# Deep Generative Models: Discrete Latent Variables

Philip Schulz and Wilker Aziz

VI Tutorial @ Host Site

- First Attempt: Wake-Sleep
- Neural Variational Inference
- Score function estimator
- Variance reduction

#### Generative Models

Joint distribution over observed data x and latent variables z.

$$p(x, z|\theta) = \underbrace{p(z)}_{\text{prior}} \underbrace{p(x|z, \theta)}_{\text{likelihood}}$$

The likelihood and prior are often standard distributions (Gaussian, Bernoulli) with simple dependence on conditioning information.

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### Deep generative models

Joint distribution with deep observation model

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Marginal likelihood

$$p(x|\theta) = \int p(x, z|\theta) dz = \int p(z)p(x|z, \theta) dz$$

intractable in general

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We need approximate inference techniques!

And we've developed the ELBO

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$$\text{ELBO} = \underbrace{\mathbb{E}_{q(z|x)} \left[ \log \frac{p(z|x)p(x)}{q(z|x)} \right]}_{\text{gap}} + \log p(x)$$

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#### Wake-sleep Algorithm

- Generalise latent variables to Neural Networks
- Train generative neural model
- Use variational inference! (kind of)

#### 2 Neural Networks:

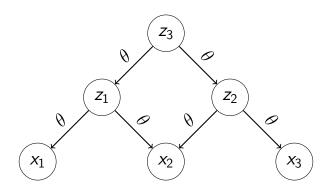
• A generation network to model the data (the one we want to optimise) – parameters:  $\theta$ 

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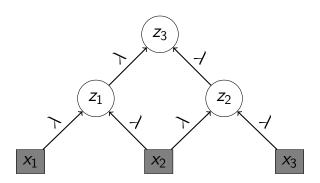
- A generation network to model the data (the one we want to optimise) parameters:  $\theta$
- An inference (recognition) network (to model the latent variable) parameters:  $\lambda$
- Original setting: binary hidden units
- Training is performed in a "hard EM" fashion

# Generator



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#### Inference Network



### Wake-sleep Training

#### Wake Phase

- Use inference network to sample hidden unit setting z from  $q(z|x,\lambda)$
- Update generation parameters  $\theta$  to maximize joint log-liklelihood of data and latents  $p(x, z|\theta)$

# Wake-sleep Training

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- Use inference network to sample hidden unit setting z from  $q(z|x,\lambda)$
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#### **Sleep Phase**

- ullet Produce dream sample  $ilde{x}$  from random hidden unit z
- Update inference parameters  $\lambda$  to maximize probability of latent state  $q(z|\tilde{x}, \lambda)$

#### Objective

$$\begin{split} & \underset{\theta}{\operatorname{arg \, max}} \ \mathbb{E}_{p(x)} \left[ \operatorname{ELBO}(\theta, \lambda | x) \right] \\ & = \underset{\theta}{\operatorname{arg \, max}} \ \mathbb{E}_{p(x)} \left[ \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(z,x|\theta) \right] + \mathbb{H}[q(z|x,\lambda)] \right] \end{split}$$

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Gradient wrt  $\theta$  for  $x \sim p(x)$ 

$$\nabla_{\theta} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(z,x|\theta) \right] + \nabla_{\theta} \mathbb{H}[q(z|x,\lambda)]$$

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Gradient wrt  $\theta$  for  $x \sim p(x)$ 

$$\begin{split} & \nabla_{\theta} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(z,x|\theta) \right] + \nabla_{\theta} \mathbb{H}[q(z|x,\lambda)] \\ &= \mathbb{E}_{q(z|x,\lambda)} \left[ \nabla_{\theta} \log p(z,x|\theta) \right] \\ & \stackrel{\mathsf{MC}}{\approx} \nabla_{\theta} \log p(z,x|\theta) \quad \text{where } z \sim q(z|x,\lambda) \end{split}$$

Assumes z to be fixed random draw from  $q(z|x, \lambda)$  and maximises  $\log p(z, x|\theta)$ .

This is simply supervised learning with imputed latent data!

