

Solⁿ to Chapter 4

4.1 $q_{\pi}(11, \text{down}) = -1$

$q_{\pi}(7, \text{down}) = -1 + v(11) = -1 - 14 = -15$

$v(11)$ calculated by code.

0	-14	-20	-22	v_{map}
-14	-18	-20	-20	
-20	-20	-18	-14	
-22	-20	-14	0	

4.2.1 IF dynamics of 13 unchanged

$v_{\pi}(15) = -1 + 0.25[-20 - 22 - 14 + v_{\pi}(15)]$

Solving $v_{\pi}(15) = -20$

For dynamic changed: By running code for 4.2 we find that.

$v_{\pi}(15)$ is still -20

Also for rest states graph stays same.

4.3

eq 4.3 $v_{\pi}(s) = E_{\pi}[R_{t+1}, \gamma v_{\pi}(s_{t+1}) | s_t = s]$

Analogous $q_{\pi}(s, a) = E[R_{t+1}, \gamma \sum_{s', a'} q_{\pi}(s', a') | s_t = s, A_t = a]$

eq 4.4 $v_{\pi}(s) = \sum_a \pi(a|s) \sum_{s', r} p(s', r|s, a) [r + \gamma v_{\pi}(s')]$

$q_{\pi}(s, a) = \sum_{s', r} p(s', r|s, a) [r + \gamma \sum_{a'} \pi(a'|s) q_{\pi}(s', a')]$

eq 4.5 $v_{k+1}(s) = \sum_a \pi(a|s) \sum_{s', r} p(s', r|s, a) [r + \gamma v_k(s')]$

9 q_{π}