PathfindImageForm _image: Bitmap _originalImage: Bitmap _width: Int32 _height: Int32 _graph: Graph<Coord> traversalObject: Traversal<Coord> prevStartNode: Coord - startNode: Coord endNode: Coord _dijkstras: Dictionary<Coord, Dictionary<Coord, Coord>> _preCalculatedTree: Dictionary<Coord, Coord> - nodes: Int32 components: IContainer imageBox: PictureBox goButton: Button exitButton: Button textBox: RichTextBox workingButton: Button runningBox: RichTextBox nodeBox: RichTextBox invalidCord: Coord + PathfindImageForm(image: Bitmap, traversal: Traversal<Coord>, graph: Graph<Coord>) PathfindImageForm() ViewImageForm_Load(sender: Object, e: EventArgs) : Void ConvertImageBoxToBitmapCord(location: Point): Coord RedrawImage(): Void DrawCross(center: Coord, colour: Color): Void commitSin(): Void imageBox_Click(sender: Object, eventArgs: EventArgs): Void exitButton_Click(sender: Object, e: EventArgs) : Void SetRunningBox(): Void GetDistanceBetweenNodes(start: Coord, goal: Coord): Int32 UpdateNodes() : Void

Program

```
+ Program()
Run(menuInstance: Menu, CLILoggingInstance: Log, settingsInstance: Settings): Void
Testing(): Void
RunSaveFile(menu: Menu, logger: Log): Void
RunNewImage(menu: Menu, logger: Log): Void
```

TextWall

goButton_Click(sender: Object, e: EventArgs) : Void

Dispose(disposing: Boolean): Void

InitializeComponent(): Void

+ SaveWelcome(menuInstance: Menu): Void + ImageWelcome(menuInstance: Menu): Void + FileDetails(menuInstance: Menu, rawImage: RawImage): Void

ViewImageForm

_width: Int32 _height: Int32 components: IContainer imageBox: PictureBox nextButton: Button

+ ViewImageForm(image: Bitmap) ViewImageForm_Load(sender: Object, e: EventArgs) : Void nextButton_Click(sender: Object, e: EventArgs) : Void # Dispose(disposing: Boolean): Void InitializeComponent(): Void

Pathfinder

_input: Double[,] _originalBitmap: Bitmap _graph: Graph<Coord> _traversal: Traversal<Coord>

+ Pathfinder(originalImage: Bitmap, input: Double[,]) + Start() : Void InstanceClasses(): Void

CannyEdgeDetection + KernelSize { get; set; } : Int32 + RedRatio { get; set; } : Double + GreenRatio { get; set; } : Double + BlueRatio { get; set; } : Double + Sigma { get; set; } : Double + LowerThreshold { get; set; } : Double + UpperThreshold { get; set; } : Double + CannyEdgeDetection() + CannyEdgeDetection(kernelSize: Int32, redRatio: Double, greenRatio: Double, blueRatio: Double, sigma: Double, lowerThreshold: Double, upperThreshold: Double) + BlackWhiteFilter(input: RGB[,]) : Double[,] + GaussianFilter(input: Double[,]) : Double[,] + CalculateGradients(input: Double[,], updateMenu: Action) : Gradients - CalculateGradientX(input: Double[,], updateMenu: Action) : Double[,] - CalculateGradientY(input: Double[,], updateMenu: Action) : Double[,] + CombineGradients(grads: Gradients) : Double[,] + GradientAngle(grads: Gradients) : Double[,] + MagnitudeThreshold(gradCombined: Double[,], gradAngle: Double[,]): Double[,]

Utility

+ TryBound(I: Int32, h: Int32, v: Double, out value: Double): Boolean + RadianToDegree(input: Double): Double + DegreeToRadian(input: Double) : Double + MapRadiansToPixel(input: Double) : Double + CombineBitmap(a: Bitmap, b: Bitmap): Bitmap + SplitImage(image: RGB[,]): RGB[,][] + CombineQuadrants(alpha: Double[,], beta: Double[,], gamma: Double[,], delta: Double[,]) : Double[,] + InverseImage(image: Double[,]) : Double[,] + RebuildPath(prev: Dictionary<T, T>, goal: T): T[] + IsYes(input: String) : Boolean + GetRed(pixel: Color) : Double + GetGreen(pixel: Color) : Double + GetBlue(pixel: Color) : Double + GetAverage(pixel: Color) : Double + GetIndustryAverage(pixel: Color) : Double

+ DoubleThreshold(input: Double[,]) : ThresholdPixel[,]

+ EdgeTrackingHysteresis(input: ThresholdPixel[,]) : Double[,]

+ GaussianDistribution(x: Int32, y: Int32, sigma: Double): Double

+ Bound(I: Int32, h: Int32, v: Double) : Double

+ GetIfExists(pixel: Color) : Double

+ <u>Uuid() : Guid</u>

+ GetDistanceBetweenNodes(a: Coord, b: Coord): Double

Logger _localApplication: Boolean Lock: Object + Logger(local: Boolean) Logger() - CreateDirStructure(): Void + CreateRun() : Guid + WriteLineToRunFile(currentGuid: Guid, message: String): Void + WriteLineToMaster(message: String): Void + SaveBitmap(currentGuid: Guid, image: Double[,], name: String): Void

Extensions

+ ToBitmap(array: Double[,]) : Bitmap + ToDoubles(image: Bitmap, getPixelFunction: Func<Color, Double>): Double[,] + ToBitmap(array: RGB[,]) : Bitmap + ToGraph(doubles: Double[,]) : Graph<Coord> + SetPixel(pixels: RGB[,], x: Int32, y: Int32, toSetPixel: RGB) : Void + GetPixel(pixels: RGB[,], x: Int32, y: Int32): RGB

+ SaveBitmap(currentGuid: Guid, image: Bitmap, name: String): Void

PreprocessingException

+ PreprocessingException() + PreprocessingException(message: String) + PreprocessingException(message: String, innerException: Exception) # PreprocessingException(info: SerializationInfo, context: StreamingContext)

Post

_imageDoubles: Double[,]

+ Post(input: Double[,]) + Start(embossCount: Int32): Void - EmbossImage(input: Double[,]) : Double[,] - FillPixelGaps(input: Double[,]) : Double[,] + Result() : Double[,]

Stack<T>

+ Size { get; } : Int32 + Stack()

- _stack: List<T>

+ Stack(input: IEnumerable<T>) + Peek() : T + Push(item: T) : Void + Pop() : T + IsEmpty() : Boolean + Contains(item: T) : Boolean

MinPriorityQueue<T>

_priorityQueue: List<Double> _queue: List<T>

+ Size { get; } : Int32 -_size { get; } : Int32 + MinPriorityQueue() - Parent(index: Int32): Int32 - Left(index: Int32) : Int32 - Right(index: Int32): Int32 + Enqueue(value: T, priority: Double): Void + ChangePriority(item: T, newPriority: Double): Void + Dequeue() : T - MinifyHeap(index: Int32) : Void - Swap(indexX: Int32, indexY: Int32): Void + Contains(neighbor: T): Boolean

Graph<T>

+ _data: Dictionary<T, List<T>> + Graph(graph: Dictionary<T, List<T>>) + AddNode(key: T) : Void + RemoveNode(key: T): Void + AddConnection(key: T, value: T): Void + GetNode(key: T) : List<T> + GetAllNodes() : T[] + ContainsNode(node: T): Boolean + Clear() : Void

MaxPriorityQueue<T>

_priorityQueue: List<Int32> _queue: List<T>

+ Size { get; } : Int32 - _size { get; } : Int32 + MaxPriorityQueue() - GetParent(index: Int32) : T - Parent(index: Int32) : Int32 - GetLeftChild(index: Int32) : T - LeftChild(index: Int32): Int32 - GetRightChild(index: Int32) : T - RightChild(index: Int32): Int32 - ShiftNodeUp(index: Int32) : Void + ChangePriority(item: T, newPriority: Int32): Void - ShiftNodeDown(index: Int32): Void + Enqueue(item: T, priority: Int32): Void + Dequeue() : T - RemoveMax() : ValueTuple<T, Int32> - Swap(indexX: Int32, indexY: Int32): Void + Contains(neighbor: T) : Boolean

GraphException

+ GraphException() + GraphException(message: String) + GraphException(message: String, innerException: Exception) # GraphException(info: SerializationInfo, context: StreamingContext)

Traversal<T>

Matrix

MatrixException

SettingsException

_matrix: Double[,]

+ X { get; } : Int32

+ Y { get; } : Int32

+ Minimize() : Void

+ MatrixException()

+ Start() : Void

+ Result() : Double[,]

+ SettingsException()

+ SettingsException(message: String)

+ SettingsException(message: String, innerException: Exception)

SettingsException(info: SerializationInfo, context: StreamingContext)

+ MatrixException(message: String)

+ MatrixException(message: String, innerException: Exception)

«interface» IHandler

MatrixException(info: SerializationInfo, context: StreamingContext)

+ Matrix(matrix: Double[,])

+ Matrix(x: Int32, y: Int32)

+ GetEnumerator() : IEnumerator

+ this[Int32 y, Int32 x] { get; set; } : Double

+ Convolution(a: Matrix, b: Matrix) : Double

+ operator +(a: Matrix, b: Matrix) : Matrix

+ operator -(a: Matrix, b: Matrix) : Matrix

+ operator *(a: Matrix, b: Matrix) : Matrix

+ operator *(a: Int32, b: Matrix) : Matrix

_graph: Graph<T>

Traversal(graph: Graph<T>)

+ DFS(start: T) : T[]

+ BFS(start: T) : T[]

+ AStar(start: T, goal: T, weightFunction: Func<T, T, Int32>): Dictionary<T, T> + Dijkstra(start: T, goal: T, endOnFind: Boolean, nodeUpdate: Action) : Dictionary<T, T>

KernelException

+ KernelException()

+ KernelException(message: String)

+ KernelException(message: String, innerException: Exception) # KernelException(info: SerializationInfo, context: StreamingContext)

Kernel<T>

_image: T[,] _width: Int32 _height: Int32

+ Kernel(image: T[,]) + Constant(x: Int32, y: Int32, size: Int32, constant: T) : T[,]

+ Duplication(x: Int32, y: Int32, size: Int32) : T[,]

+ Gaussian(sigma: Double, size: Int32) : Double[,]

MapFileException

+ MapFileException()

+ MapFileException(message: String) + MapFileException(message: String, innerException: Exception)

MapFileException(info: SerializationInfo, context: StreamingContext)

LoggerException

+ LoggerException() + LoggerException(message: String)

+ LoggerException(message: String, innerException: Exception)

LoggerException(info: SerializationInfo, context: StreamingContext)

RoadDetection

_filledBitmap: Bitmap _pathBitmap: Bitmap

pathDoubles: Double[.] _imageDoubles: Double[,]

_threshold: Double _gen: Random

+ RoadDetection(imageDoubles: Double[,], threshold: Double)

+ Start(updateAction: Action): Void - FillImage(updateAction: Action) : List<Color>

- RemoveColor(toRemove: List<Color>, updateAction: Action): Void

+ Result() : RoadResult

Queue<T>

_queue: List<T>

+ Size { get; } : Int32

+ Queue()

+ Queue(input: IEnumerable<T>)

+ Enqueue(item: T): Void

+ Dequeue() : T

+ IsEmpty() : Boolean

+ Contains(item: T) : Boolean