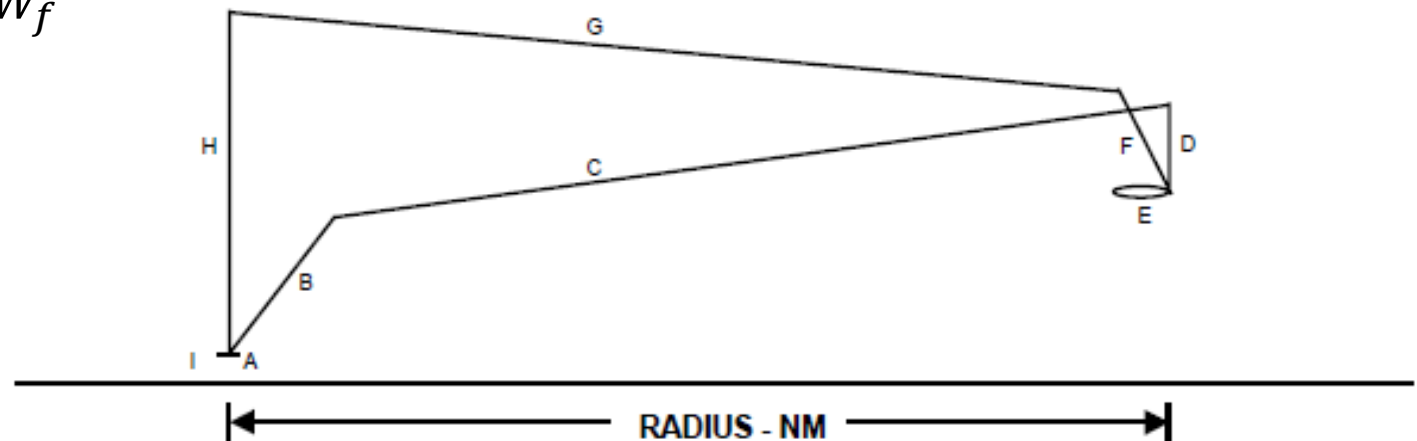


Sizing to Constraints

Errikos Levis

Based on the mission profile we have:

- Assumed $(L/D)_{max}$ and sfc based on baseline and current state of the art
- Used range and endurance equations, and empiricism to estimate
 - Gross Weight (MTOW) W_0
 - Operating Empty Weight (OEW) W_e
 - Fuel Weight W_f



Mission profile for an Airborne Warning And Control System (AWACS) aircraft (MIL-STD 3013)

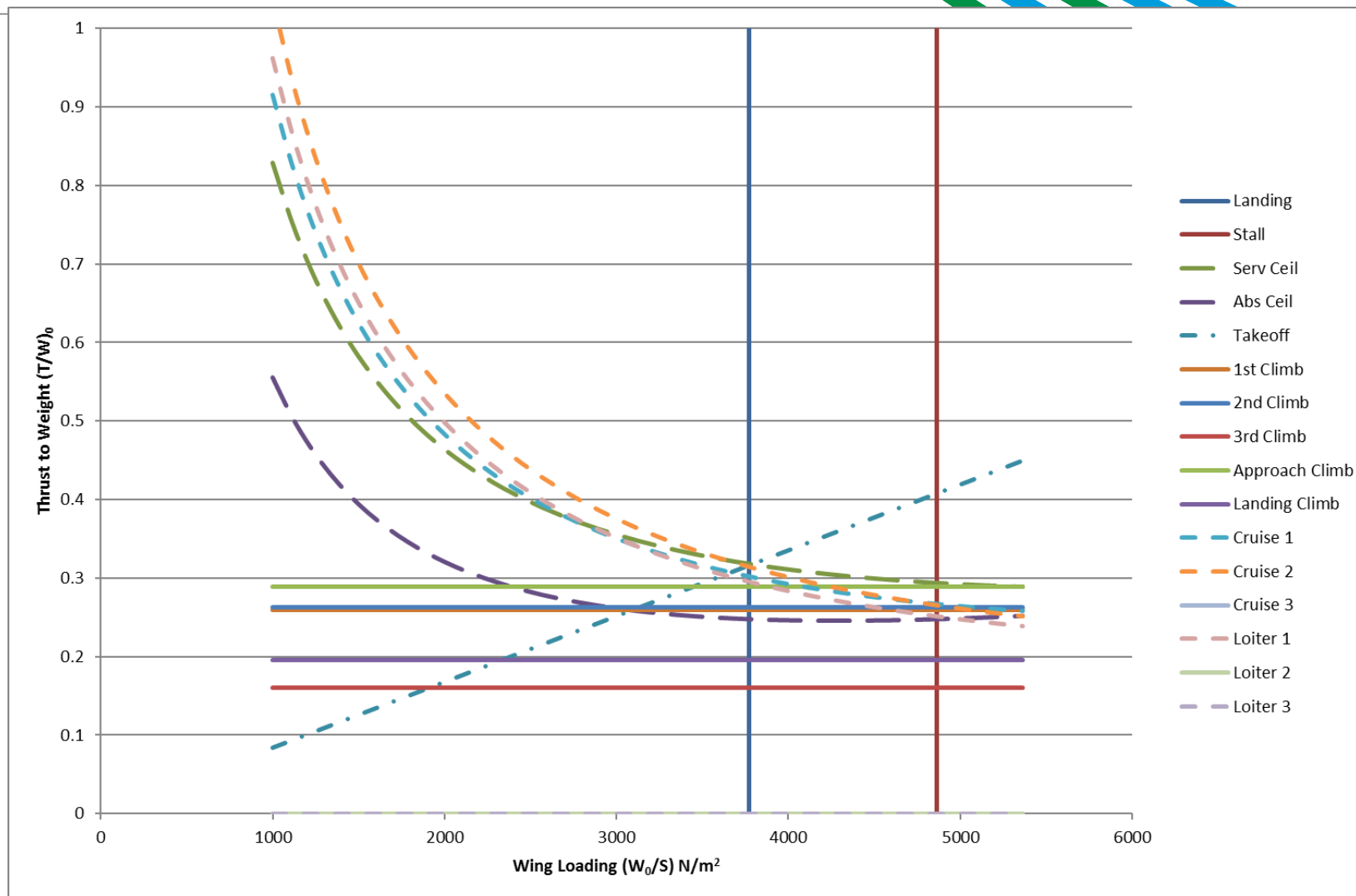
What's next?

- Make sure aircraft can complete the stipulated design mission profile
- Make sure aircraft capable of achieving performance targets like
 - Ceilings (absolute, service, combat)
 - Maximum speed
 - Time to climb / Rates of climb
 - Sustained turn rates / radii
 - Level (axial) acceleration
 - Takeoff and Landing distances (TODA & LDA)
 - Stall speed
- Make sure aircraft meets airworthiness requirements



Key Parameters?





