

Chapter 7. Cluster Analysis

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- 1. What is Cluster Analysis?**
- 2. Categories & Basic Concepts of Clustering**
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CHAMELEON



❑ Main idea

- ❑ Two clusters can be merged only if the **interconnectivity** and **closeness (proximity)** between two clusters are high
 - **Relative** to the internal interconnectivity of the clusters and internal closeness of items within the clusters

1. Draw a *k*-nearest neighbor graph (**KNN graph**) first

- ❑ **Node**: object, **edge**: *k*-nearest neighbor's link, **weight**: similarity

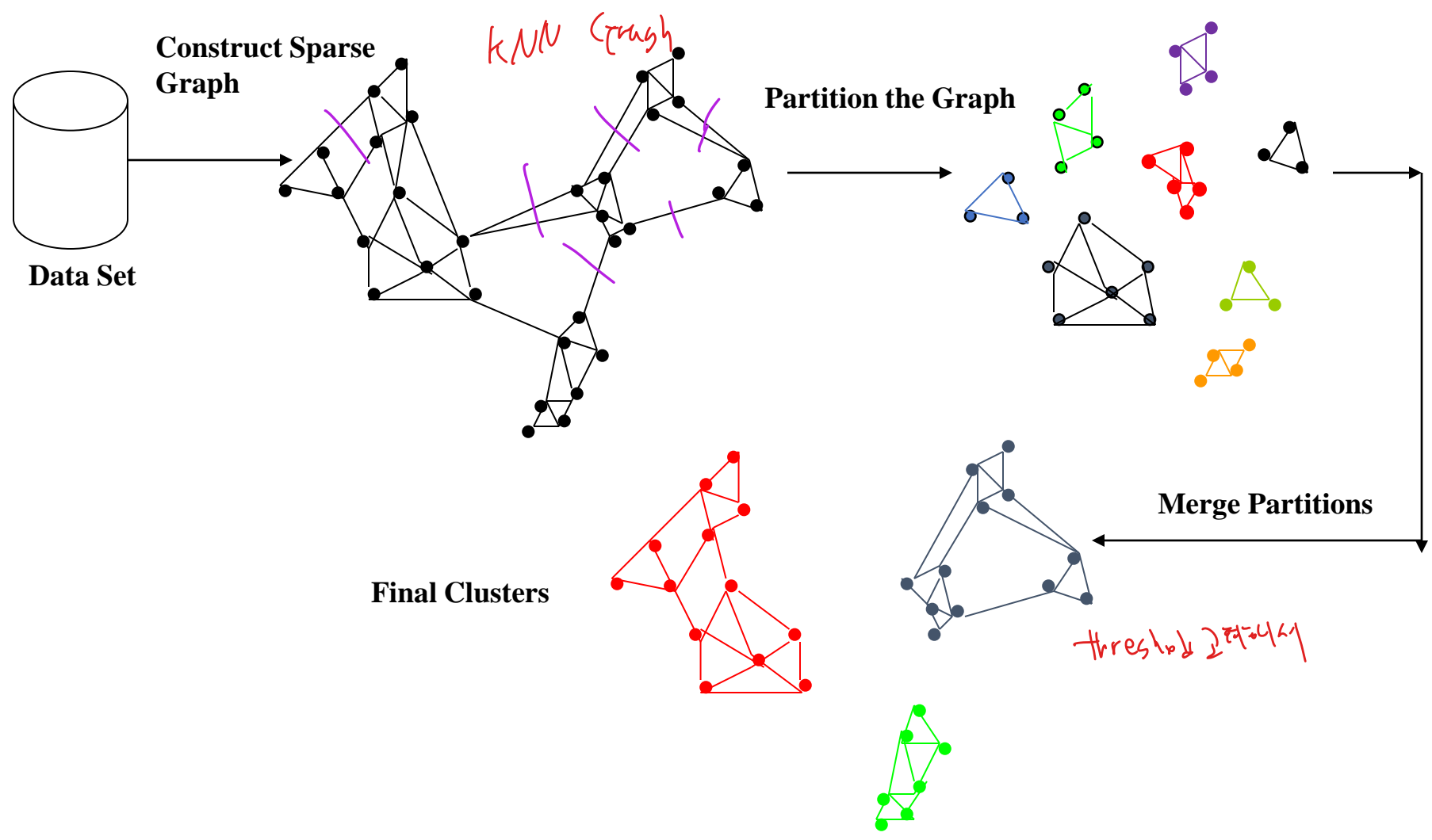
2. Partition: Use a graph partitioning algorithm

