Deep Generative Models: Continuous Latent Variables

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VI Tutorial @ Host Site Deep Generative Models

Variational Autoencoders

Posterior collapse

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Posterior collapse

Generative Model with NN Likelihood

Goal

Define model $p(x, z|\theta) = p(x|z, \theta)p(z)$ where the likelihood $p(x|z, \theta)$ is given by a neural network.

We fix p(z) for simplicity.

Example: Language Model

A deterministic language model is **one** distribution over observations:

$$p(x|\theta) = \prod_{i=1}^{n} p(x_i|x_{< i}, \theta)$$

Every sentence gets mapped from the same conditioning context, namely, the beginning of sequence symbol.

Example: Language Model (cont.)

With latent variables we can model the data as a draw from a complex marginal, which mixes conditionals from different points in space

$$p(x|\theta) = \int p(z) \prod_{i=1}^{n} p(x_i|z, x_{< i}, \theta) dz$$

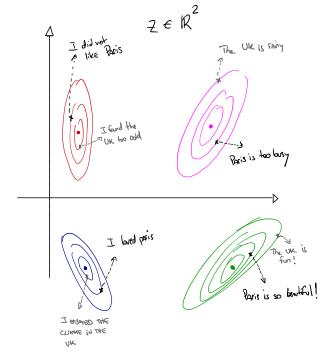
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Good training can lead to considerable amount of structure in the posterior

$$p(z|x,\theta) = \frac{p(z)p(x|z,\theta)}{p(x|\theta)}$$



Generative model:

$$Z \sim \mathcal{N}(0, I)$$

 $X_i | z, x_{< i} \sim \mathsf{Cat}(f(z, x_{< i}; \theta))$

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$$egin{aligned} h_0 &= anh\Big(W^{(ext{init})}z + b^{(ext{init})}\Big) \ h_i &= ext{rnn}ig(h_{i-1}, E_{x_{i-1}}; heta_{ ext{rnn}}ig) \end{aligned}$$

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Define model $p(x, z|\theta) = p(x|z, \theta)p(z)$ where the likelihood $p(x|z, \theta)$ is given by a neural network. (We fix p(z) for simplicity.)

Problem

 $p(x|\theta) = \int p(z)p(x|z,\theta)dz$ is intractable!

Deep Generative Models

Variational Autoencoders

Posterior collapse

$$\log p(x|\theta) \geq \underbrace{\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x,z|\theta)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}_{\text{ELBO}}$$

$$egin{aligned} \log p(x| heta) & \succeq \underbrace{\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x,z| heta)
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ight)} \end{aligned}$$

$$\begin{split} \log p(x|\theta) & \ge \overbrace{\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x,z|\theta) \right] + \mathbb{H} \left(q(z|x,\lambda) \right)}^{\mathsf{ELBO}} \\ & = \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) + \log p(z) \right] + \mathbb{H} \left(q(z|x,\lambda) \right) \\ & = \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right] - \mathsf{KL} \left(q(z|x,\lambda) \mid\mid p(z) \right) \end{split}$$

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$$\underset{\theta,\lambda}{\operatorname{arg\,max}} \ \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|Z,\theta) \right] - \operatorname{\mathsf{KL}} \left(q(z|x,\lambda) \mid\mid p(z) \right)$$

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• assume KL $(q(z|x, \lambda) || p(z))$ analytical true for exponential families

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- assume KL $(q(z|x, \lambda) \mid\mid p(z))$ analytical true for exponential families
- approximate $\mathbb{E}_{q(z|x,\lambda)}[\log p(x|z,\theta)]$ by sampling feasible because $q(z|x,\lambda)$ is simple

$$\frac{\partial}{\partial \theta} \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left(q(z|x,\lambda) \mid\mid p(z) \right)}^{constant}$$

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$$= \mathbb{E}_{q(z|x,\lambda)} \left[\frac{\partial}{\partial \theta} \log p(x|z,\theta) \right]$$

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Note: $q(z|x,\lambda)$ does not depend on θ .

$$\frac{\partial}{\partial \lambda} \left[\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right] - \mathsf{KL} \left(q(z|x,\lambda) \mid\mid p(z) \right) \right]$$

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The first term again requires approximation by sampling

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right]$$

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Not an expected gradient!

