```
!nvcc --version
```

```
nvcc: NVIDIA (R) Cuda compiler driver
Copyright (c) 2005-2024 NVIDIA Corporation
Built on Thu_Jun__6_02:18:23_PDT_2024
Cuda compilation tools, release 12.5, V12.5.82
Build cuda_12.5.r12.5/compiler.34385749_0
```

!nvidia-smi

Tue May 6 13:43:53 2025

| No running processes found

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NVIDIA-SMI 550.54.15	Driver	Version: 550.54.15	CUDA Version: 12.4
GPU Name Fan Temp Perf	Persistence-M Pwr:Usage/Cap	'	Volatile Uncorr. ECC GPU-Util Compute M. MIG M.
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```
%%writefile vector.cu
#include <bits/stdc++.h>
#include <cuda_runtime.h>
using namespace std;
using namespace std::chrono;
__global__ void add(int* A, int* B, int* C, int size){
  int tid = blockIdx.x * blockDim.x + threadIdx.x;
  if(tid < size){</pre>
    C[tid] = A[tid] + B[tid];
}
void initialize(int* vector, int size){
  for(int i=0; i<size; i++){
    cout << "Enter element " << i+1 << " of the vector: ";
    cin >> vector[i];
  cout << endl;</pre>
void print(int* vector, int size){
  for(int i=0; i<size; i++){</pre>
   cout << vector[i] << " ";
  cout << endl;</pre>
void sequentialAddition(int* A, int* B, int* C, int size){
  for(int i=0; i<size; i++){</pre>
    C[i] = A[i] + B[i];
  }
int main(){
  int N;
  cout << "Enter the size of vectors: ";</pre>
  cin >> N;
  int *A, *B, *C;
  int vectorSize = N;
  size_t vectorBytes = vectorSize * sizeof(int);
  A = new int[vectorSize];
```

B = new int[vectorSize];
C = new int[vectorSize];
initialize(A, vectorSize);

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initialize(B, vectorSize);
  cout << "Vector A: "; print(A, vectorSize);</pre>
  cout << "Vector B: "; print(B, vectorSize);</pre>
  int *X, *Y, *Z;
  cudaMalloc(&X, vectorBytes);
  cudaMalloc(&Y, vectorBytes);
  cudaMalloc(&Z, vectorBytes);
  cudaMemcpy(X, A, vectorBytes, cudaMemcpyHostToDevice);
  \verb"cudaMemcpy" (Y, B, vectorBytes, cudaMemcpyHostToDevice)";
  int threadsPerBlock = 256;
  int blocksPerGrid = (N + threadsPerBlock - 1) / threadsPerBlock;
  // Sequential Addition
  auto start = high_resolution_clock::now();
  sequentialAddition(A, B, C, N);
  auto stop = high_resolution_clock::now();
  auto seq_duration = duration_cast<microseconds>(stop-start);
  cout << "Sequential Addition: "; print(C, N);</pre>
  // Parallel Addition
  start = high_resolution_clock::now();
  add<<<blocksPerGrid, threadsPerBlock>>>(X,Y,Z,N);
  cudaDeviceSynchronize();
  cudaMemcpy(C, Z, vectorBytes, cudaMemcpyDeviceToHost);
  stop = high resolution clock::now();
  auto par_duration = duration_cast<microseconds>(stop-start);
  cout << "Parallel Addition: "; print(C, N);</pre>
  cout << "Sequential Addition Time: "<< seq_duration.count() <<" microseconds."<<endl;</pre>
  cout << "Parallel Addition Time: "<< par_duration.count() <<" microseconds."<<endl;</pre>
  delete []A;
  delete []B;
  delete []C;
  cudaFree(X);
  cudaFree(Y);
  cudaFree(Z);
  return 0:
→ Writing vector.cu
!nvcc -arch=sm_75 vector.cu -o vec
!./vec
\rightarrow Enter the size of vectors: 3
     Enter element 1 of the vector: 1
     Enter element 2 of the vector: 2
     Enter element 3 of the vector: 3
     Enter element 1 of the vector: 4
     Enter element 2 of the vector: 5
     Enter element 3 of the vector: 6
     Vector A: 1 2 3
     Vector B: 4 5 6
     Sequential Addition: 5 7 9
     Parallel Addition: 5 7 9
     Sequential Addition Time: 0 microseconds.
     Parallel Addition Time: 165 microseconds.
%%writefile matrix.cu
#include <bits/stdc++.h>
