Dropout and Data Augmentation

In this exercise we will implement two ways to reduce overfitting.

Like the previous assignment, we will train ConvNets to recognize the categories in CIFAR-10. However unlike the previous assignment where we used 49,000 images for training, in this exercise we will use just 500 images for training.

If we try to train a high-capacity model like a ConvNet on this small amount of data, we expect to overfit, and end up with a solution that does not generalize. We will see that we can drastically reduce overfitting by using dropout and data augmentation.

In [1]:

```
# A bit of setup
import numpy as np
import matplotlib.pyplot as plt
from time import time
from cs231n.layers import *
from cs231n.fast layers import *
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'
# for auto-reloading extenrnal modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
def rel error(x, y):
    """ returns relative error """
    return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

Load data

For this exercise our training set will contain 500 images and our validation and test sets will contain 1000 images as usual.

In [2]:

```
from cs231n.data utils import load CIFAR10
def get CIFAR10 data(num training=500, num validation=1000, num test=1000, normalize
    Load the CIFAR-10 dataset from disk and perform preprocessing to prepare
    it for the two-layer neural net classifier. These are the same steps as
    we used for the SVM, but condensed to a single function.
    # Load the raw CIFAR-10 data
    cifar10 dir = 'cs231n/datasets/cifar-10-batches-py'
    X train, y train, X test, y test = load CIFAR10(cifar10 dir)
    # Subsample the data
    mask = range(num training, num training + num validation)
    X_val = X_train[mask]
    y_val = y_train[mask]
    mask = range(num_training)
    X_train = X_train[mask]
    y_train = y_train[mask]
    mask = range(num_test)
    X test = X test[mask]
    y_test = y_test[mask]
    # Normalize the data: subtract the mean image
    if normalize:
        mean image = np.mean(X train, axis=0)
        X train -= mean image
        X_val -= mean_image
        X test -= mean image
    # Transpose so that channels come first
    X \text{ train} = X \text{ train.transpose}(0, 3, 1, 2).copy()
    X \text{ val} = X \text{ val.transpose}(0, 3, 1, 2).copy()
    X \text{ test} = X \text{ test.transpose}(0, 3, 1, 2).copy()
    return X train, y train, X val, y val, X test, y test
# Invoke the above function to get our data.
X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data(num_training=500)
print 'Train data shape: ', X_train.shape
print 'Train labels shape: ', y_train.shape
print 'Validation data shape: ', X_val.shape
print 'Validation labels shape: ', y_val.shape
print 'Test data shape: ', X_test.shape
print 'Test labels shape: ', y_test.shape
Train data shape: (500, 3, 32, 32)
Train labels shape: (500,)
Validation data shape: (1000, 3, 32, 32)
Validation labels shape: (1000,)
Test data shape: (1000, 3, 32, 32)
Test labels shape: (1000,)
```

Overfit

Now that we've loaded our data, we will attempt to train a three layer convnet on this data. The three layer convnet has the architecture

