

Review: MODRL

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1 Paper Profile

- Title: A Multi-Objective Deep Reinforcement Learning Framework
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The present paper proposed a new MODRL framework on DQN coded in Python. It includes the use of linear and non-linear methods to develop the framework which is able to accommodate both single-policy and multi-policy strategies. And the resulting performance on the two previously proposed benchmarks, which are the Deep Sea Treasure and Mountain-Car problems, indicate the convergence to the optimal Pareto solutions effectively.

4 Introduction

The author has summarised the past researches by quoting some good researches as below.

- Q-Learning[6]: Tabular method requiring huge memory so that impractical in practice.
- DRL(e.g., Deep Q network by Mnih et al., 2015[1]) to overcome the problem using experience replay and function approximation techniques
- Mossalam et al. (2016) [2] extended deep Q-network to handle single-policy linear MORL
- Tajmajer(2017) [3] has extended DQN with a non-linear action selection approach based on a subsumption architecture
- Vamplew et al.(2017) [5] developed an MORL framework named MORL_Glue which is based on RL_Glue(Tanner and White, 2009) [4]. Unfortunately, this framework was not compatible with Deep neural networks.

5 Proposal

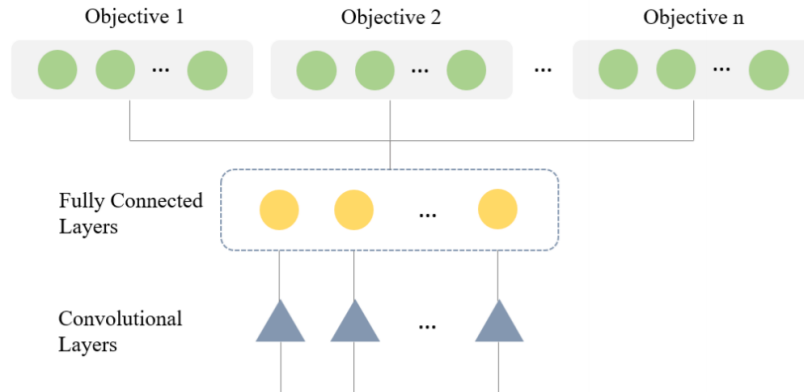


Fig. 1. Neural network structure used in our DQN-based MODRL framework.

Reference

- [1] Volodymyr Mnih et al. “Human-level control through deep reinforcement learning”. In: *Nature* 518.7540 (2015), p. 529.
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- [5] Peter Vamplew et al. “Steering approaches to Pareto-optimal multiobjective reinforcement learning”. In: *Neurocomputing* 263 (2017), pp. 26–38.
- [6] Christopher J.C.H. Watkins and Peter Dayan. “Technical Note: Q-Learning”. In: *Machine Learning* 8.3 (May 1992), pp. 279–292. ISSN: 1573-0565. DOI: 10 . 1023 / A : 1022676722315. URL: <https://doi.org/10.1023/A:1022676722315>.