



Informe: Optimizacion Convexa Taller No. 2

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1. Introducción

Development of exercises on notation, Gradient and demonstrations.

2. Desarrollo

1. Basic notation. In front of each symbol write its meaning

- R : denotes the set of real numbers.
- R_+ : denotes the set of positive real numbers.
- R_{++} : denotes the set of positive real numbers except zero.
- $R_+^{m \times n}$: denotes the set of matrices of positive real numbers of size $m * n$.
- N_+^k : denotes the set of vectors of positive natural numbers of size k .
- S_+^k : denotes the set of symmetric positive semi-defined matrices.
- $f : R^p \rightarrow R^q$: denotes a function with domain R^p and range in R^q .

2. Calculate the $\nabla f(x)$ respect to x of the following function

- $\|y - Hx\|_2^2$: (Demonstration in annex; 1)
- $\|y - Hx\|_2$: (Demonstration in annex; 1)
- $\|y - Hx\|_1$: (Demonstration in annex; 2)

3. For the special case where A is a symmetric matrix and

$$\alpha = x^T A x$$

where $x \in R^n$ and $A \in R^{n \times n}$. Then, calculate $\frac{\partial \alpha}{\partial x}$. Differs the result if A is not symmetric?

Ans: If A is not symmetric the answer change. (Demonstration in annex;3)

4. Let $A(\alpha)$ be a $m \times n$ matrix whose elements are functions of the scalar parameter α . Then the derivative of the matrix $A(\alpha)$ with respect to the scalar parameter α is the $m \times n$ matrix of element-by-element derivatives:

$$\frac{\partial A(\alpha)}{\partial \alpha} = \begin{bmatrix} \frac{\partial a_{11}}{\partial \alpha} & \frac{\partial a_{12}}{\partial \alpha} & \dots & \frac{\partial a_{1n}}{\partial \alpha} \\ \frac{\partial a_{21}}{\partial \alpha} & \frac{\partial a_{22}}{\partial \alpha} & \dots & \frac{\partial a_{2n}}{\partial \alpha} \\ \vdots & \vdots & & \vdots \\ \frac{\partial a_{m1}}{\partial \alpha} & \frac{\partial a_{m2}}{\partial \alpha} & \dots & \frac{\partial a_{mn}}{\partial \alpha} \end{bmatrix}$$

Then let $A(\alpha)$ be a nonsingular, $m \times m$ matrix whose elements are functions of the scalar parameter α . Then show what:

$$\frac{\partial A(\alpha)^{-1}}{\partial \alpha} = -A(\alpha)^{-1} \frac{\partial A(\alpha)}{\partial \alpha} A(\alpha)^{-1} \quad (\text{Demonstration in annex; 4})$$

3. Anexos

2.1 $\nabla F(x)$

2.1 $\|y - Hx\|_2^2 \quad \frac{\partial F}{\partial x} = \begin{bmatrix} \frac{\partial F}{\partial x_1} & \frac{\partial F}{\partial x_2} \end{bmatrix}$

$\left\| \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} - \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right\|_2 = \left\| \begin{bmatrix} y_1 - (a_{11}x_1 + a_{12}x_2) \\ y_2 - (a_{21}x_1 + a_{22}x_2) \end{bmatrix} \right\|_2 \quad (a)$

$Q^2 = (y_1 - (a_{11}x_1 + a_{12}x_2))^2 + (y_2 - (a_{21}x_1 + a_{22}x_2))^2 \quad (b)$

$\frac{\partial F}{\partial x_1} = -2(a_{11}(y_1 - (a_{11}x_1 + a_{12}x_2)) + a_{21}(y_2 - (a_{21}x_1 + a_{22}x_2))) \quad (c)$

$\frac{\partial F}{\partial x_2} = -2(a_{12}(y_1 - (a_{11}x_1 + a_{12}x_2)) + a_{22}(y_2 - (a_{21}x_1 + a_{22}x_2))) \quad (d)$

$\nabla F(x) = \begin{bmatrix} \frac{\partial F}{\partial x_1} \\ \frac{\partial F}{\partial x_2} \end{bmatrix} = \begin{bmatrix} -2(a_{11}(y_1 - (a_{11}x_1 + a_{12}x_2)) + a_{21}(y_2 - (a_{21}x_1 + a_{22}x_2))) \\ -2(a_{12}(y_1 - (a_{11}x_1 + a_{12}x_2)) + a_{22}(y_2 - (a_{21}x_1 + a_{22}x_2))) \end{bmatrix}$

$= -2 \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} y_1 - (a_{11}x_1 + a_{12}x_2) \\ y_2 - (a_{21}x_1 + a_{22}x_2) \end{bmatrix}$

$\downarrow \quad \quad \downarrow$

$H^T \quad \quad y - Hx$

$= 2H^T(Hx - y)$

2.2 $\|y - Hx\|_2 \rightarrow = c \quad \rightarrow$ usando Q del punto anterior

$\frac{1}{2}e = 1/(n)^{1/2} \quad \rightarrow \frac{\partial F}{\partial x_1} = (1/n)(-1/2)(e)(c) \rightarrow$ usando c