Sampling  $z \sim q(z|x,\lambda)$ 

$$\left(z_3\right)$$

 $\left(z_1\right)$ 

$$\left(z_{2}\right)$$

 $x_1$ 

*X*<sub>2</sub>

*X*3

Sampling  $z \sim q(z|x,\lambda)$ 



 $\left(z_1\right)$ 

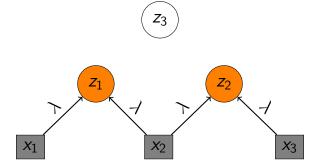


*x*<sub>1</sub>

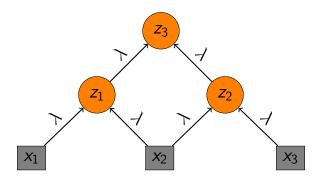
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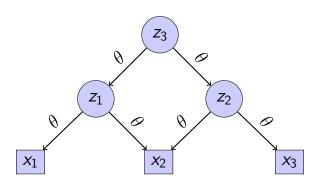


Sampling  $z \sim q(z|x,\lambda)$ 



### Wake Phase Update

#### Compute $\log p(x, z|\theta)$ and update $\theta$



# Sleep Phase Objective

#### Objective

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Gradient wrt 
$$\lambda$$
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$$\nabla_{\lambda}\mathbb{E}_{q(z|x,\lambda)}\left[\log p(z,x|\theta)\right] + \nabla_{\lambda}\mathbb{H}[q(z|x,\lambda)]$$

## Sleep Phase Objective

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Gradient wrt  $\lambda$  for  $x \sim p(x)$ 

$$\nabla_{\lambda}\mathbb{E}_{q(z|x,\lambda)}\left[\log p(z,x|\theta)\right] + \nabla_{\lambda}\mathbb{H}[q(z|x,\lambda)]$$

Let's change the objective!

Flip the direction of the KL

$$\underset{\lambda}{\operatorname{arg\,min}} \mathbb{E}_{p(x)} \left[ \mathsf{KL} \left( \frac{p(z|x,\theta)}{p(z|x,\lambda)} \right) | q(z|x,\lambda) \right) \right]$$

### Flip the direction of the KL

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#### Gradient wrt $\lambda$

$$\nabla_{\lambda}\mathbb{E}_{p(x,z|\theta)}\left[\log q(z|x,\lambda)\right]$$

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Assumes fake data  $\tilde{x}$  and latent variables z to be fixed random draws from  $p(x, z|\theta)$  via

$$z \sim p(z|\theta)$$
  
 $\tilde{x} \sim p(x|z,\theta)$ 

and maximises  $\log q(z|\tilde{x},\lambda)$ .

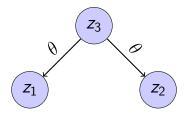
## Sleep Phase Sampling

Sampling  $(z, \tilde{x}) \sim p(x, z|\theta)$ 



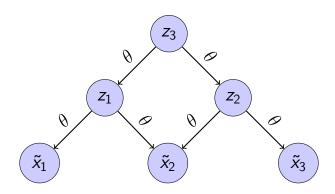
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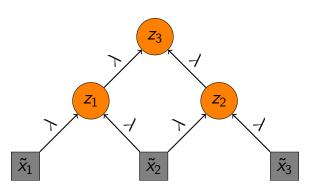
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## Sleep Phase Update

## Compute $\log q(z|\tilde{x},\lambda)$ and update $\lambda$



## Wake-sleep Algorithm

### **Advantages**

- Simple layer-wise updates
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#### **Drawbacks**

- Inference and generative networks are trained on different objectives
- ullet Inference weights  $\lambda$  are updated on fake data ilde x
- $\bullet$  Generative weights are bad initially, giving wrong signal to the updates of  $\lambda$

- First Attempt: Wake-Sleep
- Neural Variational Inference
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Generative model with NN likelihood

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• a document  $x = (x_1, ..., x_N)$  consists of n i.i.d. categorical draws from that model

Generative model with NN likelihood

Let us consider a latent factor model for topic modelling:

- a document  $x = (x_1, ..., x_N)$  consists of n i.i.d. categorical draws from that model
- the categorical distribution in turn depends on binary latent factors  $z = (z_1, \ldots, z_K)$  which are also i.i.d.