Score function estimator?

Can we apply the log-derivative trick?

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Yes, it's a general result!

What about variance?

The learning signal can only scale the gradient:

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Can we do better?

Problem

We need to re-express the gradient, but the measure of integration depends on λ

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} [\log p(x|z,\theta)]$$

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$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right]$$

What if we could re-express $q(z|x,\lambda)$ in terms of some other distribution that does not depend on λ ?

Reparametrisation trick

Find a transformation $h: z \mapsto \epsilon$ such that ϵ does not depend on λ .

- $h(z, \lambda)$ needs to be invertible
- $h(z, \lambda)$ needs to be differentiable

Reparametrisation trick

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- $h(z, \lambda)$ needs to be invertible
- $h(z, \lambda)$ needs to be differentiable
- $h(z,\lambda) = \epsilon$
- $h^{-1}(\epsilon,\lambda)=z$

Affine property

$$Az + b \sim \mathcal{N}\left(\mu + b, A\Sigma A^{T}\right) \text{ for } z \sim \mathcal{N}\left(\mu, \Sigma\right)$$

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Special case

$$Az + b \sim \mathcal{N}\left(b, AA^{T}\right) \text{ for } z \sim \mathcal{N}\left(0, \mathsf{I}\right)$$

Let an inference network compute

$$u = \mu(x; \lambda)$$
 $s = \sigma(x; \lambda)$

for a posterior $Z \sim \mathcal{N}(u, s^2)$, then we have:

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for a posterior $Z \sim \mathcal{N}(u, s^2)$, then we have:

$$h(z, \lambda; x) = \frac{z - \mu(x; \lambda)}{\sigma(x; \lambda)} = \epsilon \sim \mathcal{N}(0, 1)$$

and conversely, for $\epsilon \sim \mathcal{N}(0, I)$, we have:

$$h^{-1}(\epsilon, \lambda; x) = \mu(x; \lambda) + \sigma(x; \lambda) \odot \epsilon = z \sim \mathcal{N}(u, s^2)$$

$$= \frac{\partial}{\partial \lambda} \int q(z|x,\lambda) \log p(x|z,\theta) dz$$

$$= \frac{\partial}{\partial \lambda} \int q(z|x,\lambda) \log p(x|z,\theta) dz$$

$$= \frac{\partial}{\partial \lambda} \int q(\epsilon) \log \left(p(x|h^{-1}(\epsilon,\lambda),\theta) \right) d\epsilon$$

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$$= \int q(\epsilon) \frac{\partial}{\partial \lambda} \left[\log p(x|h^{-1}(\epsilon,\lambda),\theta) \right] d\epsilon$$

$$\mathbb{E}_{q(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p(x | \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}, \theta) \right]$$

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$$\stackrel{\text{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{\partial}{\partial \lambda} \log p(x | \overbrace{h^{-1}(\epsilon_{i}, \lambda)}^{=z}, \theta)$$
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$$\stackrel{\text{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{\partial}{\partial z} \log p(x| \overbrace{h^{-1}(\epsilon_{i}, \lambda)}^{=z}, \theta) \times \frac{\partial}{\partial \lambda} h^{-1}(\epsilon_{i}, \lambda)$$
chain rule

Derivatives of Gaussian transformation

Recall:

$$h^{-1}(\epsilon,\lambda) = \mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon$$
.

We get two gradient paths!

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• one is deterministic $\frac{\partial h^{-1}(\epsilon,\lambda)}{\partial \mu(x,\lambda)} = \frac{\partial}{\partial \mu(x,\lambda)} [\mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon] = 1$

Derivatives of Gaussian transformation

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We get two gradient paths!