- ❑ Divide the KNN graph into a large number of relatively small sub-clusters

3. Merge: Use an agglomerative hierarchical clustering algorithm

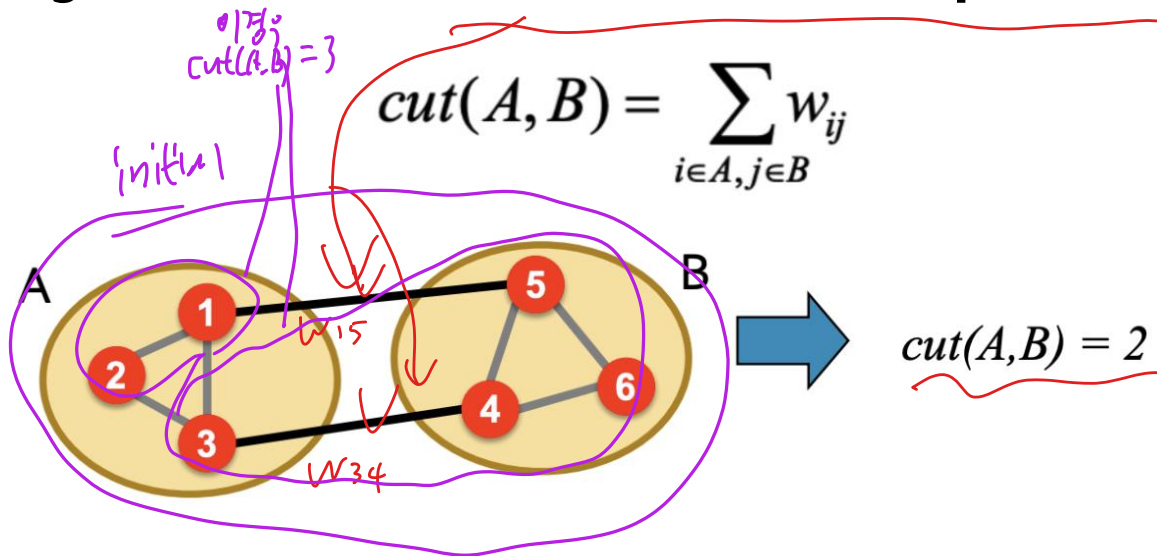
- ❑ Iteratively find clusters by repeatedly combining these sub-clusters

Overall Framework of CHAMELEON



CHAMELEON: Partitioning

- Partition the KNN graph such that the **edge cut** is minimized.
- The edge-cut of a partition is **the sum of the weights** of edges whose **vertices lie in different partitions**.



- hMeTiS library (**METIS**) is used
 - Tries to split a graph into two subgraphs of nearly equal sizes

not only edge cut is minimized
but also balance number of data points inside partition



CHAMELEON: Merging

❑ Merging the partitions

- ❑ This step computes the cluster similarity based on the **relative inter-connectivity** and **relative closeness** of the clusters.

❑ **Relative inter-connectivity**

Criteria \leftarrow $|EC_{\{C_i, C_j\}}|$ \leftarrow get 0 & edges

$$RI(C_i, C_j) = \frac{|EC_{\{C_i, C_j\}}|}{\frac{1}{2}(|EC_{C_i}| + |EC_{C_j}|)},$$

Standard \leftarrow $\frac{1}{2}(|EC_{C_i}| + |EC_{C_j}|)$ \leftarrow 평균의 비슷해야 merge

- ❑ $EC_{\{C_i, C_j\}}$ = edges that connect C_i and C_j .
- ❑ EC_{C_i} = edges that partition the cluster into roughly equal parts.