$\frac{\partial F}{\partial x_2} = (1/2)(-1/2)(e)(d) \rightarrow$ usando d

$\nabla F(x) = -e \begin{bmatrix} b \\ c \end{bmatrix} = -e \begin{bmatrix} a_{11}(y_1 - (a_{11}x_1 + a_{12}x_2)) + a_{21}(y_2 - (a_{21}x_1 + a_{22}x_2)) \\ a_{12}(y_1 - (a_{11}x_1 + a_{12}x_2)) + a_{22}(y_2 - (a_{21}x_1 + a_{22}x_2)) \end{bmatrix}$

$= -e \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} y_1 - (a_{11}x_1 + a_{12}x_2) \\ y_2 - (a_{21}x_1 + a_{22}x_2) \end{bmatrix} = -eH^T(y - Hx) = eH^T(Hx - y)$

$= (1/\|y - Hx\|_2) H^T(Hx - y) \quad t_0 = y - Hx$

$= (1/\|t_0\|_2) H^T \cdot t_0$

Figura 1: Demostracion punto 2.1 y 2.2

$$\begin{aligned}
 2.3 \quad \|y - Hx\|_1 &= \left\| \begin{bmatrix} y_1 - (a_{11}x_1 + a_{12}x_2) \\ y_2 - (a_{21}x_1 + a_{22}x_2) \end{bmatrix} \right\|_1 = |y_1 - (a_{11}x_1 + a_{12}x_2)| + |y_2 - (a_{21}x_1 + a_{22}x_2)| \\
 d(|x|)/dx &= x/|x| \\
 \frac{\partial f}{\partial x_1} &= - \left(\frac{a_{11}(y_1 - (a_{11}x_1 + a_{12}x_2))}{|y_1 - (a_{11}x_1 + a_{12}x_2)|} + \frac{a_{21}(y_2 - (a_{21}x_1 + a_{22}x_2))}{|y_2 - (a_{21}x_1 + a_{22}x_2)|} \right) \\
 \frac{\partial f}{\partial x_2} &= - \left(\frac{a_{12}(y_1 - (a_{11}x_1 + a_{12}x_2))}{|y_1 - (a_{11}x_1 + a_{12}x_2)|} + \frac{a_{22}(y_2 - (a_{21}x_1 + a_{22}x_2))}{|y_2 - (a_{21}x_1 + a_{22}x_2)|} \right) \\
 \nabla f(x) &= - \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} y_1 - (a_{11}x_1 + a_{12}x_2) \\ y_2 - (a_{21}x_1 + a_{22}x_2) \end{bmatrix} \begin{bmatrix} 1/|y_1 - (a_{11}x_1 + a_{12}x_2)| \\ 1/|y_2 - (a_{21}x_1 + a_{22}x_2)| \end{bmatrix} \\
 \nabla f(x) &= -H^T \cdot (y - Hx) \cdot (1/\|y - Hx\|_1)
 \end{aligned}$$

Figura 2: Demostracion punto 2.3

③ $A = A^T \quad \alpha = x^T A x \quad x \in \mathbb{R}^n \quad A \in \mathbb{R}^{n \times n} \quad \frac{\partial \alpha}{\partial x} ?$

$$\frac{\partial \alpha}{\partial x} = 2Ax$$

$$\alpha = [x_1 \ x_2] \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\alpha = [x_1 \ x_2] \begin{bmatrix} a_{11}x_1 + a_{12}x_2 \\ a_{21}x_1 + a_{22}x_2 \end{bmatrix} = [a_{11}x_1^2 + a_{12}x_1x_2 + a_{21}x_1x_2 + a_{22}x_2^2]$$

$$\frac{\partial \alpha}{\partial x} = \begin{bmatrix} \frac{\partial \alpha}{\partial x_1} \\ \frac{\partial \alpha}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 2a_{11}x_1 + a_{12}x_2 + a_{21}x_2 \\ a_{12}x_1 + a_{21}x_1 + 2a_{22}x_2 \end{bmatrix} \quad a_{12} = a_{21} \quad \begin{bmatrix} 2a_{11}x_1 + 2a_{12}x_2 \\ 2a_{21}x_1 + 2a_{22}x_2 \end{bmatrix}$$

$$= 2 \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 2 \cdot A \cdot x //$$

* Si A no es simétrica

$$\frac{\partial \alpha}{\partial x} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + a_{21}x_1 + a_{22}x_2 \\ a_{12}x_1 + a_{22}x_2 + a_{21}x_1 + a_{22}x_2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\frac{\partial \alpha}{\partial x} = A \cdot x + A^T \cdot x \quad // \quad \text{Si cambia si A no es simétrica}$$

Figura 3: Demostracion punto 3

Tenemos que $A(x)A(x)^{-1} = I$

$$\frac{\partial [A(x)A(x)^{-1}]}{\partial x} = \frac{\partial I}{\partial x} \quad \frac{\partial I}{\partial x} = 0$$

teniendo en cuenta que $z = f(x)g(x) \rightarrow z' = f'(x)g(x) + f(x)g'(x)$

$$\frac{\partial A(x)}{\partial x} \cdot A(x)^{-1} + A(x) \frac{\partial A(x)^{-1}}{\partial x} = 0$$

$$A(x) \frac{\partial A(x)^{-1}}{\partial x} = - \frac{\partial A(x)}{\partial x} A(x)^{-1}$$

$$\frac{\partial A(x)^{-1}}{\partial x} = - A(x)^{-1} \cdot \frac{\partial A(x)}{\partial x} \cdot A(x)^{-1}$$

Figura 4: Demostracion punto 4