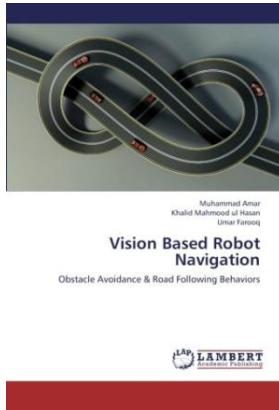


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VISION BASED ROBOT NAVIGATION



Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | Obstacle Avoidance & Road Following Behaviors | The aspiration of this research work is to design vision based intelligent mobile robot navigation techniques to capacitate an autonomous robot to navigate in indoor/outdoor environments. The images from mobile robot, accoutered with a camera, are preprocessed and are used for drivable region extraction. A novel weighted matrix algorithm (WMA) is used for drivable region division for, both, constructed and unconstructed scenarios. Hurdle distance, reckoned...

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