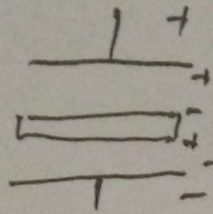


元功法

(虚位移)



$$\frac{1}{4\pi k} = \epsilon_0$$

电容器的初始电容

$$C_0 = \frac{\epsilon_0 b \cdot \frac{b}{2}}{d} + \frac{\epsilon b \cdot \frac{b}{2}}{d}$$

板进入 x 后

$$C = \frac{\epsilon_0 b (\frac{b}{2} - x)}{d} + \frac{\epsilon b (\frac{b}{2} + x)}{d}$$

电容改变 $\Delta C = C - C_0 = \frac{bx(\epsilon - \epsilon_0)}{d}$

$C \uparrow$ 电源对电容器充电

电源消耗的电功 = 电容器增加的场能 + 板移动

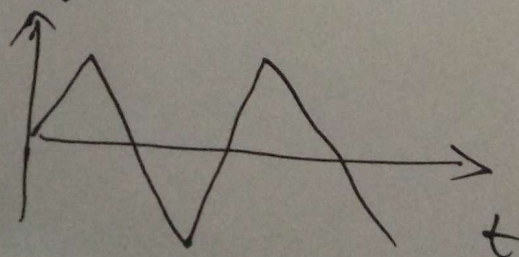
$$\Delta CU; U = \frac{1}{2} \Delta C U^2 + \frac{1}{2} mv^2$$

$$Fx = \frac{1}{2} mv^2, \quad F = ma$$

$$a = \frac{(\epsilon - \epsilon_0) U^2}{2bd^2 \rho}, \quad \frac{b}{2} = \frac{1}{2} at^2$$

板运动速度 $v = at = \frac{(\epsilon - \epsilon_0) U^2}{2bd^2 \rho} t$

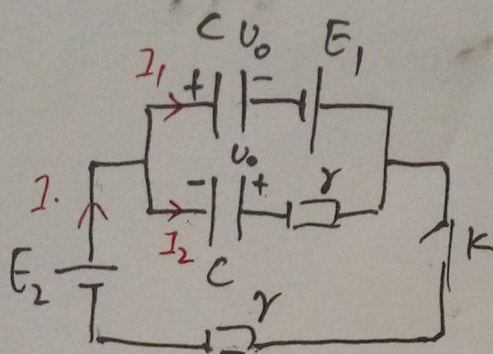
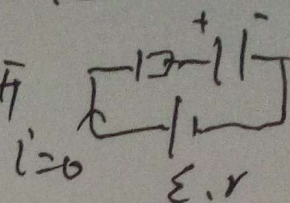
时刻 $t = \sqrt{\frac{b}{a}}$ 为 $V_{max} = \sqrt{ab}$



电路 10.

