

```

> f := (x,y) → 2·x - x2 - x·y
                                     f := (x,y) ↦ 2·x - x2 - y·x
(1)

> g := (x,y) → -y + x·y
                                     g := (x,y) ↦ -y + y·x
(2)

> ?solve
> solve( { 2·x - x2 - x·y = 0, -y + x·y = 0 } )
                                     {x=0,y=0}, {x=2,y=0}, {x=1,y=1}
(3)

> with(linalg) :
> with(VectorCalculus) :
> Jm := Jacobian([f(x,y), g(x,y)], [x,y])
                                     Jm :=  $\begin{bmatrix} -2x - y + 2 & -x \\ y & x - 1 \end{bmatrix}$ 
(4)

> A := subs([x=0,y=0], Jm)
                                     A :=  $\begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}$ 
(5)

> eigenvalues(A)
                                     2, -1
(6)

> A := subs([x=2,y=0], Jm)
                                     A :=  $\begin{bmatrix} -2 & -2 \\ 0 & 1 \end{bmatrix}$ 
(7)

> eigenvalues(A)
                                     -2, 1
(8)

> A := subs([x=1,y=1], Jm)
                                     A :=  $\begin{bmatrix} -1 & -1 \\ 1 & 0 \end{bmatrix}$ 
(9)

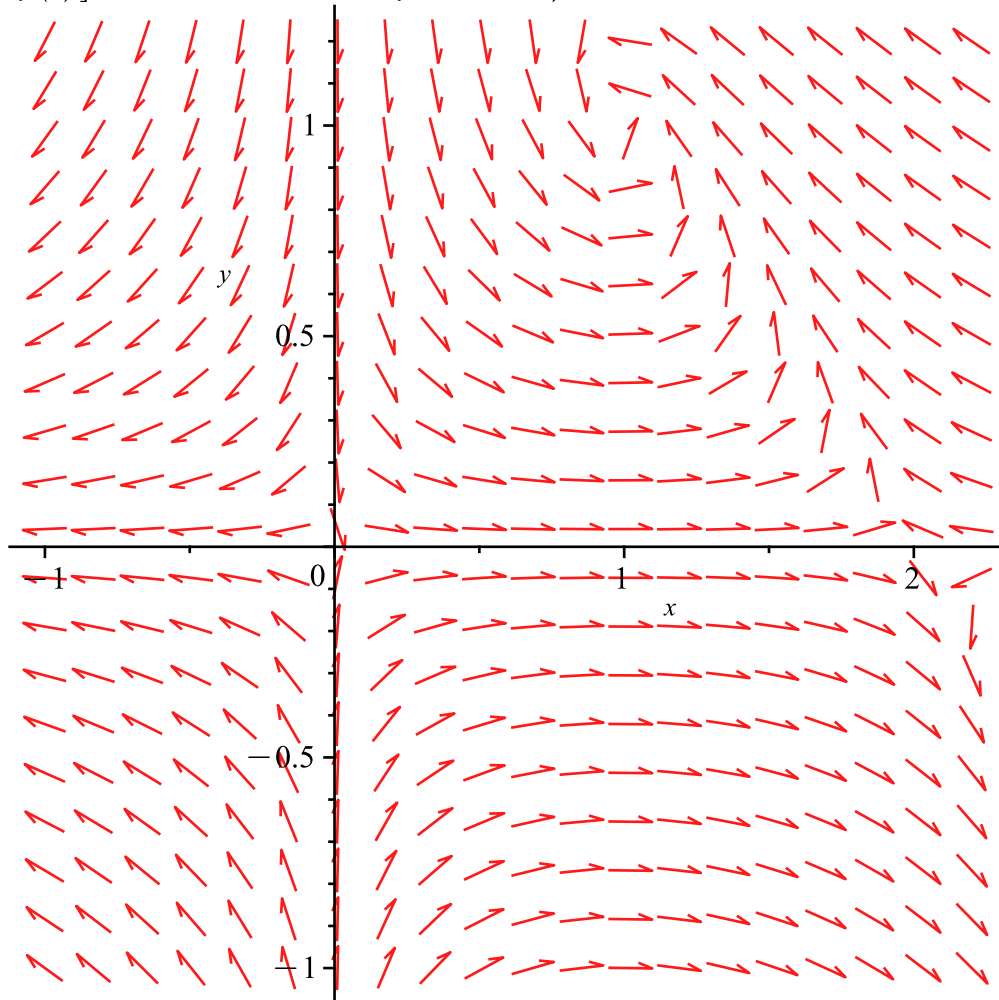
> eigenvalues(A)
                                      $-\frac{1}{2} + \frac{i\sqrt{3}}{2}, -\frac{1}{2} - \frac{i\sqrt{3}}{2}$ 
(10)

> # c
> with(DEtools)
[AreSimilar, Closure, DENormal, DEplot, DEplot3d, DEplot_polygon, DFactor, DFactorLCLM,
 DFactorsols, Dchangevar, Desingularize, FindODE, FunctionDecomposition, GCRD, Gosper,
 Heunsols, Homomorphisms, IVPsol, IsHyperexponential, LCLM, MeijerGsols,
 MultiplicativeDecomposition, ODEInvariants, PDEchangecoords, PolynomialNormalForm,
 RationalCanonicalForm, ReduceHyperexp, RiemannPsols, Xchange, Xcommutator, Xgauge,
 Zeilberger, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsym, canoni, caseplot,
 casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys,

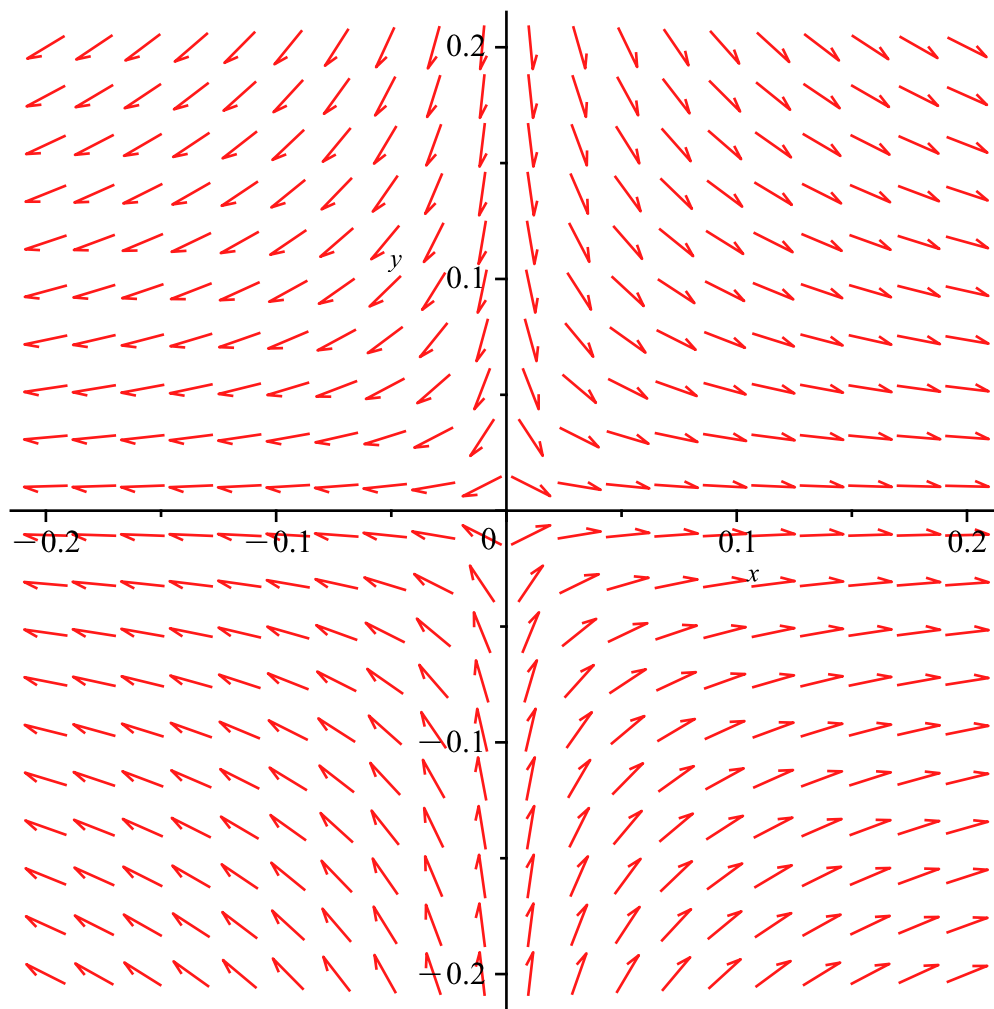
```