- one is deterministic $\frac{\partial h^{-1}(\epsilon,\lambda)}{\partial \mu(x,\lambda)} = \frac{\partial}{\partial \mu(x,\lambda)} [\mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon] = 1$
- the other is stochastic $\frac{\partial h^{-1}(\epsilon,\lambda)}{\partial \sigma(x,\lambda)} = \frac{\partial}{\partial \sigma(x,\lambda)} [\mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon] = \epsilon$

Gaussian KL

ELBO

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

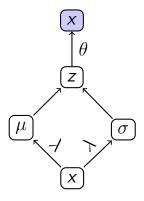
Gaussian KL

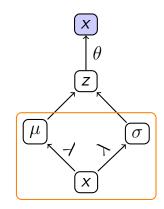
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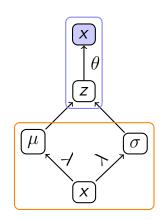
Analytical computation of $- KL(q(z|x, \lambda) || p(z))$:

$$\frac{1}{2} \sum_{i=1}^{N} \left(1 + \log \left(\sigma_i^2 \right) - \mu_i^2 - \sigma_i^2 \right)$$

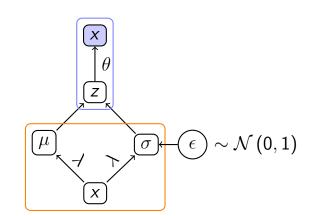




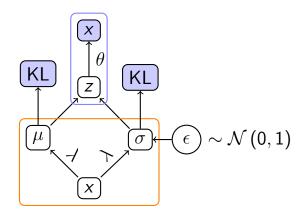
generation model

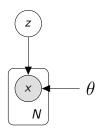


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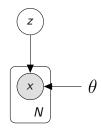


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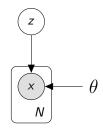


- Draw a document embedding $Z \sim \mathcal{N}(0, I)$
- Draw N words $X_i|z \sim \mathsf{Cat}(f(z;\theta))$



Generative story

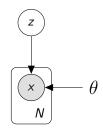
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$$h = \operatorname{relu}(W_1 z + b_1)$$

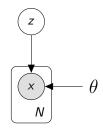


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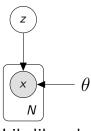
 $f(z, \theta) = \operatorname{softmax}(W_2h + b_2)$



Generative story

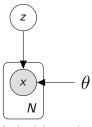
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 $\theta = \{W_1, b_1, W_2, b_2\}$



Likelihood

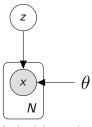
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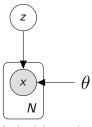
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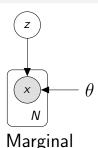
$$p(x|z,\theta) = \prod_{i=1}^{N} p(x_i|z,\theta) = \prod_{i=1}^{N} \operatorname{Cat}(x_i|\underbrace{f(z;\theta)}_{=\psi})$$



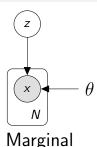
Likelihood

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$$= \prod_{i=1}^{N} \psi_{x_i}$$



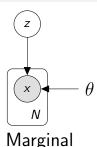
- Draw a document embedding $Z \sim \mathcal{N}(0, I)$
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Generative story

- Draw a document embedding $Z \sim \mathcal{N}(0, I)$
- Draw N words $X_i|z \sim \mathsf{Cat}(f(z;\theta))$

$$p(x|\theta) = \int p(z) \prod_{i=1}^{N} p(x_i|z,\theta) dz$$



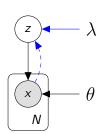
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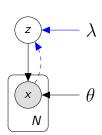
Inference model

• $Z|x \sim \mathcal{N}(\mu(x; \lambda), \sigma(x; \lambda)^2)$



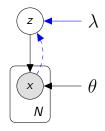
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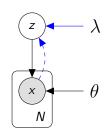
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$$s = \sum_{i=1}^{N} E_{x_i}$$