## Latent factor model

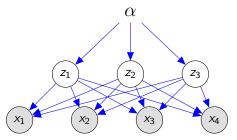
$$Z_j \sim \mathsf{Bernoulli}\left(lpha
ight) \qquad (1 \leq k \leq K) \ X_i | z \sim \mathsf{Categorical}\left(f(z; heta)
ight) \quad (1 \leq i \leq N)$$

Here  $0 < \alpha < 1$  specifies a Bernoulli prior and  $f(\cdot; \theta)$  is a function computed by a neural network with softmax output, e.g.

$$f(z; \theta) = \text{softmax}(Wz + b)$$
  
 $\theta = \{W, b\}$ 

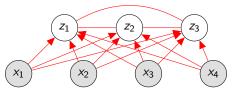
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## Example Model



Joint distribution: independent latent variables

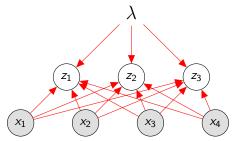
## Example Model



Posterior: latent variables are marginally dependent.

For our variational distribution we are going to assume that they are not (recall: mean field assumption).

## Mean Field Inference



The inference network needs to predict K Bernoulli parameters  $b_1^K$ . Any neural network with sigmoid output will do that job.

## Inference Network

$$q(z|x,\lambda) = \prod_{k=1}^K \mathsf{Bern}(z_k|b_k)$$
 where  $b_1^K = g(x;\lambda)$ 

Example architecture

$$h = \frac{1}{N} \sum_{i=1}^{N} E_{x_i}$$
  $b_1^K = sigmoid(Mh + c)$ 

$$\lambda = \{E, M, c\}$$

## Objective

$$\mathsf{ELBO} = \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x,z| heta) 
ight] + \mathbb{H} \left( q(z|x,\lambda) 
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## Objective

$$\mathsf{ELBO} = \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x,z| heta) \right] + \mathbb{H} \left( q(z|x,\lambda) \right) \ = \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z, heta) \right] - \mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right)$$

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Parameter estimation

$$rg \max_{ heta, \lambda} \; \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z, heta) \right] - \mathsf{KL} \left( q(z|x,\lambda) \; || \; p(z) 
ight)$$

## KL

KL between K independent Bernoulli distributions is tractable

$$\mathsf{KL}\left(q(z|x,\lambda)\mid\mid p(z|\alpha)\right) = \sum_{k=1}^{K} \mathsf{KL}\left(q(z_k|x,\lambda)\mid\mid p(z_k|\alpha)\right)$$

## KL

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## KL

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### Generative Network Gradient

$$\frac{\partial}{\partial \theta} \left( \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right)}^{\mathsf{constant wrt } \theta} \right)$$

## Generative Network Gradient

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$$= \underbrace{\mathbb{E}_{q(z|x,\lambda)} \left[ \frac{\partial}{\partial \theta} \log p(x|z,\theta) \right]}_{\mathsf{expected gradient } :)}$$

## Generative Network Gradient

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## Inference Network Gradient

$$\frac{\partial}{\partial \lambda} \left( \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right)}^{\mathsf{analytical}} \right)$$

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The first term again requires approximation by sampling, but there is a problem

$$rac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} \left[ \log p_{ heta}(x|z) 
ight]$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\ = \frac{\partial}{\partial \lambda} \sum_{z} q(z|x,\lambda) \log p(x|z,\theta)$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)]$$

$$= \frac{\partial}{\partial \lambda} \sum_{z} q(z|x,\lambda) \log p(x|z,\theta)$$

$$= \sum_{z} \frac{\partial}{\partial \lambda} (q(z|x,\lambda)) \log p(x|z,\theta)$$
not an expectation

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MC estimator is non-differentiable

$$\begin{split} &\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} \left[ \log p_{\theta}(x|z) \right] \\ &= \frac{\partial}{\partial \lambda} \sum_{z} q(z|x,\lambda) \log p(x|z,\theta) \\ &= \underbrace{\sum_{z} \frac{\partial}{\partial \lambda} (q(z|x,\lambda)) \log p(x|z,\theta)}_{\text{not an expectation}} \end{split}$$

