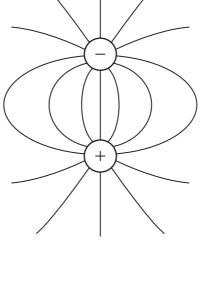
18	Motors usually have a rotating component which can do work W .		
	(a) A motor lifts a load in a time t . The axle of the motor has a radius r and exerts a force F .		
	axle axle load		
	The power produced by a motor can be calculated by using the following word equation.		
	Power = moment of the force exerted by the rotating axle × angular velocity		
Derive this equation starting with newer $R = W$			
	Derive this equation, starting with power $P = \frac{W}{t}$. (4)		
	(b) An electrostatic motor was first demonstrated by Benjamin Franklin in 1750.		
	The diagram shows a simplified version of part of this motor.		
This consists of a rod, with an oppositely charged sphere at either end, which rotates around a fixed pivot. Two stationary charged spheres apply a force on the spheres at either end of the rod.			
	stationary charged sphere		
	rod pivot		
	(+) (-)		
	+ stationary charged sphere		
	(i) In the diagram below, electric field lines have been drawn around one pair of		
	these spheres.		
	Add to the diagram to show		
	• the directions of the field lines		
	• the lines of equipotential. (3)		



(ii) The distance between the centres of each charged sphere in this pair is 5.0 cm. Show that the force between this pair of charged spheres is about 0.04 N. charge on each sphere = 0.10 μ C (2)

(c) The table shows the typical power and the corresponding angular velocity required for three different appliances.

| Power / W | Angular velocity / rad s⁻¹

2.0×10^{4}	300
	300
1.4×10^{3}	1000
0.5	200
	se the electrostatic motor in (
	0.5

You should use the word equation in (a) and assume that the length of the rod in the electrostatic motor is 8.0 cm.

Assume that the electrostatic motor would deliver a constant force throughout one

complete rotation.

(4)