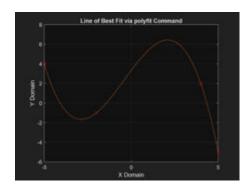
```
%Roshan Jaiswal-Ferri
%Section - 03
%Aero 300 Lab 4 - Iterative Methods to Solve Matrix Equations: 4/26/24
```

## **Workspace Prep**

## **PART 1:**

```
%Define x and y as coordinate points
x = [-5, -2, 4, 5];
y = [4, -1, 2, -5];
p = polyfit(x,y,3); %using Polyfit for x and y finding degree 3 coeffecients
disp(p) %displaying results, each coefficient is for their respective degree
% Define x and y domain to plot line graph of polyfit
x1 = -5:0.1:5; %Plotting along x axis -5 to 5
y1 = polyval(p,x1); %using polyval to create y values
% Plot figure
figure
plot(x,y,'x','MarkerEdgeColor','r','MarkerSize',12)
hold on
grid on
plot(x1, y1)
xlabel('X Domain')
ylabel('Y Domain')
title('Line of Best Fit via polyfit Command')
%Polyfit() looks like it uses newton's divided difference because they both
%use interpolation methods to find a line with best fit that uses a
%polynomial of a certain degree. QR factorization could relate to the least
*squares method which finds approx silution for a system to fit a curve.
  Columns 1 through 3
  -0.131216931216931 -0.152910052910053 2.380423280423280
  Column 4
   3.322751322751321
```



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