

RUDOLF REITER

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elo-x.eu



I am passionately committed to shaping the future through innovative solutions and advancing the fields of optimization, artificial intelligence, and control. Moreover, I am motivated to tackle new challenges and eager to embrace responsibility.

EDUCATION

Ph.D. Candidate <i>Systems Control and Optimization Laboratory</i> University of Freiburg, Prof. Dr. Moritz Diehl <i>Optimization-Based Motion Planning for Autonomous Driving</i> <ul style="list-style-type: none">• Marie Skłodowska-Curie Innovative Training Network Fellow: “<i>ELO-X</i>: Embedded learning and optimization for the next generation.”• Research stays at IMT Lucca (Italy), ODYS S.r.l. (Milano, Italy), MERL (Cambridge, USA), ETH Zürich (Switzerland)• 50 ECTS course work in machine learning	Mar. 2020 ~ Nov. 2024 Freiburg, Germany
Master of Science <i>Electrical Engineering: Control Systems and Mechatronics</i> Technical University of Graz / University of Utah GPA: 1.2 (<i>passed with honours</i>) <i>Master's Thesis: Modeling of Specific Nonlinear Drive-Train Dynamics</i>	Oct. 2013 – Jan. 2016 Graz, Austria
Bachelor of Science <i>Electrical Engineering: Control Systems and Mechatronics</i> Technical University of Graz GPA: 1.5 (<i>passed with honours</i>) <i>Bachelor's Thesis: Modeling of Complex Magnetic Fields utilizing the Finite Elements Method</i>	Oct. 2009 – June 2012 Graz, Austria
Community Service Paramedic at the Red Cross	Aug. 2008 – May 2009 Salzburg, Austria
Secondary Technical College <i>Electronic Engineering and Information Systems</i> <i>Diploma Project: High-Resolution USB Measurement System - Hardware and Software</i>	Sep. 2003 – Jun. 2008 Salzburg, Austria

WORK EXPERIENCE

Software Developer Autonomous Racing Graz, <i>ARG</i> <ul style="list-style-type: none">• Development of embedded algorithms for real-world autonomous racing• Focus on prediction, planning, and control algorithms	Dec. 2019 ~ Aug. 2024 Graz, Austria
Robotics Motion Planning Intern Mitsubishi Electric Research Laboratories, <i>MERL</i> <ul style="list-style-type: none">• Research on learning-based mixed-integer optimization for motion planning	Jan. 2023 – May 2023 Cambridge (MA), USA
Software Developer, Researcher Virtual Vehicle Research Center <ul style="list-style-type: none">• Algorithms for path planning and control of autonomous vehicles• Developing simulation frameworks for autonomous driving	Dec. 2018 – Jul. 2021 Graz, Austria
Control Systems Specialist Anton Paar GmbH <ul style="list-style-type: none">• Development of high-end control systems for mass production• Worldwide first full automation of an atmospheric distillation analyzer• Viscosity measurement: main author of US patent <i>US 10,976,230 B2</i>	Jul. 2016 – July 2018 Graz, Austria
Master's Thesis Internship Virtual Vehicle Research Center	Apr. 2015 – Dez. 2015 Graz, Austria

Control Systems Engineering Internship Bernecker&Rainer Industrial Automation GmbH <ul style="list-style-type: none"> • Development of an “H-infinity” control for electric drives 	Sep. 2012 – Dez. 2012 Salzburg, Austria
Software Engineering Internship Bernecker&Rainer Industrial Automation GmbH	Jul. 2010 – Aug. 2010 Salzburg, Austria
Software Engineering Internship Step4 GmbH	Apr. 2009 – Jul. 2009 Salzburg, Austria
Robotic Engineering Internship Sony DADC Austria AG	Jul. 2006 – Aug. 2006 Salzburg, Austria

EXEMPLARY PUBLICATIONS

Equivariant Deep Learning of Mixed-Integer Optimal Control Solutions for Vehicle Decision Making and Motion Planning IEEE Transactions on Control System Technology Reiter R., Quirynen R., Diehl M., Di Cairano S.	June 2024
A Long-Short-Term Mixed-Integer Formulation for Highway Lane-Change Planning IEEE Transactions on Intelligent Vehicles Reiter R., Nurkanovic A., Bernardini D., Diehl M., Bemporad A.	June 2024
A Hierarchical Approach for Strategic Motion Planning in Autonomous Racing European Control Conference, Int. Conf. on Machine Learning, Poster 2024 Reiter R., Hoffmann J., Boedecker J., Diehl M.	June 2023
Frenet-Cartesian Model Representations for Automotive Obstacle Avoidance within Nonlinear MPC European Journal of Control 2023 Reiter R., Nurkanovic A., Frey J., Diehl M.	June 2023

SKILLS

Languages	German (Native), English (fluent)
Programming Languages	Python, C, C++, MATLAB
Optimization Libraries	CasADi, Acados, Yalmip, Gurobi, CVXPY, MOSEK
Machine Learning Libraries	PyTorch, TensorFlow, Stable Baselines 3, RLLIB, OpenCV
Platforms and OS	Windows, Linux, ROS1, ROS2, NVIDIA Drive PX2, Speedgoat

PRIVATE

Besides my technical interests, I enjoy being outdoors. I am passionate about climbing, hiking, listening to jazz music, and reading.

Freiburg, August 14, 2024