```
conv - relu - pool - affine - relu - affine - softmax
```

We will use 32 5x5 filters, and our hidden affine layer will have 128 neurons.

This is a very expressive model given that we have only 500 training samples, so we should expect to massively overfit this dataset, and achieve a training accuracy of nearly 0.9 with a much lower validation accuracy.

In [3]:

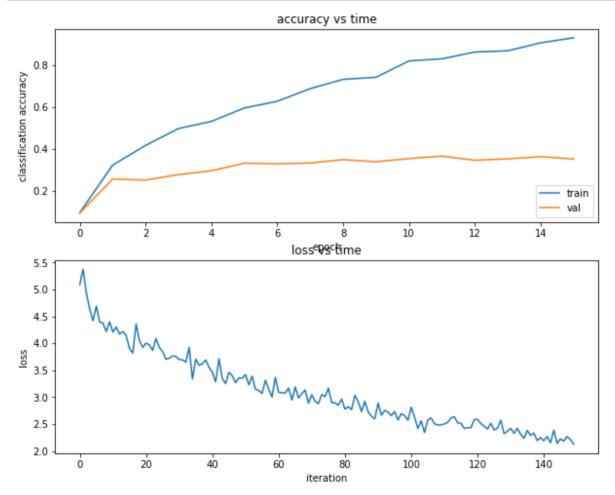
```
starting iteration 0
Finished epoch 0 / 15: cost 5.088299, train: 0.098000, val 0.096000, 1
r 5.000000e-05
Finished epoch 1 / 15: cost 4.400376, train: 0.324000, val 0.258000, 1
r 5.00000e-05
starting iteration 10
Finished epoch 2 / 15: cost 3.922261, train: 0.418000, val 0.253000, 1
r 5.00000e-05
starting iteration 20
Finished epoch 3 / 15: cost 3.754873, train: 0.498000, val 0.279000, 1
r 5.000000e-05
starting iteration 30
Finished epoch 4 / 15: cost 3.553548, train: 0.532000, val 0.297000, 1
r 5.000000e-05
starting iteration 40
Finished epoch 5 / 15: cost 3.350040, train: 0.596000, val 0.333000, 1
r 5.000000e-05
starting iteration 50
Finished epoch 6 / 15: cost 3.366896, train: 0.628000, val 0.330000, 1
r 5.000000e-05
starting iteration 60
Finished epoch 7 / 15: cost 2.888512, train: 0.688000, val 0.334000, l
r 5.000000e-05
starting iteration 70
Finished epoch 8 / 15: cost 2.964902, train: 0.732000, val 0.350000, 1
r 5.000000e-05
starting iteration 80
Finished epoch 9 / 15: cost 2.595897, train: 0.742000, val 0.340000, 1
r 5.000000e-05
starting iteration 90
Finished epoch 10 / 15: cost 2.569820, train: 0.820000, val 0.355000,
lr 5.000000e-05
starting iteration 100
Finished epoch 11 / 15: cost 2.482471, train: 0.830000, val 0.367000,
 lr 5.00000e-05
starting iteration 110
Finished epoch 12 / 15: cost 2.582510, train: 0.862000, val 0.347000,
lr 5.000000e-05
starting iteration 120
Finished epoch 13 / 15: cost 2.363852, train: 0.868000, val 0.354000,
 lr 5.000000e-05
starting iteration 130
Finished epoch 14 / 15: cost 2.245143, train: 0.906000, val 0.364000,
 lr 5.00000e-05
starting iteration 140
Finished epoch 15 / 15: cost 2.121581, train: 0.930000, val 0.353000,
 lr 5.00000e-05
finished optimization. best validation accuracy: 0.367000
```

In [4]:

```
# Visualize the loss and accuracy for our network trained on a small dataset

plt.subplot(2, 1, 1)
plt.plot(train_acc_history)
plt.plot(val_acc_history)
plt.title('accuracy vs time')
plt.legend(['train', 'val'], loc=4)
plt.xlabel('epoch')
plt.ylabel('classification accuracy')

plt.subplot(2, 1, 2)
plt.plot(loss_history)
plt.title('loss vs time')
plt.xlabel('iteration')
plt.ylabel('loss')
plt.show()
```



Dropout

The first way we will reduce overfitting is to use dropout.

You have already implemented this in Q1 of this exercise, but let's just check that it still works :-)

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In [5]:

```
# Check the dropout forward pass

x = np.random.randn(100, 100)
dropout_param_train = {'p': 0.25, 'mode': 'train'}
dropout_param_test = {'p': 0.25, 'mode': 'test'}

out_train, _ = dropout_forward(x, dropout_param_train)
out_test, _ = dropout_forward(x, dropout_param_test)

# Test dropout training mode; about 25% of the elements should be nonzero
print np.mean(out_train != 0)

# Test dropout test mode; all of the elements should be nonzero
print np.mean(out_test != 0)
```

```
0.2432
1.0
```

In [6]:

```
from cs231n.gradient_check import eval_numerical_gradient_array

# Check the dropout backward pass

x = np.random.randn(5, 4)
dout = np.random.randn(*x.shape)
dropout_param = {'p': 0.8, 'mode': 'train', 'seed': 123}

dx_num = eval_numerical_gradient_array(lambda x: dropout_forward(x, dropout_param)[
_, cache = dropout_forward(x, dropout_param)
dx = dropout_backward(dout, cache)

# The error should be around 1e-12
print 'Testing dropout_backward function:'
print 'dx error: ', rel_error(dx_num, dx)
```

```
Testing dropout_backward function: dx error: 5.60619585502e-12
```

Data Augmentation

The next way we will reduce overfitting is to implement data augmentation. Since we have very little training data, we will use what little training data we have to generate artificial data, and use this artificial data to train our network.

CIFAR-10 images are 32x32, and up until this point we have used the entire image as input to our convnets. Now we will do something different: our convnet will expect a smaller input (say 28x28). Instead of feeding our training images directly to the convnet, at training time we will randomly crop each training image to 28x28, randomly flip half of the training images horizontally, and randomly adjust the contrast and tint of each training image.

Open the file cs231n/data_augmentation.py and implement the random_flips, random_crops, random_contrast, and random_tint functions. In the same file we have implemented the fixed_crops function to get you started. When you are done you can run the cell below to visualize the effects of each type of data augmentation.

In [9]:

