

Guidlines:

- All functions are implemented in the notebook
- Names of functions are determined by the question number
- All functions are called in the main function (last function in the notebook)

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import math
```

```
In [2]: def calcGaussian(x,mu,sigma,pi = 1):
    # Calculate the denominator of the Gaussian distribution
    denominator = math.sqrt(2 * math.pi * sigma**2)

    # Calculate the exponent term
    exponent = -0.5 * ((x - mu) / sigma) ** 2

    # Calculate the Gaussian distribution
    gaussian = (1 / denominator) * np.exp(exponent)

    return pi*gaussian
```

```
In [3]: def plotGaussian(x,gauss,N=1000):

    plt.plot(x,gauss)
    plt.grid(visible=True)
    plt.xlabel("x")
    plt.ylabel("p(x)")

    return
```

```
In [4]: def calcParams(D):
    muML = np.mean(D)
    sigmaML = np.mean((D-muML)**2)
    return muML,np.sqrt(sigmaML);
```

Q2:

```
In [5]: def q2(mu,sig):
    N = 1000;
    x = np.linspace(mu-4*sig,mu+4*sig,N)
    gauss = calcGaussian(x,mu,sig)
    plotGaussian(x,gauss,N)
    plt.title("Estimated Gaussian");
    plt.legend(["mu = %.1f, sigma = %.1f" %(mu,sig**2)])
    return #np.array([mu,sig])
```

Q3:

```
In [6]: def q3(mu,sig, N = 1000):
    x = np.linspace(min(mu-4*sig),max(mu+4*sig),N)
    gauss_real = calcGaussian(x,mu[1],sig[1])
    plotGaussian(x,gauss_real);
    plt.title("Real Gaussian vs. Estimated Gaussian");
    plt.legend(labels = ("Est: mu = %.1f, sigma = %.1f" %(mu[0],sig[0]**2), "Real:
    return
```

Q4:

```
In [7]: def q4(mu_,sig_,N_ = 30):
        newD = np.random.normal(mu_,sig_,N_)
        params = calcParams(newD);
        mu = np.array([params[0], mu_]);
        sig = np.array([params[1], sig_]);
        q2(mu[0],sig[0]) # plot on Data basis
        q3(mu,sig) # plot real gauss
        return
```

Q5:

```
In [8]: def q5(mu_,sig_,N_=30):
        muVec = np.array([]);
        sigVec = np.array([]);
        for i in range(10):
            newD = np.random.normal(mu_,sig_,N_)
            params = calcParams(newD);
            muVec = np.append(muVec,params[0]); # for later calculations of grid
            sigVec = np.append(sigVec,params[1]); # etc.
            q2(params[0],params[1]);

        muVec = np.append(muVec,mu_);
        sigVec = np.append(sigVec,sig_);
        q3(muVec,sigVec);

        return
```

Q6:

```
In [9]: # implemented in main using q5
```

```
In [10]: def main():
        # Data for all questions:
        D = np.array([1.42,5.01,2.45,1.92,1.41,4.83,1.81]);

        # q2:
        plt.figure()
        params = calcParams(D)
        q2(params[0],params[1]);

        # q3 (uses plot of estimated gaussian called in q2):
        plt.figure()
        q2(params[0],params[1]); # plot est gauss

        mu = np.array([params[0], 2]);
        sig = np.array([params[1],np.sqrt(1.5)]);
        q3(mu,sig); # plot real gauss

