

Fig 1(a): True $P(t)$, GPR estimate & forecast, and 300-sample MA & forecast

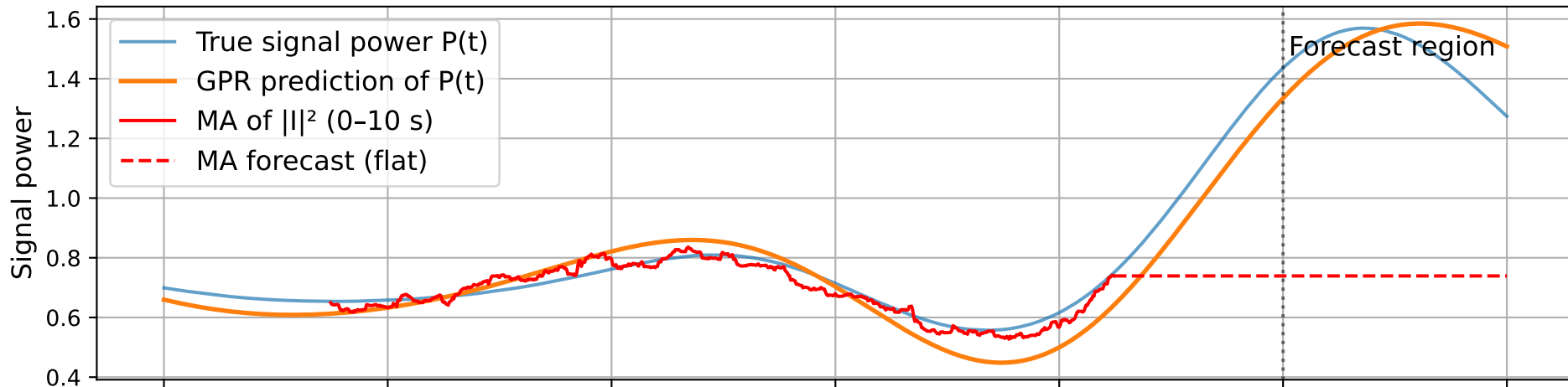


Fig 1(b): Non-stationary Gaussian noise $I(t)$ with sampled observations