- MC estimator is non-differentiable
- Differentiating the expression does not yield an expectation: cannot approximate via MC

### Score function estimator

We can again use the log identity for derivatives

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\ = \sum_{z} \frac{\partial}{\partial \lambda} (q(z|x,\lambda)) \log p(x|z,\theta)$$

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$$= \sum_{z} q(z|x,\lambda) \frac{\partial}{\partial \lambda} (\log q(z|x,\lambda)) \log p(x|z,\theta)$$

$$= \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right]$$
expected gradient:)

We can now build an MC estimator

$$\begin{split} & \frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] \\ & = \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right] \end{split}$$

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We can now build an MC estimator

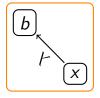
$$\begin{split} & \frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] \\ &= \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right] \\ & \stackrel{\mathsf{MC}}{\approx} \frac{1}{S} \sum_{s=1}^{S} \log p(x|z^{(s)},\theta) \frac{\partial}{\partial \lambda} \log q(z^{(s)}|x,\lambda) \\ & \text{where } z^{(s)} \sim q(z|x,\lambda) \end{split}$$

• magnitude of  $\log p(x|z,\theta)$  varies widely

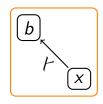
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- magnitude of  $\log p(x|z,\theta)$  varies widely
- model likelihood does not contribute to direction of gradient

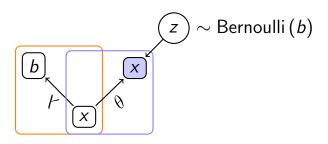


inference model



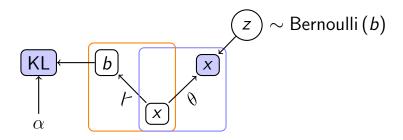


inference model



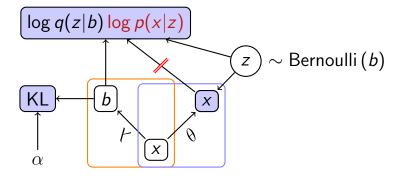
inference model

generation model



inference model

generation model



inference model

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#### Pros and Cons

- Pros
  - Applicable to all distributions
  - Many libraries come with samplers for common distributions

### Pros and Cons

- Pros
  - Applicable to all distributions
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- Cons
  - High Variance!

- First Attempt: Wake-Sleep
- Neural Variational Inference
- Score function estimator
- Variance reduction

# When variance is high we can

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• sample more

## When variance is high we can

- sample more
- use variance reduction techniques (e.g. baselines and control variates)

### Control variates

#### Intuition

To estimate  $\mathbb{E}[f(z)]$  via Monte Carlo we compute the empirical average of  $\hat{f}(z)$  where  $\hat{f}(z)$  is chosen so that  $\mathbb{E}[\hat{f}(z)] = \mathbb{E}[f(z)]$  and  $Var(f) > Var(\hat{f})$ .

Let  $\bar{f} = \mathbb{E}[f(z)]$  be an expectation of interest

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- say we know  $\bar{c} = \mathbb{E}[c(z)]$
- then for  $\hat{f}(z) \triangleq f(z) b(c(z) \mathbb{E}[c(z)])$ it holds that  $\mathbb{E}[\hat{f}(z)] = \mathbb{E}[f(z)]$
- ullet and  $Var(\hat{f}) = Var(f) 2b Cov(f, c) + b^2 Var(c)$

- $\hat{f}(z) \triangleq f(z) b(c(z) \mathbb{E}[c(z)])$

How do we choose b and c(z)?

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Of course,  $\mathbb{E}[c(z)]$  must be known!