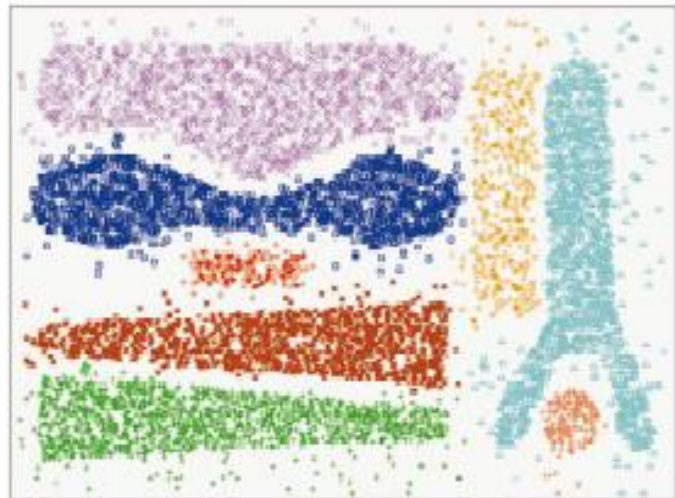
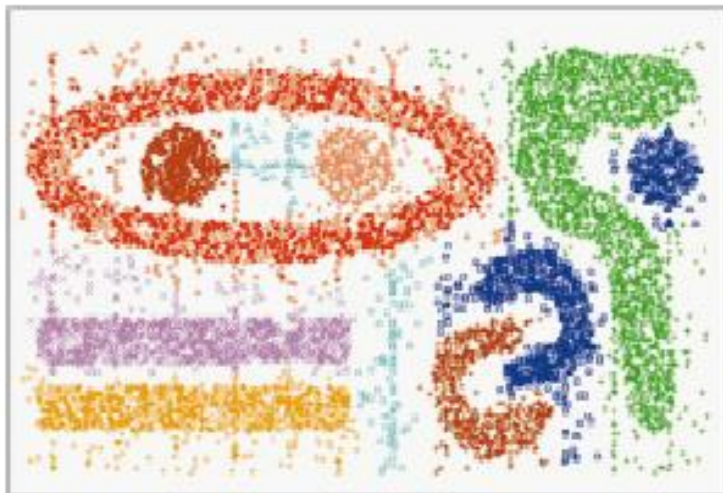
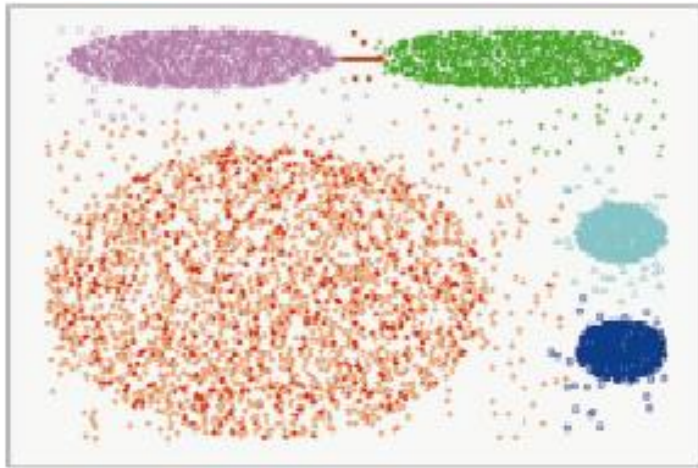
Relative closeness

크기 다 같아

$= 0.65$

- where alpha controls the importance of RC

CHAMELEON (Clustering Complex Objects)



