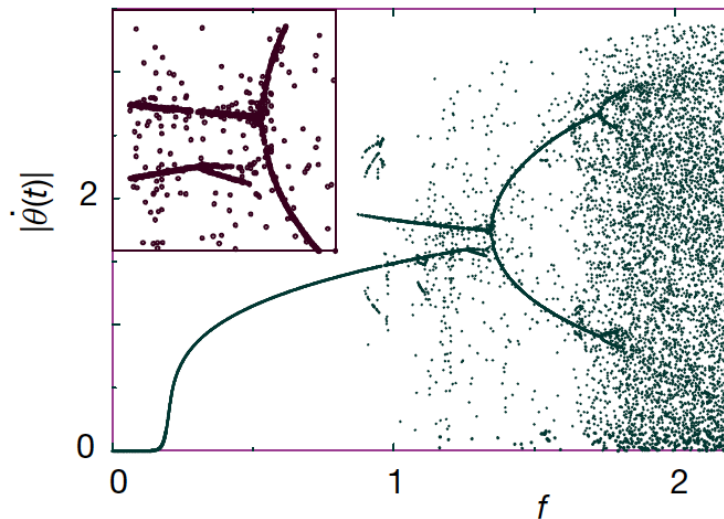
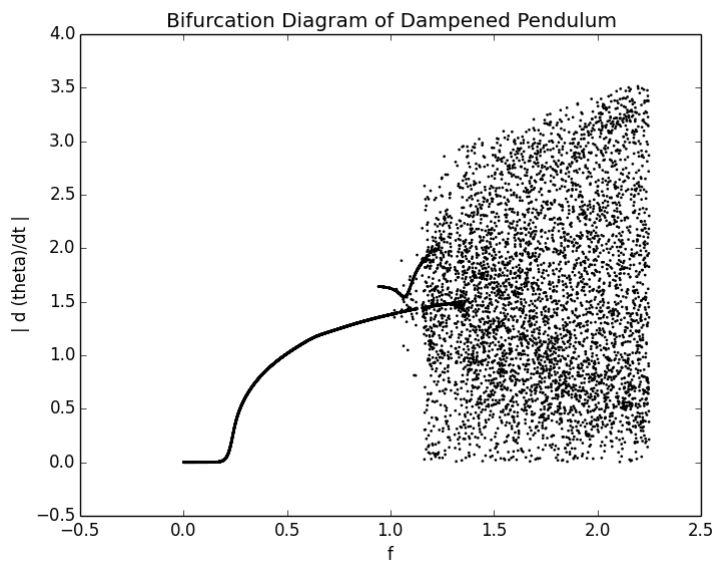


15.3

Create the bifurcation diagram from the book:



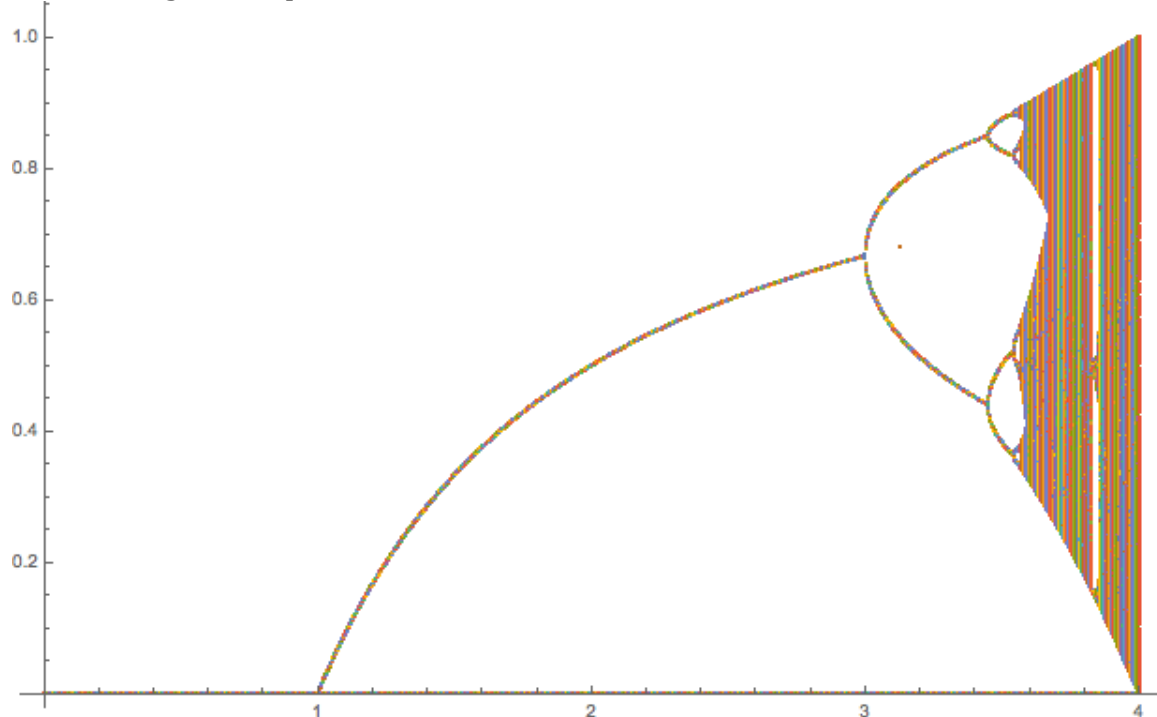
And so I did this:



By iterating through RK4 a certain (specified) number of times in time, and then plotting the last value of $d\theta/dt$.

It doesn't look perfect, but it looks relatively close to what we expected – the chaotic behavior begins occurring earlier in f than in the book, and also there are fewer meaningful bifurcations.

Here is a logistic map that I made in mathematica:

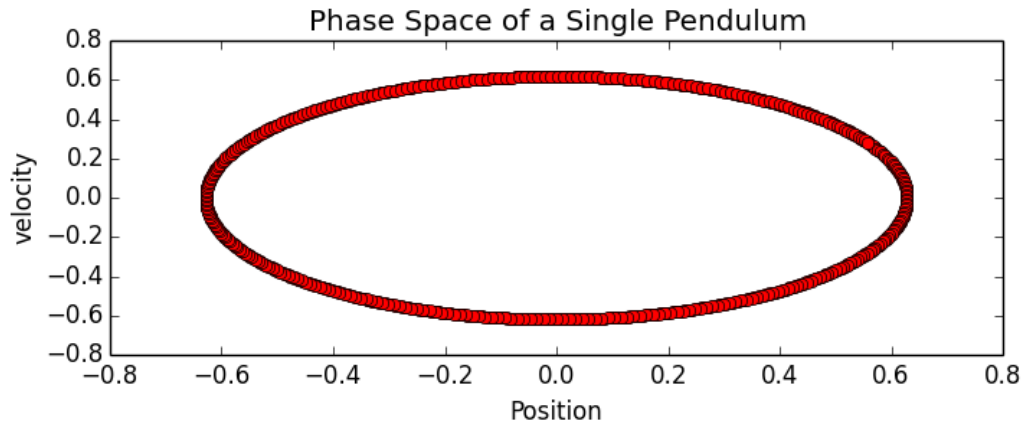


Here is a logistic map that I made in python, largely from scrapping code from the internet (it looks a lot nicer than in mathematica), but also is white on black– don't print this – delete this picture before printing, it will be a waste of ink.



This week I worked mostly on creating a double pendulum simulation entirely from scratch – entirely using Lagrangian equations of motion, and applying rk4 technique we developed previously

