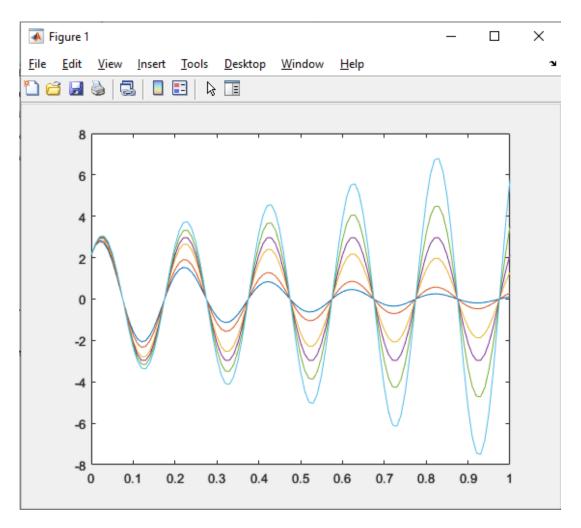
```
Task A

A = 3;
phi = -1/4*pi;
w=2*pi*5;
f=5;
lam = [-3 -2 -0.5 0 0.5 1];
t=(0:0.01:1)';
for ii= 1:length(lam)
    y(:,ii)=A.*exp(lam(ii).*t).*cos(w.*t+phi)
end

plot(t,y)
```



```
Task B
```

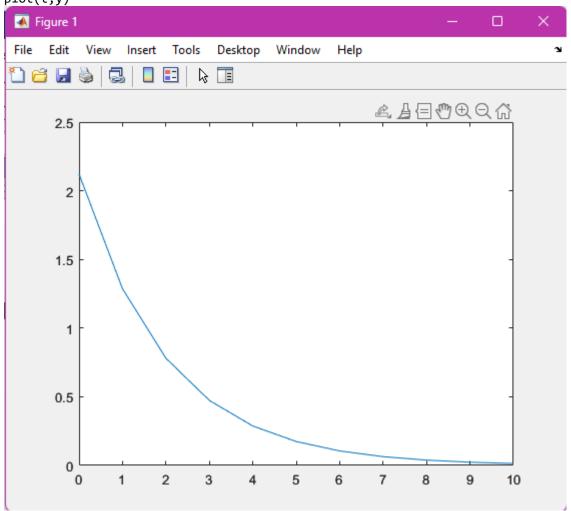
$$\Lambda = -0.5$$

$\Lambda = 1/RC \rightarrow -0.5=1/T \Rightarrow T=2$ (time constant)

RC=time constant

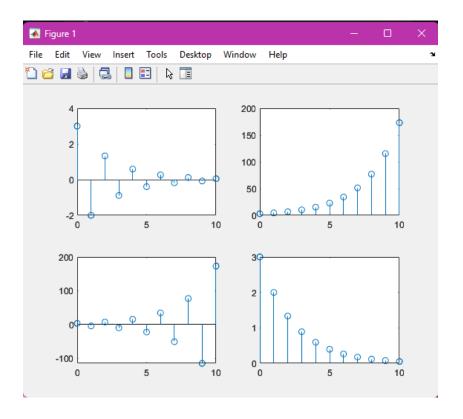
$Y(t) = A*e^{\Lambda}t$

```
Task C
A = 3;
phi = -1/4*pi;
w=0;
f=5;
lam = -0.5;
t= (0:10);
y= A.*exp(lam.*t).*cos(w.*t+phi);
plot(t,y)
```

