§1 05-13

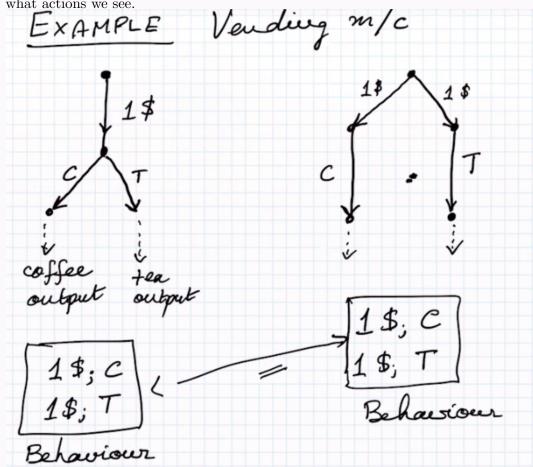
§1.1 Bisimulation

Transition systems as models of software or hardware or embedded systems. Nondeterminism, need not be finite state.

When are two systems observably the same?

Example 1.1 (Vending Machine)

Difference from DFA, some actions get rejected. The rejection is different from the rejection in an NFA because really that encodes a state where you can't escape, while this is more true rejection. No start states or accept states. Just interested in what actions we see.



Internal vs. external choice is what makes these two machines different. This shows how sequences are inadequate description of the behavior. So how can we actually compare to LTS? With bisimulation.

Definition 1.2 (LTS (Labeled Transition System)).

$$S \to \text{ set of states, perhaps infinite}$$
 $A \to \text{ set of actions, finite}$ $\to \subseteq S \times A \times S$ $(s, a, s') \in \to, \quad s \xrightarrow{a} s'$

From state s, if action a is performed, you can end up in s'.

Definition 1.3 (Bisimulation (semi-formed)). When comparing two systems, we form a binary relation between the states of a simple. This isn't a big deal because we could merge the two systems.

We say $s, t \in S$ are <u>bisimilar</u> (written $s \sim t$) if

$$\forall a \in A \ s \xrightarrow{a} s' \Rightarrow \exists t's.t.t \xrightarrow{a} t' \text{ and } s' \sim t'$$

 $\forall a \in At \xrightarrow{a} t' \Rightarrow \exists s's.t.s \xrightarrow{a} s' \text{ and } s' \sim t'$

If s can do something, t can do the same thing. And they may end up in different states, but those states themselves will be bisimilar. This should make you uneasy because it's an inductive definition with no base case.

There are 4 ways of clarifying this definition.

1. We define an $\mathbb N$ indexed family of equivalence relations (infinitely many of them) as follows: $s \sim_0 t$ always. Then

$$s \sim_{n+1} if \ \forall a \in A \ s \xrightarrow{a} s' \Rightarrow \exists t's.t.t \xrightarrow{a} t' \text{ and } s' \sim_n t'$$
 vice versa

Now we say that $\sim = \cap_n \sim_n$

In the vending machine example $s_0 \sim_1 t_0$ but $s_0 \nsim_2 t_0$ and hence they are certainly not bisimilar systems.

2. R the family of equivalence relations $\subseteq S \times S$ order by inclusion. Smallest is everything is related to itself. Largest is everything related to everything. This forms a complete lattice. $F: R \to R$.

$$sF(R)t$$
 if $\forall as \xrightarrow{a} s' \Rightarrow \exists t's.t.t \xrightarrow{a} t'$ and $s'Rt'$ vice versa

F is easily seen to be monotone i.e. if $R_1 \subseteq R_2$ then $F(R_1) \subseteq F(R_2)$. It follows that there is a unique greatest fixed point. i.e. a special $\sim \in R$ such that $F(\sim) = \sim$ and if R is any relation such that F(R) = R then $R \subseteq \sim$. This is called fixed point bisimilarity.

3. We saw R is a dynamic relation or a bisimulation relation if whenever sRt then .

$$\forall a \forall s' \ s \xrightarrow{a} s' \Rightarrow \exists t' s.t.t \xrightarrow{a} t' \text{ and } s'Rt'$$
vice versa

Note that this is not circular. R is given somehow and it may or may not have this property. We say that $s \sim t$ if $\exists R$, a bisimulation relation with sRt.

Fact 1.4. If R_i is any family of bisimulation relations, then $\cup_i R_i$ is also a bisimulation as is $\cap_i R_i$. $\sim = \cup_{R_a} R$.

Easy to see that (2) and (3) are equivalent. (1) is <u>not</u> equivalent without a further assumption.

§1.2 Lattice Theory and Fixed Points

Remember that a poset is a partially ordered set. i.e. a set equipped with a partial order.

Given (S, \leq) , we say that u is the least upper bound of $X \subseteq S$ if

$$\forall x \in X, \ x \leq u \text{ and } \forall y \in S, if \ \forall x \in X, x \leq y \Rightarrow u \leq y$$

If $X \subseteq S$ we say v is a lower bound of x if $\forall x \in X, v \leq x$. If v in addition is greater than any other lower bound, we call it the Infimum.

