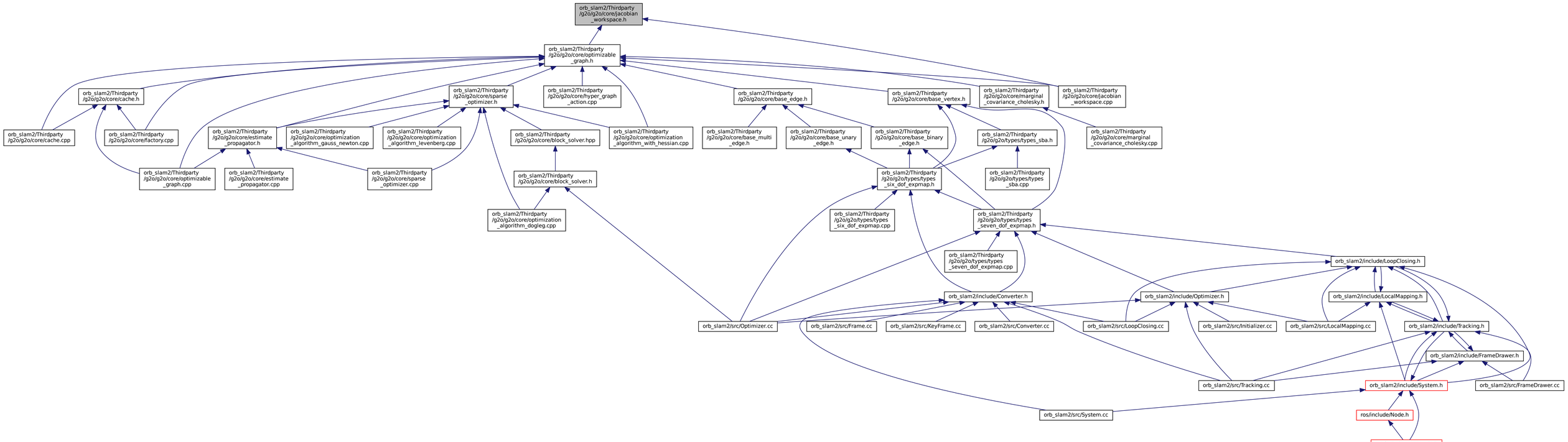
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orb_slam2/Thirdparty/g2o/g2o/core/optimizable_graph.h
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ros/include/MonoNode.h