# 5 Implementação Viola-Jones em Python

#### 5.1 Porquê a implementação em Python?

Existem inúmeras implementações do algoritmo na internet, nas mais diversas linguagens, sendo mais comuns em *MatLab*, *Java* e *Python*.

A implementação em MatLab não era muito interessante devido a ferramenta em si, é uma boa ferramenta para desenvolver procedimentos tais como esse de detecção facial. Entretanto é uma ferramenta paga, e em um projeto nessa escala, no qual muitas pessoas iriam interagir, não ter a licença de uso, dificultaria muito o processo, e por isso foi descartada.

Java era muito abundante no GitHub, entretanto a maioria estava incompleta, não possuindo os códigos para treinar a rede, o que é fundamental para o sucesso do algoritmo, ter uma base de dados ampla gerando uma maior eficiência na detecção de imagens. Os códigos que estavam completos, a documentação era quase inexistente, o que dificultaria a utilização, sendo mais vantajoso desenvolver desde o início uma amplicação do que gastar tempo em código alheio.

Entretanto escolhemos a implementação de *Simon Hohberg* do algoritmo em *Python* disponibilizado no seu *GitHub* pessoal: https://github.com/Simon-Hohberg/Viola-Jones

Python é uma linguagem mais simples, mas nem por isso menos robusta, é amplamente usada em processos de machine learning e a implementação encontrada, está com todas as partes do algoritmo, desde a parte de detecção até a de treinamento, e a documentação do código está bem feita, o que possibilitaria o uso.

A seguir segue os principais códigos do algoritmo implementado em *Python* por *Simon Hohberg*: https://github.com/Simon-Hohberg/Viola-Jones

#### 5.2 IntegralImage.py

```
import numpy as np
2
3
  In an integral image each pixel is the sum of all pixels in the
     original image
  that are 'left and above' the pixel.
  Original
               Integral
9
    1 2 3 .
                    0
                 0
                       0
    4 5 6 .
                 0
                    1 3
                 0
                    5 12 21 .
12
13
15
16
17
  def to_integral_image(img_arr):
18
19
      Calculates the integral image based on this instance's original
20
     image data.
      :param img_arr: Image source data
21
      :type img_arr: numpy.ndarray
22
      :return Integral image for given image
23
      :rtype: numpy.ndarray
```

```
25
      \# an index of -1 refers to the last row/column
26
      \# since row_sum is calculated starting from (0,0),
27
      \# \operatorname{rowSum}(x, -1) == 0 \text{ holds for all } x
28
      row_sum = np.zeros(img_arr.shape)
29
      # we need an additional column and row
30
      integral_image_arr = np.zeros((img_arr.shape[0] + 1, img_arr.shape
31
      [1] + 1)
      for x in range (img_arr.shape[1]):
32
           for y in range (img_arr.shape [0]):
33
               row_sum[y, x] = row_sum[y-1, x] + img_arr[y, x]
34
               integral\_image\_arr[y+1, x+1] = integral\_image\_arr[y+1, x
35
      -1+1] + row_sum[y, x]
      return integral_image_arr
36
37
  def sum_region(integral_img_arr, top_left, bottom_right):
39
40
      Calculates the sum in the rectangle specified by the given tuples.
41
      :param integral_img_arr:
42
      :type integral_img_arr: numpy.ndarray
      :param top_left: (x, y) of the rectangle's top left corner
44
      : type \ top\_left: \ (int \ , \ int)
4.5
      :param bottom_right: (x, y) of the rectangle's bottom right corner
46
      :type bottom_right: (int, int)
47
      return The sum of all pixels in the given rectangle
48
      :rtype int
49
      ,, ,, ,,
50
      # swap tuples
51
      top_left = (top_left[1], top_left[0])
52
      bottom_right = (bottom_right[1], bottom_right[0])
5.9
      if top_left == bottom_right:
           return integral_img_arr[top_left]
      top\_right = (bottom\_right[0], top\_left[1])
56
      bottom_left = (top_left[0], bottom_right[1])
57
      return integral_img_arr[bottom_right] - integral_img_arr[top_right]
58
      - integral_img_arr [bottom_left] + integral_img_arr [top_left]
```