1. 闭合瞬间 电容器电量不变

稳定后 电容器 → 断开



K 合上前 $U_0 = \frac{E_1}{2}$, $q_0 = \frac{1}{2} C E_1$

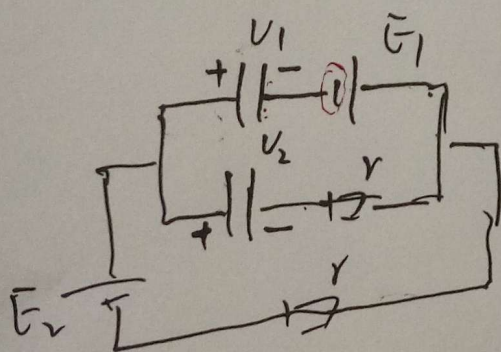
$$I = I_1 + I_2$$

$$E_1 + E_2 - U_0 = I \cdot r$$

$$I = \frac{E_2 + E_1/2}{r}$$

$$E_2 + U_0 - I_2 r - I r = 0 \Rightarrow I_2 = 0$$

$$I_1 = I = \frac{2E_2 + E_1}{2r}$$



$$U_2 = E_2 \Rightarrow q_2 = C E_2$$

$$U_1 = E_1 + E_2 \Rightarrow q_1 = C (E_1 + E_2)$$

$$q = q_1 + q_2 = C (2E_2 + E_1)$$

(3) 通过 E_2 的电量为 q . 电池 E_2 做功

$$W_2 = q E_2 = C E_2 (2E_2 + E_1)$$

(2) 初始时 $E_0 = 2 \cdot \frac{1}{2} C U_0^2 = \frac{1}{4} C E_1^2$

末态电势 $E = \frac{1}{2} C E_2^2 + \frac{1}{2} C (E_1 + E_2)^2$

$$\Delta E = E - E_0 = \frac{C}{4} (E_1 + 2E_2)^2$$

通过 E_1 的电势 $\Delta q = C U_1 - C U_0 = C (E_2 + \frac{1}{2} E_1)$

电池做功 $W_1 = \Delta q E_1 = \frac{C (2E_2 + E_1)}{2} E_1$

由 $Q = W - \Delta E = \frac{1}{4} C (E_1 + 2E_2)^2 - \frac{C}{4} (E_1 + 2E_2)^2 = 0$ $W = W_1 + W_2 = \frac{1}{2} C (E_1 + 2E_2)^2$

磁场

一. 安培力和安培力矩

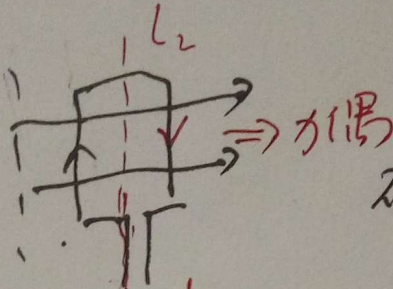
1. 磁场：毕奥-萨伐尔定律

$$\uparrow B = \frac{\mu_0 I}{2\pi r}$$

螺线管 $B = \mu_0 n I$

2. 安培力

3. 安培力矩



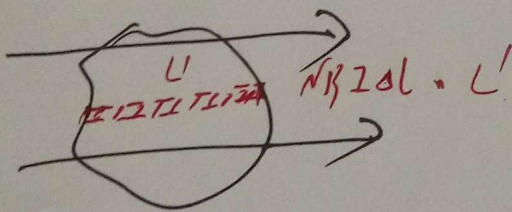
安培力矩 $M = N B I S \cos \theta$

θ 为 B 与法线夹角

$$M = 2 N B I l_1 \cdot \frac{l_2}{2}$$

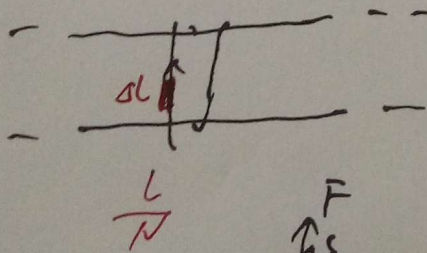
① M 与转轴的位置有关 (B ⊥ 轴)

③ M 与线框的形状有关



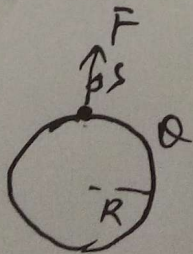
$$\begin{aligned} M &= n B I \bar{\Delta} l \cdot l' \\ &= n B I \bar{\Delta} S \\ &= n B I S \end{aligned}$$

1. \Rightarrow 内部 $B = \mu_0 \frac{N}{L} I$



$$F = B \cdot I \cdot \Delta L$$

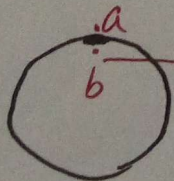
类点



$$E = k \frac{Q}{R^2}$$

$$\vec{E} = \frac{k Q \vec{r}}{r^3}$$

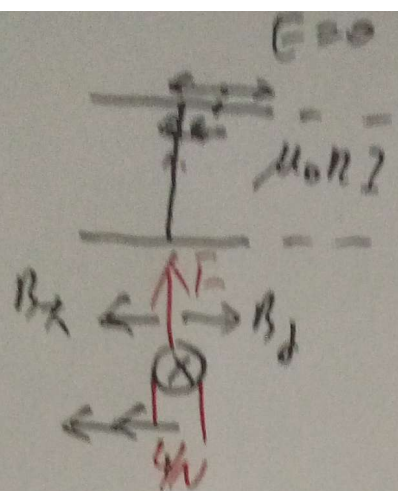
$$\vec{F} = \frac{Q}{4\pi R^2} \cdot \Delta S \cdot \frac{E}{2}, P = \frac{\vec{F}}{\Delta S}$$



