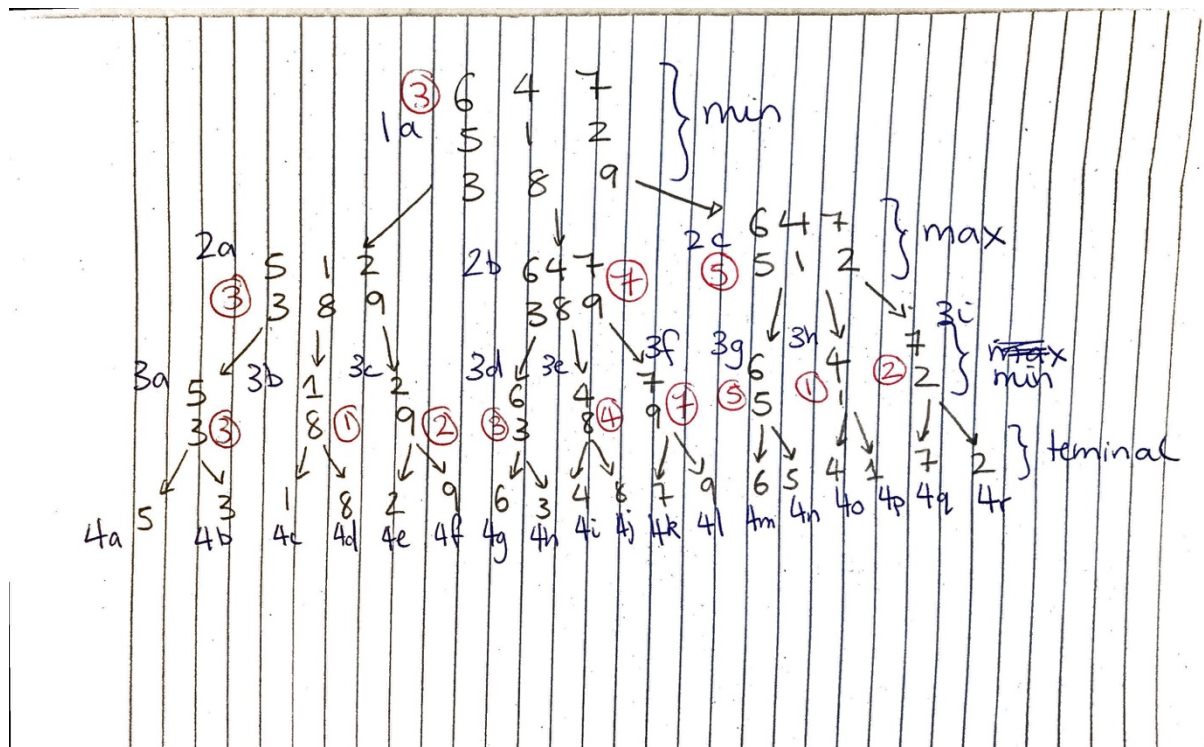


Homework 3

A)



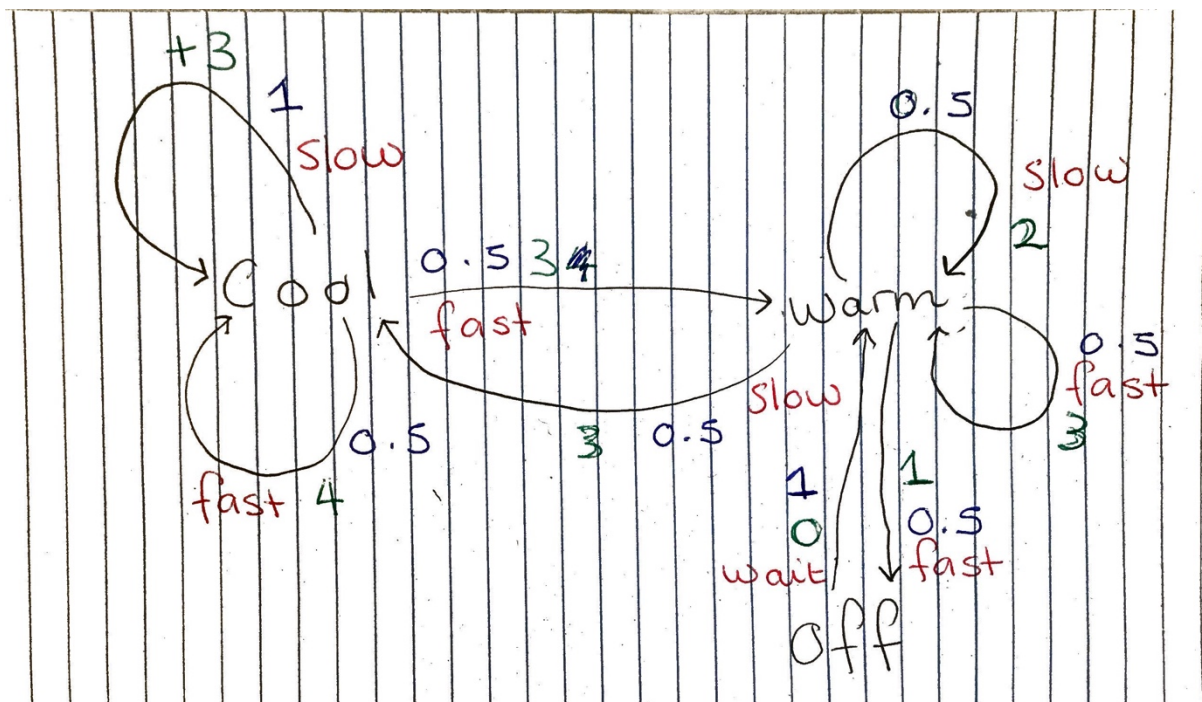
b)

