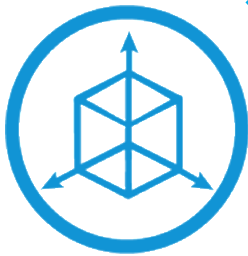

Gesture Recognition using IMU sensors

Amitangshu Pal

IMU Sensors

IMU Sensors



Accelerometer
(measures
acceleration)



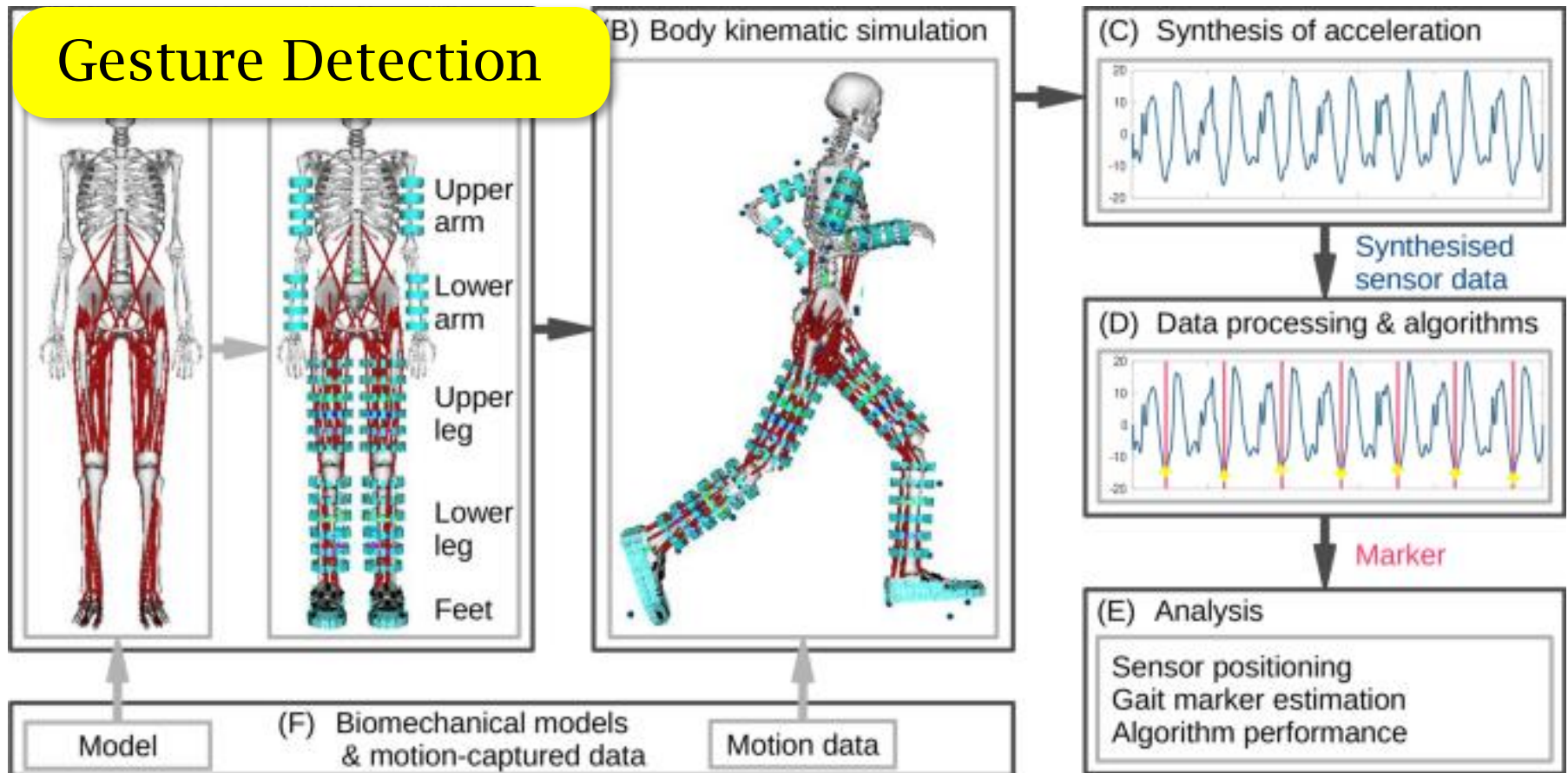
Gyroscope
(measures
angular velocity)



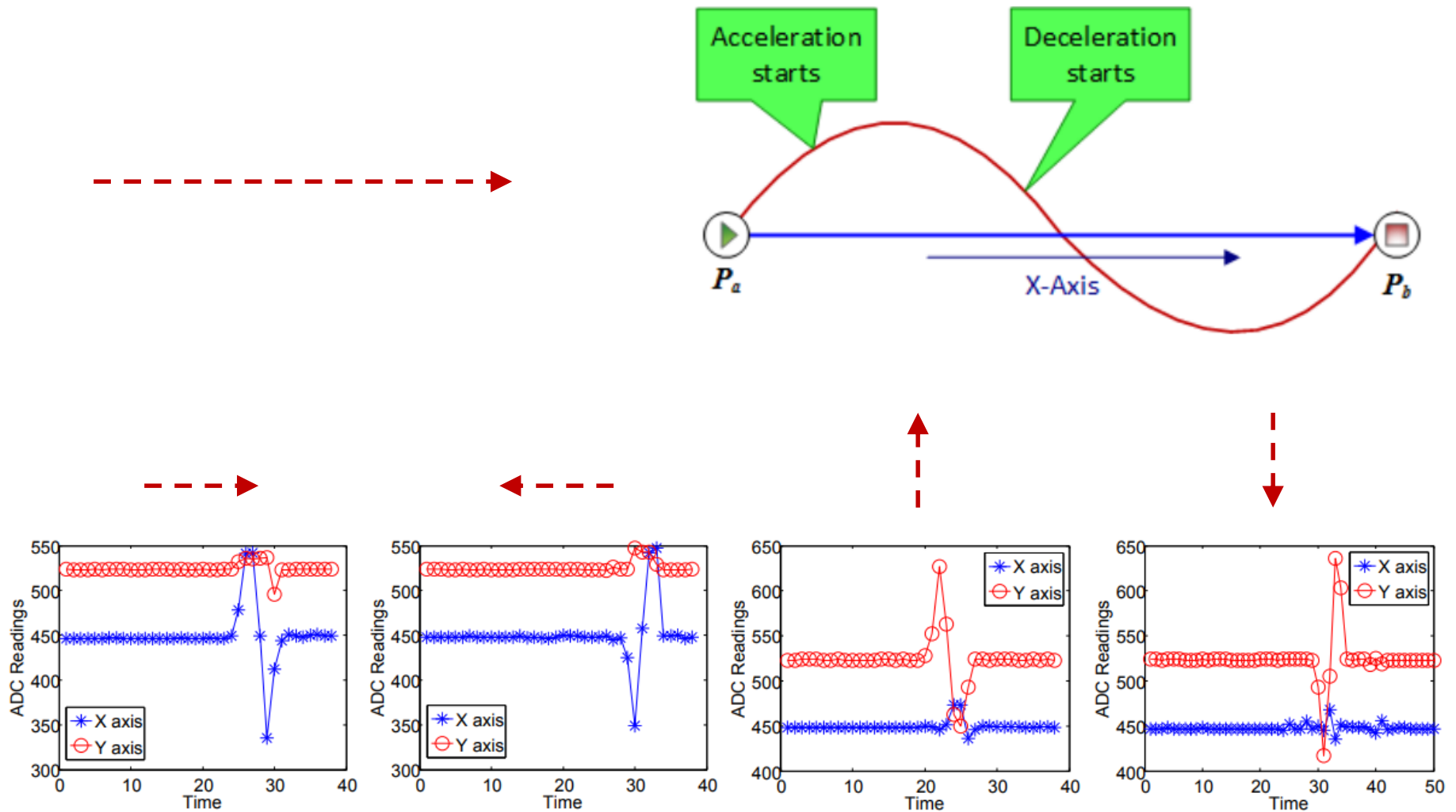
Magnetometer
(measures earth
magnetic field)