$$\vec{E}_b = 0 = \vec{E}_{\text{大环}} + \vec{E}_{\text{小环}}$$

$$\vec{E}_a = \vec{E}_{\text{大环}} + \vec{E}_{\text{小环}}$$

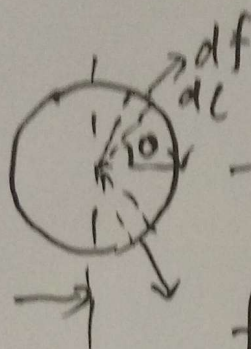
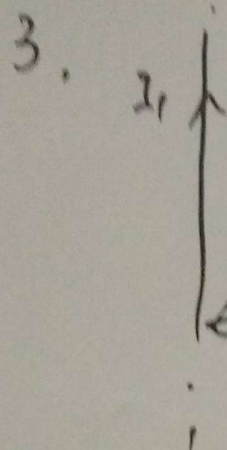
$$\vec{E}_{\text{大环}} = \frac{k Q}{2 R^2}$$



- 大塊在 - 小塊處 $B = \frac{1}{2} \mu_0 \frac{N}{L} I$

$$F = \frac{1}{2} \mu_0 \cdot \frac{N}{L} I \cdot \Delta l$$

$$P = \frac{F}{\Delta l \cdot \frac{L}{N}} = \frac{\mu_0 N^2 I^2}{2L^2}$$



$$B = \frac{\mu_0 I_1}{2\pi} \cdot \frac{1}{l + R \cos \theta}$$

$$df = B I_2 dl = B I_2 R d\theta$$

$$f = \int df_x = \int_0^{2\pi} B I_2 R \cos \theta \cdot d\theta$$

$$= \mu_0 I_1 I_2 \cdot \left(1 - \frac{l}{\sqrt{l^2 - R^2}}\right)$$

二、粒子在磁場中的運動

1. 圓周運動 $B \perp v_0$ 垂直. $B q v_0 = m \frac{v_0^2}{R} \Rightarrow R = \frac{m v_0}{B q}$

$$T = \frac{2\pi R}{v_0} = \frac{2\pi m}{B q}, \text{ 與 } v_0 \text{ 無關}$$

$$m = \frac{m_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$

↓
應用 回旋加速器

於是 ① 磁場區域有限 \Rightarrow 侷限

速度 ↑ 粒子 兩半徑交點 \Rightarrow 圖 6

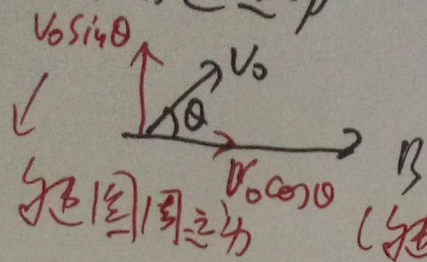
② 多個粒子 加速. $\left\{ \begin{array}{l} \text{位置} \\ \text{時間} \end{array} \right.$

$$= 1, v_0 = \frac{B q a \sqrt{a^2 + b^2}}{m h}$$

$$v_1 = \frac{3 B q a \sqrt{a^2 + b^2}}{4 m h}$$

$$v_2 = \frac{2 B q a \sqrt{a^2 + b^2}}{3 m h}$$

2. 螺旋运动.