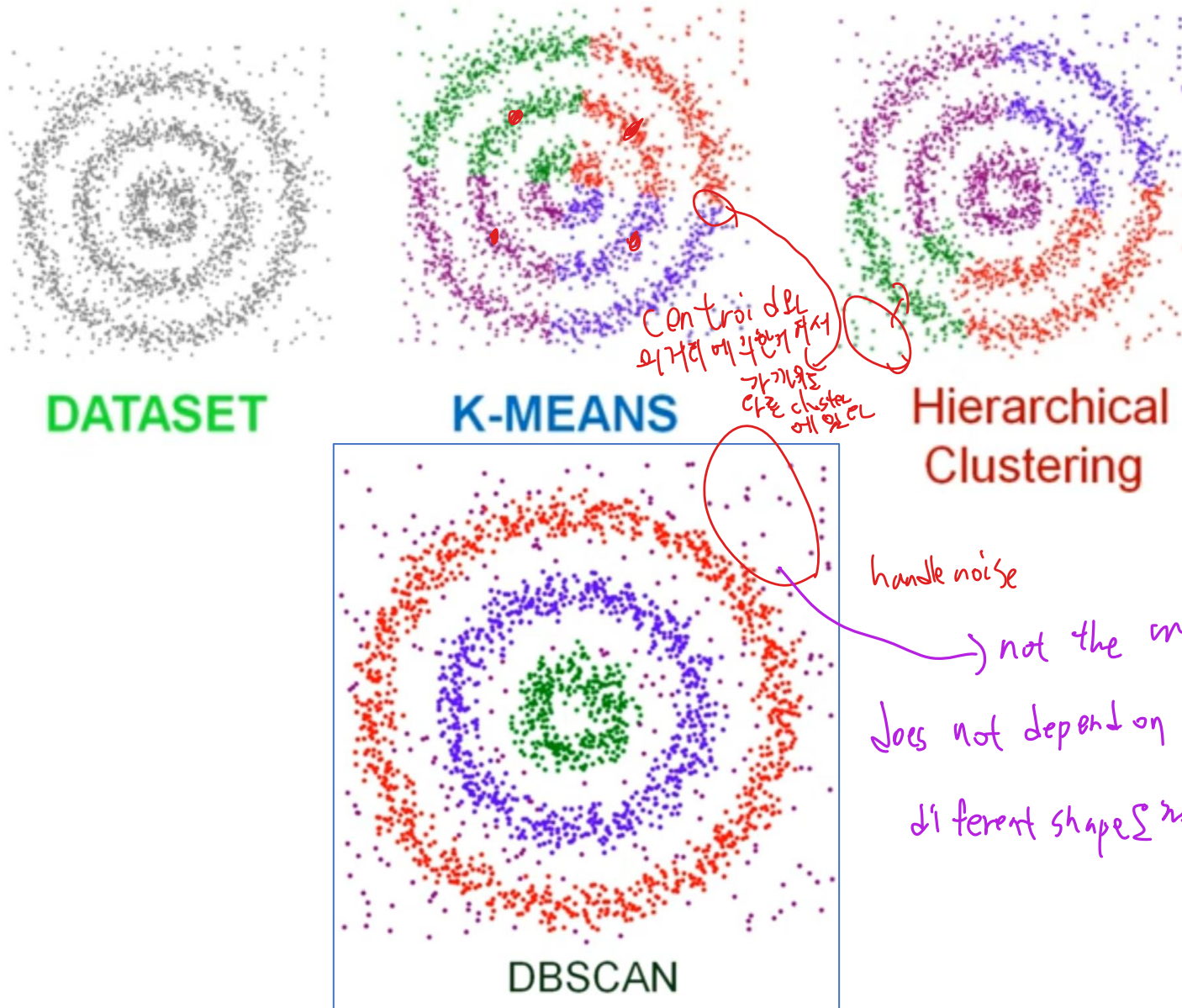


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Why Density-based Clustering?