Sensing, Communication and Networking for Smart Wireless Devices

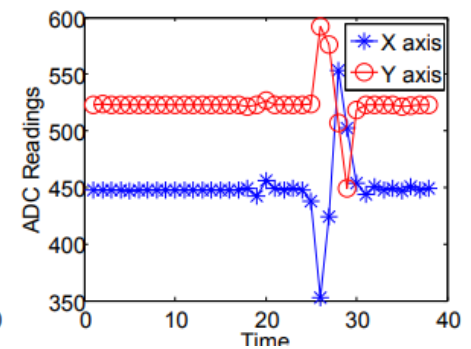
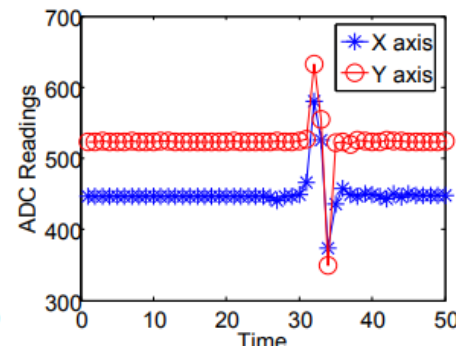
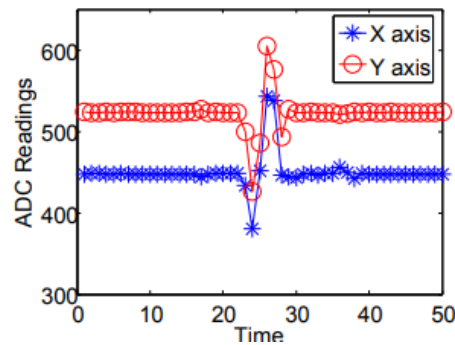
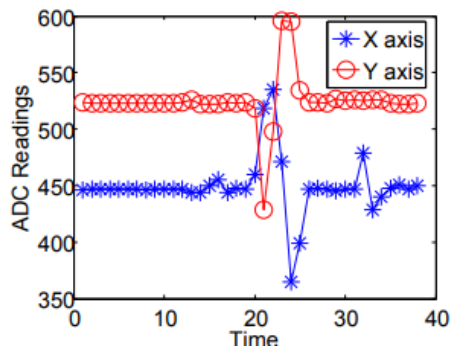
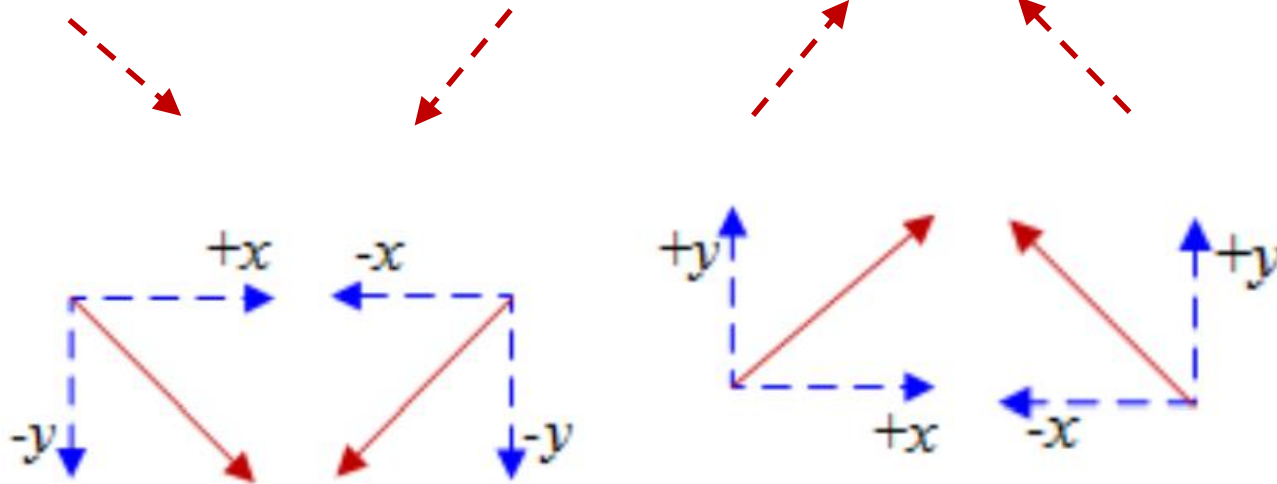
Gesture Detection



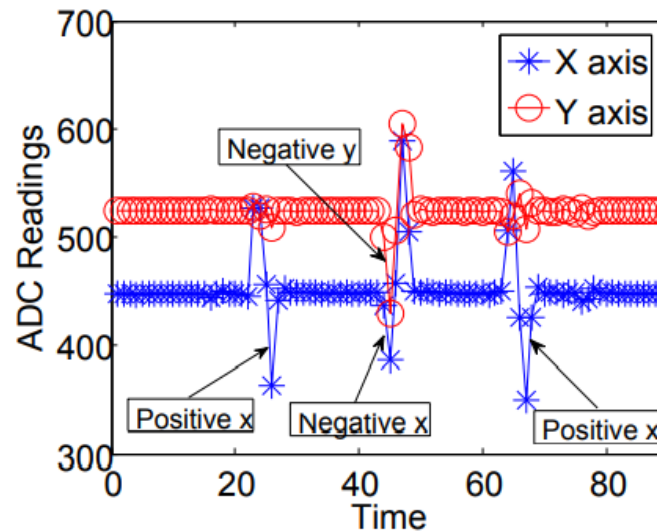
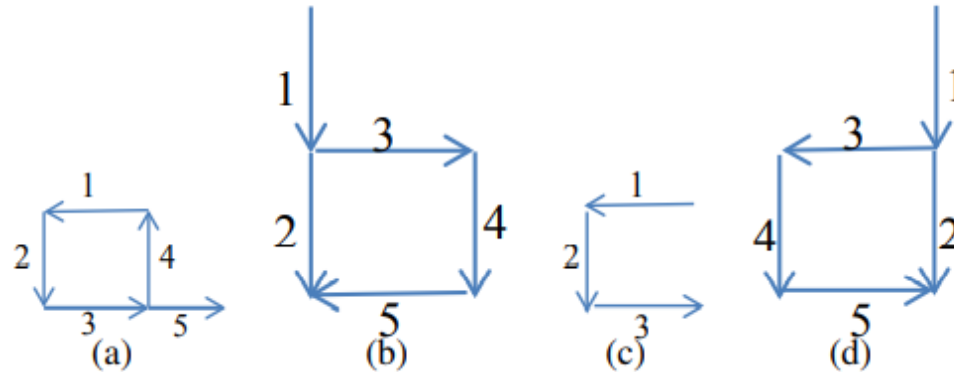
Hand Movement Detection with Strokes



Hand Movement Detection with Strokes



Hand Movement Detection with Strokes



Sensing, Communication and Networking for Smart Wireless Devices

Gesture Detection



Audio Signal Matching

Doors and corners, kid. That's
where they get you.