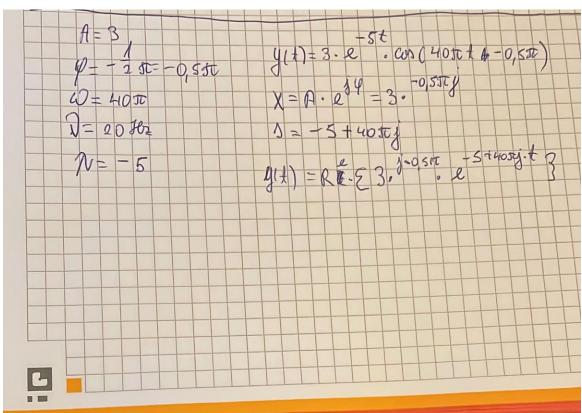


```
Task D
A = 3;
phi = -1/4*pi;
w=2*pi*5;
f=5;
lam = -0.5
tau = 2
t=(0:10)
y= A.*exp(lam.*t).*cos(w.*t+phi)
y2= A.*exp(lam.*tau).*cos(w.*tau+phi)
plot(t,y,tau,y2,'o')
                                                               Figure 1
                                                                     X
<u>File Edit View Insert Tools Desktop Window</u>
                                           <u>H</u>elp
🖺 🍯 🖬 🦫 🗔
                 B I
      2.5
       2
      1.5
       1
      0.5
              1
                    2
                                          6
                                                7
                                                      8
        0
                          3
                                     5
                                                            9
                                                                 10
```

```
Task E
0.78/2.12 = 0.37
1-0.37 = 0.63 \rightarrow \text{to get } \% \rightarrow 0.63*100 = 63\%
Y1 coordinate = 2.12
Y2 Coordinate = 0.78
X 0 X 2
Y 2.12132 Y 0.78039
Tasks F,G,H,I
A=3;
phi=0;
n=0:10;
subplot(2,2,1);%f
OMEGA=pi;
a=2/3;
y=A*a.^n.*cos(OMEGA*n+phi);
stem(n,y)
subplot(2,2,2);%g
OMEGA=0;
a=3/2;
y=A*a.^n.*cos(OMEGA*n+phi);
stem(n,y)
subplot(2,2,3);%h
OMEGA=pi;
y=A*a.^n.*cos(OMEGA*n+phi);
stem(n,y)
subplot(2,2,4);%i
a=2/3;
OMEGA=0;
y=A*a.^n.*cos(OMEGA*n+phi);
stem(n,y)
```

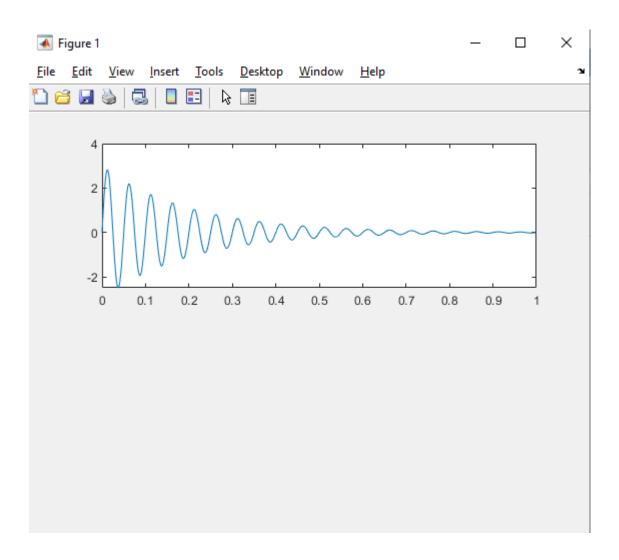


Task J



```
A = 3;
phi = -0.5*pi;
w=2*pi*f;
f=20;
lam = -5;
t=0:0.001:1;

Y=3.*exp(-1j*0.5*pi);
s= -5+40*pi*1j;
subplot(2,1,1)
plot(t,real(Y.*exp(s.*t)))
```



```
Task L
  A = 3;
  phi = -0.5*pi;
  w=2*pi*f;
  f=20;
  lam = -5;
  t=0:0.001:1;
  Y=3.*exp(-1j*0.5*pi);
  s= -5+40*pi*1j;
  y=A.*exp(lam.*t).*cos(w.*t+phi);
  subplot(2,1,1)
  plot(t,real(Y.*exp(s.*t)))
  subplot(2,1,2)
  plot(t,y)
Figure 1
                                                                Х
<u>File Edit View Insert Tools Desktop Window</u>
                                           <u>H</u>elp
🖺 🔓 📙 🦫
            4
       2
       0
       -2
                         0.3
                                           0.6
                                                 0.7
                                                      0.8
                                                            0.9
        0
             0.1
                   0.2
                               0.4
                                     0.5
       4
       2
       0
       -2
        0
             0.1
                   0.2
                         0.3
                               0.4
                                     0.5
                                           0.6
                                                0.7
                                                      0.8
                                                            0.9
```