        # q4 (uses functions of q3,q2 with new data)
        plt.figure()
        q4(mu[1],sig[1]);

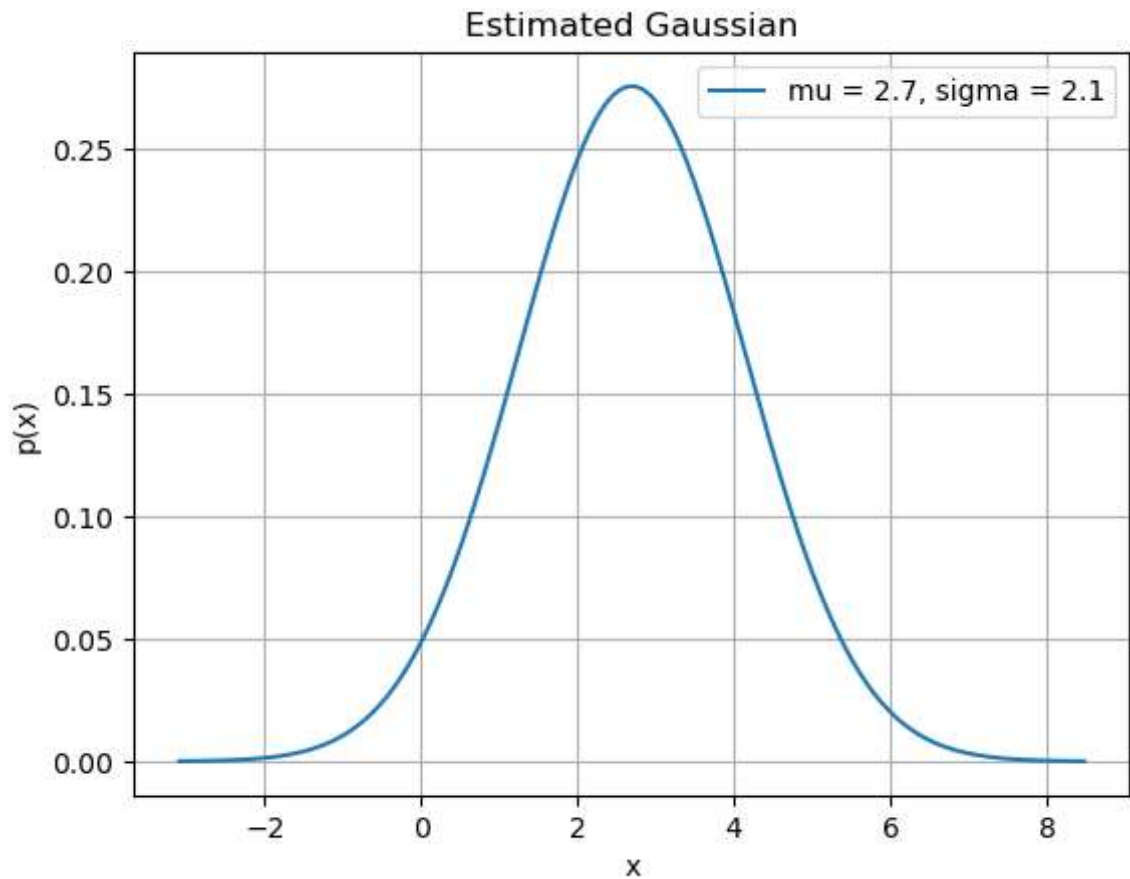
        # q5
        plt.figure()
        q5(mu[1],sig[1]);
```

```
plt.legend(["mu = %.1f, sigma = %.1f" %(mu[1],sig[1]**2)]) # real values for si