Doors and corners, kid. That's
where they get you.



You walk into a room too fast, the
room eats you.

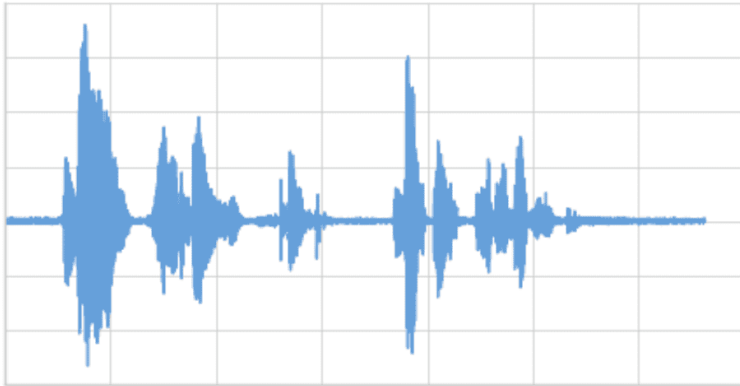


Doors and corners, kid. That's
where they get you.

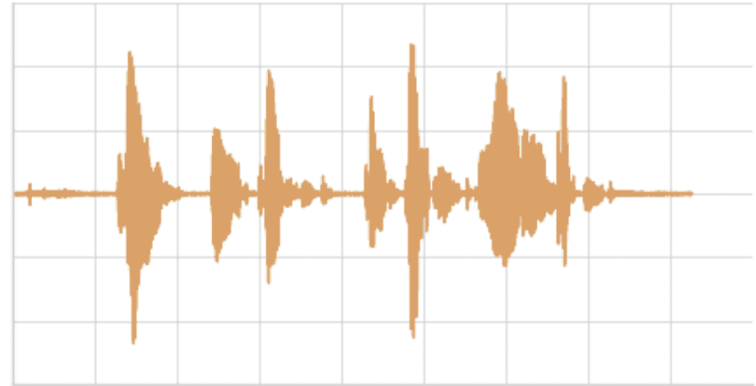


Audio Signal Matching

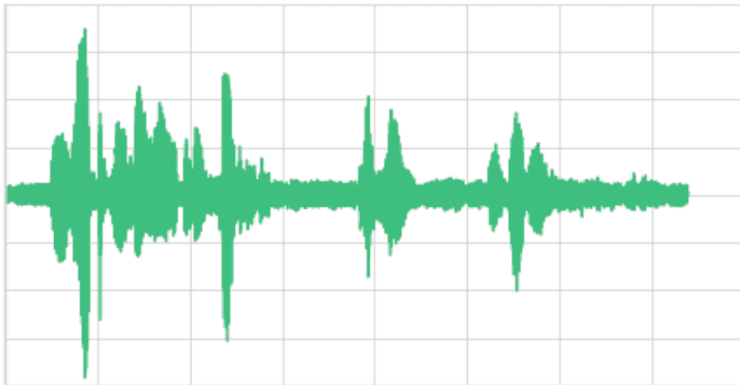
Doors and Corners, Kid. That's where they get you.



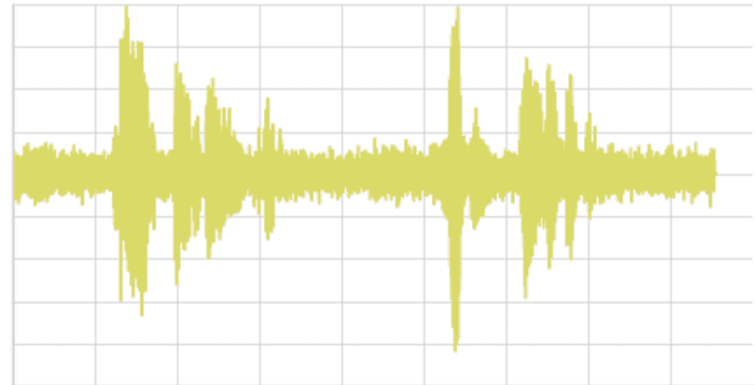
Doors and Corners, Kid. That's where they get you.(v2)



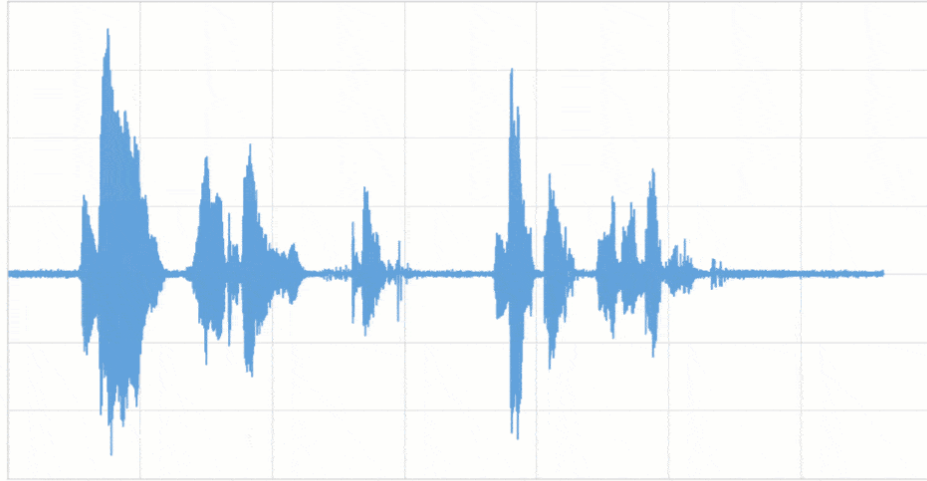
You walk into the room too fast, the room eats you.