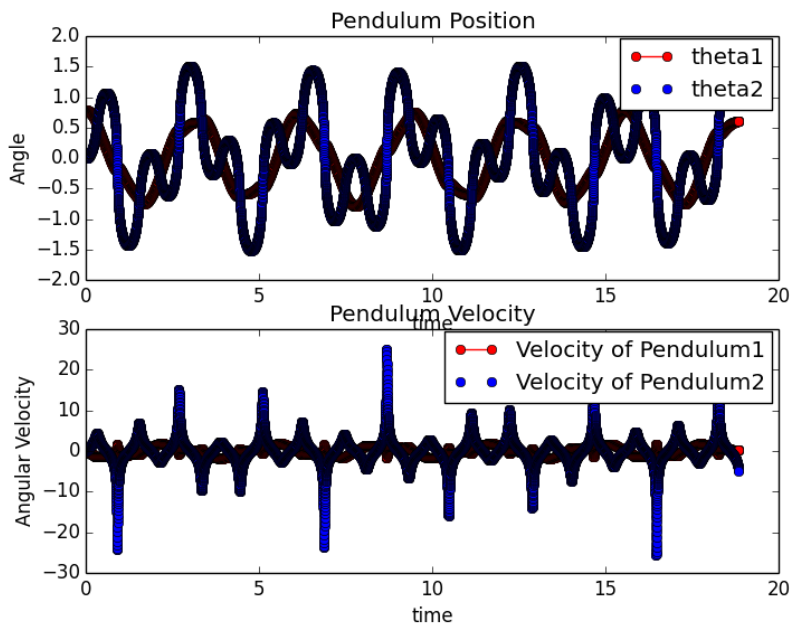
To prove that the methodology works, here is the same algorithm applied on a single pendulum:



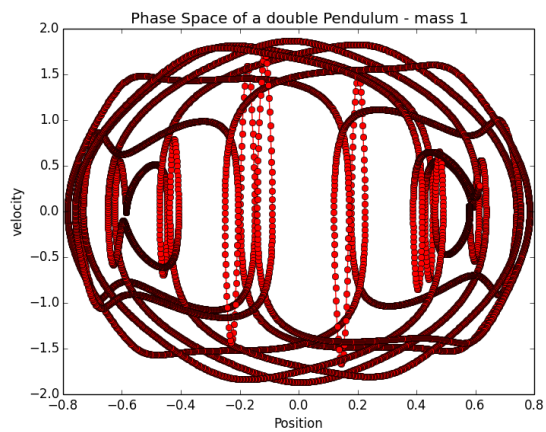
The following images are for an evolution in time for initial conditions : $m_1 = 2$; $m_2 = 1$; $L_2 = 2$; $L_1 = 1$; angular velocity 1 = 0; angular velocity 2 = 0; angle2 = 0; and angle1 = $\pi/4$

Here is a plot of the angles of both individual pendulums as a function of time, as well as the angular velocities of both pendulums as a function of time.

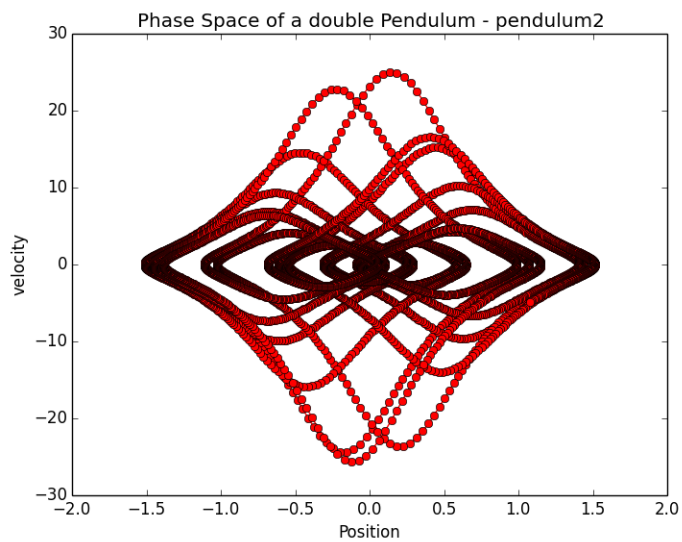
The Position of Mass 1 is largely sinusoidal, and mass 2 looks more like a beat frequency.



Here is a plot of the phase space of mass 1 of the double pendulum



Here is a plot of the phase space of mass 1 of the double pendulum



Here is a snapshot of a simulation of a double pendulum that I created:

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