recursos/codigo\_python/Viola-Jones-master/violajones/IntegralImage.py

### 5.3 HaarLikeFeature.py

```
import violajones.IntegralImage as ii

def enum(**enums):
    return type('Enum', (), enums)

FeatureType = enum(TWO_VERTICAL=(1, 2), TWO_HORIZONTAL=(2, 1),
    THREE_HORIZONTAL=(3, 1), THREE_VERTICAL=(1, 3), FOUR=(2, 2))

FeatureTypes = [FeatureType.TWO_VERTICAL, FeatureType.TWO_HORIZONTAL,
    FeatureType.THREE_VERTICAL, FeatureType.THREE_HORIZONTAL,
    FeatureType.FOUR]

class HaarLikeFeature(object):
    """
    Class representing a haar-like feature.
    """
```

```
def __init__(self, feature_type, position, width, height, threshold
16
      , polarity):
          " " "
          Creates a new haar-like feature.
18
          :param feature_type: Type of new feature, see FeatureType enum
          :type feature_type: violajonse.HaarLikeFeature.FeatureTypes
20
          :param position: Top left corner where the feature begins (x, y
21
          :type position: (int, int)
22
          :param width: Width of the feature
23
          :type width: int
          :param height: Height of the feature
25
          :type height: int
26
          :param threshold: Feature threshold
27
          :type threshold: float
          :param polarity: polarity of the feature -1 or 1
          :type polarity: int
30
31
          self.type = feature_type
32
          self.top_left = position
          self.bottom\_right = (position [0] + width, position [1] + height)
34
          self.width = width
35
          self.height = height
36
37
          self.threshold = threshold
          self.polarity = polarity
38
          self.weight = 1
39
40
      def get_score(self, int_img):
42
          Get score for given integral image array.
4.9
          :param int_img: Integral image array
          :type int_img: numpy.ndarray
45
          :return: Score for given feature
46
          :rtype: float
47
48
          score = 0
49
          if self.type == FeatureType.TWO_VERTICAL:
50
               first = ii.sum_region(int_img, self.top_left, (self.
      top\_left \ [0] \ + \ self.width \ , \ int(self.top\_left \ [1] \ + \ self.height \ / \ 2)))
               second = ii.sum_region(int_img, (self.top_left[0], int(self
      .top_left[1] + self.height / 2)), self.bottom_right)
               score = first - second
53
           elif self.type == FeatureType.TWO_HORIZONTAL:
               first = ii.sum_region(int_img, self.top_left, (int(self.
55
      top_left[0] + self.width / 2), self.top_left[1] + self.height))
               second = ii.sum_region(int_img, (int(self.top_left[0] +
56
      self.width / 2), self.top_left[1]), self.bottom_right)
               score = first - second
57
           elif self.type == FeatureType.THREE_HORIZONTAL:
58
               first = ii.sum_region(int_img, self.top_left, (int(self.
      top_left[0] + self.width / 3), self.top_left[1] + self.height))
               second = ii.sum_region(int_img, (int(self.top_left[0] +
60
      self.width / 3), self.top_left[1]), (int(self.top_left[0] + 2 *
      self.width / 3), self.top_left[1] + self.height))
               third = ii.sum_region(int_img, (int(self.top_left[0] + 2 *
61
      self.width / 3), self.top_left[1]), self.bottom_right)
               score = first - second + third
62
          elif self.type == FeatureType.THREE_VERTICAL:
63
```

```
first = ii.sum_region(int_img, self.top_left, (self.
64
     bottom_right[0], int(self.top_left[1] + self.height / 3)))
               second = ii.sum_region(int_img, (self.top_left[0], int(self
65
      .top_left[1] + self.height / 3)), (self.bottom_right[0], int(self.
      top_left[1] + 2 * self.height / 3))
               third = ii.sum_region(int_img, (self.top_left[0], int(self.
66
      top_left[1] + 2 * self.height / 3)), self.bottom_right)
               score = first - second + third
67
          elif self.type == FeatureType.FOUR:
              # top left area
69
               first = ii.sum_region(int_img, self.top_left, (int(self.
70
      top\_left[0] + self.width / 2), int(self.top\_left[1] + self.height / 2)
      2)))
              # top right area
71
              second = ii.sum_region(int_img, (int(self.top_left[0] +
72
      self.width / 2), self.top_left[1]), (self.bottom_right[0], int(self
      . top_left[1] + self.height / 2))
              # bottom left area
73
               third = ii.sum_region(int_img, (self.top_left[0], int(self.
74
      top_left[1] + self.height / 2)), (int(self.top_left[0] + self.width
      / 2), self.bottom_right[1]))
              # bottom right area
75
               fourth = ii.sum_region(int_img, (int(self.top_left[0] +
      self.width / 2), int(self.top_left[1] + self.height / 2)), self.
     bottom_right)
               score = first - second - third + fourth
77
          return score
78
79
      def get_vote(self, int_img):
80
81
          Get vote of this feature for given integral image.
89
          :param int_img: Integral image array
          :type int_img: numpy.ndarray
84
          :return: 1 iff this feature votes positively, otherwise -1
85
          :rtype: int
86
87
          score = self.get_score(int_img)
88
          return self.weight * (1 if score < self.polarity * self.
89
     threshold else -1)
```

