

# Algorithm description and analysis

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## General description

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The quick sort algorithm basically repeats two operations:

1. Partition the array into two parts: Elements  $\leq$  pivot and Elements  $>$  pivot;
2. Recursively apply the quick sort algorithm to both parts of the array, respectively.

Both operations are parallelized. To avoid spawning too much threads on dealing with small base cases, a parameter  $G = 1024$  is used to stop spawning threads when input array size is less than  $G$ .

I parallel two recursive calls simply by using *task* directive in openmp.

## Partition algorithm

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### Description

Let's say we would like to partition an array  $A$  of length  $N$  according to a *pivot*. The partition parts consist of 3 steps:

1. Create two array *leq* and *gt* and initialize all elements as 0. Iterate over the original array. If an element is  $\leq$  pivot, mark corresponding position of *leq* as 1. Otherwise, mark corresponding position of *gt* as 1.
2. Update *leq* and *gt* to be their inclusive prefix sum, respectively.
3. Create an array *temp*. Iterate over the original array  $A$ . If an element  $A[i] \leq$  pivot, lookup *leq* to find out its index in *temp*, which is *leq*[i]-1. Otherwise, lookup *gt* to find out its index in *temp*, which is  $N - gt[i]$ . Set *temp* with the value in  $A$ . After the iteration, overwrite  $A$  with *temp*.

Below is the pseudocode for this algorithm:

```
#STEP1
for i=0 to N-1 do:
    if A[i] <= pivot: leq[i] = 1
    else: gt[i] = 1

#STEP2
leq = inclusive-scan(leq)
gt = inclusive-scan(gt)

#STEP3
for i=0 to N-1 do:
    if A[i] <= pivot: tmp[leq[i]-1] = A[i]
```

```
else: tmp[N-gt[i]] = A[i]
copy tmp to A
```

All 3 steps are paralleled by `#pragma omp parallel for`.

## Auxiliary storage

Obviously, the parallel partition algorithm above requires auxiliary storage. All 3 steps requires using *leq* and *gt* array of size  $N$ . Both STEP2 and STEP3 requires using a *tmp* array of size  $N$ , but can be destroy after the step is finished.

Hence, the overall auxiliary storage for this parallel partition algorithm should be  $3N \in O(N)$ .

## Work and Depth

Both STEP1 and STEP3 have  $O(N)$  work. For STEP2, I use parallel scan algorithm #2 in the slide, so the work is  $O(N \lg N)$ . Hence, the total work should be  $W = W_1 + W_2 + W_3 = O(N \lg N)$ .

Both STEP1 and STEP3 are parallel for loop, so  $D_1 = D_3 = O(\lg N)$ . Parallel scan algorithm #2 has depth  $D_2 = O(\lg N)$ . 3 steps run serially, so total depth  $D = D_1 + D_2 + D_3 = O(\lg N)$ .