

## 2) Robust Regression

(a) According to Majorize-Minimize Algorithm, we find a majorizing function  $\bar{J}(\vec{\theta}, \vec{\theta}_t)$  and then iterate  $\vec{\theta}_t$  with solution for  $\vec{\theta}_{t+1} = \arg \min \bar{J}(\vec{\theta}, \vec{\theta}_t)$

According to the lemma in notes, we have such  $\bar{J}$  s.t.

$$\bar{J}(\vec{\theta}, \vec{\theta}_t) = \sum_{i=1}^n \bar{\rho}(y_i - \vec{\omega}^T \vec{x}_i - b)$$

$$\text{where } \bar{\rho}(r) = \rho(r_{t,i}) - \frac{1}{2} r_{t,i} \psi(r_{t,i}) + \frac{1}{2} \frac{\psi(r_{t,i})}{r_{t,i}} r^2$$

$$\psi(r) = \rho'(cr), \quad r_{t,i} = y_i - \vec{\omega}_t^T \vec{x}_i - b_t$$

It's nothing but

$$\vec{\theta}_{t+1} = \arg \min \left( \sum_{i=1}^n \left( \rho(r_{t,i}) - \frac{1}{2} r_{t,i} \psi(r_{t,i}) + \frac{1}{2} \frac{\psi(r_{t,i})}{r_{t,i}} r^2 \right) \right)$$

since for time  $t$ ,  $r_{t,i}$  is known (can be computed)

$$\text{Then } \vec{\theta}_{t+1} = \arg \min \sum_{i=1}^n \frac{1}{2} \frac{\psi(r_{t,i})}{r_{t,i}} r^2$$

Suppose  $c_{t,i} = \frac{1}{2} \frac{\psi(r_{t,i})}{r_{t,i}}$ , then

$$\vec{\theta}_{t+1} = \arg \min_{\vec{\theta}} \sum_{i=1}^n c_{t,i} (y_i - \vec{\theta}^T \vec{x}_i)^2$$

Since that  $c_{t,i}$  is changing with iteration time  $t$  changes, we can think MM algorithm as "iteratively reweighted least squares"

Explain of robustness: From the lemma we know that

$$c_{t,i} = \frac{1}{2} \frac{\psi(r_{t,i})}{r_{t,i}} \text{ is nonincreasing for } r_{t,i} > 0.$$

That is to say, for outliers who have larger error  $r_{t,i}$ , the weight  $c_{t,i}$  will be smaller. (Noting that since  $\rho(r)$  is symmetric