```
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%Section - 01
%Aero 320 HW 2 - Rotation Matricies: 10/8/24
```

Workspace Prep

PART 1: Finding Rotation Matrix:

```
rV = [6783; 3391; 1953]; %Position Vector km
vV = [-3.5; 4.39; 4.44]; %Vel Vector km/s

%Converting to F'LVLH

Zlvlh = -(rV/norm(rV));
Ylvlh = -(cross(rV, vV) / norm(cross(rV, vV)));
Xlvlh = cross(Ylvlh, Zlvlh);

%Creating Matrix with new vectors

Clvlh_eci = [Xlvlh, Ylvlh, Zlvlh];
disp(Clvlh_eci)

-0.486148869433620 -0.115648764227618 -0.866189725222505
    0.614721997304824     0.659242753609288     -0.433031012565165
    0.621108801079152 -0.742983415121945 -0.249398280017625
```

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