### MC

We then use the estimate

$$ar{f} \overset{\mathsf{MC}}{pprox} rac{1}{S} \left( \sum_{s=1}^{S} f(z^{(s)}) - bc(z^{(s)}) 
ight) + bar{c}$$

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$$ar{f} \stackrel{\mathsf{MC}}{pprox} rac{1}{S} \left( \sum_{s=1}^{S} f(z^{(s)}) - bc(z^{(s)}) 
ight) + bar{c}$$

And recall that for us

$$f(z) = \log p(x|z, \theta) \frac{\partial}{\partial \lambda} \log q(z|x, \lambda)$$

and 
$$z^{(s)} \sim q(z|x,\lambda)$$

$$\mathbb{E}_{q(z|x,\lambda)}\left[rac{\partial}{\partial \lambda}\log q(z|x,\lambda)
ight]$$

$$\mathbb{E}_{q(z|x,\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right]$$
$$= \int q(z|x,\lambda) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) dz$$

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$$= \int q(z|x,\lambda) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) dz$$

$$= \int \frac{\partial}{\partial \lambda} q(z|x,\lambda) dz$$

The Expectation of the score function is 0.

$$\mathbb{E}_{q(z|x,\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right]$$

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$$= \frac{\partial}{\partial \lambda} \int q(z|x,\lambda) dz$$

$$= \frac{\partial}{\partial \lambda} 1 = 0$$

#### **Baselines**

With

$$f(z) = \log p(x|z, \theta) \frac{\partial}{\partial \lambda} \log q(z|x, \lambda)$$

and

$$c(z) = \frac{\partial}{\partial \lambda} \log q(z|x,\lambda)$$

we have

$$\hat{f}(z) =$$

#### **Baselines**

With

$$f(z) = \log p(x|z, \theta) \frac{\partial}{\partial \lambda} \log q(z|x, \lambda)$$

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we have

$$\hat{f}(z) = (\log p(x|z, \theta) - b) \frac{\partial}{\partial \lambda} \log q(z|x, \lambda)$$

#### **Baselines**

With

$$f(z) = \log p(x|z, \theta) \frac{\partial}{\partial \lambda} \log q(z|x, \lambda)$$

and

$$c(z) = \frac{\partial}{\partial \lambda} \log q(z|x,\lambda)$$

we have

$$\hat{f}(z) = (\log p(x|z, \theta) - b) \frac{\partial}{\partial \lambda} \log q(z|x, \lambda)$$

b is known as baseline (Williams, 1992).

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• Moving average of  $\log p(x|z, \theta)$  based on previous batches

- Moving average of  $\log p(x|z, \theta)$  based on previous batches
- A trainable constant b

- Moving average of log  $p(x|z, \theta)$  based on previous batches
- A trainable constant b
- A neural network prediction based on x e.g.  $b(x; \omega)$

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- A trainable constant b
- A neural network prediction based on x e.g.  $b(x; \omega)$
- The likelihood assessed at a deterministic point, e.g.  $b(x) = \log p(x|z^*, \theta)$  where  $z^* = \arg \max_z q(z|x, \lambda)$

#### Trainable baselines

Baselines are predicted by a regression model (e.g. a neural net).

The model is trained using an  $L_2$ -loss.

$$\min_{\omega} (b(x; \omega) - \log p(x|z, \theta))^2$$

 Wake-Sleep: train inference and generation networks with separate objectives

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- NVIL: a single objective (ELBO) for both models
- Use score function estimator
- Always use baselines for variance reduction!

### **Implementation**

Check one of our notebooks, e.g.

 inducing rationales for sentiment classification github.com/vitutorial/exercises/tree/ master/SST

#### Literature I

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- G. E. Hinton, P. Dayan, B. J. Frey, and R. M. Neal. The wake-sleep algorithm for unsupervised neural networks. *Science*, 268:1158–1161, 1995. URL http://www.gatsby.ucl.ac.uk/~dayan/papers/hdfn95.pdf.
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#### Literature III

Rajesh Ranganath, Sean Gerrish, and David Blei. Black Box Variational Inference. In Samuel Kaski and Jukka Corander, editors, *AISTATS*, pages 814–822, 2014. URL http://proceedings.mlr.press/v33/ranganath14.pdf.

Ronald J. Williams. Simple statistical gradient-following algorithms for connectionist reinforcement learning. Machine Learning, 8(3-4):229–256, 1992. URL https://doi.org/10.1007/BF00992696.