dalembertsol, dcoeffs, de2diffop, dfieldplot, diff_table, diffop2de, dperiodic_sols, dpolyform, dsubs, eigenring, endomorphism_charpoly, equinv, eta_k, eulersols, exactsol, expsols, exterior_power, firint, firtest, formal_sol, gen_exp, generate_ic, genhomosol, gensys, hamilton_eqs, hypergeometricsols, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate_sols, intfactor, invariants, kovacicsols, leftdivision, liesol, line_int, linearsol, matrixDE, matrix_riccati, maxdimsystems, moser_reduce, muchange, mult, mutest, newton_polygon, normalG2, ode_int_y, ode_y1, odeadvisor, odepde, parametricsol, particularsol, phaseportrait, poincare, polysols, power_equivalent, rational_equivalent, ratsols, redode, reduceOrder, reduce_order, regular_parts, regularsp, remove_RootOf, riccati_system, riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, singularities, solve_group, super_reduce, symgen, symmetric_power, symmetric_product, symtest, transinv, translate, untranslate, varparam, zoom]

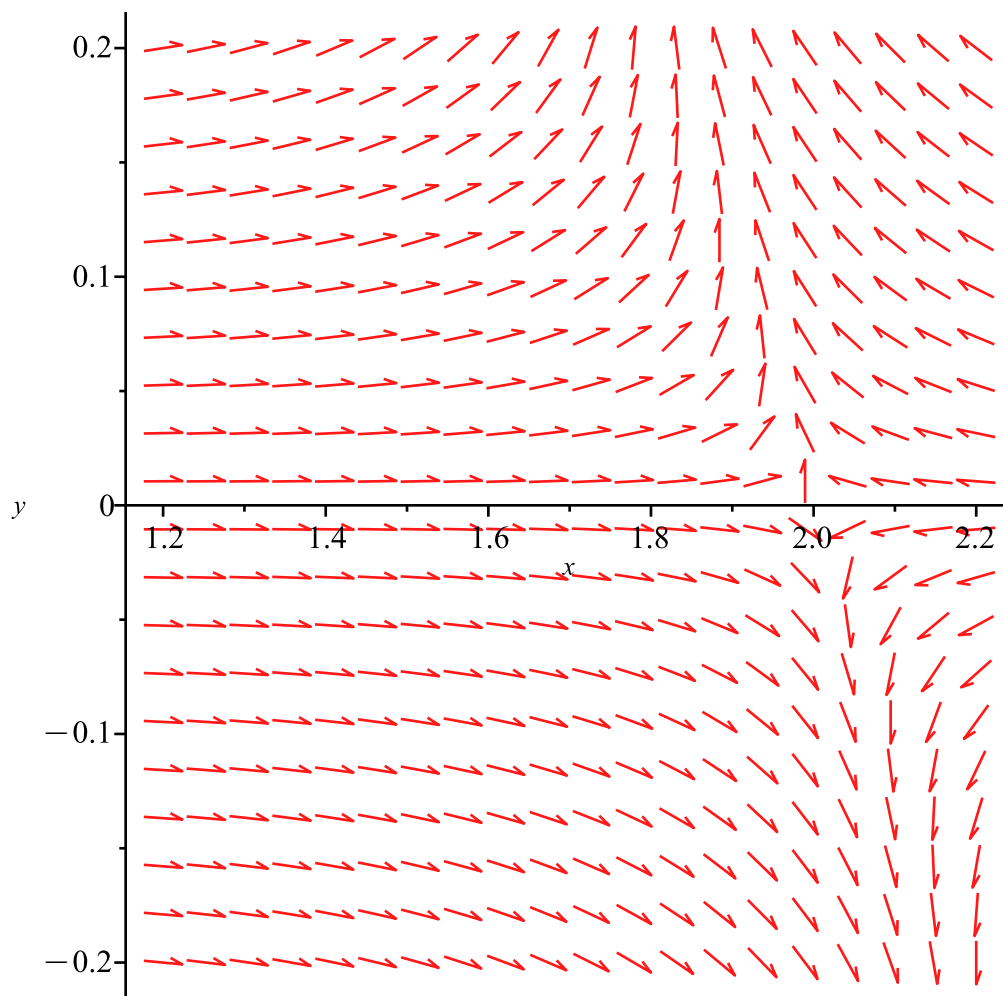
> *dfieldplot*([*diff*($x(t)$, t) = $2 \cdot x(t) - x(t)^2 - x(t) \cdot y(t)$, *diff*($y(t)$, t) = $-y(t) + x(t) \cdot y(t)$],
 [$x(t)$, $y(t)$], $t = -3 \dots 3$, $x = -1 \dots 2.2$, $y = -1 \dots 1.2$);