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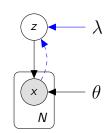
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$$b = \text{rolu}(M)$$

$$h = \mathsf{relu}(M_1 s + c_1)$$

Inference model

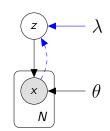
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$$s=\sum_{i=1}^N E_{x_i}$$
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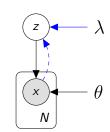
$$\mu(x; \lambda) = M_2 h + c_2$$

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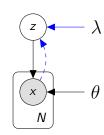
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Generative Model

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- Likelihood: $X_i|z \sim \text{Cat}(f(z;\theta))$

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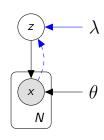


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ELBO

$$egin{aligned} \log p(x| heta) &\geq \mathbb{E}_{\epsilon \sim \mathcal{N}(0,I)} \left[\sum_{i=1}^N \log \psi_{x_i}
ight] \ &- \mathsf{KL} \left(\mathcal{N}(z|u,s^2) \mid\mid \mathcal{N}(z|0,I)
ight) \end{aligned}$$

where $u = \mu(x; \lambda)$, $s = \sigma(x; \lambda)$, and $\psi = f(z = u + \epsilon \odot s, \theta)$

We are point estimating $p(x, z|\theta)$ along with $q(z|x, \lambda)$

• where $p(x, z|\theta) = p(z) \prod_{i=1}^{n} p(x_i|z, x_{< i}, \theta)$

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• the true posterior collapses to the prior

Strong generators

If your likelihood model is able to express dependencies between the output variables (e.g. an RNN), the model may simply ignore the latent code.

Note that though
$$X \perp Z$$
 (or $X_i \perp Z \mid X_{< i}$) $\prod_{i=1}^n p(x_i \mid x_{< i}, \theta)$ still is an exact factorisation of $p(x \mid \theta)$.

We call such models strong generators.

Fact: the rate $R = \mathbb{E}_X[\mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)]$ is an upperbound on I(X;Z)

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- greedy decoding arg $\max_{x_i} \log p(x_i|z, x_{< i})$ from a prior sample $z \sim p(z)$ is deterministic;
- this does not mean ancestral samples from $p(x|z,\theta)$ will be bad

KL scaling

Gradually incorporate the KL term into the objective

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \beta \operatorname{\mathsf{KL}}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

where β starts at 0 and goes to 1 after a number of steps.

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where β starts at 0 and goes to 1 after a number of steps.

This sometimes helps reach better local optimum, but there are not guarantees. In fact, oftentimes, soon after we reach 1, the posterior collapses again.

Free bits

Another strategy is to promote the posterior to deviate a bit from the prior by not penalising for the first few nats of information:

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \max(r,\mathsf{KL}\left(q(z|x,\lambda)\mid\mid p(z)
ight))$$

where $r \ge 0$ is known as "free bits"

This is an attempt to promote solutions where $R \ge r$

Attention!

But note that if we scale down the KL term permanently, or allow too many free bits, then the conditional $p(x|z,\theta)$ will over-specialise to samples from the approximate posterior $q(z|x,\lambda)$. This can lead to bad generalisation and/or poor samples when generating from the prior.

Variational Autoencoder

Advantages

- Backprop training
- Easy to implement
- Posterior inference possible
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- Amortised inference

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Drawbacks

- Discrete latent variables are not possible
- Optimisation may be difficult with several latent variables

Summary

- Wake-Sleep: train inference and generation networks with separate objectives
- VAE: train both networks with same objective
- Reparametrisation
 - ullet Transform parameter-free variable ϵ into latent value z
 - Update parameters with stochastic gradient estimates
- If you employ strong generators, watch out for posterior collapse

Implementation

Try one of our notebooks, e.g.

Original VAE: MNIST
 https:
 //github.com/philschulz/VITutorial/blob/
 master/code/vae_notebook_pytorch.ipynb

SentenceVAE
 https://github.com/probabll/dgm4nlp/tree/master/notebooks/sentencevae

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