## Math 589 Midterm Take-home-exam Solution



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## Question 2(b)

To apply the C-N scheme derived in (a), we use Thomas Algorithm to get the numerical result, notice we find solutions for two different terminal time: T=0.1 and T=0.2.

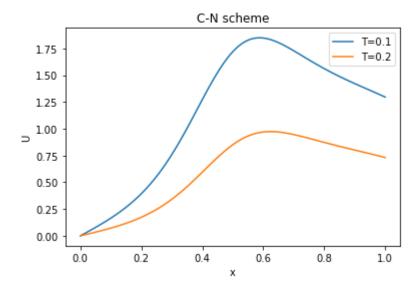
```
In [1]: import numpy as np
    from matplotlib import pyplot as plt

In [2]: # function of p
    def p(x):
        return np.exp(np.cos(2*np.pi*x))
```

```
In [3]: # initial settings
                        dx = 0.01
                        mu = 0.1 # convergence satisfied
                        dt = mu*dx**2
                        x = np.array([i*dx for i in range(int(1/dx)+1)])
                        # Thomas Algorithm
                         p_{minus} = p(x-0.5*dx)
                         p plus = p(x+0.5*dx)
                         b = 1+0.5*mu*(p_minus+p_plus)
                        b[-2] = b[-2]-0.5*mu*p_plus[-2]/(1+dx) # boundary condition
                         a = 0.5*mu*p minus
                         c = 0.5*mu*p plus
                         alpha = np.zeros(len(x))
                         alpha[1] = b[1]
                         for i in range(2,len(x)-1):
                                    alpha[i] = b[i]-(a[i]*c[i-1])/alpha[i-1]
                         T = [0.1, 0.2]
                        U result = []
                         for t in T:
                                    N = int(t/dt)
                                    U = 4/(1+x**2) # initial condition
                                    for n in range(N):
                                                ## prepare at the beginning
                                                s = np.zeros(len(x))
                                                d = np.zeros(len(x))
                                                ## forward elimination
                                                d[1:-1] = 0.5*mu*p_minus[1:-1]*U[:-2]+(1-0.5*mu*(p_minus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plus[1:-1]+p_plu
                                                s[1] = d[1]
                                                for i in range(2,len(x)-1):
                                                            s[i] = d[i]+(a[i]*s[i-1])/alpha[i-1]
                                                ## backward subsititution
                                                U new = np.zeros(len(U))
                                                U_new[0] = 0 # boundary condition
                                                U \text{ new}[-2] = s[-2]/alpha[-2]
                                                U \text{ new}[-1] = U \text{ new}[-2]/(dx+1) \# boundary condition
                                                for i in range(len(U new)-3,0,-1):
                                                            U new[i] = (s[i]+c[i]*U new[i+1])/alpha[i]
                                                U = U new
                                    U result.append(U)
```

```
In [4]: i = 0
for u in U_result:
    plt.plot(x,u,label='T='+str(T[i]))
    i+=1
plt.xlabel('x')
plt.ylabel('U')
plt.title('C-N scheme')
plt.legend()
```

