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#define IrSensor 2
#define Buzzer 3

int count = 0;
void setup()
{
  pinMode(IrSensor, INPUT);
  pinMode(Buzzer, OUTPUT);
  Serial.begin(9600);
}

void myfunc()
{
  if(count >= 5)
  {
    Serial.println("CALL NURSE!");
    digitalWrite(Buzzer, HIGH);
    delay(1500);
  }
  else if(count >=2 and count<5)
  {
    Serial.println("WATER");
    digitalWrite(Buzzer, HIGH);
    delay(800);
  }
  else if(count == 1)
  {
    Serial.println("HUNGRY");
    digitalWrite(Buzzer, HIGH);
    delay(300);
  }
  count = 0;
  digitalWrite(Buzzer, LOW);
}

void loop()
{
  int ir = digitalRead(IrSensor);
  if(ir==0)
  {
    count = count + 1;
    delay(1000);
  }
  if(ir==1)
  {
    myfunc();
  }
}

```