Introduction to ThumbTrak

Ru Wang

2/12/2019

Overview:

- Motivation: One-handed thumbon-fingers input scenarios.
- It allows the user to use the thumb to continuously input on fingers by tracking the position of the thumb using 2 IMUs.
- It consists of a thumb-ring and a wristband.



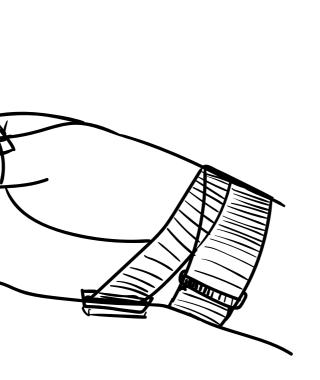
Form Factor:

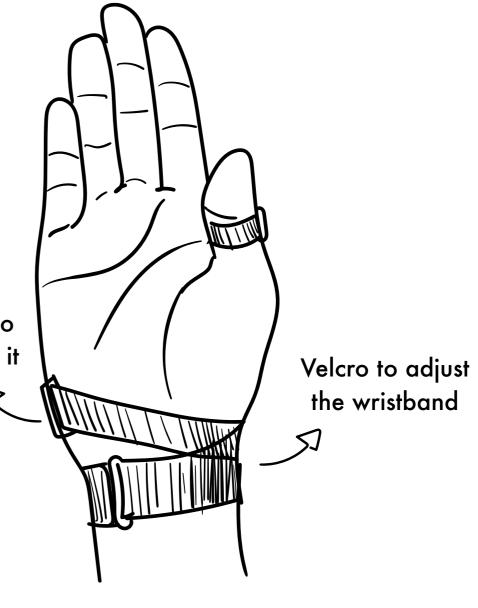
 The user can fix the sensor at the bottom of the hand (on top of the wrist) by simply tightening the wristband.

• Without adhesive.

• Ensures flexibility.

A 3D printed base to mount the sensor on it



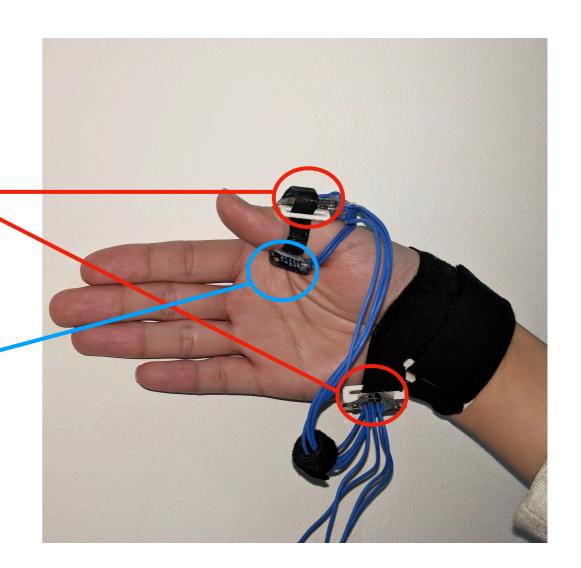


Hardware Prototyping:

• Teensy 3.2 board: Micro controller.

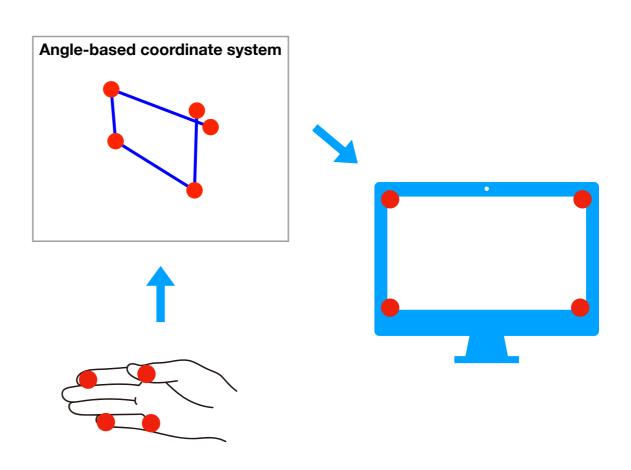
• 2 IMUs (BNO055): To compute the relative orientation (rotation) of the thumb with respect to the hand.

 Proximity Sensor (APDS9960): To measure the distance between the bottom of the thumb and the hand in order to detect tap and release.



Algorithms:

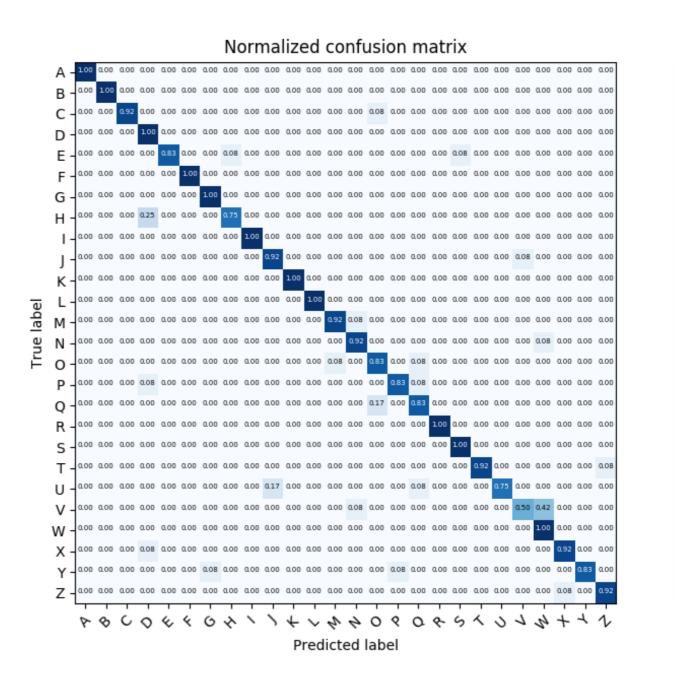
- Angle-based coordinate system:
 We build a coordinate system based
 on the angle derived from the relative
 rotation.
- Perspective transformation: To map the user's drawing from the irregular quadrilateral canvas on angle-based coordinate system to a rectangular canvas on the screen.
- KNN + \$P Recognizer[1]: To recognize the letter the user draws with this device. We collected 1400+ unistroke templates.
- Kalman Filter: To smooth the trajectory with low latency.



[1] http://depts.washington.edu/ilab/proj/dollar/pdollar.html

User Study:

- Text Entry: We let the participants use this device to write letters. The performance of our algorithm is shown on the right.
- Gesture Entry: We let the participants use this device to draw the graphics shown on the screen, and then we analyze the similarity of the shape.
- Fitts' Law Test: We let the participants use this device as a mouse to click on the red dots on the screen according to the prompt, and then we analyze the accuracy and the speed.



- 0.4

0.2

Demo

Video demo of text entry task:

https://www.youtube.com/watch?v=NEGMpqcbZIE