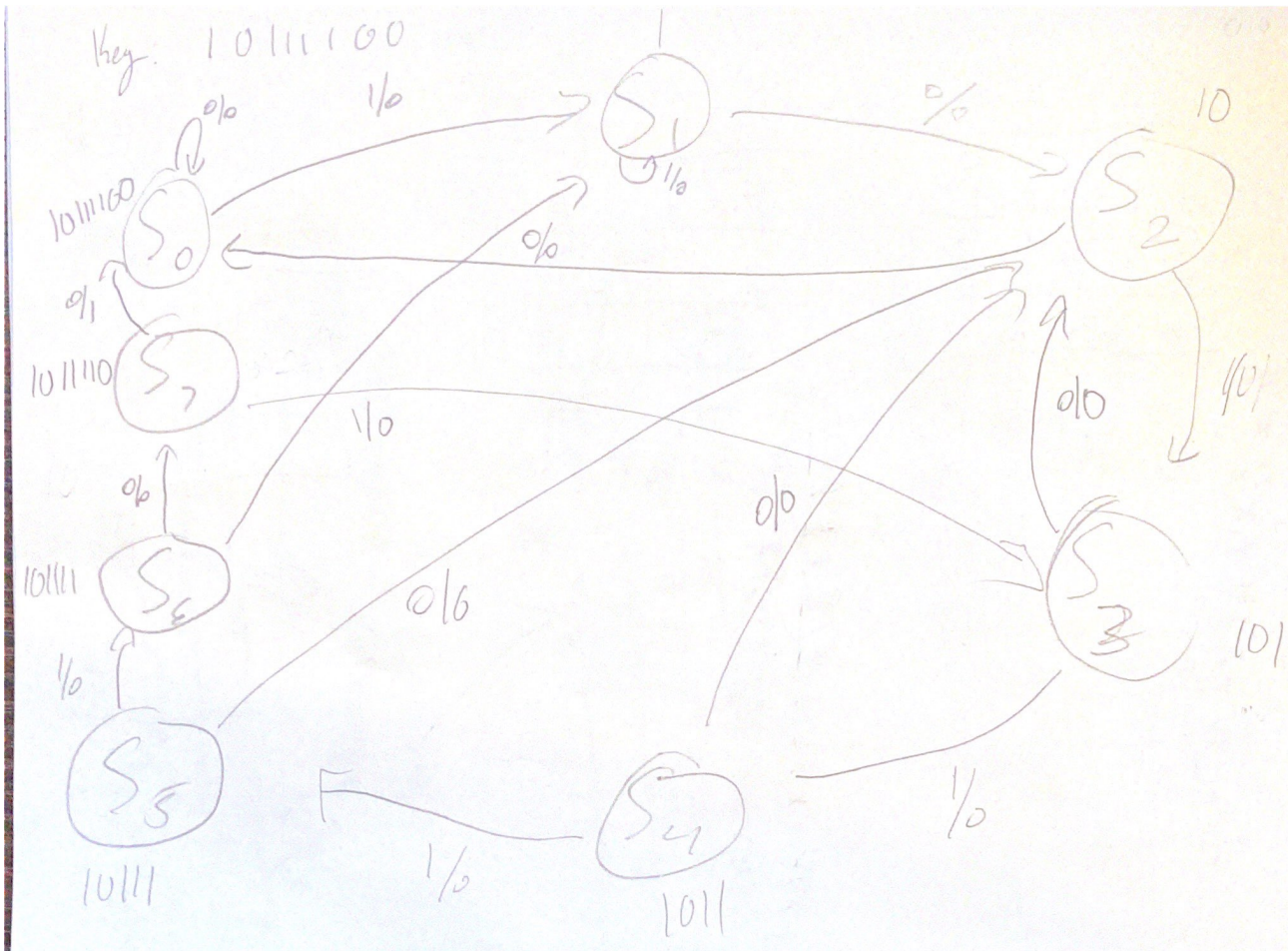


| Present State | | | Input X | Next State | | | Output U |
|---------------|---|---|------------|----------------|----------------|----------------|-------------|
| C | B | A | | D _C | D _B | D _A | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 0 |
| 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 0 |
| 1 | 0 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 | 0 | 0 | 0 | 1 |
| 1 | 1 | 1 | 0 | 0 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 0 | 1 | 1 | 0 |



D_A

Rubin Rubalcaba

| AB \ CX | 00 | 01 | 11 | 10 |
|---------|----|----|----|----|
| 00 | 0 | 1 | 3 | 2 |
| 01 | 4 | 5 | 7 | 6 |
| 11 | 12 | 13 | 15 | 14 |
| 10 | 8 | 9 | 11 | 10 |

$$D_A = ABC\bar{x} + \bar{A}BCx + ABx$$

D_B

| A B \ CX | 00 | 01 | 11 | 10 |
|----------|----|----|----|----|
| 00 | 0 | 1 | 3 | 2 |
| 01 | 4 | 5 | 7 | 6 |
| 11 | 12 | 13 | 15 | 14 |
| 10 | 8 | 9 | 11 | 10 |

$$D_B = A\bar{C}\bar{x} + \bar{A}C\bar{x} + \bar{A}B\bar{C}x + ACx + \bar{A}B\bar{C}$$

$$\bar{A}C\bar{x} + \bar{B}C\bar{x} + A\bar{C}\bar{x} + ACx + \bar{A}B\bar{C}x$$

D_C

| AB \ CX | 00 | 01 | 11 | 10 |
|---------|----|----|----|----|
| 00 | 0 | 1 | 3 | 2 |
| 01 | 4 | 5 | 7 | 6 |
| 11 | 12 | 13 | 15 | 14 |
| 10 | 8 | 9 | 11 | 10 |

$$D_C = \bar{C}x + \bar{A}Bx + AB\bar{C} + ABx$$

$$V = ABC\bar{x}$$