Point Performance

Errikos Levis

From definition of Specific Excess Power:

for thrust producing powerplants (jet)

$$\frac{dh}{dt} + \frac{V_{\infty}}{g} \frac{dV_{\infty}}{dt} = V_{\infty} \left(\frac{T - D}{W} \right)$$

for power producing powerplants (jet)

$$\frac{dh}{dt} + \frac{V_{\infty}}{g} \frac{dV_{\infty}}{dt} = \frac{P}{W} - \frac{V_{\infty} D}{W}$$

Assuming a parabolic drag curve at load factor n

$$\frac{D}{W} = \frac{\frac{1}{2}\rho V_{\infty}^2 C_{D_0}}{W/S_{ref}} + \frac{n^2 W/S_{ref}}{\frac{1}{2}\rho V_{\infty}^2 \pi AR e}$$

where $C_{D_0} = f(S_{wet}/S_{ref})$

$$\left(\frac{L}{D}\right)_{max} = \frac{1}{2} \sqrt{\frac{\pi AR e}{C_{D_0}}} = K_{LD} \sqrt{\frac{AR}{S_{wet}/S_{ref}}}$$

and dependent on configuration:

undercarriage	$\Delta C_{D_0} \approx 0.02$	$\Delta e \approx -0.05$
t/o flaps	$\Delta C_{D_0} \approx 0.02$	$\Delta e \approx -0.05$
landing flaps	$\Delta C_{D_0} \approx 0.07$	$\Delta e \approx -0.10$

SEP equation for jet becomes

$$\frac{dh}{dt} + \frac{V_{\infty}}{g} \frac{dV_{\infty}}{dt} = V_{\infty} \left(\frac{T}{W} - \frac{\frac{1}{2}\rho V_{\infty}^2 C_{D_0}}{W/S_{ref}} - \frac{n^2 W/S_{ref}}{\frac{1}{2}\rho V_{\infty}^2 \pi AR e} \right)$$

or

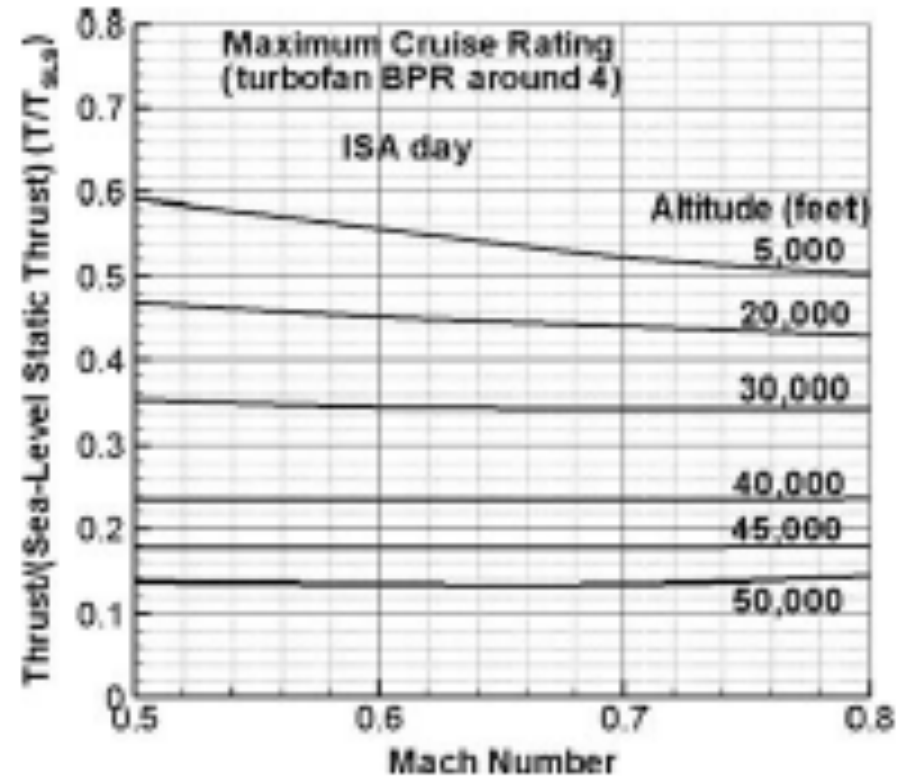
$$\frac{T}{W} = \frac{1}{V_{\infty}} \frac{dh}{dt} + \frac{1}{g} \frac{dV_{\infty}}{dt} + \frac{\frac{1}{2}\rho V_{\infty}^2 C_{D_0}}{W/S_{ref}} + \frac{n^2 W/S_{ref}}{\frac{1}{2}\rho V_{\infty}^2 \pi AR e}$$

Scaling to sea-level, static, takeoff conditions

(Kundu, Aircraft Design, 2010)

$$\alpha = \frac{W}{W_0}$$

$$\beta = \frac{T}{T_0}$$



Hence for jet

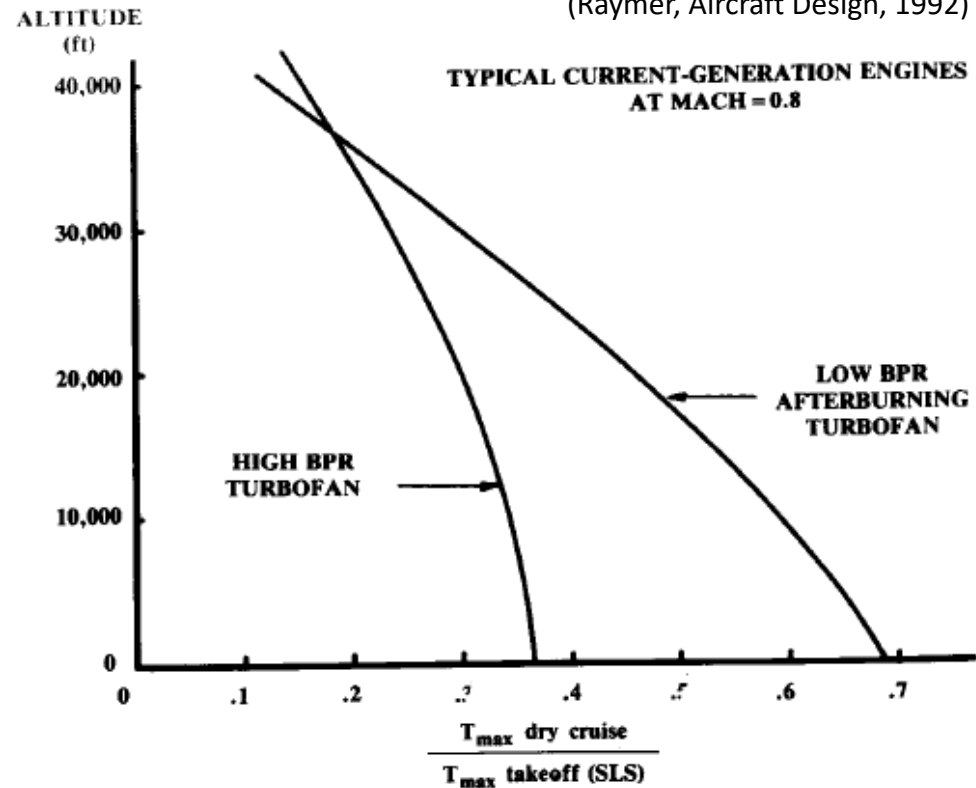
$$\left(\frac{T}{W}\right)_0 = \frac{\alpha}{\beta} \left[\frac{1}{V_\infty} \frac{dh}{dt} + \frac{1}{g} \frac{dV_\infty}{dt} + \frac{\frac{1}{2} \rho V_\infty^2 C_{D_0}}{\alpha W_0 / S_{ref}} + \frac{\alpha n^2 W_0 / S_{ref}}{\frac{1}{2} \rho V_\infty^2 \pi AR e} \right]$$

Scaling to sea-level, static, takeoff conditions

$$\alpha = \frac{W}{W_0}$$

$$\beta = \frac{T}{T_0}$$

(Raymer, Aircraft Design, 1992)



Hence for jet

$$\left(\frac{T}{W}\right)_0 = \frac{\alpha}{\beta} \left[\frac{1}{V_\infty} \frac{dh}{dt} + \frac{1}{g} \frac{dV_\infty}{dt} + \frac{\frac{1}{2} \rho V_\infty^2 C_{D_0}}{\alpha W_0 / S_{ref}} + \frac{\alpha n^2 W_0 / S_{ref}}{\frac{1}{2} \rho V_\infty^2 \pi A R e} \right]$$

Consider aircraft with following assumed characteristics

$$C_{D_0} = 0.02$$

$$AR = 7$$

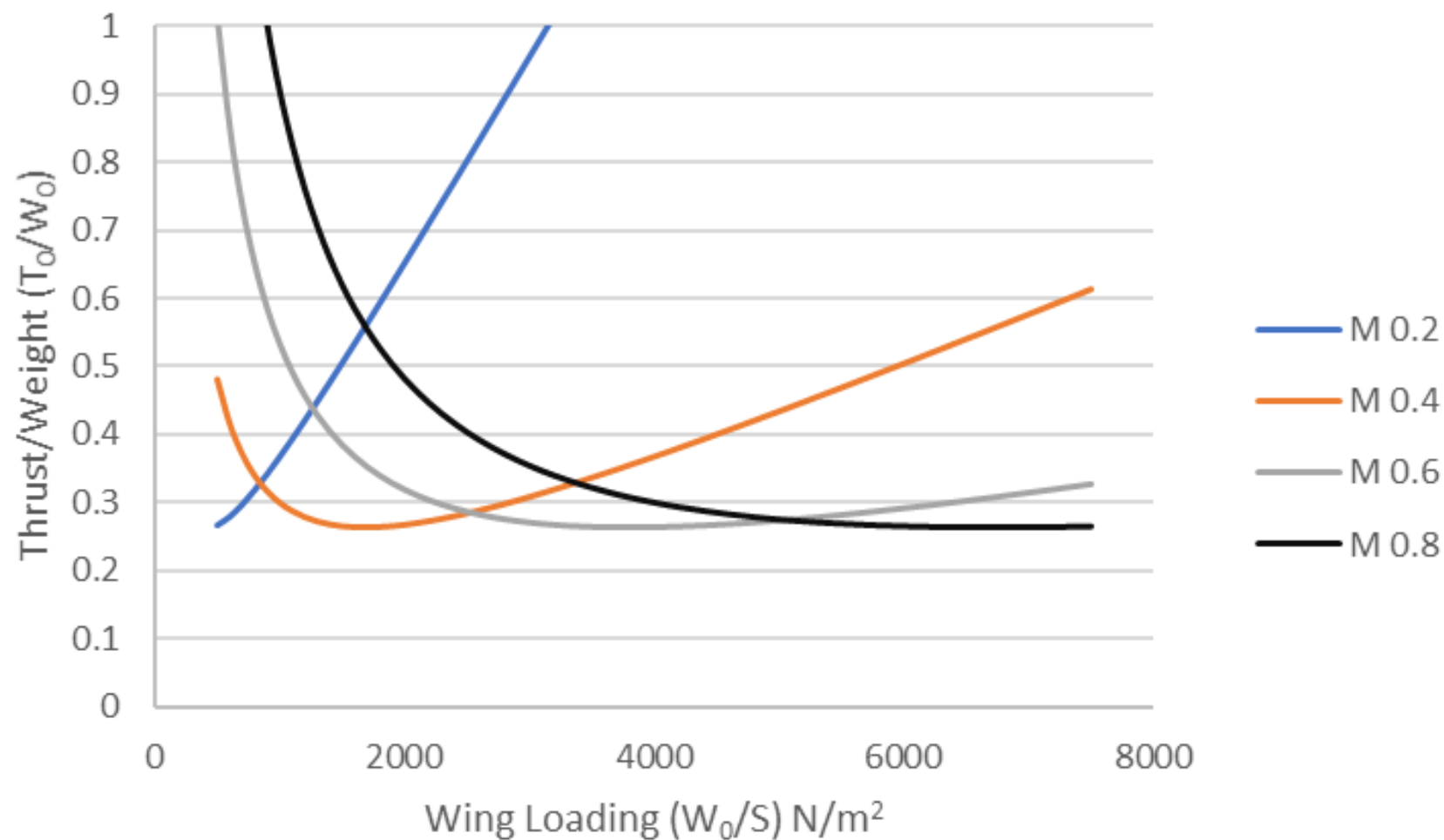
$$e = 0.9$$

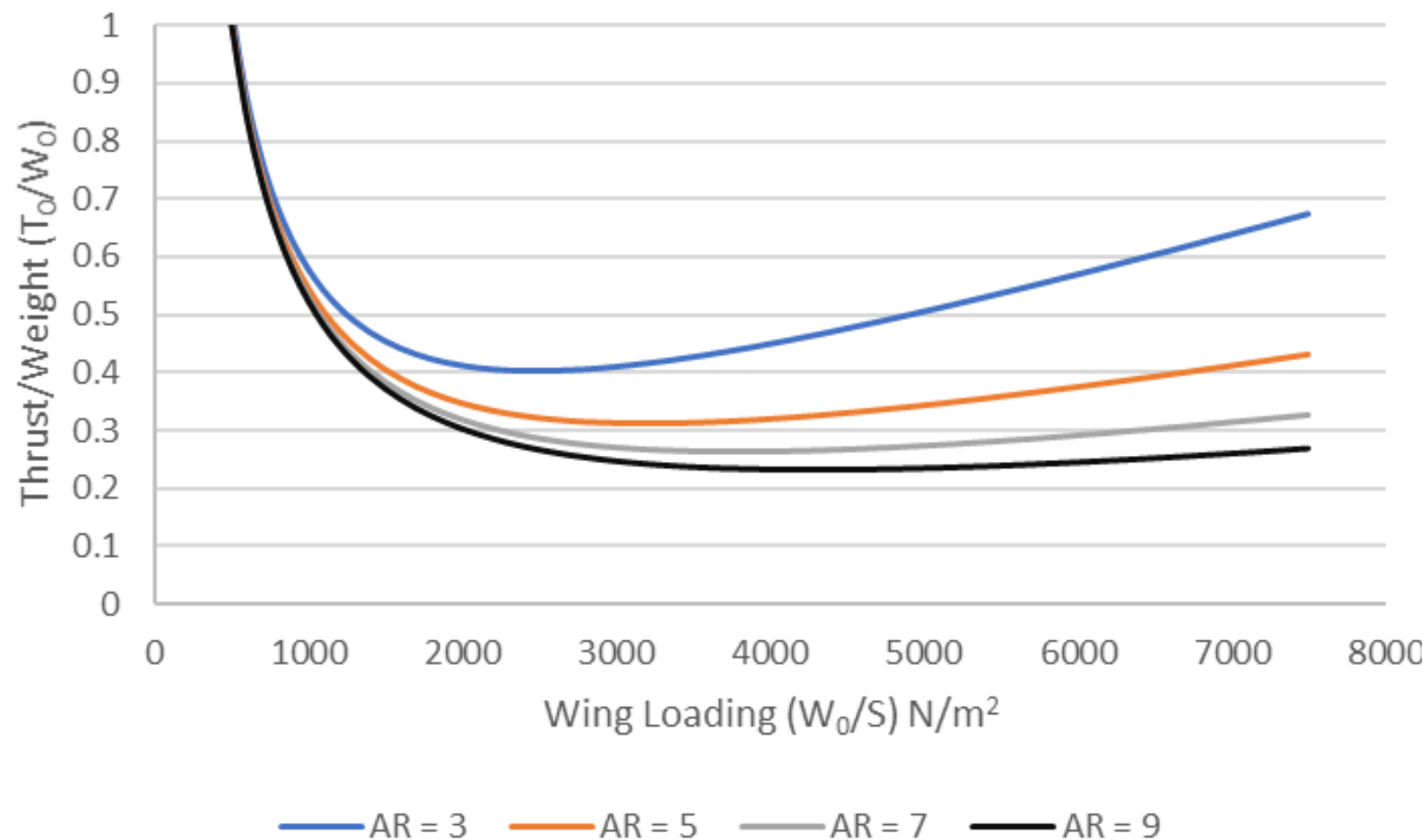
analyzed at the start of its cruise segment, at 11,000 ft and Mach 0.6, in steady level flight where

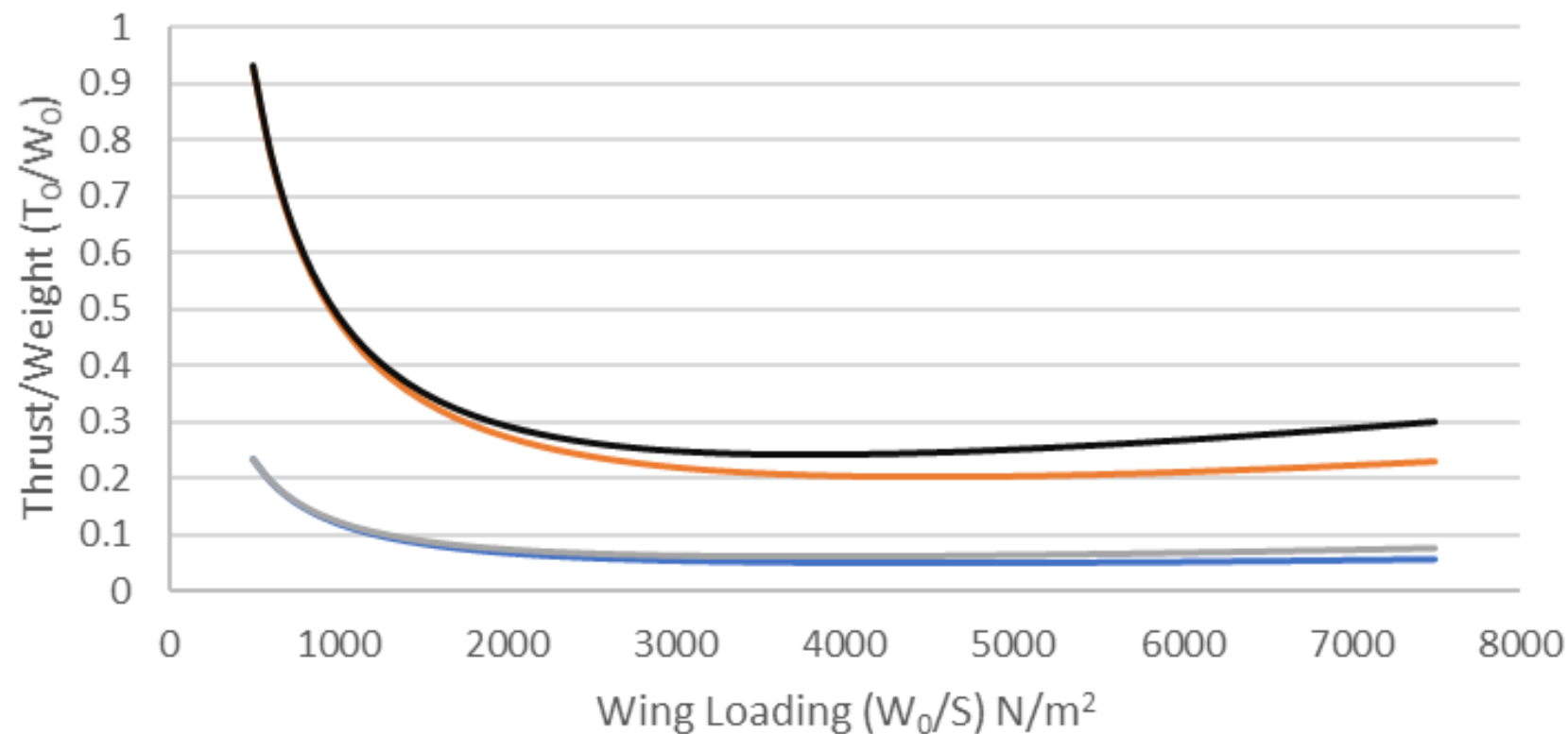
$$\frac{T}{T_0} = 0.23$$

$$\frac{W}{W_0} = 0.96$$

(all values assumed for illustration purposes)





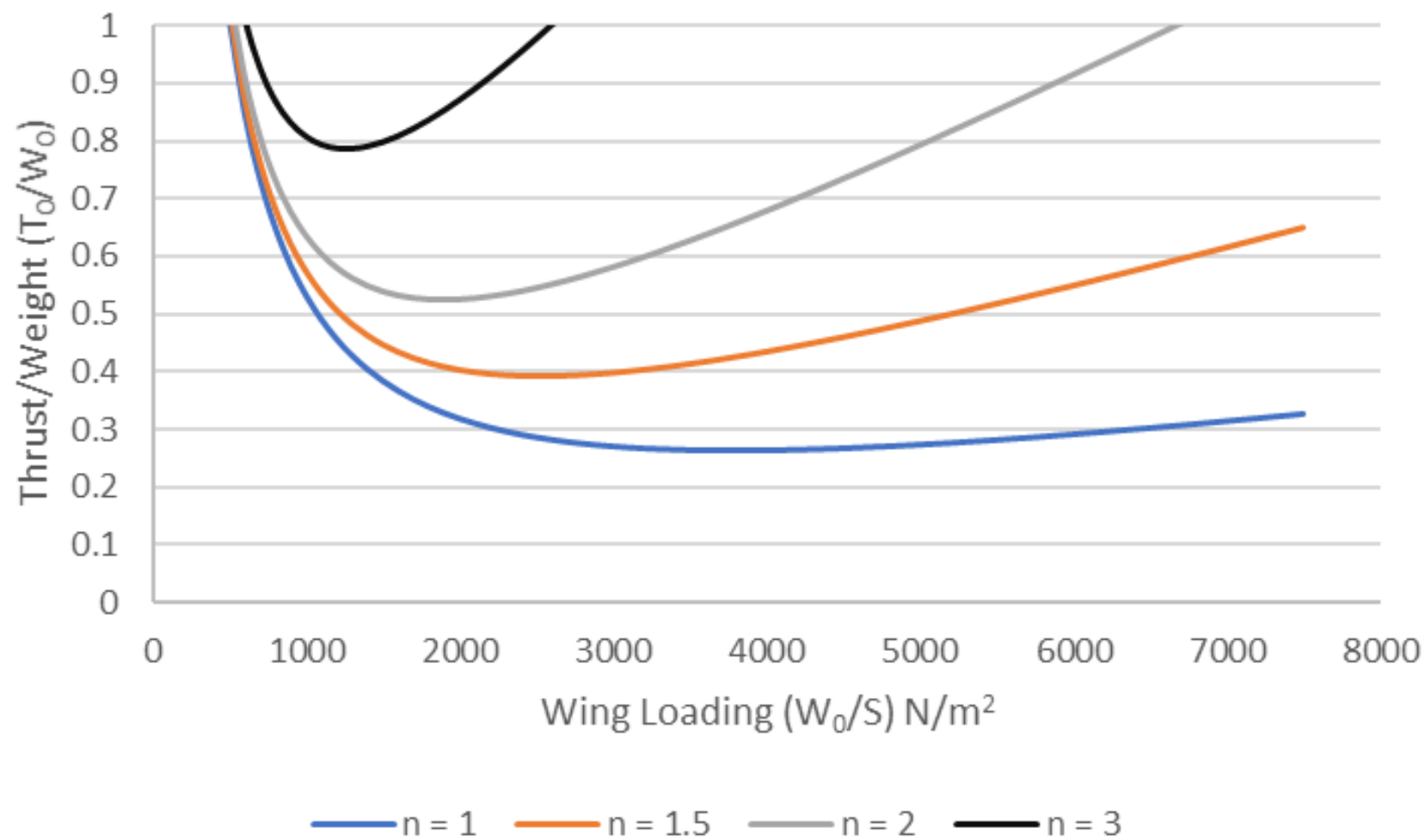


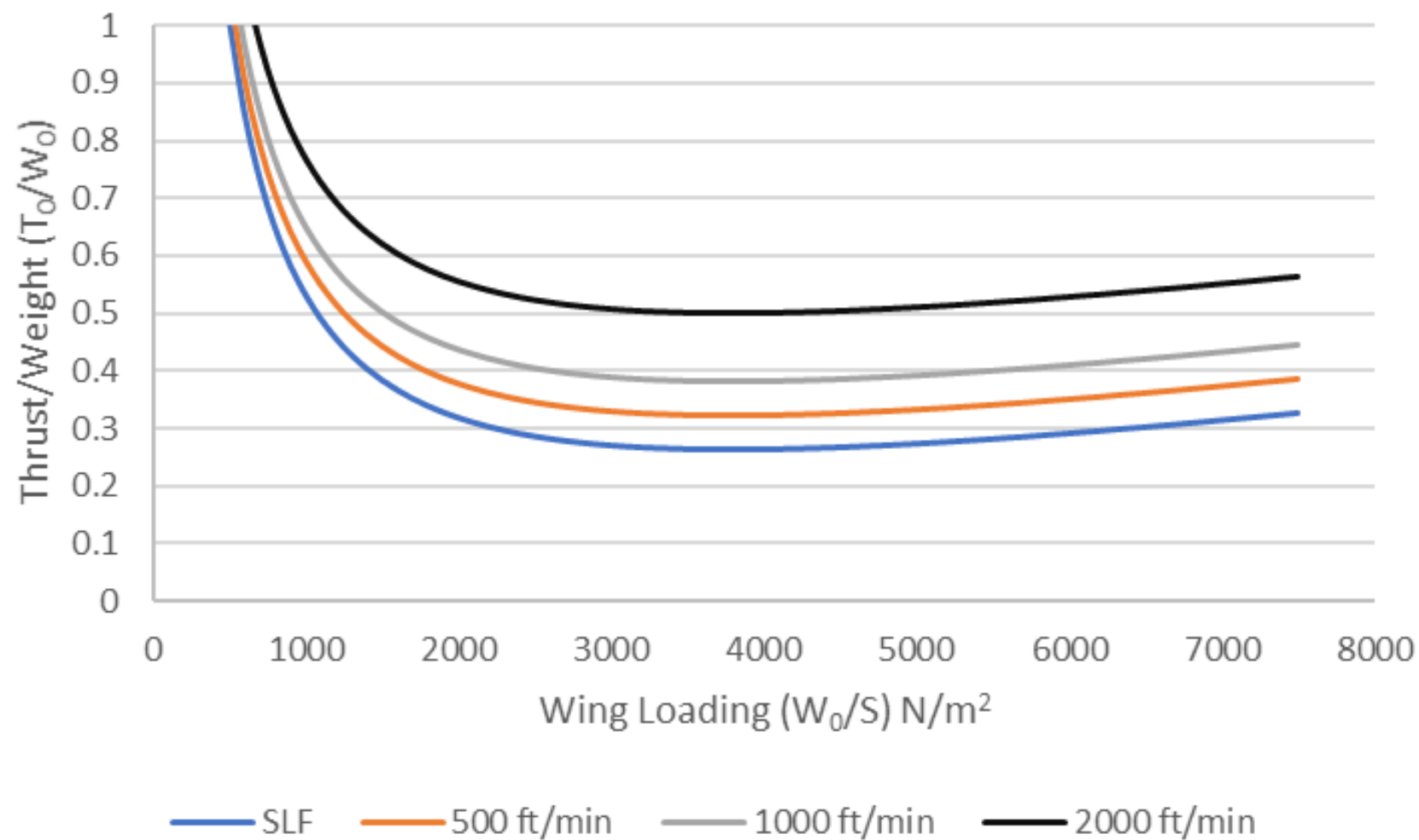
— $W/W_0 = 0.8$ & $T/T_0 = 1$

— $W/W_0 = 0.8$ & $T/T_0 = 0.25$

— $W/W_0 = 0.95$ & $T/T_0 = 1$

— $W/W_0 = 0.95$ & $T/T_0 = 0.25$





Field Performance

Errikos Levis

Key terms:

Take-Off Distance Available (TODA)

Landing Distance Available (LDA)

Take-Off Distance Required

Landing Distance Required

Actual TakeOff Distance

Balanced Field Length

Actual Landing Distance

(for design purposes we always assume dry, flat runway with no crosswind)

Key terms:

Take-Off Distance Available (TODA)

Landing Distance Available (LDA)

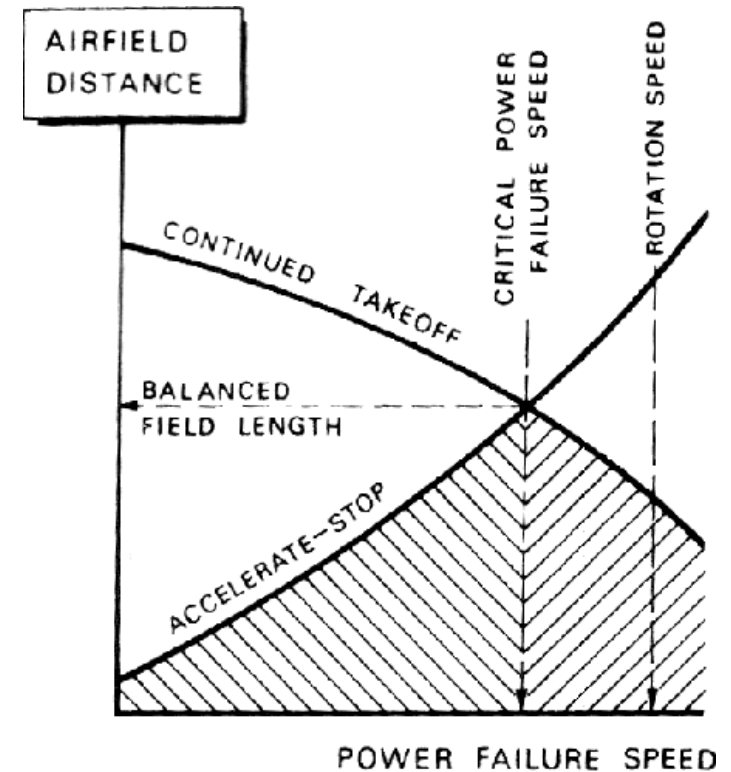
Take-Off Distance Required

Landing Distance Required

Actual TakeOff Distance

Balanced Field Length

Actual Landing Distance



(Torenbeek, Synthesis of Subsonic Aircraft Design, 1982)

(for design purposes we always assume dry, flat runway with no crosswind)

Parameters affecting Takeoff Distance

- Stall Speed
- Ground Acceleration
- Excess Power
- Obstacle Height

Empirically (in SI):

BFL - $TODA \geq (0.297 - 0.019 N_E) TOP$

AEO to 50 ft - $TODA \geq 0.144 TOP$

$$\text{where } TOP = \frac{W/S}{T/W \sigma C_{L_{LOF}}}$$

(Similar methods for propeller available in literature but $TOP = \frac{W/S}{P/W \sigma C_{L_{LOF}}}$)

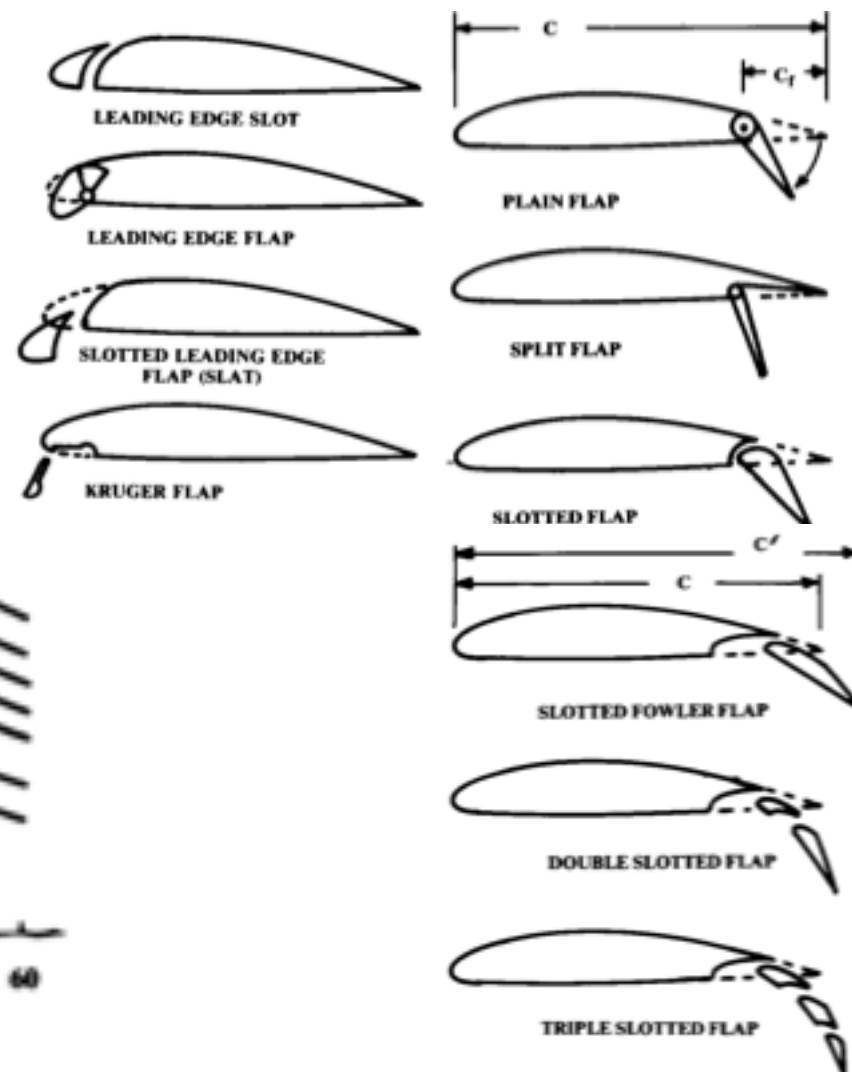
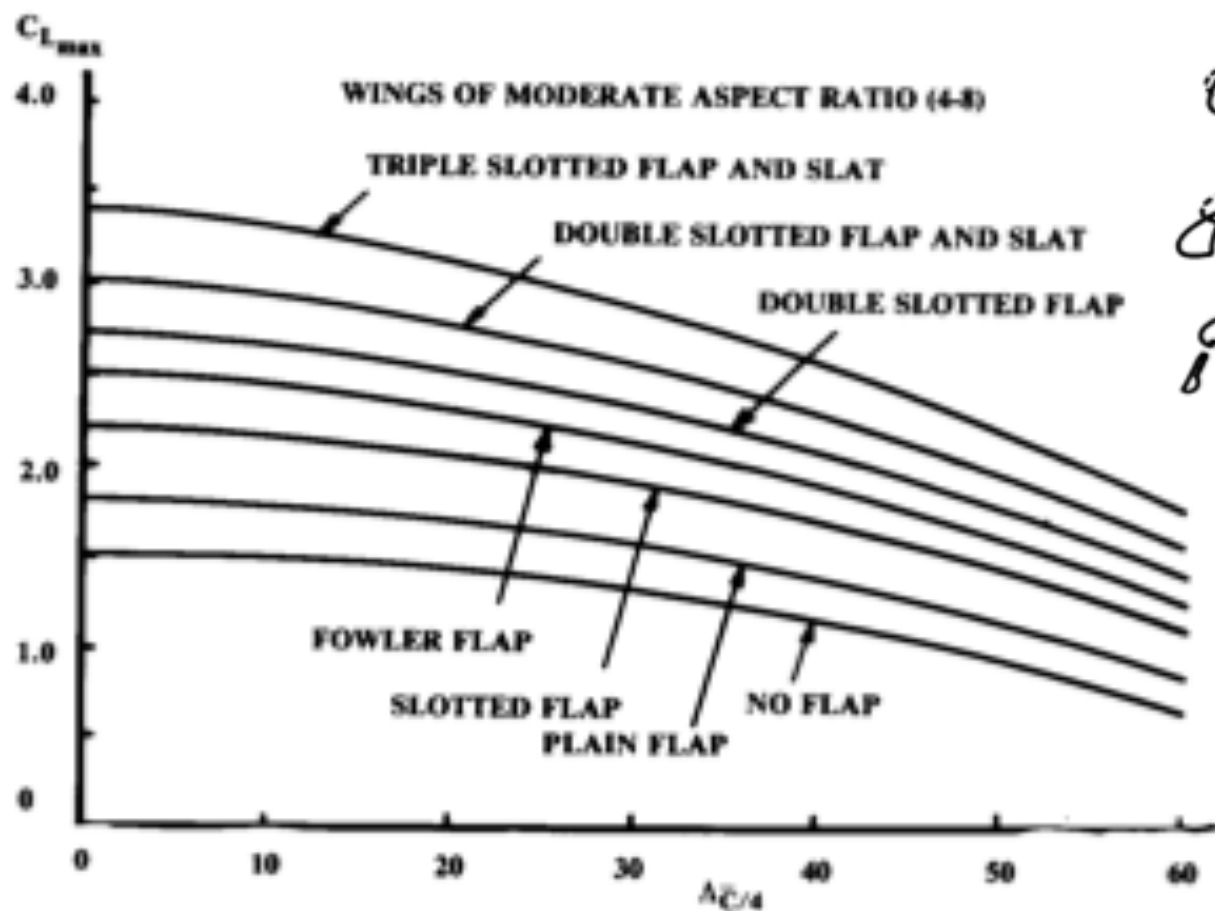
Parameters affecting Landing Distance

- Approach Speed
- Deceleration
- Glide Slope
- Obstacle Height

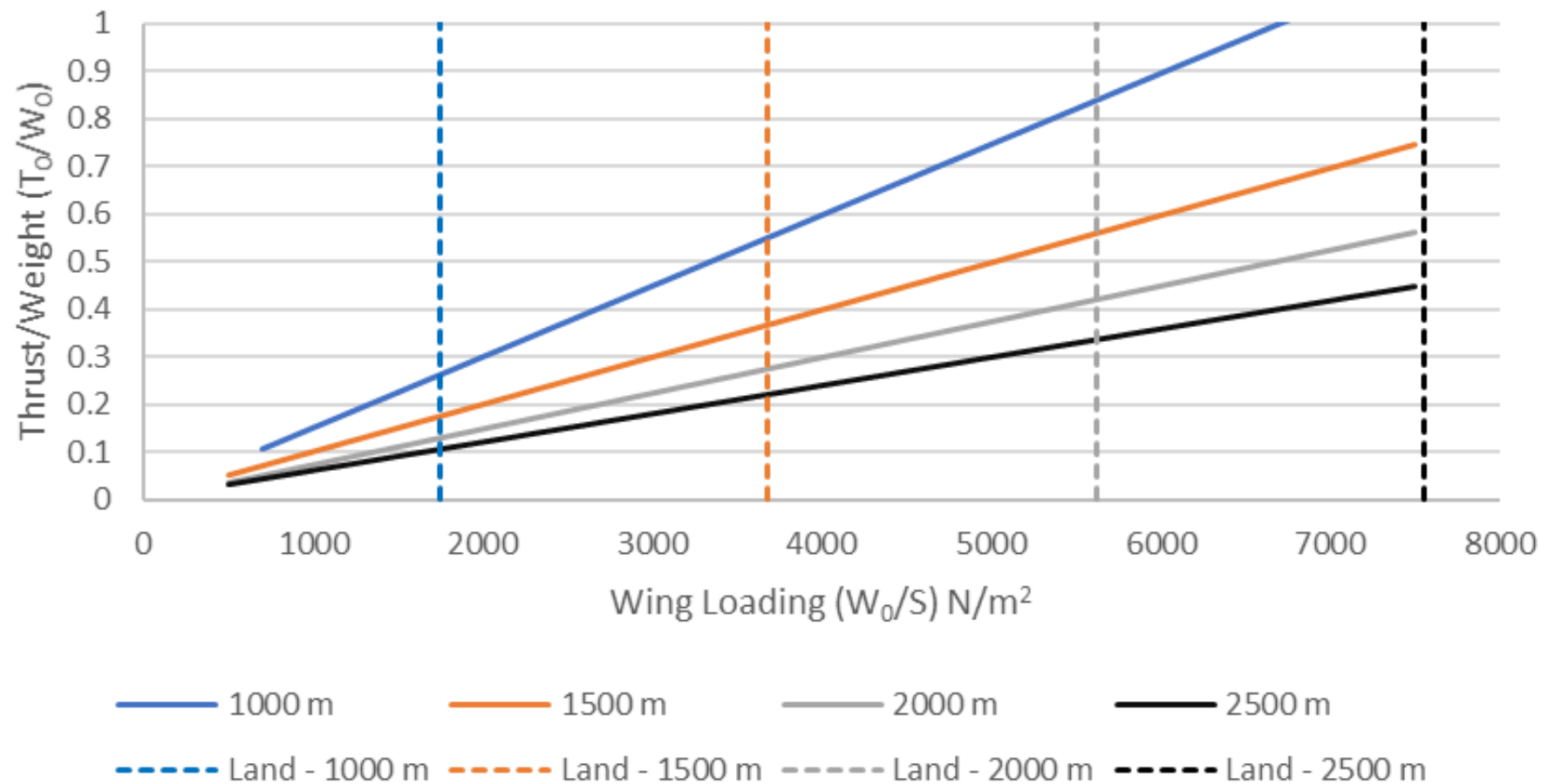
Empirically (in SI):

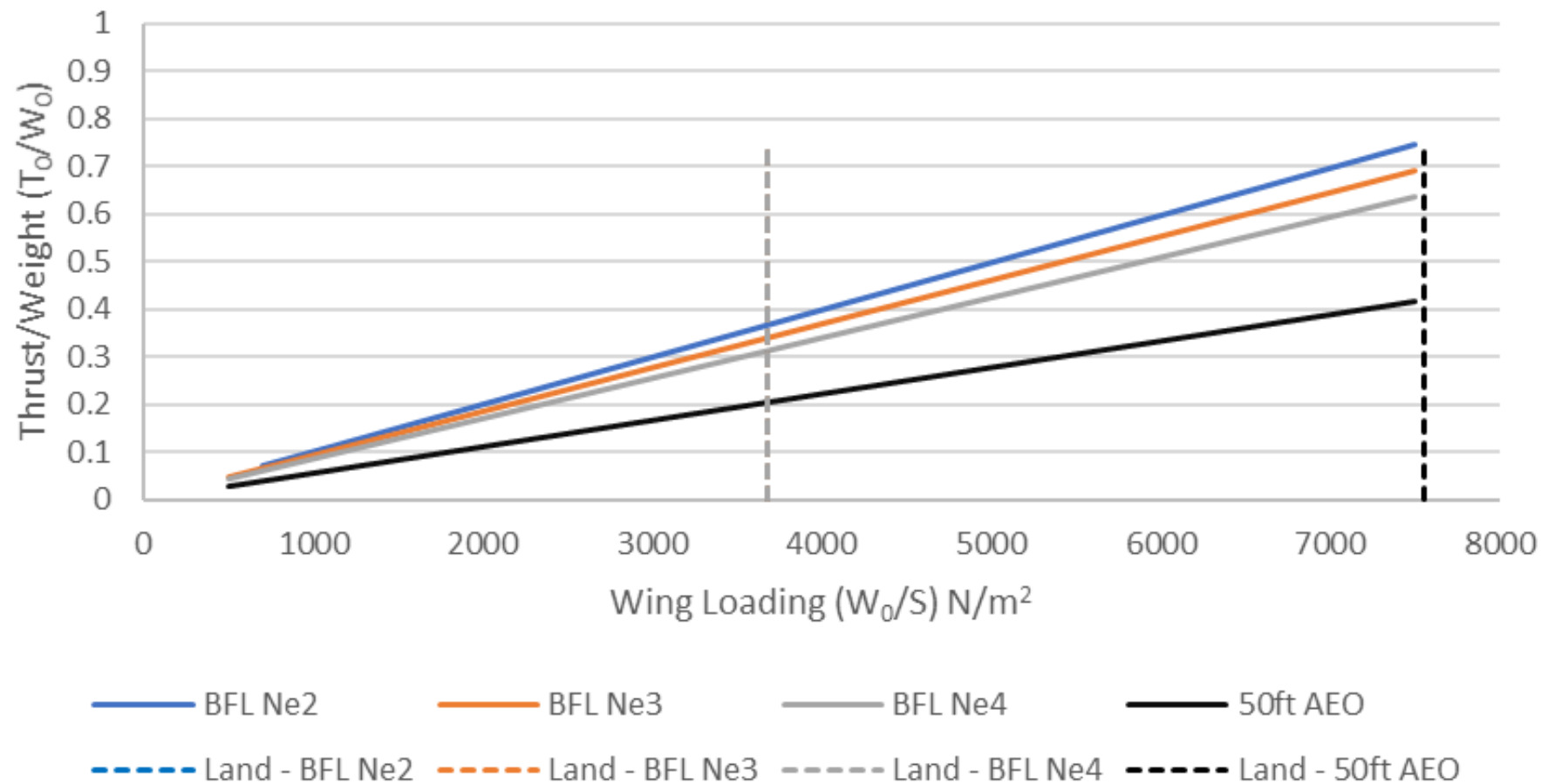
$$ALD = 0.51 \frac{W/S}{\sigma C_{L_{maxL}}} K_R + S_a$$

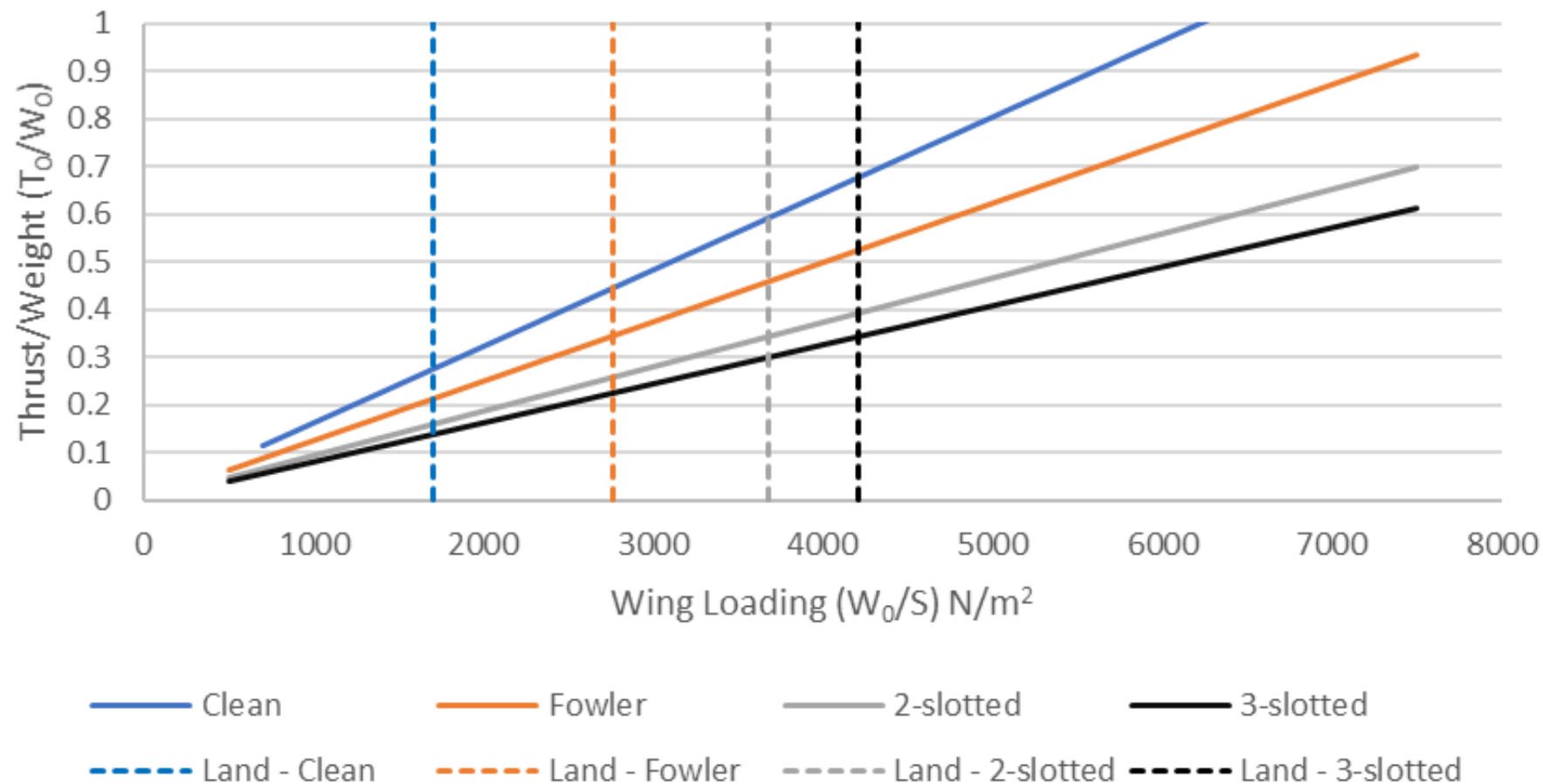
S_a	
305 m	Airliner type 3 degree glideslope
183 m	For GA type powered off approach
137 m	For STOL, 7 degree glideslope

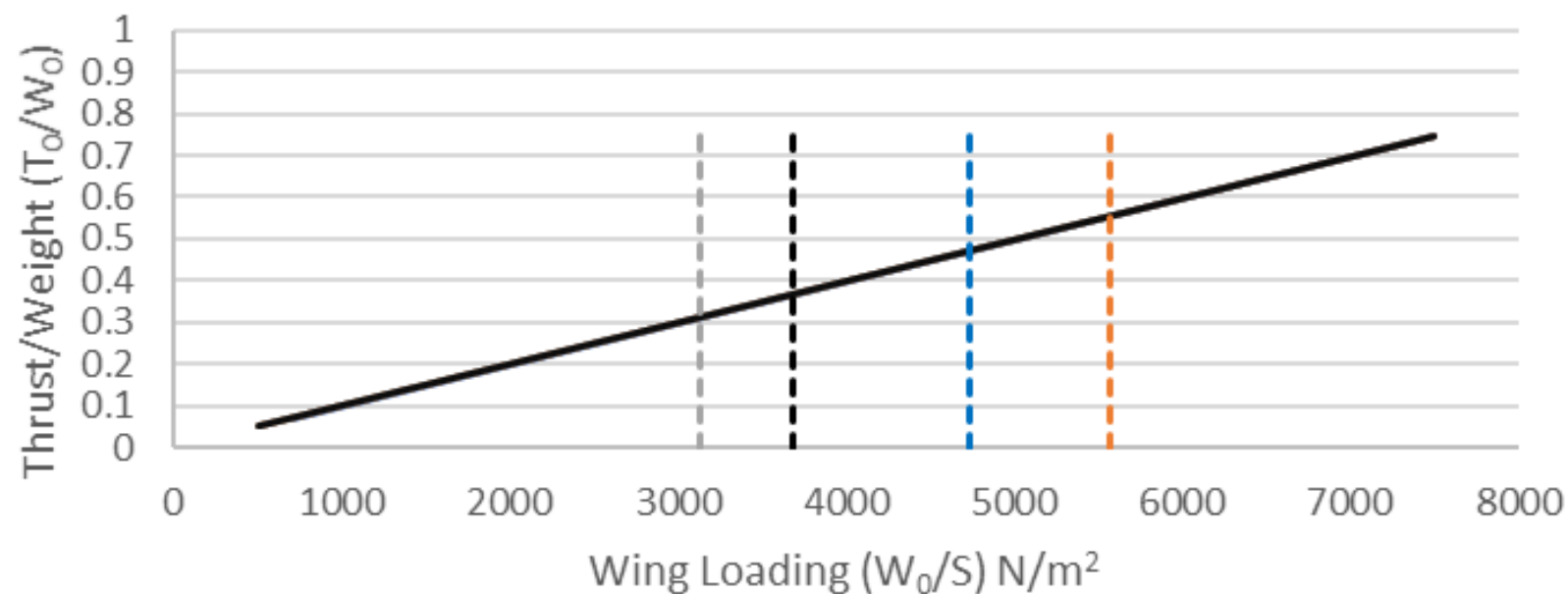


(Raymer, Aircraft Design, 1992)









— $WL/W_o = 1$, Trev

— $WL/W_o = 0.85$, Trev

— $WL/W_o = 1$

— $WL/W_o = 0.85$

- - - Land - $WL/W_o = 1$, Trev

- - - Land - $WL/W_o = 0.85$, Trev

- - - Land - $WL/W_o = 1$

- - - Land - $WL/W_o = 0.85$