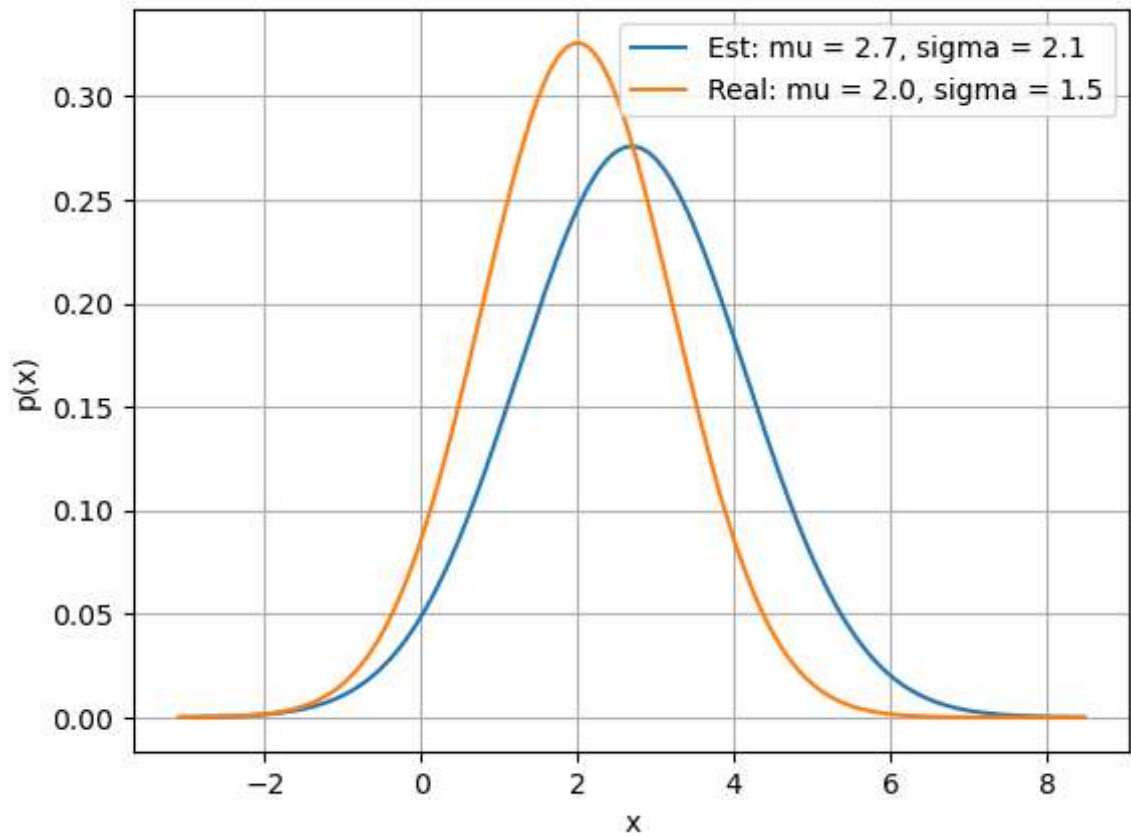
# q6 (based on q5 that take N as an input)
plt.figure()
N = 3000
q5(mu[1],sig[1],N)
plt.legend(["mu = %.1f, sigma = %.1f" %(mu[1],sig[1]**2)]) # real values for si