Step	Node	$\alpha(\text{in})$	$\beta(\text{in})$	Value (out)	Children Skipped
1	1a	$-\infty$	$+\infty$	3	
2	2a	$-\infty$	$+\infty$	3	
3	3a	$-\infty$	$+\infty$	3	
4	4a	$-\infty$	$+\infty$	5	
5	4b	$-\infty$	5	3	
6	3b	3	$+\infty$	1	4d
7	4c	3	$+\infty$	1	
8	3c	3	$+\infty$	2	4f
9	4e	3	$+\infty$	2	
10	2b	$-\infty$	3	3	3e, 3f
11	3d	$-\infty$	3	3	
12	4g	$-\infty$	3	6	
13	4h	$-\infty$	3	3	
14	2c	$-\infty$	3	5	3h, 3i
15	3g	$-\infty$	3	5	
16	4m	$-\infty$	3	6	
17	4n	$-\infty$	3	5	

c)

d)

For the evaluation function 2) – There are now two equally viable actions that can be made. The first row can be eliminated or the third row can be eliminated, and both actions return a result of 1.



b)

$$V^{\pi f}(\text{warm}) = 13.79 \text{ (2dp)}$$

If $w = 13.79 \rightarrow$

Then $V^{\pi^f}(\text{cool}) = 2 + 0.45(c + 13.79) \Rightarrow 0.55c = 9.706... \Rightarrow$

$$V^{\pi^f}(\text{cool}) = 17.64$$

$$\text{Then } V^{\pi^f}(\text{off}) = 0.9(13.79) = 12.41$$

$$V^{\pi^f}(\text{cool}) = 17.64$$

$$V^{\pi^f}(\text{warm}) = 13.79 \text{ (2dp)}$$

$$\text{Then } V^{\pi^f}(\text{off}) = 12.41$$

c)

$$\begin{aligned}\pi_{i+1}(\text{cool}) &= \text{argmax}((\text{cool}, \text{fast}), (\text{cool}, \text{slow})) = \text{argmax}(17.64, 1(3 + 0.9(17.64))) = \\ &= \text{argmax}(17.64, 18.88 \text{ (2dp)}) = 18.88\end{aligned}$$

Therefore, the action that is returned is for the car to choose the slow action at the cool state.

$$\begin{aligned}\pi_{i+1}(\text{warm}) &= \text{argmax}((\text{warm}, \text{fast}), (\text{warm}, \text{slow})) \\ &= \text{argmax}(13.79, 0.5(2 + 0.9(13.79)) + 0.5(3 + 0.9(17.64))) = \text{argmax}(13.79, 16.64) = 16.64\end{aligned}$$

Therefore, the action that is returned is for the car to choose the slow action at the warm state.

$$\pi_{i+1}(\text{off}) = \text{argmax}(\text{off}, \text{wait}) = \text{argmax}(12.41) = 12.41$$

There is only one policy for the car in the off state, which means that that is the only policy it will ever take.

d)

$$V_1(\text{cool}) = \max(3 + 0.9(V_0(C)), 0.5(4 + 0.9(V_0(c))) + 0.5(3 + 0.9(V_0(w)))) = \max(3, 3.5) = 3.5$$

$$\begin{aligned}V_1(\text{Warm}) &= \\ &= \max(0.5(3 + 0.9(V_0(w))) + 0.5(1 + 0.9(V_0(\text{off}))), 0.5(2 + 0.9(V_0(w))) + 0.5(3 + 0.9(V_0(c)))) \\ &= \max(2, 2.5) = 2.5\end{aligned}$$

$$V_1(\text{off}) = \max(1(0 + 0.9(V_0(w))) = \max(0) = 0$$

$$V_2(\text{cool}) = \max(3 + 0.9(3.5), 0.5(4 + 0.9(3.5))) + 0.5(3 + 0.9(2.5))) = \max(6.15, 6.2)$$

$$\begin{aligned}V_2(\text{warm}) &= \\ &= \max(0.5(3 + 0.9(2.5)) + 0.5(1 + 0.9(0)), 0.5(2 + 0.9(2.5)) + 0.5(3 + 0.9(3.5))) \\ &= \max(2.875, 3.6625) = 3.6625\end{aligned}$$

$$V_2(\text{Off}) = \max(1(0 + 0.9(2.5))) = 2.25$$

State	$V_0(s)$	$V_1(s)$	$V_2(s)$
Cool	0	3.5	6.2
Warm	0	2.25	3.6625
Off	0	0	2.25

e)

$T^*(s, a, s')$:

$T(\text{cool}, \text{slow}, \text{cool}) = 1$
 $T(\text{cool}, \text{fast}, \text{cool}) = 1/3$
 $T(\text{cool}, \text{fast}, \text{warm}) = 2/3$
 $T(\text{warm}, \text{slow}, \text{cool}) = 1$
 $T(\text{warm}, \text{fast}, \text{off}) = 1$
 $T(\text{off}, \text{wait}, \text{off}) = 0.5$
 $T(\text{off}, \text{wait}, \text{warm}) = 0.5$

$R^*(s, a, s')$:

$T(\text{cool}, \text{slow}, \text{cool}) = 2$
 $T(\text{cool}, \text{fast}, \text{cool}) = 2$
 $T(\text{cool}, \text{fast}, \text{warm}) = 4$
 $T(\text{warm}, \text{slow}, \text{cool}) = 2$
 $T(\text{warm}, \text{fast}, \text{off}) = 0$
 $T(\text{off}, \text{wait}, \text{off}) = 0$
 $T(\text{off}, \text{wait}, \text{warm}) = 0$