by Ruben Mercade Prieto

PI Control - Photoresistor + LED

by Ruben Mercade Prieto - June 2021

Watch explanation Video.

This is an example of a PI control using a photoresistor as a sensor and LED(s) as the controller. You can choose between a Red, Green or Blue LED, or a combination thereof. Obviously, the more LED selected, the more light - which may be a problem to control low light conditions. The ESP32 is currently used in several commercial industrial control solutions, e.g.: [1], [2], [3].

The minimum value of the photoresistor is measured from the environmental conditions at the startup of the ESP32; the maximum value is found similarly with all the 3 LEDs at maximum power.

Let us revisit the key equation in a PI control. Led(t) is the controlled variable, an 8bit PWM signal from the ESP32, and Led_{bias} is the initial value, often zero. P_{SP} and P_{PV} are the set point and process variable, respectively, which in this case corresponds to the 12bit (0-4096) value from the photoresistor. Their difference is the key error to calculate, e(t). The tunable parameters are K_P , the proportional constant, and τ_I , the integral time

$$egin{align} Led(t) &= Led_{bias} + K_P(P_{SP} - P_{PV}) + rac{K_P}{ au_I} \int_0^t \left(P_{SP} - P_{PV}
ight) dt \ &= Led_{bias} + K_P e(t) + rac{K_P}{ au_I} \int_0^t e(t) dt \ &Led(t) pprox Led_{bias} + K_P e(t) + rac{K_P}{ au_I} \sum_{i=1}^{n_t} e_i(t) \Delta t \ \end{gathered}$$

where in this ESP32 example, it has been selected $\Delta t = 0.5s$.



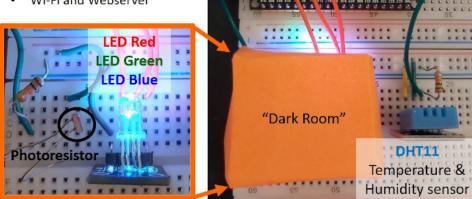
(Xtensa 32-bit LX6 microprocessors)

Core 0:

- Sensor reading & storage
- PI control

Core 1:

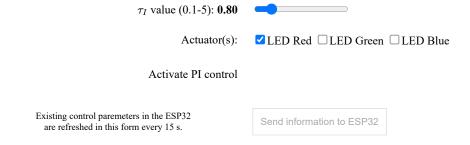
Wi-Fi and Webserver

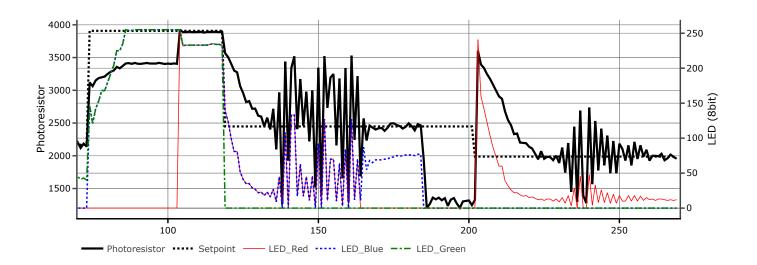


Photoresistor target value P_{SP} (1378-4139): **1988.00**

 K_P value (0.005-0.1): **0.015**







The code files, explanations, and references used in this project are given in my GitHub repository at $https://github.com/RubenMercadePrieto/ESP32_PIControl_DHT11$