Out[4]: <matplotlib.legend.Legend at 0x223cef11610>



## (c)

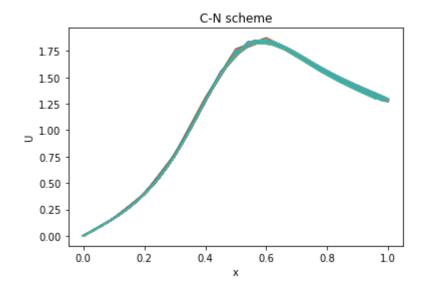
To verify the convergence numerically, we can fixed terminal time T, then choose different  $(\Delta x, \Delta t) \to 0$ (or different  $\mu$ ), as long as they all satisfy the convergence condition  $\mu \leq \frac{1}{e}$ . And then check if the solution is stable. Here we choose  $\Delta x = [0.001, 0.01], \mu = [0.01, 0.1]$  and both of them are decreasing for every loop. Then we plot the final result for numerical solution U.

```
In [3]: # fix T=0.1
                      # initial settings
                      Dx = np.linspace(0.1, 0.01, 10)
                      mu arr = np.linspace(0.2,0.1,10) # convergence satisfied
                       T = [0.1]
                      X = []
                       U result = []
                       for t in T:
                                 for j in range(len(Dx)):
                                            for 1 in range(len(mu arr)):
                                                       dx = Dx[j]
                                                       mu = mu arr[1]
                                                       dt = mu*dx**2
                                                       N = int(t/dt)
                                                       x = np.array([k*dx for k in range(int(1/dx)+1)])
                                                       X.append(x)
                                                       # Thomas Algorithm
                                                        p minus = p(x-0.5*dx)
                                                       p plus = p(x+0.5*dx)
                                                       b = 1+0.5*mu*(p_minus+p_plus)
                                                       b[-2] = b[-2]-0.5*mu*p plus[-2]/(1+dx) # boundary condition
                                                       a = 0.5*mu*p minus
                                                       c = 0.5*mu*p_plus
                                                       alpha = np.zeros(len(x))
                                                        alpha[1] = b[1]
                                                       for i in range(2,len(x)-1):
                                                                  alpha[i] = b[i]-(a[i]*c[i-1])/alpha[i-1]
                                                       U = 4/(1+x**2) # initial condition
                                                       for n in range(N):
                                                                  ## prepare at the beginning
                                                                  s = np.zeros(len(x))
                                                                  d = np.zeros(len(x))
                                                                  ## forward elimination
                                                                  d[1:-1] = 0.5*mu*p_minus[1:-1]*U[:-2]+(1-0.5*mu*(p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus[1:-1]+p_minus
                                                                  s[1] = d[1]
                                                                  for i in range(2,len(x)-1):
                                                                             s[i] = d[i]+(a[i]*s[i-1])/alpha[i-1]
                                                                  ## backward subsititution
                                                                  U new = np.zeros(len(U))
                                                                  U_new[0] = 0 # boundary condition
                                                                  U_new[-2] = s[-2]/alpha[-2]
                                                                  U new[-1] = U new[-2]/(dx+1) # boundary condition
                                                                  for i in range(len(U new)-3,0,-1):
                                                                             U new[i] = (s[i]+c[i]*U new[i+1])/alpha[i]
                                                                  U = U new
                                                       U result.append(U)
```

```
In [5]: for j in range(len(U_result)):
    x = X[j]
    u = U_result[j]
    plt.plot(x,u,label=str(j))

plt.xlabel('x')
plt.ylabel('U')
plt.title('C-N scheme')
```

Out[5]: Text(0.5, 1.0, 'C-N scheme')



We can see that the numerical solution converges as  $(\Delta x, \Delta t) \rightarrow 0$ .

```
In [16]: # # Inverse matrix
                                                                           \# U = 4/(1+x**2)
                                                                           \# al = -0.5*mu*p(x-0.5*dx)
                                                                           # bl = 1+0.5*mu*(p(x-0.5*dx)+p(x+0.5*dx))
                                                                           \# cl = -0.5*mu*p(x+0.5*dx)
                                                                           # AL = np.eye(len(al), len(al), k=-1)*np.roll(al, -1) + np.eye(len(bl), len(bl))*bl + np.eye(l
                                                                           \# ar = 0.5*mu*p(x-0.5*dx)
                                                                           \# br = 1-0.5*mu*(p(x-0.5*dx)+p(x+0.5*dx))
                                                                           \# cr = 0.5*mu*p(x+0.5*dx)
                                                                           # Ar = np.eye(len(ar), len(ar), k=-1)*np.roll(ar, -1) + np.eye(len(br), len(br))*br + np.eye(len(br), len(br), len(br))*br + np.eye(len(br), len(br), len(br))*br + np.eye(len(br), len(br), len(br), len(br))*br + np.eye(len(br), len(br), len(br), len(br))*br + np.eye(len(br), len(br), len(br)
                                                                           # for n in range(N):
                                                                                                                           U_new = np.zeros(len(U))
                                                                                                                           U_new[1:] = np.dot(np.linalg.inv(AL[1:,1:]), np.dot(Ar[1:,1:],U[1:]))
                                                                                                                           U \text{ new}[0] = 0
                                                                                                                          U_new[-1] = U_new[-1]/(1+dx)
                                                                                                                           U = U new
                                                                           #
```