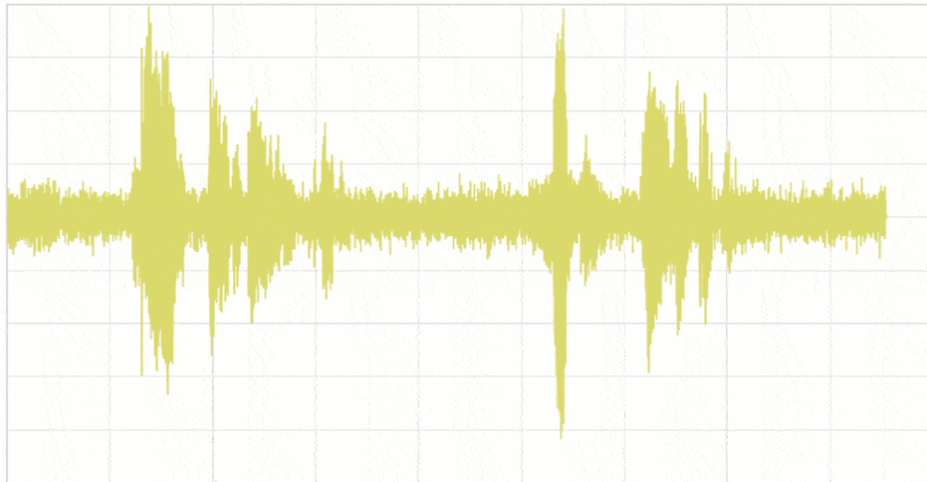
Doors and Corners, Kid. That's where they get you.(v3)



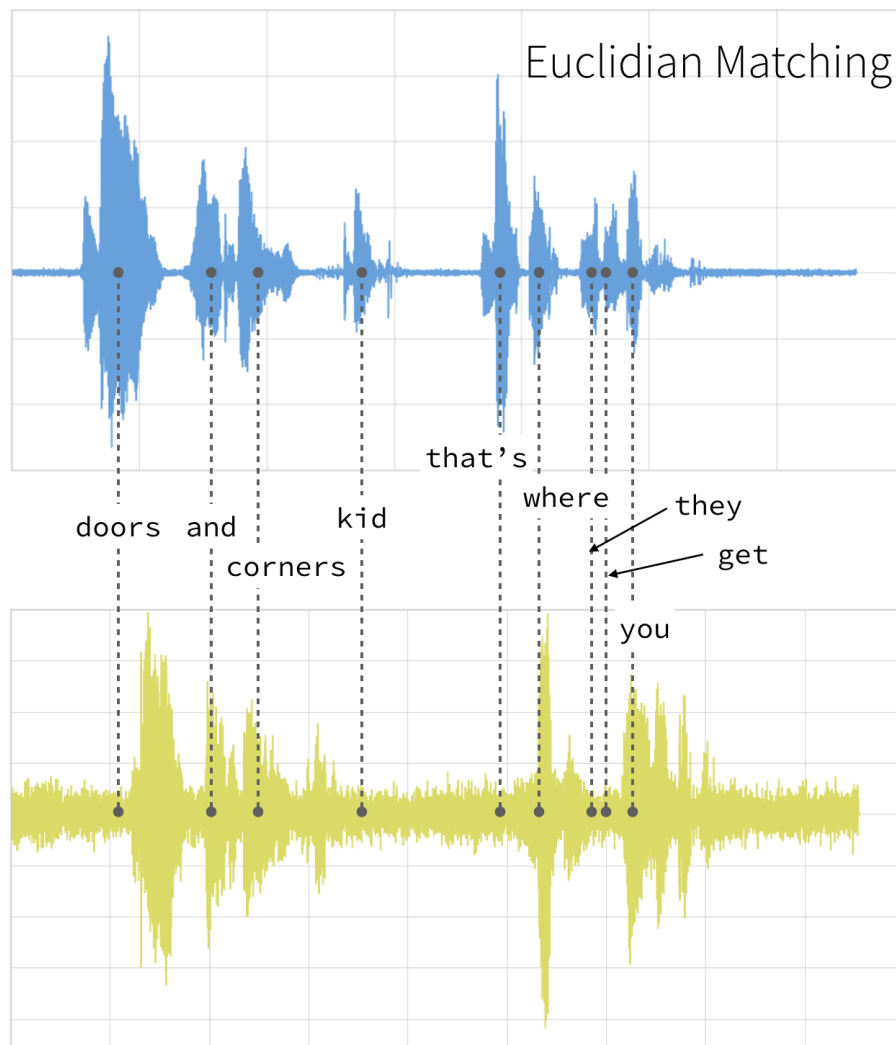
Audio Signal Matching



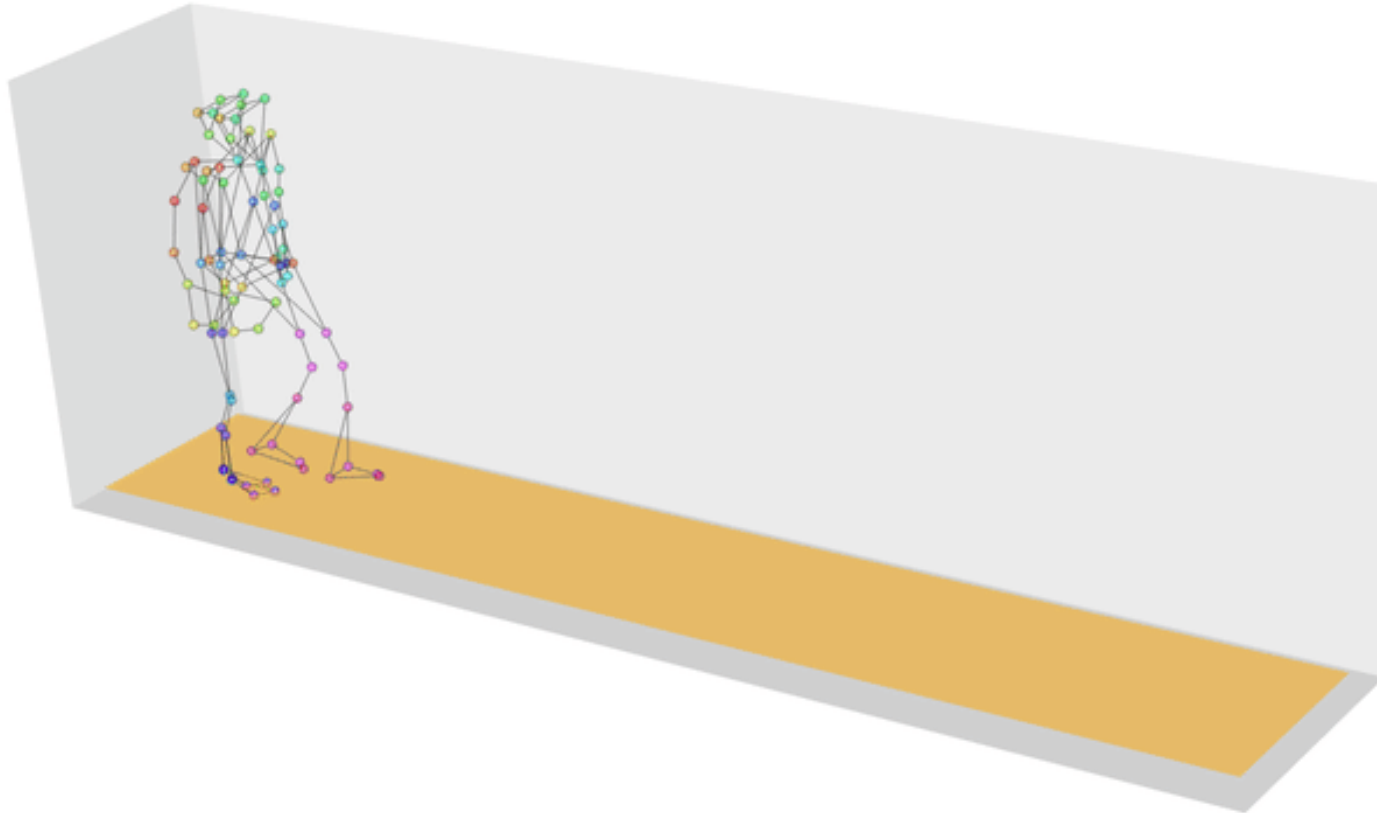
Doors and corners, kid. That's where they get you.