Density-Based Clustering Methods

- ❑ Clustering based on **density** (local cluster criterion), such as density-connected points, rather than just a distance
- ❑ Major features:
 - ❑ Discover clusters of arbitrary shape
 - ❑ Handle noise
 - ❑ One scan, thus being efficient
 - ❑ Need density parameters as termination condition
- ❑ Several interesting studies:
 - ❑ DBSCAN
 - ❑ OPTICS
 - ❑ CLIQUE

programmer의 optimal인 hyper parameter 정해야 함



Density-Based Clustering: Hyper-Parameters

Two parameters:

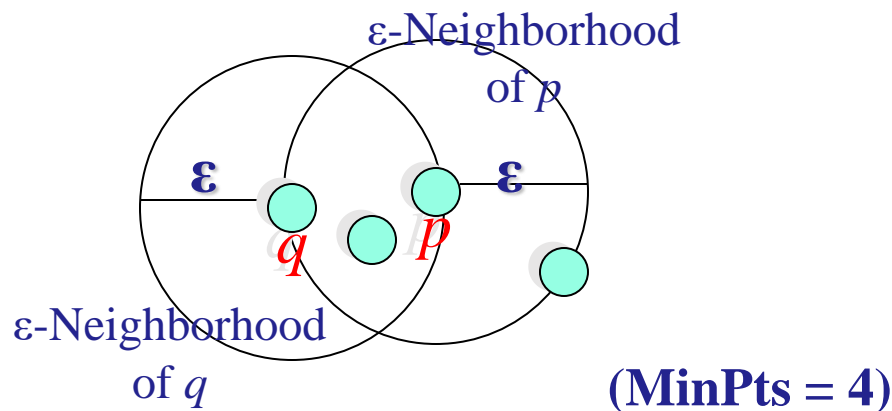
- ϵ : radius for the neighborhood of any point p :

$$N_{\epsilon}(p) := \{\text{any } q \text{ in dataset } D \mid \text{dist}(p, q) \leq \epsilon\}$$

- ϵ -Neighborhood – Objects within a radius of ϵ from an object.

- MinPts : minimum number of points in the given neighborhood

- “High density” : ϵ -Neighborhood of an object contains at least MinPts of objects



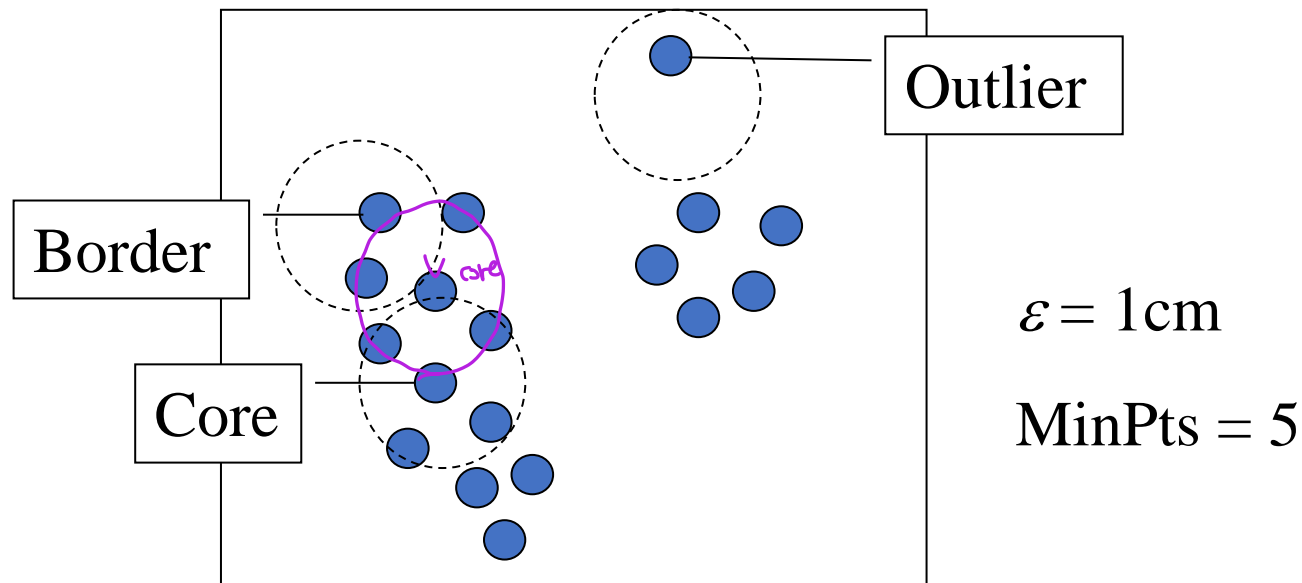
Density of p is “high”

