

Fig 1(a): True P(t), GPR estimate & forecast, and 300-sample MA & forecast

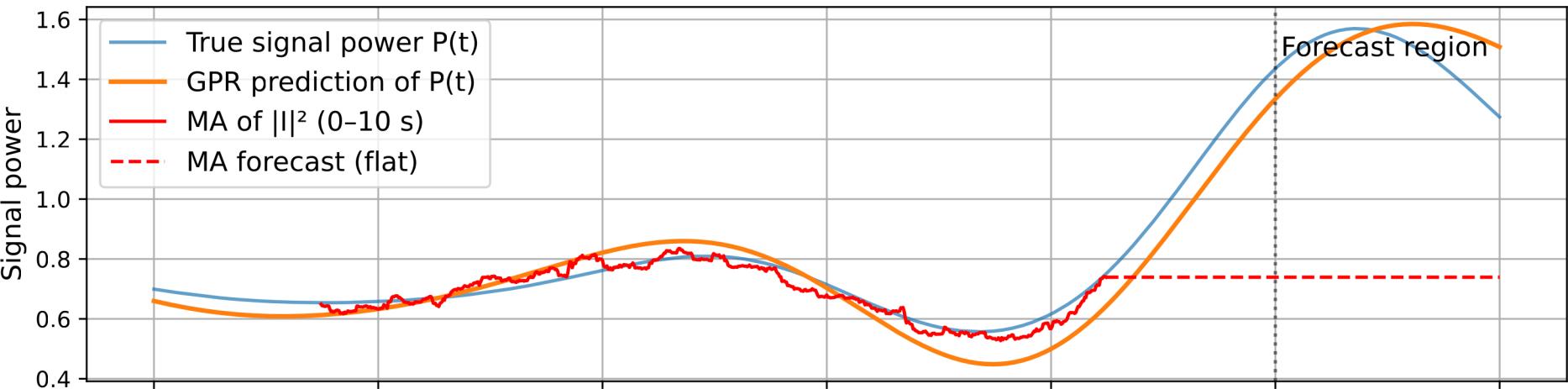


Fig 1(b): Non-stationary Gaussian noise I(t) with sampled observations