```
from cs231n.data augmentation import *
X = get CIFAR10 data(num training=100, normalize=False)[0]
num imgs = 8
print X.dtype
X = X[np.random.randint(100, size=num imgs)]
X flip = random flips(X)
X rand crop = random_crops(X, (28, 28))
# To give more dramatic visualizations we use large scales for random contrast
# and tint adjustment.
X_contrast = random_contrast(X, scale=(0.5, 1.0))
X \text{ tint} = \text{random tint}(X, \text{scale}=(-50, 50))
next plt = 1
for i in xrange(num imgs):
    titles = ['original', 'flip', 'rand crop', 'contrast', 'tint']
    for j, XX in enumerate([X, X_flip, X_rand_crop, X_contrast, X_tint]):
        plt.subplot(num_imgs, 5, next_plt)
        img = XX[i].transpose(1, 2, 0)
        if j == 4:
            # For visualization purposes we rescale the pixel values of the
            # tinted images
            low, high = np.min(img), np.max(img)
            img = 255 * (img - low) / (high - low)
        plt.imshow(img.astype('uint8'))
        if i == 0:
            plt.title(titles[j])
        plt.gca().axis('off')
        next plt += 1
plt.show()
```

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Train again

We will now train a new network with the same training data and the same architecture, but using data augmentation and dropout.

If everything works, you should see a higher validation accuracy than above and a smaller gap between the training accuracy and the validation accuracy.

Networks with dropout usually take a bit longer to train, so we will use more training epochs this time.

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```
In [10]:
```

```
input shape = (3, 28, 28)
def augment fn(X):
    out = random flips(random crops(X, input shape[1:]))
    out = random tint(random contrast(out))
    return out
def predict fn(X):
    return fixed crops(X, input_shape[1:], 'center')
model = init three layer convnet(filter size=5, input shape=input shape, num filter
trainer = ClassifierTrainer()
best model, loss history, train acc history, val acc history = trainer.train(
          X_train, y_train, X_val, y_val, model, three_layer_convnet,
          reg=0.05, learning rate=0.00005, learning rate decay=1.0,
          batch_size=50, num_epochs=30, update='rmsprop', verbose=True, dropout=0.6
          augment fn=augment fn, predict fn=predict fn)
starting iteration
Finished epoch 0 / 30: cost 4.462354, train: 0.116000, val 0.109000, 1
r 5.000000e-05
Finished epoch 1 / 30: cost 3.949423, train: 0.256000, val 0.207000, 1
r 5.000000e-05
starting iteration 10
Finished epoch 2 / 30: cost 3.870883, train: 0.344000, val 0.279000, 1
r 5.000000e-05
starting iteration 20
Finished epoch 3 / 30: cost 3.689486, train: 0.384000, val 0.293000, 1
r 5.000000e-05
starting iteration 30
Finished epoch 4 / 30: cost 3.404734, train: 0.392000, val 0.295000, 1
r 5.000000e-05
starting iteration
                   40
Finished epoch 5 / 30: cost 3.404313, train: 0.410000, val 0.297000, 1
r 5.00000e-05
starting iteration 50
Finished epoch 6 / 30: cost 3.349540, train: 0.444000, val 0.344000, 1
r 5.000000e-05
starting iteration 60
Finished epoch 7 / 30: cost 3.266141, train: 0.442000, val 0.311000, 1
r 5.00000e-05
starting iteration 70
Finished epoch 8 / 30: cost 3.274204, train: 0.440000, val 0.321000, l
r 5.000000e-05
starting iteration 80
Finished epoch 9 / 30: cost 3.023025, train: 0.510000, val 0.348000, 1
r 5.000000e-05
starting iteration 90
Finished epoch 10 / 30: cost 2.939756, train: 0.476000, val 0.337000,
 lr 5.00000e-05
starting iteration 100
Finished epoch 11 / 30: cost 2.837103, train: 0.480000, val 0.336000,
 lr 5.000000e-05
starting iteration 110
Finished epoch 12 / 30: cost 3.081674, train: 0.542000, val 0.355000,
 lr 5.00000e-05
starting iteration 120
Finished epoch 13 / 30: cost 2.817488, train: 0.542000, val 0.348000,
```

```
Ir 5.000000e-05
starting iteration 130
Finished epoch 14 / 30: cost 2.863651, train: 0.528000, val 0.352000,
 lr 5.000000e-05
starting iteration 140
Finished epoch 15 / 30: cost 2.725764, train: 0.530000, val 0.345000,
 lr 5.00000e-05
starting iteration 150
Finished epoch 16 / 30: cost 2.741285, train: 0.558000, val 0.357000,
 lr 5.000000e-05
starting iteration 160
Finished epoch 17 / 30: cost 2.677579, train: 0.552000, val 0.360000,
 lr 5.000000e-05
starting iteration 170
Finished epoch 18 / 30: cost 2.648138, train: 0.576000, val 0.374000,
lr 5.000000e-05
starting iteration 180
Finished epoch 19 / 30: cost 2.461526, train: 0.568000, val 0.356000,
 lr 5.00000e-05
starting iteration 190
Finished epoch 20 / 30: cost 2.637206, train: 0.592000, val 0.367000,
 lr 5.00000e-05
starting iteration 200
Finished epoch 21 / 30: cost 2.600418, train: 0.576000, val 0.366000,
 lr 5.00000e-05
starting iteration 210
Finished epoch 22 / 30: cost 2.544883, train: 0.592000, val 0.373000,
 lr 5.00000e-05
starting iteration 220
Finished epoch 23 / 30: cost 2.495177, train: 0.614000, val 0.380000,
 lr 5.000000e-05
starting iteration 230
Finished epoch 24 / 30: cost 2.355899, train: 0.620000, val 0.375000,
 lr 5.00000e-05
starting iteration 240
Finished epoch 25 / 30: cost 2.704518, train: 0.610000, val 0.369000,
lr 5.000000e-05
starting iteration 250
Finished epoch 26 / 30: cost 2.257667, train: 0.626000, val 0.368000,
 lr 5.000000e-05
starting iteration 260
Finished epoch 27 / 30: cost 2.501569, train: 0.630000, val 0.368000,
 lr 5.000000e-05
starting iteration 270
Finished epoch 28 / 30: cost 2.231723, train: 0.654000, val 0.376000,
 lr 5.000000e-05
starting iteration 280
Finished epoch 29 / 30: cost 2.467361, train: 0.656000, val 0.370000,
 lr 5.000000e-05
starting iteration 290
Finished epoch 30 / 30: cost 2.228828, train: 0.654000, val 0.392000,
lr 5.000000e-05
finished optimization. best validation accuracy: 0.392000
```