recursos/codigo\_python/Viola-Jones-master/violajones/HaarLikeFeature.py

### 5.4 AdaBoost.py

```
from functools import partial
import numpy as np
from violajones. HaarLikeFeature import HaarLikeFeature
from violajones. HaarLikeFeature import FeatureTypes
import progressbar
from multiprocessing import Pool

LOADING_BARLENGTH = 50

# TODO: select optimal threshold for each feature
# TODO: attentional cascading

def learn(positive_iis, negative_iis, num_classifiers=-1,
    min_feature_width=1, max_feature_width=-1, min_feature_height=1,
```

```
\max_{\text{feature\_height}} = -1):
      Selects a set of classifiers. Iteratively takes the best
      classifiers based
      on a weighted error.
17
      :param positive_iis: List of positive integral image examples
18
      :type positive_iis: list [numpy.ndarray]
19
      :param negative_iis: List of negative integral image examples
20
      :type negative_iis: list[numpy.ndarray]
21
      :param num_classifiers: Number of classifiers to select, -1 will
22
      use all
      classifiers
      :type num_classifiers: int
24
25
      :return: List of selected features
26
      :rtype: list[violajones.HaarLikeFeature.HaarLikeFeature]
27
28
29
      num_pos = len(positive_iis)
      num_neg = len(negative_iis)
30
      num\_imgs = num\_pos + num\_neg
31
      img\_height, img\_width = positive\_iis[0].shape
33
      # Maximum feature width and height default to image width and
34
      height
      max_feature_height = img_height if max_feature_height == -1 else
35
      max_feature_height
      max_feature_width = img_width if <math>max_feature_width = -1 else
36
      max_feature_width
      # Create initial weights and labels
38
      pos\_weights = np.ones(num\_pos) * 1. / (2 * num\_pos)
39
      neg\_weights = np.ones(num\_neg) * 1. / (2 * num\_neg)
40
      weights = np.hstack((pos_weights, neg_weights))
41
      labels = np.hstack((np.ones(num_pos), np.ones(num_neg) * -1))
42
43
      images = positive_iis + negative_iis
44
45
      # Create features for all sizes and locations
46
      features = _create_features(img_height, img_width,
47
      min_feature_width, max_feature_width, min_feature_height,
      max_feature_height)
      num_features = len(features)
48
      feature_indexes = list(range(num_features))
49
      num_classifiers = num_features if num_classifiers == -1 else
51
      num_classifiers
50
      print('Calculating scores for images..')
54
      votes = np.zeros((num_imgs, num_features))
      bar = progressbar.ProgressBar()
56
      # Use as many workers as there are CPUs
      pool = Pool(processes=None)
58
      for i in bar(range(num_imgs)):
           votes [i, :] = np.array(list(pool.map(partial(_get_feature_vote,
60
       image=images[i]), features)))
61
      # select classifiers
62
63
      classifiers = []
64
```

```
