

Further Changepoint Analysis

Rebecca Killick(r.killick@lancs.ac.uk) NHS Workshop 2020

Workshop Plan



- Recap of changepoints
- Checking assumptions
- Autocorrelation
- Influence
- Multivariate changepoints

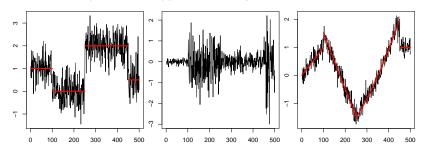
There will be tasks throughout the sections.

Recall: changepoints



For data y_1, \ldots, y_n , if a changepoint exists at τ , then y_1, \ldots, y_{τ} differ from $y_{\tau+1}, \ldots, y_n$ in some way.

There are many different types of change.



Packages



Today we will use the following packages

```
library(changepoint)
```

library(EnvCpt)

library(changepoint.influence)

library(changepoint.geo)

Other notable R packages are available for changepoint analysis including

- ecp for univariate and multivariate energy test statistics
- InspectChangepoint for multivariate Inspect projection direction mean only change
- hdbinseg for multivariate double CUSUM test statistic
- BayesProject for multivariate changepoints

Checking Assumptions



The main assumptions for a Normal likelihood ratio test for a change in mean are:

- Independent data points;
- Normal distributed points pre and post change;
- Constant variance across the data.

How can we check these?

How to check



Check the residuals

```
set.seed(1)
m1=c(rnorm(100,0,1),rnorm(100,5,1))
m1.amoc=cpt.mean(m1)
means=param.est(m1.amoc)$mean
m1.resid=m1-rep(means, seg.len(m1.amoc))
shapiro.test(m1.resid)
##
##
    Shapiro-Wilk normality test
##
  data: m1.resid
## W = 0.99228, p-value = 0.3721
```

Residual Check



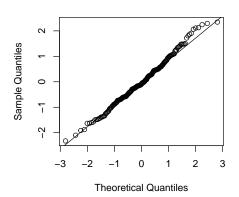
```
ks.test(m1.resid,pnorm,mean=mean(m1.resid),sd=sd(m1.resid))
##
## One-sample Kolmogorov-Smirnov test
##
## data: m1.resid
## D = 0.045812, p-value = 0.7953
## alternative hypothesis: two-sided
```

Residual Check



qqnorm(m1.resid)
qqline(m1.resid)

Normal Q-Q Plot

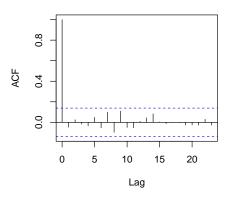


Residual Check



acf(m1.resid)

Series m1.resid

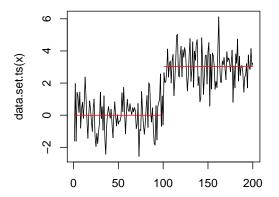


Autocorrelation



What effect does autocorrelation have on our analysis?

```
set.seed(879123)
x=c(rnorm(100),rnorm(100,3))
plot(cpt.meanvar(x,method='PELT'))
```

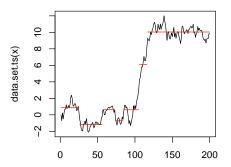


Autocorrelation +ve



What effect does autocorrelation have on our analysis?

```
source('sim.cpt.AR1.R')
set.seed(879123)
x=sim.cpt.AR1(cpts=c(0,100,200),X=cbind(rep(1,200)),init=0,
    beta=rbind(c(0,0.9),c(1,0.9)),sig2=(1-0.9^2),nsim=1)
plot(cpt.meanvar(x,method='PELT'))
```

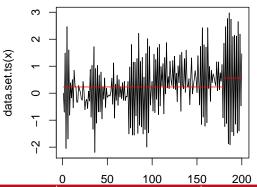


Autocorrelation -ve



What effect does autocorrelation have on our analysis?

```
set.seed(879123)
x=sim.cpt.AR1(cpts=c(0,100,200),X=cbind(rep(1,200)),init=0,
    beta=rbind(c(0,-0.9),c(1,-0.9)),sig2=(1-0.9^2),nsim=1)
plot(cpt.meanvar(x,method='PELT'))
```



EnvCpt



EnvCpt automatically fits 12 different models to your data:

- Flat mean (+AR1, +AR2, +Change, +AR1+Change, +AR2+Change)
- Trend mean (+AR1, +AR2, +Change, +AR1+Change, +AR2+Change)

AR1= autoregressive of order 1 = current data point is strongly related to the last data point.

BONUS: Can see which model is best

PITFALL: Might be best to use another model which isn't checked - always look at the fit!