Calculating Euclidian Distance is not Sufficient

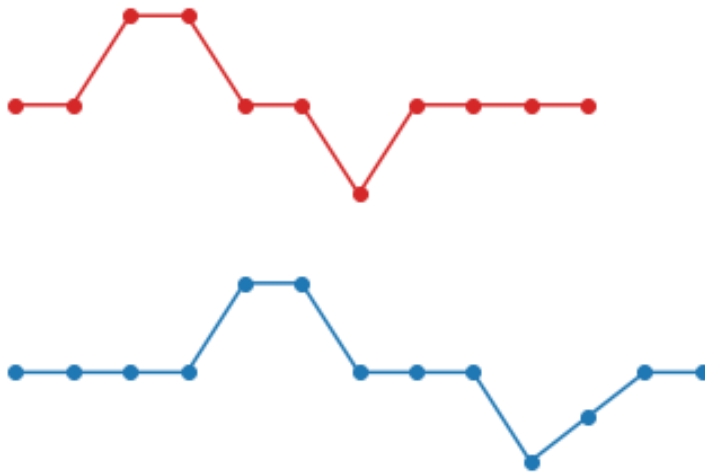
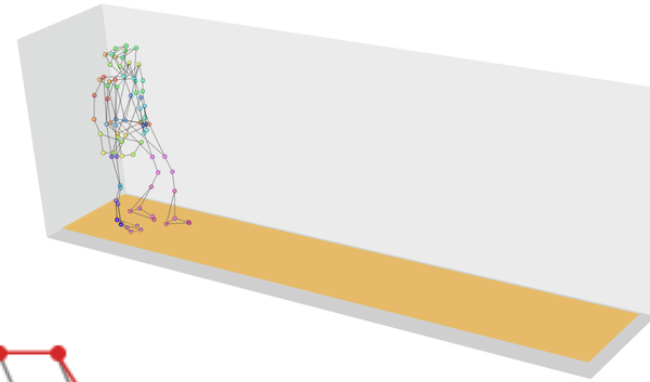


Walking Pattern Matching

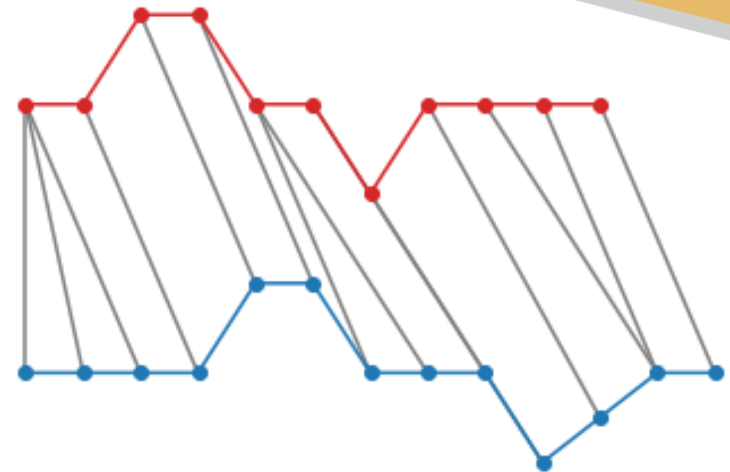


Dynamic Time Warping

- How similar are two signals?
- Which points corresponding to one another?