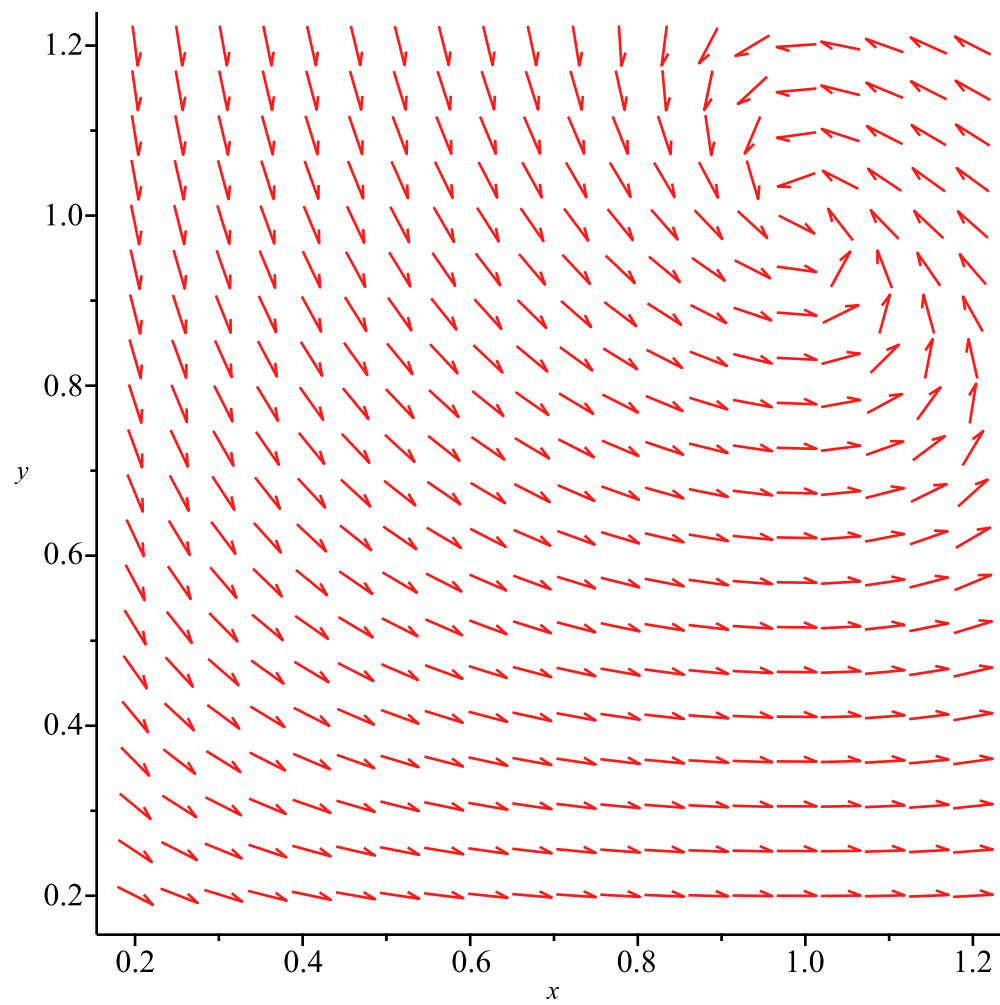
> *dfieldplot*([*diff*($x(t)$, t) = $2 \cdot x(t) - x(t)^2 - x(t) \cdot y(t)$, *diff*($y(t)$, t) = $-y(t) + x(t) \cdot y(t)$],
 [$x(t)$, $y(t)$], $t = -3 \dots 3$, $x = -0.2 \dots 0.2$, $y = -0.2 \dots 0.2$);



