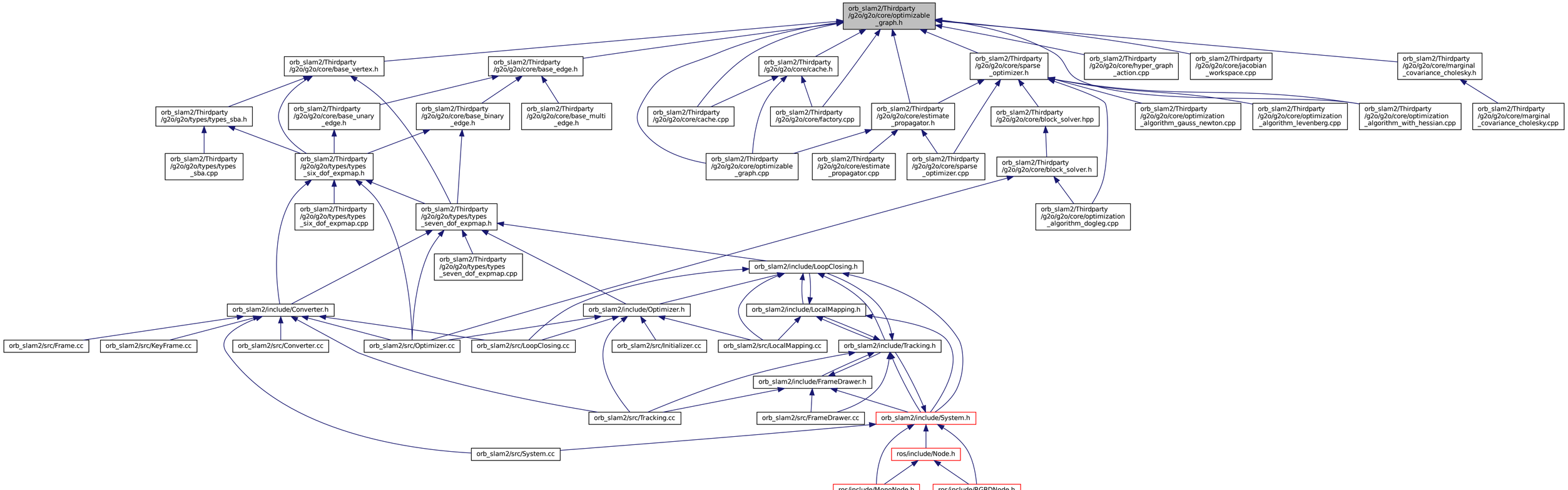
orb_slam2/Thirdparty /g2o/g2o/core/optimizable _graph.h
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ros/include/RGBDNode.h