EnvCpt: Example

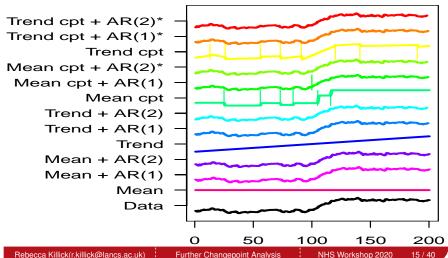


```
set.seed(879123)
x=sim.cpt.AR1(cpts=c(0,100,200),X=cbind(rep(1,200)),init=0,
    beta=rbind(c(0,0.9),c(1,0.9)),sig2=(1-0.9<sup>2</sup>),nsim=1)
out=envcpt(x)
## Fitting 12 models
##
which.min(BIC(out))
  meanar1cpt
##
```

EnvCpt: Example



plot(out)



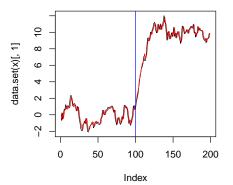
EnvCpt: Example



```
cpts(out$meanar1cpt)
```

[1] 100

```
plot(out[[which.min(BIC(out))+1]])
abline(v=cpts(out$meanar1cpt),col='blue')
```

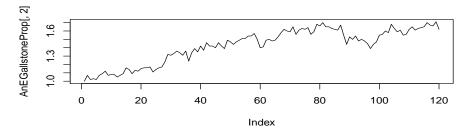


EnvCpt: A&E Gallstone



HES Data on monthly proportion of A&E admissions for gallstone disease from Jan 2010 - Dec 2019.

```
load('AnEGallstoneProp.Rdata')
plot(AnEGallstoneProp[,2],type='1')
```



Use EnvCpt to see if there is evidence for changes in the monthly proportion of A&E admissions for gallstone disease.

Multivariate changes



In moving to the multivariate setting a number of different scenarios could arise.

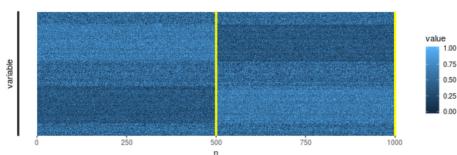
- The process in each channel could be unconnected to the rest (i.e. repeated use of univariate cpt methods might be appropriate);
- There may be some shared structure across channels. For example
 - Changes occur at the same time in all channels;
 - Changes occur in a subset of channels at the same time.
- The nature of the change could vary from one channel to another;
- ... and doubtless many more scenarios!

Multivariate changes



In the multivariate setting we encounter new challenges:

- Computational expense.
- Sparsity of changepoints.
- Incorporating multivariate power.



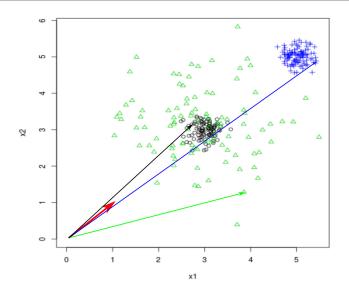
Many methods



Some well known multivariate changepoint approaches include:

- ecp: James, Matteson (2015)
- Inspect: Wang, Samworth (2017)
- DoubleCUSUM: Cho (2016)

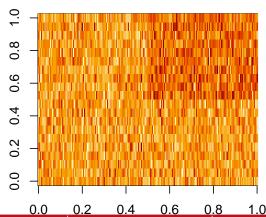
GeomCP Intuition



GeomCP Mean Ex



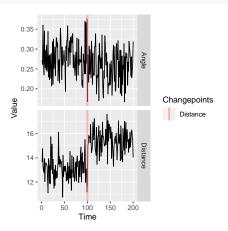
```
set.seed(1)
Y=rbind(matrix(rnorm(100*20),ncol=20),cbind(matrix(rnorm(100*0.00),ncol=10)),matrix(rnorm(100*10,1),ncol=10)))
image(Y)
```



GeomCP: Mean Ex

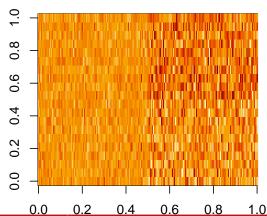


res <- geomcp(Y)
plot(res)</pre>



GeomCP MeanVar Ex

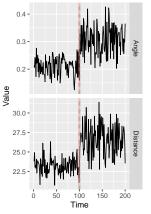




GeomCP: MeanVar Ex



res <- geomcp(Y)
plot(res)</pre>





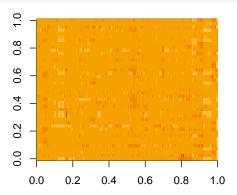


Task: Genetics



Analyse the ACGH Bladder Tumor data from the ecp package. It is 2215x43 with 43 patients. How many changes do you find?

data(ACGH)
image(ACGH\$data)



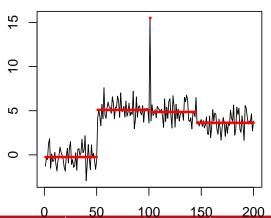
Influence



- Which data points are influential for obtaining the segmentation?
 - Changepoints versus Outliers
 - How to measure influence?
- How stable is the obtained segmentation?