Definition 1.5. In a lattice there is a supremum and infimum for <u>every pair</u> of elements. They are not necessarily unique. By induction it follows that every finite set of elements has a supremum and infimum. Infinite numbers may not.

Definition 1.6 (Complete Lattice). A lattice is complete if every subset has a least upper bound.

Fact 1.7. It follows that every set has a greatest lower bound.

The least upper bound of \emptyset is a least element of the whole set.

Proof. Let $X \subseteq L$, where L is a complete lattice. Let $V = \{v \in L \mid \forall x \in X \ v \leq x\}$ be the set of lower bounds of X.

Let $g = \sup(V)$. Claim g is $\inf(X)$.

Note 1.8. $\forall x \in X, \ \forall v \in V, \ v \leq x$. i.e. $\forall x \in X, \ x$ is an upper bound for V so since g is the lesat upper bound for V we have that $\forall x \in X, \ g \leq x$, i.e. $g \in V$.

Since g is an upper bound for V it is greatre than any element of V so it is the glb of X.

Theorem 1.9

If $f: L \to L$ is monotone and L is a complete lattice, then the fixed points of f, i.e. x s.t. f(x) = x forms a complete lattice in its own right. In particular there is a least fixed point and a greatest fixed point. There is a least fixed point and a greatest fixed point.

Proof. Find the upper bound of set of inflationary points and show that it is fixed. \Box

Note to be a bisimulation relation means $R \subseteq F(R)$. Least upper bound of $\{R \mid R \text{ is a bisimulation}\} = \bigcup_R R = gfp(F)$ (greatest fixed point). (2) and (3) are really the same. (1) is not the same unless the transition system has a special property $\forall s, a\{t \mid s \rightarrow_a t\}$ is finite. This is called image-finiteness.

If TS is image finite then (1) is equivalent to (2) and (3). The definition of bisimulation is an example of a co-inductive definition.

§1.3 Logical Characterization of Bisimulation

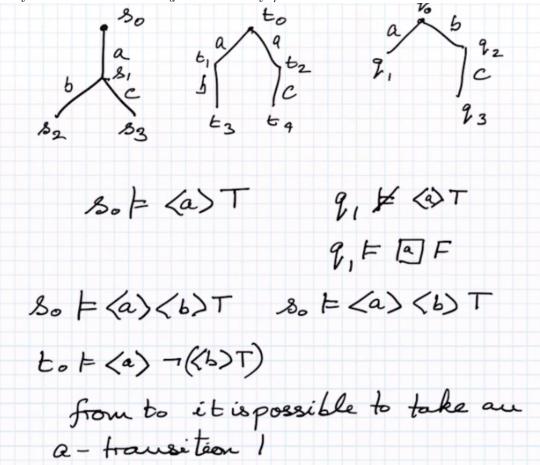
Given an LTS, we define a modal logic called Hennessy-Milner Logic.

$$\varphi ::== T \mid \neg \varphi \mid \varphi_1 \wedge \varphi_2 \mid \langle a \rangle \varphi$$

 $s \models \langle a \rangle \varphi \rangle$ if $\exists t \ s.t. \ s \rightarrow_a t$ and $t \models \varphi$. At least one state satisfies.

$$[a]\varphi = \neg \langle a \rangle \neg \varphi$$

Every state t such that $s \to_a t$ must satisfy φ .



Theorem 1.10

 $s \sim t$ if and only if $\forall \varphi s \models \varphi \Leftrightarrow t \models \varphi$ (image finiteness assumed). Don't be afraid of infinite conjunctions.

Proof. We define a new equivalence relation \approx . $s \approx t \Leftrightarrow \forall \varphi \ s \models \varphi \Leftrightarrow t \models \varphi$.

Idea is to prove that \approx is a bisim relation. Suppose $s \approx t$ and suppose $s \to_a s'$. We want to show that $\exists t' \ s.t.t \to_a t'$ and $s' \approx t'$.

Assume that s and t are not bisimilar. Then $\forall t'$ s.t. $t \to_a t'$, $s' \not\approx t'$. There are only finitely many such $t': t'_1, \ldots, t'_n$.

§1.4 Probabilistic Bisimulation and Logical Characterizaiton

Probabilistic transition systems. $s \models \langle a \rangle_q \varphi$. $a \in Act$, $q \in Q \cap [0,1]$ The probability of winding up in a state sastisfying φ after doing an a action in state $s \geq q$. Larsen and Skou proved logical characterization using

$$\langle a \rangle_q \varphi$$
 and $\neg \varphi$ and $\varphi_1 \wedge \varphi_2$

They also assumed a very strong finite branching property. And probabilities must be integer multiples of some fixed rational number.

AMAZINGLY proved logical characterization with no finite branching assumption and no negation in the logic. We alo got logical characterization of simulation.