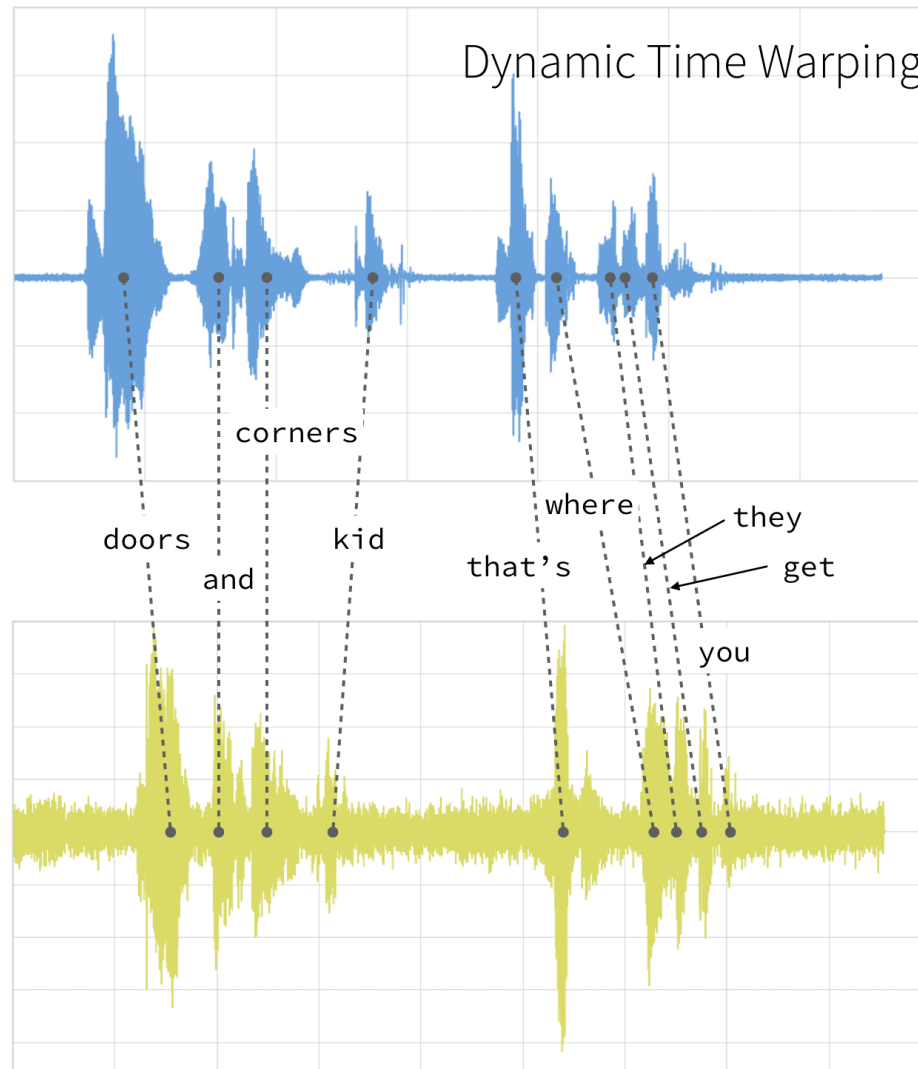


ED: Produces poor similarity score



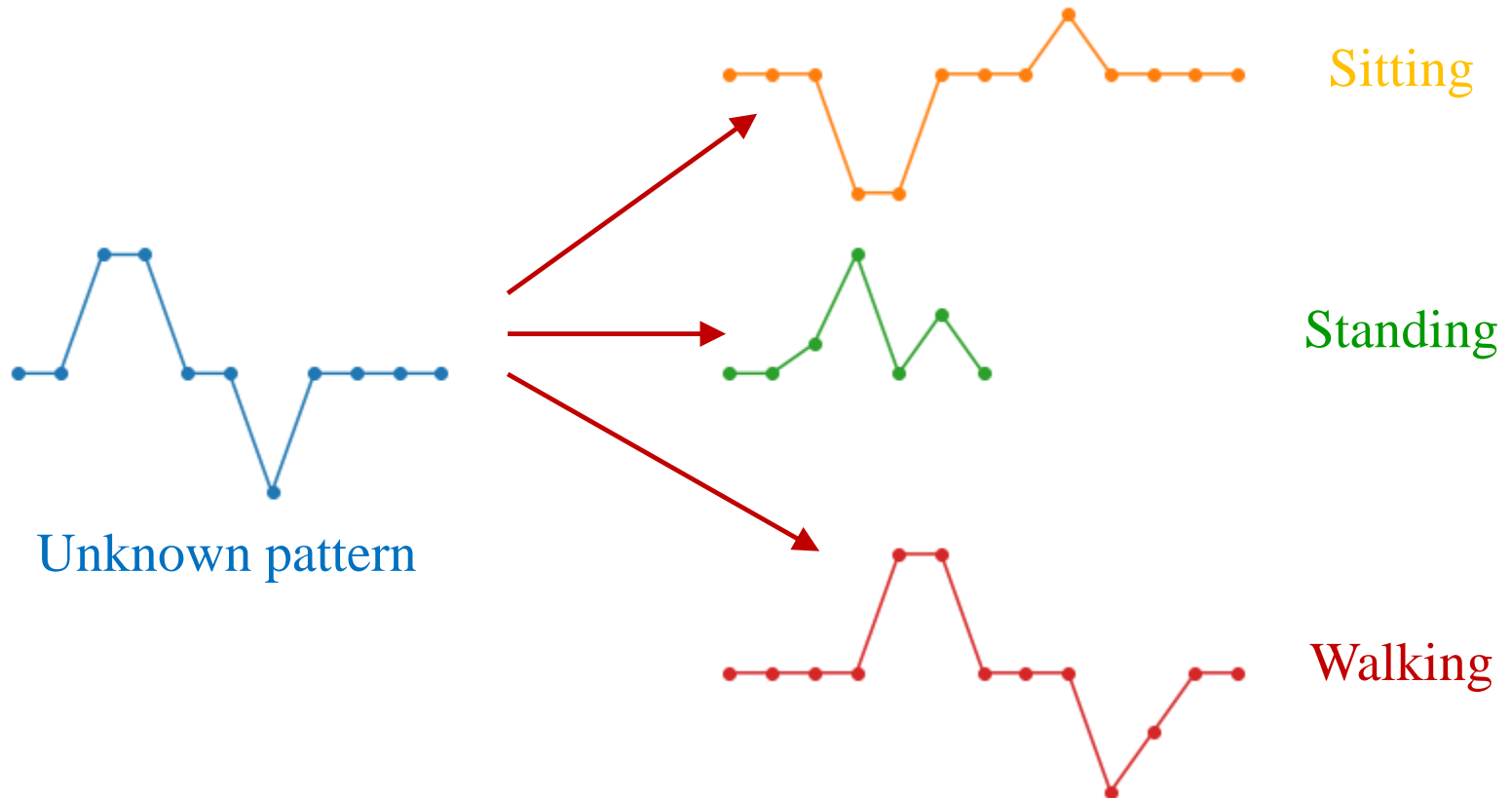
DTW: More intuitive similarity score → allows similar shapes to match even if they are out of phase

DTW for Audio Signal Matching



DTW for Posture Detection

- How similar are two signals?
- Which points corresponding to one another?



Systematic DTW Algorithm

Inputs: $x_{1:N}$ and $y_{1:M}$

Cost matrix: $D \in \mathbb{R}^{N+1 \times M+1}$

Initialization: for $i = 1$ to N : $D_{i,0} = \infty$

for $j = 1$ to M : $D_{0,j} = \infty$

$D_{0,0} = 0$

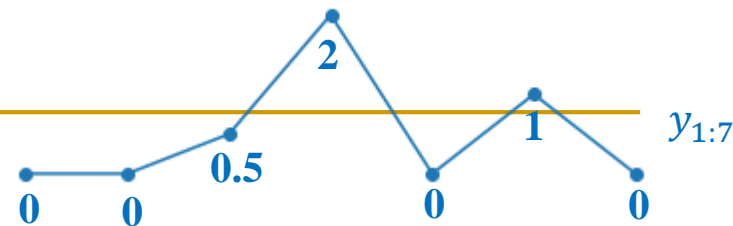
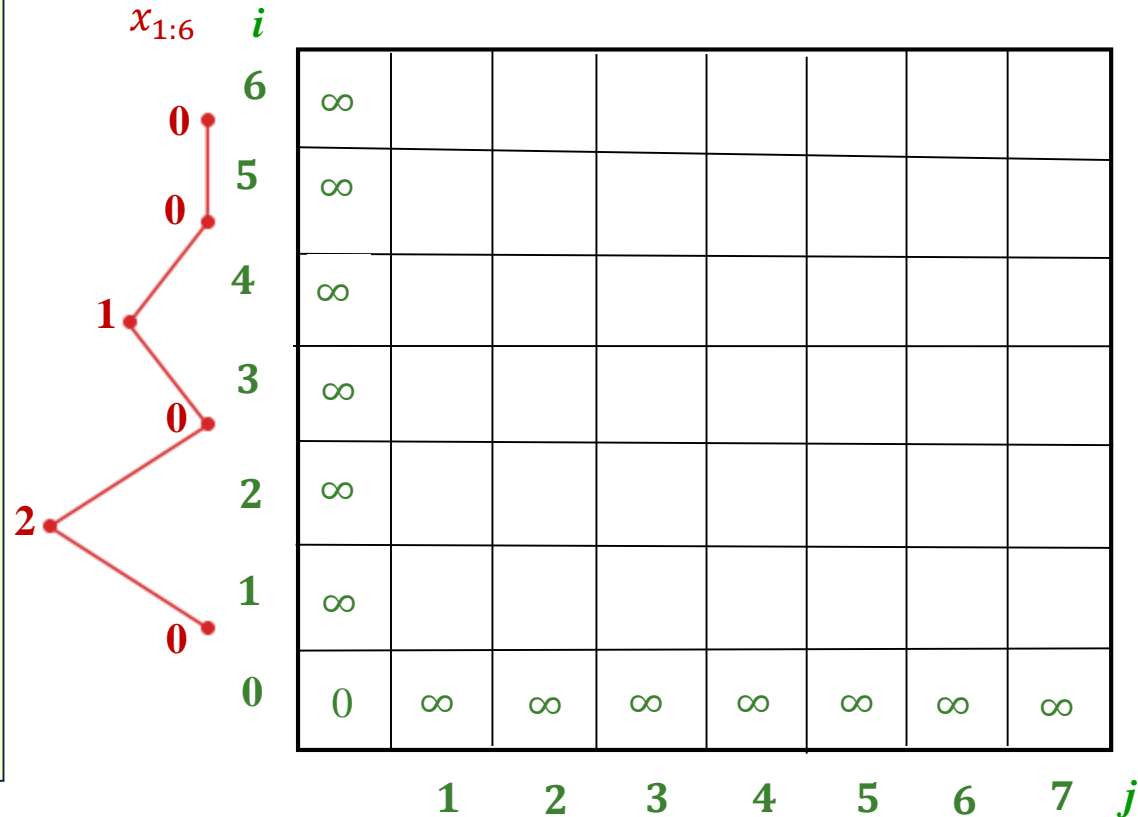
Calculate cost matrix:

for $i = 1$ to N :

for $j = 1$ to M :

$$D_{ij} = d(x_i, y_j) + \min \begin{bmatrix} D_{i-1,j-1} \\ D_{i-1,j} \\ D_{i,j-1} \end{bmatrix}$$