Influence: Example

```
set.seed(30)
x=c(rnorm(50),rnorm(50,mean=5),rnorm(1,mean=15),rnorm(49,mean
xcpt=cpt.mean(x,method='PELT')
plot(xcpt,cpt.width=3,ylab='')
```



How to measure?



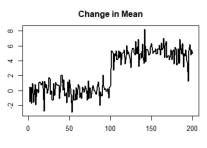
Sources of Inspiration:

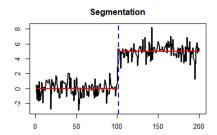
- Regression Analysis: Measures of Influence (e.g., Cook's distance)
- Robust Statistics: Influence Functions

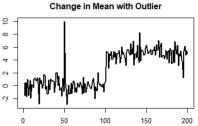
Two routes:

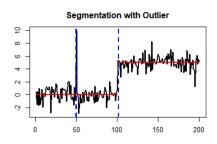
- Modifying an observation
- Leaving out an observation

Modify









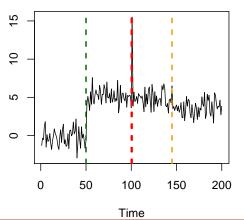
Stability Dashboard: Mod





```
x.inf=influence.generate.PELT(xcpt,method='modify')
stability.overview(x,cpts(xcpt),x.inf,cex.main=0.9)
```

Stability dashboard using modify method

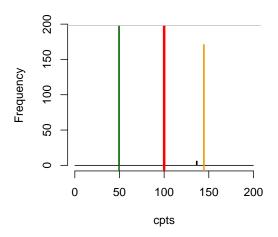


Location Stability: Mod



location.stability(cpts(xcpt),x.inf,cex.main=0.9)

Location Stability using modify method



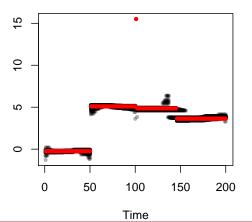
Parameter Stability: Mod





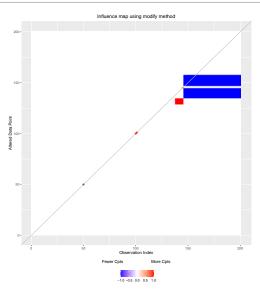
parameter.stability(x.inf,original.mean=rep(param.est(xcpt)\$)
times=diff(c(0,xcpt@cpts))),cex.main=0.9)

Parameter Stability using outlier method



Influence Map: Mod



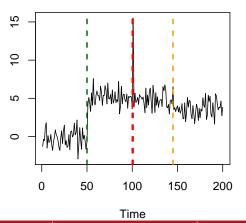


Stability Dashboard: Del



```
x.inf=influence.generate.PELT(xcpt,method='delete')
stability.overview(x,cpts(xcpt),x.inf,cex.main=0.9)
```

Stability dashboard using delete method

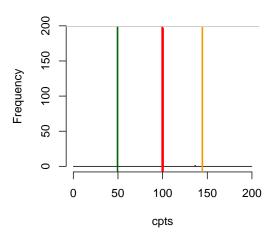


Location Stability: Del



location.stability(cpts(xcpt),x.inf,cex.main=0.9)

Location Stability using delete method

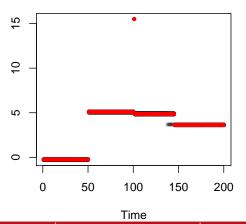


Parameter Stability: Del



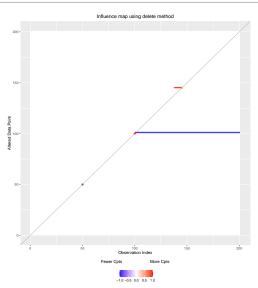
parameter.stability(x.inf,original.mean=rep(param.est(xcpt)\$n
times=diff(c(0,xcpt@cpts))),cex.main=0.9)

Parameter Stability using deletion method



Influence Map: Del





Summary



- Multivariate is interesting but still lots of challenges in the univariate space
- Lots of interesting research in the changepoint space
- Always looking for interesting problems to work on
- Reach out if you want help / guidance

References



PELT: Killick, Fearnhead, Eckley (2012)

EnvCpt: Beaulieu, Killick (2018)

geomCP: Grundy, Killick (2020)

Influence: Wilms, Killick, Matteson (2020+)