return
```

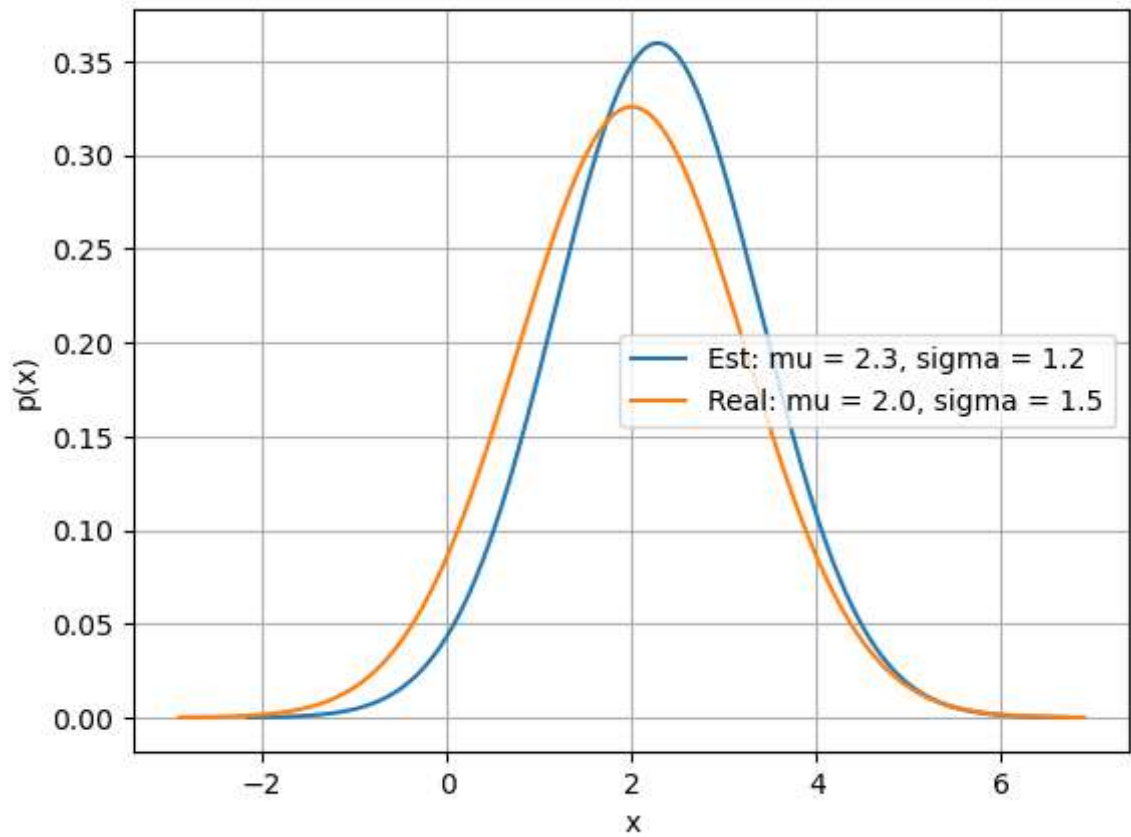
In [11]: main()

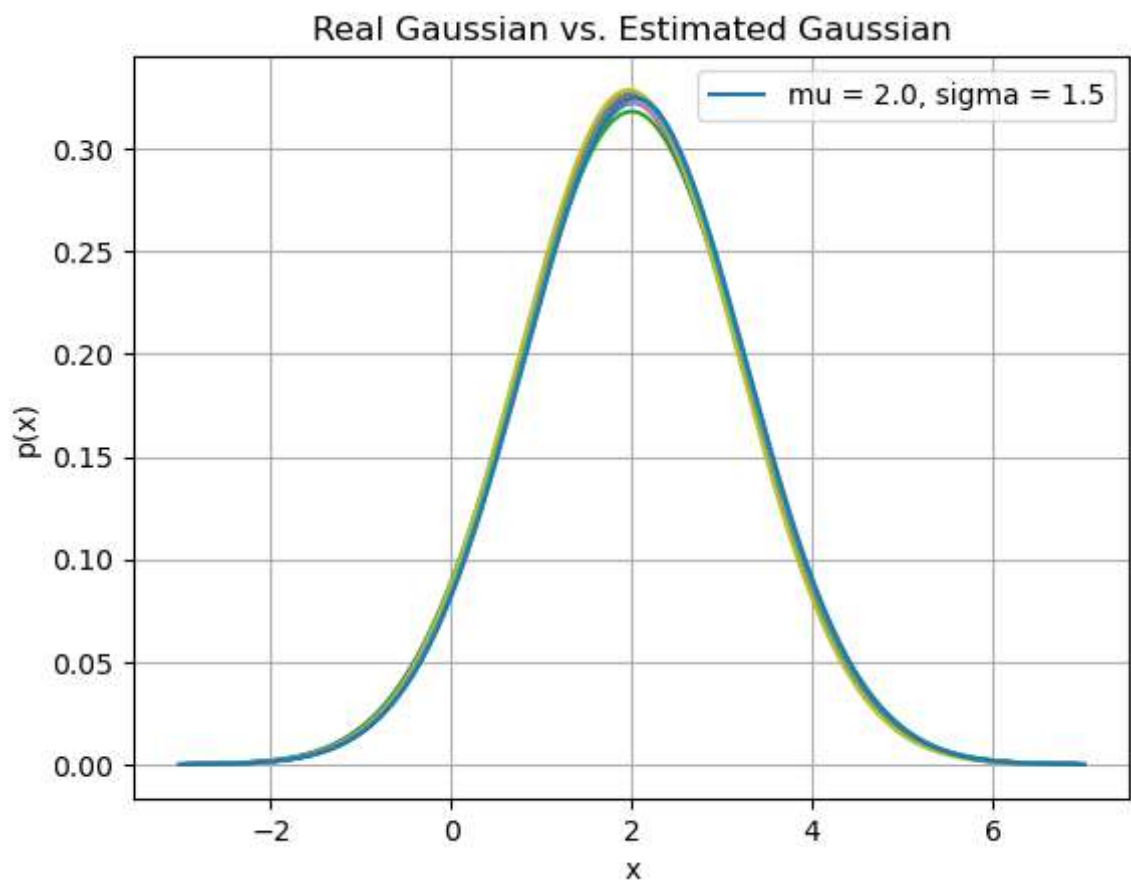
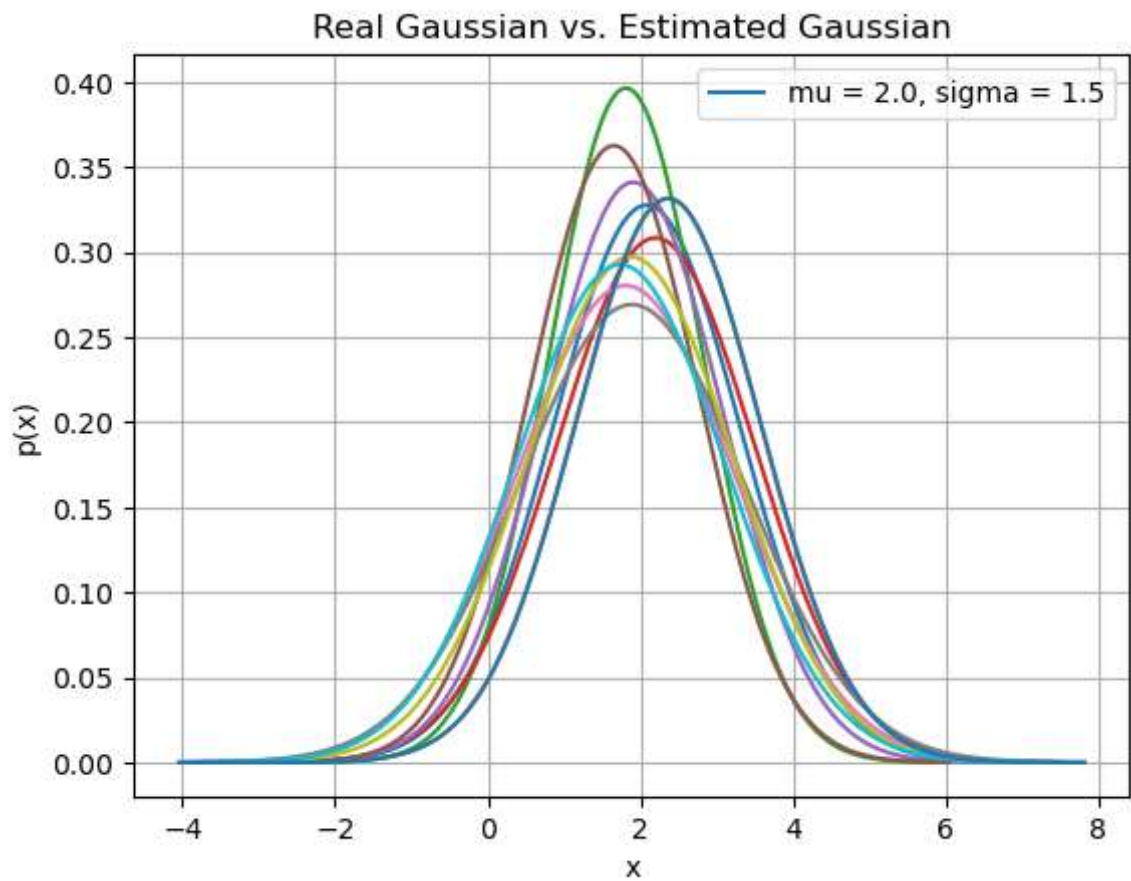


Real Gaussian vs. Estimated Gaussian



Real Gaussian vs. Estimated Gaussian





שאלה 7:

מסקנות

- משערך התוחלת הוא משערך חסר הטיה אסימפטוטית, משמע, שככל שנגדיל את כמות הדגימות שאנחנו מגרילים, כך נתקרב לממוצע האמיתי של התהליך

- משערך השונוט מתקרב גם הוא לערך השונוט האמיתי ככל שמגדילים את אורך המדגם

In [ ]: