Chapter 5: Performance Analysis

Elements of Parallel Computing

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Work-Depth Analysis

- Depth: parallel execution time
- ▶ Work: sequential execution time to complete all tasks
- Parallelism: work/depth. Upper bound on performance gain.

Depth

- Consider all possible paths in task graph
- Depth given as longest time of all paths
- ▶ If all tasks take the same time then depth is time of longest path: *critical path*
- No matter how many computational resources, solution cannot be computed in less time than depth

Work Efficiency

Parallel algorithm is **work-efficient** if its work has the same complexity as the best sequential algorithm

Reduction

- work: O(n)
 - work efficient
- depth: $O(\log n)$
- ▶ parallelism: $O(n/\log n)$

Naive Merge Sort

- work: $O(n \log n)$
- ▶ depth: from recurrence relation d(n) = d(n/2) + O(n), gives depth of O(n)
- ightharpoonup parallelism: $O(\log n)$

Merge Sort with Parallel Merge:

- ▶ parallel merge: O(n) work and $O(\log^2 n)$ depth
- work of merge sort still $O(n \log n)$
- depth: recurrence relation for $d(n) = d(n/2) + O(\log^2 n)$, yields $O(\log^3 n)$
- parallelism: $O(n/\log^2 n)$

Hillis and Steele Scan

```
for k \leftarrow 0 to \log n - 1 do j \leftarrow 2^k \{a[i] \leftarrow a[i-j] + a[i] : i \in [0..n) \mid i \ge j\} end
```

- ▶ $n-2^k$ independent tasks (each doing an addition) at each level
- tasks in one level complete before next level starts
- ▶ depth: $O(\log n)$, work: $O(n \log n)$ (not work efficient), parallelism: O(n)

Blelloch Scan

Two traversals of reduction tree, so same complexity as reduction: O(n) work, $O(\log n)$ depth, and $O(n/\log n)$ parallelism

Performance Metrics

- Speedup
- Cost
- Efficiency
- Throughput

Speedup

- relative speedup: ratio of the execution time of the parallel program on one core to the time on p cores
- ▶ absolute speedup: ratio of the execution time of the best known sequential algorithm to the execution time of the parallel algorithm on p

Cost

Cost: product of the asymptotic execution time and the number of cores.

- Not the same as work!
- ▶ Reduction: O(n) work. If p = n/2 cores used, cost is $O(p \log p)$. Reduction is work efficient but is not cost efficient
- Reduction: if fewer cores used, then each core first sums n/p before parallel reduction. This takes $O(n/p + \log p)$ time, so cost is $O(n + p \log p)$. If n is greater than $p \log p$ then this algorithm is cost efficient and its speedup is O(n/(n/p)) = O(p), which is optimal.

Efficiency

- Efficiency: ratio of the speedup to the number of cores.
- ► Also given by ratio of the execution time of the sequential algorithm to the cost

Throughput Metrics

- When sequential time not possible or meaningful, such as for GPU execution
- ► E.g.: floating point operations per second (FLOPS), cell updates per second, . . .
- Operation count must be based on best known sequential algorithm

Comparing Scan Algorithms

- ▶ Hillis and Steele with p = n cores: log n time and $n/\log n$ speedup
- ▶ Blelloch with p = n/2 cores: $n/(2 \log n)$ speedup.
- ▶ Both algorithms cost-inefficient, at $O(n \log n)$
- Better to use fewer cores, as for reduction

SPMD Shared Memory Scan

```
// assumes n divisible by p
shared a. b
start \leftarrow id * n/p
sum \leftarrow 0
for j \leftarrow 0 to n/p - 1 do
    sum \leftarrow sum + a[start + j]
     a[start + i] \leftarrow sum
end
b[id] \leftarrow a[(id+1)*n/p-1] // sum of all values in
    sub-array
scan(b)
if id > 0 then
     for i \leftarrow 0 to n/p - 1 do
          a[start + i] \leftarrow a[start + i] + b[id - 1]
     end
end
```

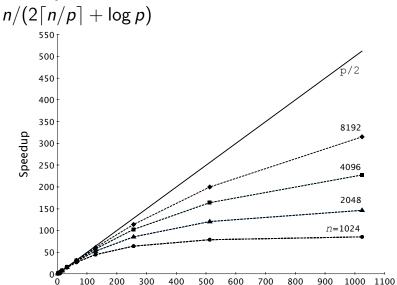
Analysis of SPMD Scan

Parallel execution time:

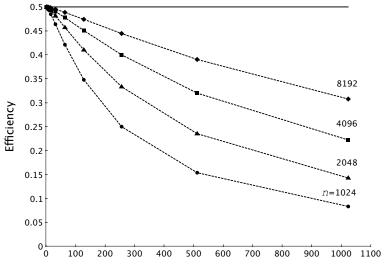
- ▶ Hillis and Steele: $2\lceil n/p \rceil + \log p$
- ▶ Blelloch: $2\lceil n/p \rceil + 2\log p$

Cost is $O(n + p \log p)$, so cost efficient if n is greater than $p \log p$

Speedup of SPMD Hillis and Steele scan



Efficiency of SPMD Hillis and Steele scan

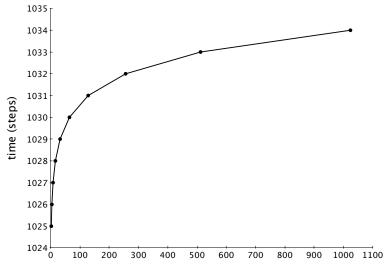


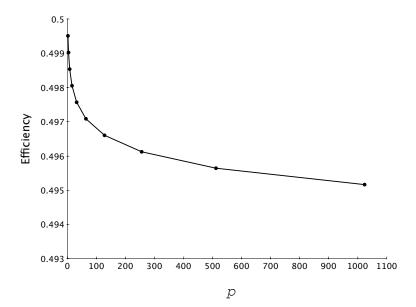
Strong and Weak Scaling

- Strong scaling: problem size fixed as number of cores increases
- Weak scaling: amount of work per core is kept fixed as number of cores increases

Weak Scaling of SPMD Hillis and Steele

Problem size scaled as n = 512p

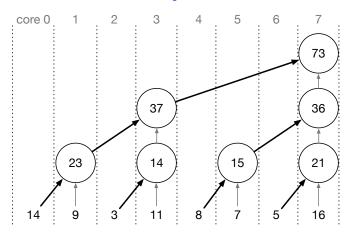




Communication Analysis

- ▶ Communication over a link: $t_{comm} = \lambda + m/\beta$, for HW/SW latency λ and bandwidth β .
- Communication topology of application: virtual topology
- At runtime, virtual topology embedded on the physical topology

Communication Analysis: Reduction



 $t_{\rm reduction} = (\sigma + \lambda + m/\beta) \log p = O(m \log p)$, σ is time to add two values and m is size of a value.

Analysis of Game of Life

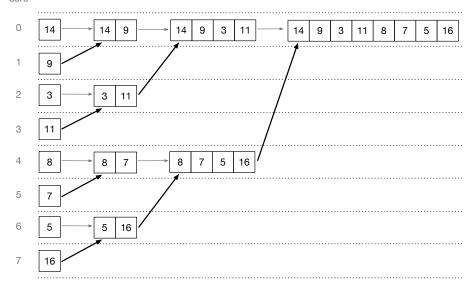
- ▶ 1D decomposition: each core sends 2 messages of size n, $t_{1D} = O(n^2/p + n)$
- ▶ 2D decomposition: each core sends 4 messages of size n/\sqrt{p} , $t_{\rm 2D} = O(n^2/p + n/\sqrt{p})$
- Both decompositions are cost efficient
- ▶ 2D decomposition has lower time and better weak scaling (increasing n as a function of \sqrt{p}), with an efficiency of O(1)

Analysis of 1D Matrix-Vector Multiplication

- communication: gather result vectors and broadcast gathered vector
- ▶ Broadcast has same topology as reduction, $t_{\text{broadcast}} = (\lambda + n/\beta) \log p = O(n \log p)$
- Gather is similar, but message size increases at each step

Gather





Gather Analysis

```
// Assumes p = 2^i and n \mod p = 0
for i \leftarrow 0 to \log p - 1 do
   if id mod 2^i = 0 then
       if id/2^i \mod 2 = 1 then
           send array of length 2^i n/p to id - 2^i
       else
           receive array starting at position
           (id + 2^i)n/p from id + 2^i
       end
   end
end
```

▶ log p steps and the message size at step i is $2^{i}n/p$

1D vs. 2D Matrix-Vector Multiplication

$$t_{1D} = O(n^2/p + n \log p)$$

$$t_{\text{2D}} = O(n^2/p + (n/\sqrt{p})\log\sqrt{p} + (n/\sqrt{p})\log\sqrt{p})$$

= $O(n^2/p + (n/\sqrt{p})\log p)$