# §1 Lecture 02-24

**Definition 1.1** (Bilinear Forms). A bilinear form  $B: V \times V \to F$  is said to be left non degenerate if B(v, w) = 0,  $\forall w \in V \Rightarrow v = 0$ .

Note 1.2.

$$B(v, w) = \langle v, w \rangle$$

Key remark: A non-degenerate bilinear form induces a linear injection

$$l: V \to V^*$$
$$v \mapsto l_v$$
$$l_v(w) = \langle v, w \rangle$$

Now to show the following:

- 1.  $l_v$  is indeed a linear transformation (follows from the linearity of  $\langle , \rangle$  in the second variable)
- 2. The assignment  $v \mapsto lv$  is linear (follows from the linearity of  $\langle , \rangle$  in the first variable.

#### Lemma 1.3

If dim  $V < \infty$ , then l is an isomorphism between V and  $V^*$ .

*Proof.*  $\langle,\rangle$  is left-nondegenerate  $\Rightarrow l:V\hookrightarrow V^*$  is injective.

The rank-nullity theorem implies that since  $\dim V = \dim V^*$ , l is also surjective.  $\square$ 

Is it possible to classify all possible bilinear forms on V, up to isomorphism?

If V is finite dimensional, we can choose a basis  $\sum = (e_1, \dots, e_n)$  for V such that

$$v = \sum_{i=1}^{n} x_i e_i$$

$$w = \sum_{j=1}^{n} y_j e_j$$

$$\langle v, w \rangle = \langle \sum_{j=1}^{n} x_i e_i, \sum_{j=1}^{n} y_j e_j \rangle$$

$$= \sum_{i,j=1}^{n} x_i y_j \langle e_i, e_j \rangle$$

**Definition 1.4.** The pairing matrix associated to  $B(v, w) = \langle v, w \rangle$ , and the basis  $\sum$ .

$$M_{B,\sum} = (\langle e_i, e_j \rangle)_{i,j=1,\dots,n}$$
$$\langle v, w \rangle = (x_1, \dots, x_n) M_{B,\sum} \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

The most general bilinear form on  $F^n$  is given by a matrix M, by

$$\langle (x_1, \dots, x_n), (y_1, \dots, y_n) \rangle = (x_1, \dots, x_n) M \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

 $\langle,\rangle$  is left-nondegenerate  $\Leftrightarrow M_{B,\sum}$  is invertible. Proof. Left as exercise.

## §1.1 Change of Basis

Let  $\sum = (e_1, \ldots, e_n)$  and  $\sum' = (e'_1, \ldots, e'_n)$  be two bases for V. How are  $M_{B,\sum}$  and  $M_{B,\Sigma'}$  related?

$$\begin{pmatrix} e'_1 \\ \vdots \\ v'_n \end{pmatrix} = P_i \begin{pmatrix} e_1 \\ \vdots \\ e_n \end{pmatrix}$$

$$p \in M_n(F), \text{ invertible}$$

$$m_{B,\Sigma} = \langle \begin{pmatrix} e_1 \\ \vdots \\ e_n \end{pmatrix}, (e_1, \dots, e_n) \rangle$$

$$M_{B,\Sigma'} = \langle \begin{pmatrix} e'_1 \\ \vdots \\ e'_n \end{pmatrix}, (e'_1, \dots, e'_n) \rangle$$

$$(e'_1, \dots, e'_n) = (e_1, \dots, e_n) P^t$$

$$P = (a_{ij}) \quad p^t = (a_{ji})$$

$$M_{B,\Sigma'} =$$

$$M_{B,\Sigma'} = PM_{B,\Sigma}P^t$$

### Corollary 1.6

Two matrices  $M_1$  and  $M_2$  represent the same bilinear form  $\Leftrightarrow$  there exists an invertible linear transformation P such that  $M_1 = PM_2P^t$ 

Isomorphism classes of linear transformations on  $F^n = M_n(F)/\operatorname{GL}_n(F)$  where the group  $\operatorname{GL}_n(F)$  acts on the set  $M_n(F)$  by conjugation  $M^g = gMg^{-1}$ .

Isomorphism classes of bilinear forms we likewise identified with

$$M_n(F)/\operatorname{GL}_n(F)$$

, but where the action of n(F) on  $M_n(F)$  is very different

$$g * M = gMg^t$$

## Example 1.7

- 1. Orbit of  $I_n$  for the conjugation action =  $\{I_n\}$ .
- 2. Orbit of  $I_n$  for the second action is the set of  $\{pp^t, p \in GL_n(F)\}$

**Exercise 1.8.** There are no orbits of size 1 for the action  $M \mapsto gMg^t$ .

**Definition 1.9.** A vector space equipped with a non-degenerate bilinear form B is called a quadratic space (V, B).

An isomorphism  $T:(V_1,B_2)\to (V_2,B_2)$  is the natural notion. A linear isomorphism  $T:V_1\to V_2, \forall v,w\in V_1,$ 

$$\langle v, w \rangle_{B_1} = \langle Tv, Tw \rangle_{B_2}$$

The adjoint of a linear transformation  $T:V\to V$  when V is a quadratic space, endowed with a nondegerenate form.

$$T: V \to V$$
$$T^*: V^* \to V^*$$
$$T^*(l) = l \circ T$$

The adjoint of T on the quadratic space V is the linear transformation defined by

$$T^*(lv) = l_{T^*(v)}$$

$$T^*(lv)(w) = l'_{T^*v}(w)$$

$$lv \circ T(w) = \langle T^*v, w \rangle$$

$$\langle v, T(w) \rangle$$

$$\langle v, Tw \rangle = \langle T^*v, w \rangle$$