65
       print('Selecting classifiers..')
66
       bar = progressbar. ProgressBar()
67
       for _ in bar(range(num_classifiers)):
68
69
           classification_errors = np.zeros(len(feature_indexes))
70
71
           # normalize weights
72
           weights *= 1. / np.sum(weights)
74
           # select best classifier based on the weighted error
75
           for f in range(len(feature_indexes)):
               f_{idx} = f_{eature_{indexes}}[f]
               # classifier error is the sum of image weights where the
78
      classifier
               # is right
79
               error = sum(map(lambda img_idx: weights[img_idx] if labels[
80
      img_idx] != votes[img_idx, f_idx] else 0, range(num_imgs)))
                classification_errors[f] = error
81
82
           # get best feature, i.e. with smallest error
           min_error_idx = np.argmin(classification_errors)
84
           best_error = classification_errors [min_error_idx]
85
           best_feature_idx = feature_indexes [min_error_idx]
87
           # set feature weight
88
           best_feature = features [best_feature_idx]
89
           feature\_weight = 0.5 * np.log((1 - best\_error) / best\_error)
90
           best_feature.weight = feature_weight
92
           classifiers.append(best_feature)
9.9
94
95
           # update image weights
           weights = np.array(list(map(lambda img_idx: weights[img_idx] *
96
      np.sqrt((1-best_error)/best_error) if labels[img_idx] != votes[
      img_idx, best_feature_idx] else weights[img_idx] * np.sqrt(
      best_error/(1-best_error)), range(num_imgs))))
97
           # remove feature (a feature can't be selected twice)
98
           feature_indexes.remove(best_feature_idx)
100
       return classifiers
  def _get_feature_vote(feature, image):
       return feature.get_vote(image)
105
106
  def _create_features(img_height, img_width, min_feature_width,
108
      max_feature_width, min_feature_height, max_feature_height):
       print('Creating haar-like features..')
       features = []
110
       for feature in FeatureTypes:
111
           # FeatureTypes are just tuples
119
           feature\_start\_width = max(min\_feature\_width, feature[0])
           for feature_width in range (feature_start_width,
      max_feature_width, feature [0]):
               feature\_start\_height = max(min\_feature\_height, feature[1])
               for feature_height in range (feature_start_height,
116
      max_feature_height, feature[1]):
```

```
for x in range(img_width - feature_width):

for y in range(img_height - feature_height):

features.append(HaarLikeFeature(feature, (x, y)

feature_width, feature_height, 0, 1))

features.append(HaarLikeFeature(feature, (x, y)

feature_width, feature_height, 0, -1))

print('..done. ' + str(len(features)) + ' features created.\n')

return features
```