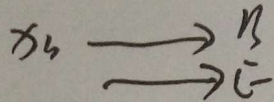
$$R = \frac{m v_0 \sin \theta}{B q}$$

$$T = \frac{2\pi m}{B q}$$

螺旋运动

$$螺距 s = v_0 \cos \theta \cdot \frac{2\pi m}{B q}$$

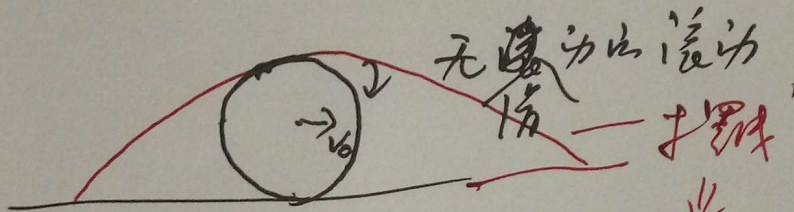
互相垂直



不螺旋运动

$$a = \frac{qE}{m}$$

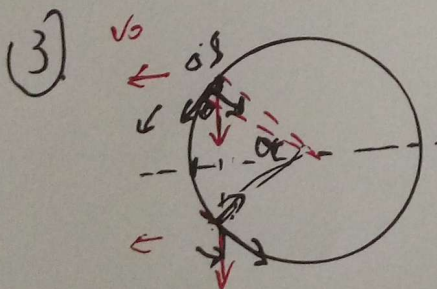
3. 摆线运动



与速度运动和与磁场同方向

4. 磁矩

在同一平面内的合成



$$F_{Bi} = B \cdot \sigma \cdot \Delta s \cdot v_i \quad (v_i \text{ 为切线速度})$$

切线方向

$$F_{Bi} \cos \theta = F_{Bi} \cos \theta$$

$$\text{由于磁场运动 } F_{Bi}' = B \cdot \sigma \cdot \Delta s \cdot v_i'$$

对磁场无影响

$$F_{\text{合力}} = B \sigma v_i \Delta s \cos \theta$$

切线方向投影的合力

$$M_i = F_{\text{合力}} \cdot R = B \sigma v_i R L i$$

$$M_i = MR^2 \cdot \frac{d\omega}{dt} \quad v_i = \omega R$$

$$M_0 M_i = B \sigma v_i L i \sigma t$$

因为 $Mu = B\sigma \pi R^2 \Rightarrow \sigma = \frac{Mu}{B\pi R^2}$

1. 合力总是不做功 证明如下

$$\frac{1}{2} M V_0^2 = \frac{1}{2} M u^2 + \frac{1}{2} M u^2 \quad u = \frac{V_0}{\sqrt{2}}$$

$$\sigma = \frac{M V_0}{\sqrt{2} B \pi R^2}$$

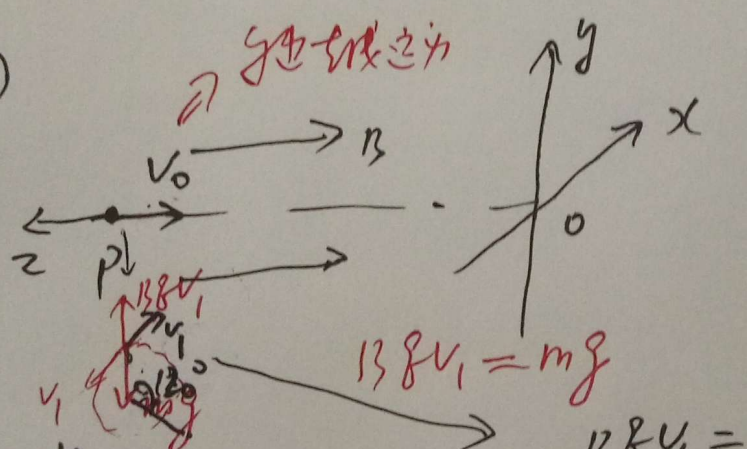
磁场的电荷量 $q = \sigma \cdot 2\pi R = \frac{\sqrt{2} M V_0}{B R}$

三. 粒子在复合场中的运动

1. 复合场包括重力场 电场、磁场

2. 运动的初速度方向

3. 受力互用满足关系 (合力总是不做功)