Get alignment: Trace back from $D_{N,M}$ to $D_{0,0}$



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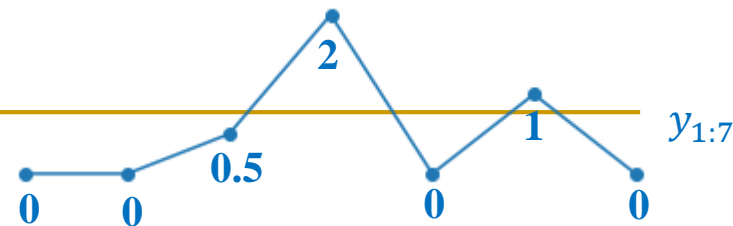
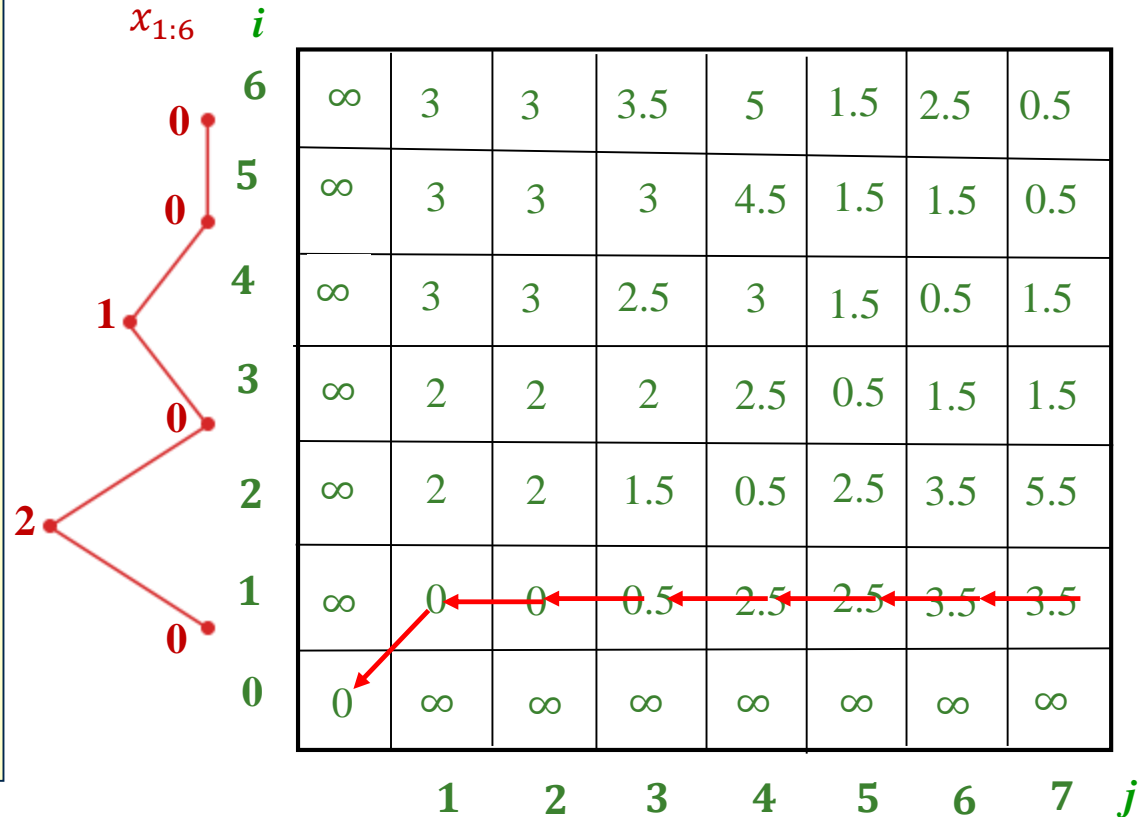
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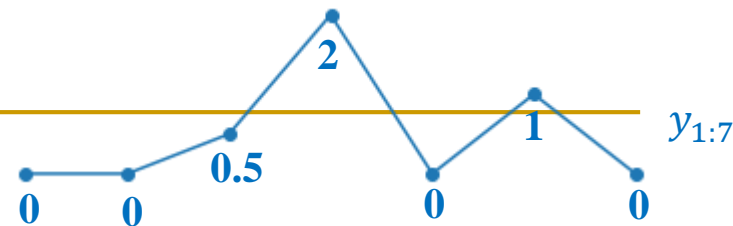
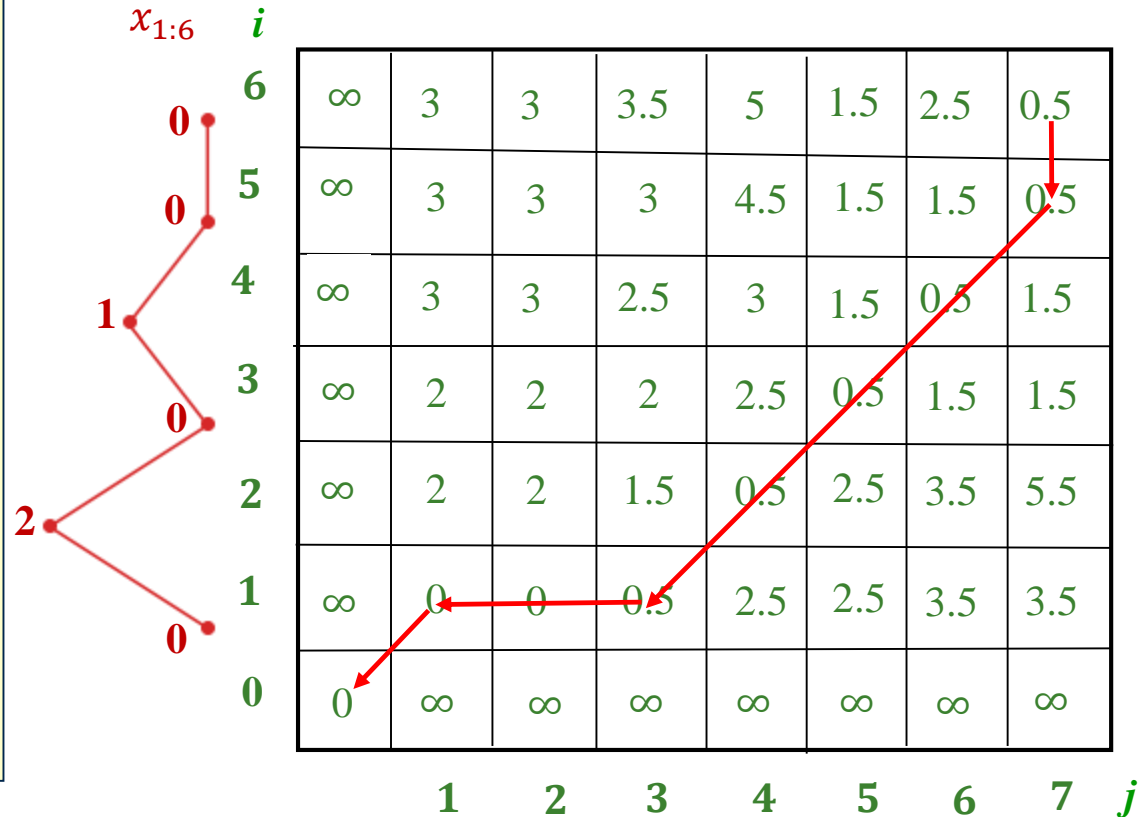
Calculate cost matrix:

for $i = 1$ to N :

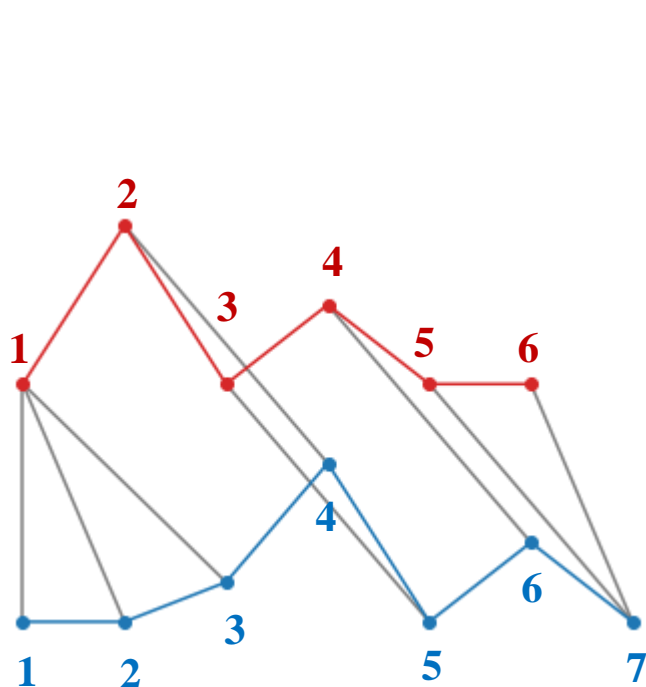
for $j = 1$ to M :

$$D_{ij} = d(x_i, y_j) + \min \begin{bmatrix} D_{i-1,j-1} \\ D_{i-1,j} \\ D_{i,j-1} \end{bmatrix}$$

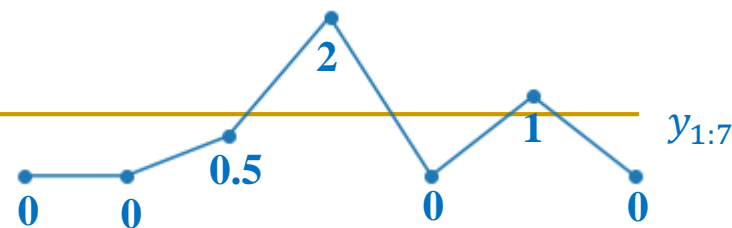
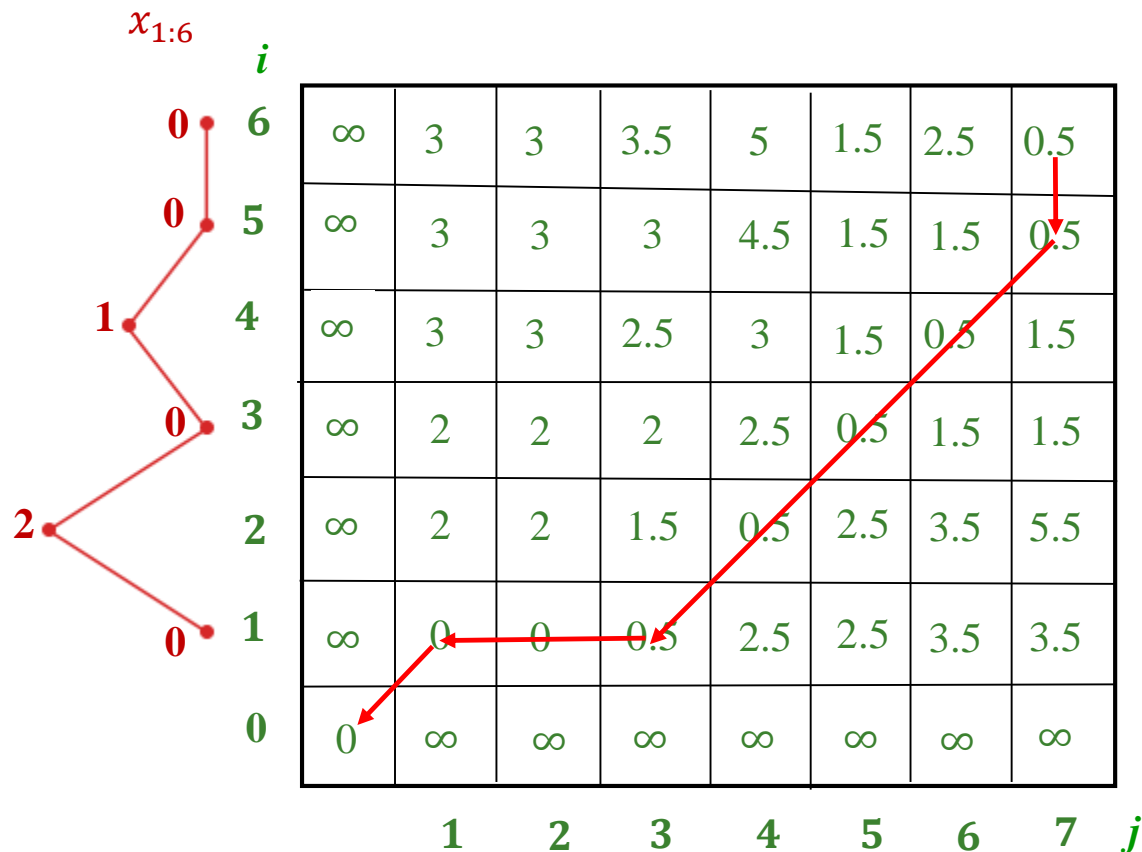
Get alignment: Trace back from $D_{N,M}$ to $D_{0,0}$



Systematic DTW Algorithm



Cost: 0.5



DTW for Audio Signal Matching

Doors and corners, kid. That's
where they get you.



Doors and corners, kid. That's
where they get you.



Base	Query	Distance
Clip 1	Clip 2	480148446.0
	Clip 3	310038909.0
	Clip 4	293547478.0

You walk into a room too fast, the
room eats you.



Doors and corners, kid. That's
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