Density of q is “low”



Density-Based Clustering: Types of Points

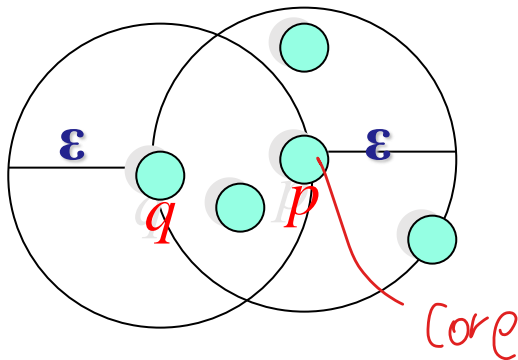
- ❑ A point is a **core point** if it has points more than $MinPts$ within ε
- ❑ A **border point** has fewer than $MinPts$ within ε , but is in the neighborhood of a core point
- ❑ **Outlier** is any point that is not a core point nor a border point. It is thus a noise, or an outlier.





Directly Density-Reachable

- **Directly density-reachable:** A point q is directly density-reachable from a point p if p is a core object and q is in p 's ϵ -neighborhood.



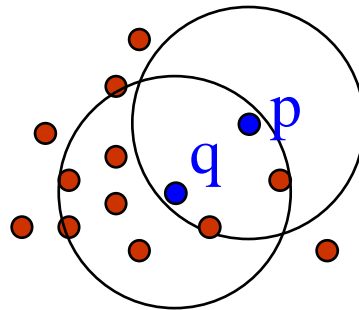
MinPts = 4

- q is directly density-reachable from p
 - p is **NOT** directly density-reachable from q
 - Density-reachability is **asymmetric**.
- Handwritten notes: "Core" in red next to p, "MinPts = 4" in purple below the list, and "q is core" in purple to the right of the list.*

Directly Density-Reachable

❑ **Directly density-reachable:** A point q is **directly density-reachable** from a point p if p is a core object and q is in p 's ε -neighborhood.

- ❑ p belongs to $N_\varepsilon(q)$
- ❑ p is directly density-reachable from q
- ❑ q is NOT directly density-reachable from p

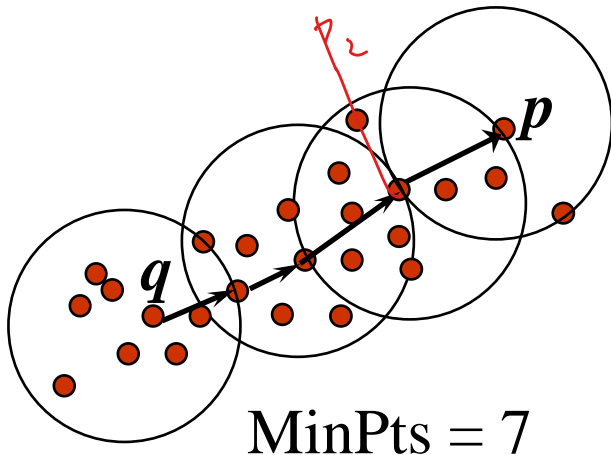


MinPts = 5

Density-Reachability

□ Density-Reachable (**directly** and **indirectly**):

- A point p is directly density-reachable from p_2 ;
- p_2 is directly density-reachable from p_1 ;
- p_1 is directly density-reachable from q ;
- $p \leftarrow p_2 \leftarrow p_1 \leftarrow q$ form a chain.
- Then, p is (**indirectly**) **density-reachable** from q



- A point p is density-reachable from a point q if there is a chain of points $p_1, \dots, p_n, p_1 = q, p_n = p$ such that p_{i+1} is directly density-reachable from p_i
- Is q not density-reachable from p ? ~~NO~~ p is not core

Thank You