① 

粒子 (g, m)
 $OP = \frac{2\pi m V_0}{3Bq}$

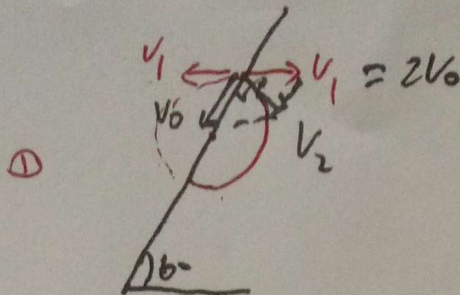
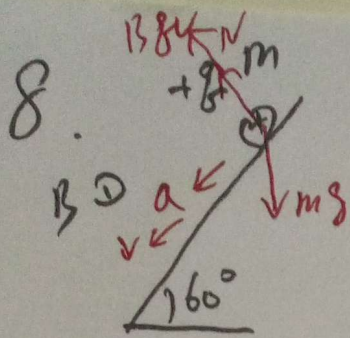
$138v_1 = mg$
 $138v_1 = m \frac{v_1^2}{R} \quad R = \frac{m v_1}{138q} = \frac{m^2 g}{138^2 q^2}$

↓ 对复合场运动

运动时间 $t = \frac{OP}{v_0} = \frac{2\pi m}{3Bq} = \frac{1}{3}$

$$y = -(R + R \cos 60^\circ) = -\frac{3}{2} R = -\frac{3m^2 g}{2 \cdot 138^2 q^2}$$

$$x = -v_1 t + R \sin 60^\circ = -\frac{m^2 g}{138^2 q^2} \left(\frac{2}{3} \pi - \frac{\sqrt{3}}{2} \right)$$



(1) $N=0$ 物体会离开斜面 $1384 = mg \cos 60^\circ$

$$\Rightarrow v_0 = \frac{mg}{2138}$$

(2) 1. 向左 v_1 + 向右 v_1 $1384 v_1 = mg$ $v_1 = 2v_0$

2. 继续运动 v_2 继续运动

$$v_2 = \frac{\sqrt{3} mg}{2138}$$

$$v_{max} = v_1 + v_2 = \left(1 + \frac{\sqrt{3}}{2}\right) \frac{mg}{1384}$$

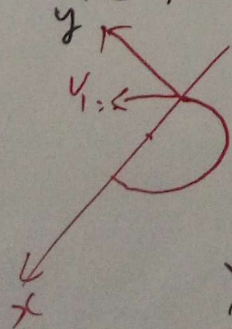
(3) 最大位移 \Rightarrow 对地速度为0

$$v_{min} = (v_1 - v_2) = \left(1 - \frac{\sqrt{3}}{2}\right) \frac{mg}{1384}$$

$$-mgh = \frac{1}{2} m v_{min}^2 - \frac{1}{2} m v_0^2$$

$$h = \frac{\sqrt{3} - 1.5}{2g} \left(\frac{mg}{1384}\right)^2$$

说明不会撞到斜面



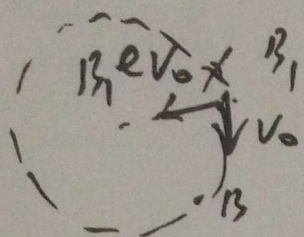
设运动到 x, y

设撞击 $y=0$

$$X = \frac{-v_x t - 2R \pm 2\sqrt{R^2 - v_y^2 t^2}}{2}$$

X 无实数 不撞

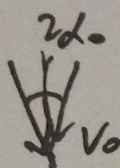
1) $eU_0 = \frac{1}{2} m v_0^2$



$$B_1 e v_0 = m \frac{v_0^2}{R}$$

$$\Rightarrow B_1 = 3.7 \times 10^{-3} \text{ T}$$

(2) — 电子螺旋.



$\alpha_0 \ll 1$ $v_{||0} = v_0 \cos \alpha = v_0 (-\text{just})$

$v_{\perp 0} = v_0 \sin \alpha \approx v_0 \alpha$

$v_{\perp 0} \rightarrow$ 螺旋轴作圆周运动的力

$v_{||0} = v_0 \rightarrow$ 螺旋轴作圆周运动的力

$$T = \frac{2\pi m}{B e}$$

$$b = v_{||0} \cdot T = \frac{2\pi R}{4}$$

$$\Rightarrow B = \frac{4}{12} \sqrt{\frac{2mU_0}{e}} = 1.48 \times 10^{-2} \text{ T}$$

3) 角动量守恒、能量守恒

~~计算~~ 1 若 $\delta = 4 \text{ m}$, $r = 5.3 \text{ m}$
 $= 1.11 R$