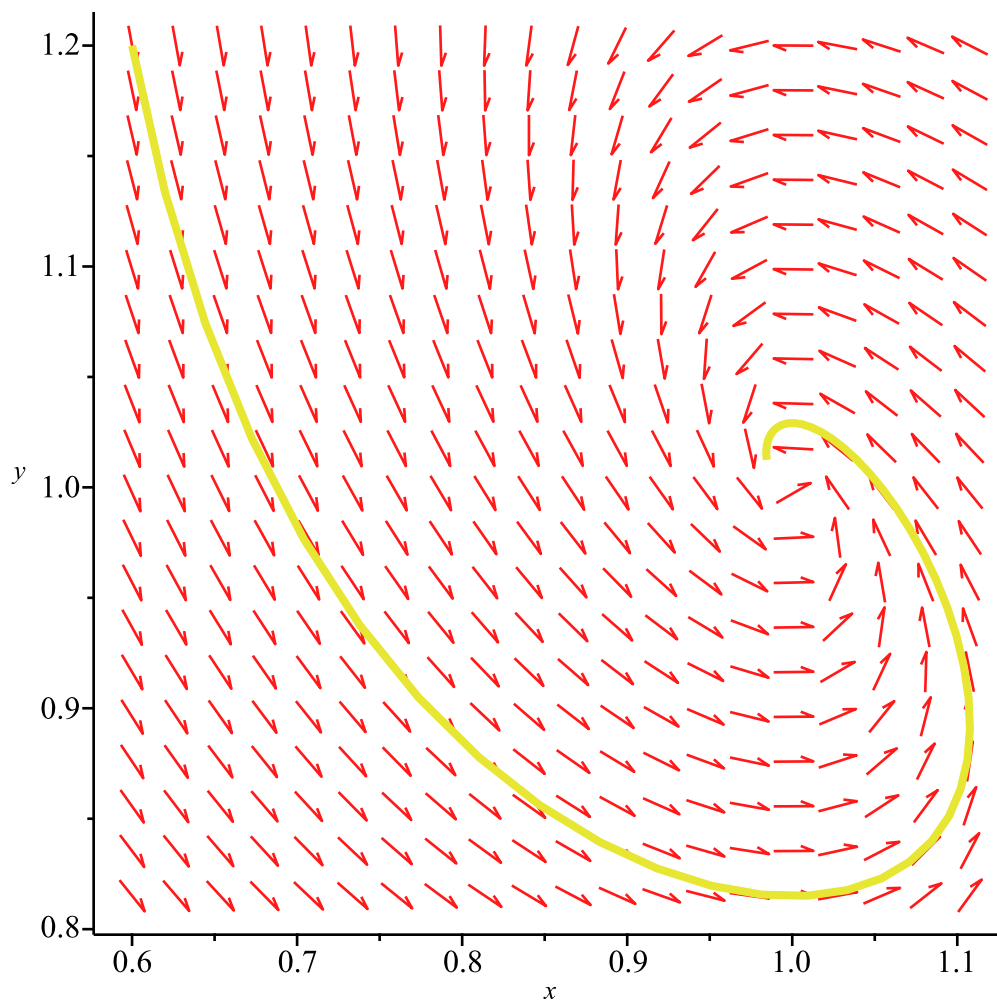
```
> dfieldplot([diff(x(t), t) = 2·x(t) - x(t)2 - x(t)·y(t), diff(y(t), t) = -y(t) + x(t)·y(t)],
[x(t), y(t)], t = -3 .. 3, x = 1.2 .. 2.2, y = -0.2 .. 0.2);
```



```
> dfieldplot([diff(x(t), t) = 2·x(t) - x(t)2 - x(t)·y(t), diff(y(t), t) = -y(t) + x(t)·y(t)],
[x(t), y(t)], t = -3 .. 3, x = 0.2 .. 1.2, y = 0.2 .. 1.2);
```



> $DEplot\left(\left[\text{diff}(x(t), t) = 2 \cdot x(t) - x(t)^2 - x(t) \cdot y(t), \text{diff}(y(t), t) = -y(t) + x(t) \cdot y(t)\right], [x(t), y(t)], t = 0 \dots 7, [[x(0) = 0.6, y(0) = 1.2]]\right);$



$$\begin{aligned} > f := (x, y) \mapsto y \\ & \qquad \qquad \qquad f := (x, y) \mapsto y \end{aligned} \tag{12}$$

$$\begin{aligned} > g := (x, y) \mapsto (-4) \cdot \sin(x) \\ & \qquad \qquad \qquad g := (x, y) \mapsto (-4) \cdot \sin(x) \end{aligned} \tag{13}$$

$$\begin{aligned} > \text{solve}(\{y=0, (-4) \cdot \sin(x)=0\}) \\ & \qquad \qquad \qquad \{x=0, y=0\} \end{aligned} \tag{14}$$

$$\begin{aligned} > \text{dsolve}\left(\text{diff}(y(x), x) = \frac{(-4 \cdot \sin(x))}{y(x)}, y(x)\right) \\ & \qquad \qquad \qquad y(x) = \sqrt{8 \cos(x) + _CI}, y(x) = -\sqrt{8 \cos(x) + _CI} \end{aligned} \tag{15}$$

$$\begin{aligned} > Jm := \text{Jacobian}([f(x, y), g(x, y)], [x, y]) \\ & \qquad \qquad \qquad Jm := \begin{bmatrix} 0 & 1 \\ -4 \cos(x) & 0 \end{bmatrix} \end{aligned} \tag{16}$$

$$\begin{aligned} > A := \text{subs}([x=0, y=0], Jm) \\ & \qquad \qquad \qquad A := \begin{bmatrix} 0 & 1 \\ -4 \cos(0) & 0 \end{bmatrix} \end{aligned} \tag{17}$$

$$> \text{eigenvalues}(A)$$

$\left[\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right]$

$$2I, -2I$$

(18)