#include <cuda_runtime.h>
using namespace std;
using namespace std::chrono;
 _global__ void multiply(int *A, int *B, int *C, int M, int N, int K){
  int row = blockIdx.y * blockDim.y + threadIdx.y;
```

```
int col = blockIdx.x * blockDim.x + threadIdx.x;
  if(row<M && col<K){</pre>
    int sum = 0;
    for(int i=0; i<N; i++){
      sum += A[row * N + i] * B[K * i + col];
    C[row * K + col] = sum;
  }
void initialize(int *matrix, int rows, int cols){
  for(int i=0; i< rows*cols; i++){</pre>
    cout << "Enter element " << i+1 << " : ";</pre>
    cin >> matrix[i];
}
void print(int *matrix, int rows, int cols){
  for(int row=0: row<rows: row++){</pre>
    for(int col=0; col<cols; col++){</pre>
      cout << matrix[row * cols + col] << " ";</pre>
    cout << endl;</pre>
  cout << endl;</pre>
}
void sequentialMultiply(int *A, int *B, int *C, int M, int N, int K){
  for(int i=0; i<M; i++){
    for(int j=0; j<K; j++){</pre>
      int sum = 0;
      for(int k=0; k<N; k++){
        sum += A[i*N+k] * B[k*K+j];
      C[i*K+j] = sum;
    }
  }
}
int main(){
  int M,N,K;
  cout << "Enter number of rows and columns of first matrix: ";</pre>
  cin >> M >> N:
  cout << "Enter number of columns of second matrix: ";</pre>
  cin >> K;
  int *A, *B, *C;
  A = new int[M*N];
  B = new int[N*K];
  C = new int[M*K];
  initialize(A, M, N);
  initialize(B, N, K);
  cout<<"Matrix A:"<<endl; print(A, M, N);</pre>
  cout<<"Matrix B:"<<endl; print(B, N, K);</pre>
  int *X, *Y, *Z;
  cudaMalloc(&X, M*N*sizeof(int));
  cudaMalloc(&Y, N*K*sizeof(int));
  cudaMalloc(&Z, M*K*sizeof(int));
  \verb"cudaMemcpy"(X,A,M*N*size of (int), \verb"cudaMemcpyHostToDevice")";
  cudaMemcpy(Y,B,N*K*sizeof(int),cudaMemcpyHostToDevice);
  int THREADS = 16;
  int BLOCKS = (M + THREADS - 1) / THREADS;
  dim3 threads(THREADS, THREADS);
  dim3 blocks(BLOCKS, BLOCKS);
  // Sequential multiplication
    auto start = high_resolution_clock::now();
    sequentialMultiply(A, B, C, M, N, K);
    auto stop = high resolution clock::now();
    auto seq_duration = duration_cast<microseconds>(stop - start);
    cout << "Sequential Multiplication of matrix A and B: \n";</pre>
    print(C, M, K);
     // Parallel multiplication
```

```
start = high_resolution_clock::now();
    multiply<<<blocks, threads>>>(X, Y, Z, M, N, K);
    cudaMemcpy(C, Z, M * K * sizeof(int), cudaMemcpyDeviceToHost);
    stop = high resolution clock::now();
    auto par_duration = duration_cast<microseconds>(stop - start);
    cout << "Parallel Multiplication of matrix A and B: \n";</pre>
    print(C, M, K);
    cout << "Sequential Multiplication Time: " << seq_duration.count() << " microseconds" << endl;
cout << "Parallel Multiplication Time: " << par_duration.count() << " microseconds" << endl;</pre>
    delete[] A;
    delete[] B;
    delete[] C;
    cudaFree(X);
    cudaFree(Y);
    cudaFree(Z);
    return 0;
}

→ Overwriting matrix.cu

!nvcc -arch=sm_75 matrix.cu -o mat
!./mat
→ Enter number of rows and columns of first matrix: 2
     Enter number of columns of second matrix: 1
     Enter element 1 : 2
     Enter element 2 : 3
     Enter element 3 : 4
     Enter element 4 : 5
     Enter element 5 : 6
     Enter element 6 : 7
     Enter element 1 : 1
     Enter element 2 : 2
     Enter element 3 : 3
     Matrix A:
     2 3 4
     5 6 7
     Matrix B:
     1
     2
     3
     Sequential Multiplication of matrix A and B:
     Parallel Multiplication of matrix A and B:
     20
     38
     Sequential Multiplication Time: 0 microseconds
     Parallel Multiplication Time: 130 microseconds
```