recursos/codigo\_python/Viola-Jones-master/violajones/AdaBoost.py

#### 5.5 Utils.py

```
import numpy as np
  from PIL import Image
  from violajones. HaarLikeFeature import FeatureType
  from functools import partial
  import os
  def ensemble_vote(int_img, classifiers):
      Classifies given integral image (numpy array) using given
     classifiers, i.e.
      if the sum of all classifier votes is greater 0, image is
      positively (1) else negatively (0). The threshold is 0, because
12
     votes can be
      +1 or -1.
13
      :param int_img: Integral image to be classified
14
      :type int_img: numpy.ndarray
      :param classifiers: List of classifiers
      :type classifiers: list [violajones.HaarLikeFeature]
17
      :return: 1 iff sum of classifier votes is greater 0, else 0
18
      :rtype: int
19
20
      return 1 if sum([c.get_vote(int_img) for c in classifiers]) >= 0
21
22
23
  def ensemble_vote_all(int_imgs, classifiers):
24
25
      Classifies given list of integral images (numpy arrays) using
26
     classifiers,
      i.e. if the sum of all classifier votes is greater 0, an image is
27
      positively (1) else negatively (0). The threshold is 0, because
2.8
     votes can be
      +1 or -1.
29
      :param int_imgs: List of integral images to be classified
30
      :type int_imgs: list[numpy.ndarray]
31
      :param classifiers: List of classifiers
32
      :type classifiers: list [violajones.HaarLikeFeature]
33
      :return: List of assigned labels, 1 if image was classified
34
     positively, else
35
      :rtype: list[int]
36
      vote_partial = partial(ensemble_vote, classifiers=classifiers)
```

```
return list (map(vote_partial, int_imgs))
39
40
41
  def reconstruct(classifiers, img_size):
42
43
      Creates an image by putting all given classifiers on top of each
44
      producing an archetype of the learned class of object.
45
      :param classifiers: List of classifiers
46
      :type classifiers: list[violajones.HaarLikeFeature.HaarLikeFeature]
      :param img_size: Tuple of width and height
48
      :type img_size: (int, int)
49
      :return: Reconstructed image
50
      :rtype: PIL.Image
51
52
      image = np.zeros(img_size)
      for c in classifiers:
54
55
          # map polarity: -1 -> 0, 1 -> 1
           polarity = pow(1 + c.polarity, 2)/4
56
           if c.type == FeatureType.TWO_VERTICAL:
57
               for x in range(c.width):
58
                   sign = polarity
59
                    for y in range(c.height):
60
                        if y >= c.height/2:
61
                            sign = (sign + 1) \% 2
62
                        image[c.top_left[1] + y, c.top_left[0] + x] += 1 *
63
      sign * c.weight
           elif c.type == FeatureType.TWO_HORIZONTAL:
64
               sign = polarity
65
               for x in range(c.width):
66
                   if x >= c. width / 2:
67
                        sign = (sign + 1) \% 2
68
                    for y in range(c.height):
69
                        image[c.top_left[0] + x, c.top_left[1] + y] += 1 *
70
      sign * c.weight
           elif c.type == FeatureType.THREE_HORIZONTAL:
71
               sign = polarity
72
               for x in range(c.width):
73
                   if x \% c. width/3 == 0:
                        sign = (sign + 1) \% 2
                    for y in range (c. height):
76
                        image[c.top_left[0] + x, c.top_left[1] + y] += 1 *
      sign * c.weight
           elif c.type == FeatureType.THREE_VERTICAL:
78
               for x in range(c.width):
79
                   sign = polarity
80
                    for y in range(c.height):
81
                        if x \% c.height/3 = 0:
                            sign = (sign + 1) \% 2
83
                        image[c.top_left[0] + x, c.top_left[1] + y] += 1 *
84
      sign * c.weight
           elif c.type == FeatureType.FOUR:
               sign = polarity
86
               for x in range(c.width):
87
                   if x \% c. width/2 == 0:
                        sign = (sign + 1) \% 2
89
                   for y in range(c.height):
90
                        if x \% c.height/2 = 0:
91
                            sign = (sign + 1) \% 2
92
```

```
image[c.top_left[0] + x, c.top_left[1] + y] += 1 *
93
      sign * c.weight
       image -= image.min()
94
       image /= image.max()
9.5
       image *= 255
96
       result = Image.fromarray(image.astype(np.uint8))
97
       return result
98
99
100
   def load_images (path):
101
       images = []
       for _file in os.listdir(path):
           if _file.endswith('.png'):
               img_arr = np.array(Image.open((os.path.join(path, _file))),
105
       dtype=np.float64)
                img_arr /= img_arr.max()
106
                images.append(img_arr)
       return images
108
```

recursos/codigo\_python/Viola-Jones-master/violajones/Utils.py

#### 5.6 example.py

```
import violajones. IntegralImage as ii
  import violajones. AdaBoost as ab
  import violajones. Utils as utils
  if __name__ = "__main__":
      pos_training_path = 'trainingdata/faces'
      neg_training_path = 'trainingdata/nonfaces'
      pos_testing_path = 'trainingdata/faces/test'
      neg_testing_path = 'trainingdata/nonfaces/test'
10
      num_classifiers = 2
      # For performance reasons restricting feature size
      min_feature_height = 8
      max_feature_height = 10
      min_feature_width = 8
15
      max_feature_width = 10
      print ('Loading faces..')
18
      faces_training = utils.load_images(pos_training_path)
19
      faces_ii_training = list(map(ii.to_integral_image, faces_training))
20
      print('..done. ' + str(len(faces_training)) + ' faces loaded.\n\
21
     nLoading non faces..')
      non_faces_training = utils.load_images(neg_training_path)
      non_faces_ii_training = list (map(ii.to_integral_image,
     non_faces_training))
      print('..done. ' + str(len(non_faces_training)) + ' non faces
24
     loaded.\n')
25
      # classifiers are haar like features
      classifiers = ab.learn(faces_ii_training, non_faces_ii_training,
27
     num_classifiers , min_feature_height , max_feature_height ,
     min_feature_width, max_feature_width)
      print ('Loading test faces..')
29
      faces_testing = utils.load_images(pos_testing_path)
30
      faces_ii_testing = list(map(ii.to_integral_image, faces_testing))
31
```

```
print('..done. ' + str(len(faces_testing)) + ' faces loaded.\n\
32
     nLoading test non faces..')
      non_faces_testing = utils.load_images(neg_testing_path)
33
      non_faces_ii_testing = list (map(ii.to_integral_image,
34
     non_faces_testing))
      print('..done. ' + str(len(non_faces_testing)) + ' non faces loaded
35
     .\n')
36
      print('Testing selected classifiers..')
37
      correct_faces = 0
38
      correct_non_faces = 0
39
      correct_faces = sum(utils.ensemble_vote_all(faces_ii_testing,
40
     classifiers))
      correct_non_faces = len(non_faces_testing) - sum(utils.
41
     ensemble_vote_all(non_faces_ii_testing, classifiers))
42
                                        Faces: ' + str(correct_faces) + '/
      print('..done.\n\nResult:\n
      ' + str(len(faces_testing))
           + ' (' + str((float(correct_faces) / len(faces_testing)) *
44
     100) + \%\n non-Faces:
            + str(correct_non_faces) + '/' + str(len(non_faces_testing))
            + str((float(correct_non_faces) / len(non_faces_testing)) *
46
     100) + \%)
47
      # Just for fun: putting all haar-like features over each other
48
     generates a face-like image
      recon = utils.reconstruct(classifiers, faces_testing[0].shape)
49
      recon.save('reconstruction.png')
```

recursos/codigo\_python/Viola-Jones-master/example.py

### 6 Referências Bibliográfica

VIOLA, Paul; JONES, Michael. Rapid object detection using a boosted cascade of simple features. Proceedings of the 2001 IEEE Computer Society Conference on Computer Vision and Pattern Recognition. CVPR 2001, v. 1, p. I-511-I-518, 2001. Disponível em: <a href="http://ieeexplore.ieee.org/document/990517/">http://ieeexplore.ieee.org/document/990517/</a>>.

VIOLA, Paul; JONES, Michael. Robust Real-Time Face Detection International Journal of Computer Vision 57(2), 137–154, 2004.

CHAVES, Bruno Butilhão. Estudo do algoritmo AdaBoost de aprendizagem de máquina aplicado a sensores e sistemas embarcados. 2011. Dissertação (Mestrado em Engenharia de Controle e Automação Mecânica) - Escola Politécnica, Universidade de São Paulo, São Paulo, 2011. doi:10.11606/D.3.2011.tde-12062012-163740. Acesso em: 2017-10-11..

IRGENS, Peter et al. An efficient and cost effective FPGA based implementation of the Viola-Jones face detection algorithm. HardwareX, v. 1, p. 68-75, 2017. Disponível em: <a href="http://linkinghub.elsevier.com/retrieve/pii/S2468067216300116">http://linkinghub.elsevier.com/retrieve/pii/S2468067216300116</a>.

SANTOS, Ligneul. **Detecção de faces através do algoritmo de Viola-Jones**. Coppe/Ufrj, 2011.

FAUX, Francis e LUTHON, Franck. **Theory of evidence for face detection and tracking**. International Journal of Approximate Reasoning, v. 53, n. 5, p. 728–746, 2012. Disponível em: <a href="http://dx.doi.org/10.1016/j.ijar.2012.02.002">http://dx.doi.org/10.1016/j.ijar.2012.02.002</a>.

BODHI, S. R. e NAVEEN, S. Face detection, registration and feature localization experiments with RGB-D face database. Procedia Computer Science, v. 46, n. Icict 2014, p. 1778–1785, 2015. Disponível em: <a href="http://dx.doi.org/10.1016/j.procs.2015.02.132">http://dx.doi.org/10.1016/j.procs.2015.02.132</a>.