APPENDIX A PROOF OF LEMMA 1

Lemma 1. Given any feasible task replication and power allocation, the Lyapunov drift-plus-penalty function B in our formulation (32) is upper bounded by the following expression.

$$\begin{split} B &\geq \frac{1}{2} E\left[\left(Q(t)\right)^2 + \omega^2\right] \\ &+ \frac{1}{2} \sum_{i=1}^I E\left[\left(\frac{1}{T} \sum_{t=0}^{T-1} D_{i,b}(t)\right)^2 + \epsilon^2\right], \end{split}$$

where ω is the restricted queue length in the cloud, and $R_{i,b}(t)$ is denoted as the total amount of computing from TaV i in the time slot t, ϵ is the average delay constraint.

Proof. By squaring both sides of the equation (12), we can get the expression below.

$$H(t+1)^{2}$$
= $(\max \{H(t) + Q(t) - \omega, 0\})^{2}$
 $\leq H(t)^{2} + \omega^{2} + Q(t)^{2} + 2H(t)Q(t)$
 $-2\omega Q(t) - 2\omega H(t).$

The following inequality can be obtained as follows.

$$\begin{split} &\frac{1}{2}[H(t+1)^2 - H(t)^2] \\ &\leq \frac{1}{2} \left(\omega^2 + Q(t)^2 + 2Q(t)H(t) \right. \\ &\left. -2\omega Q(t) - 2\omega H(t) \right) \\ &\leq \frac{1}{2} \left[Q(t)^2 + \omega^2 + 2H(t) \left(Q(t) - \omega \right) \right]. \end{split}$$

Similarly, we can obtain the following expression.

$$\frac{1}{2}[G_{i}(t+1)^{2} - G_{i}(t)^{2}]$$

$$\leq \frac{1}{2} \left[\epsilon^{2} + \left(\frac{1}{T} \sum_{t=0}^{T-1} D_{i,b}(t) \right)^{2} - 2\epsilon G_{i}(t) - 2\epsilon \sum_{t=0}^{T-1} D_{i,b}(t) \right]$$

$$+2G_{i}(t) \sum_{t=0}^{T-1} D_{i,b}(t) \right]$$

$$\leq \frac{1}{2} \left[\left(\sum_{t=0}^{T-1} D_{i,b}(t) \right)^{2} + \epsilon^{2} + 2G_{i}(t) \left(\sum_{t=0}^{T-1} D_{i,b}(t) - \epsilon \right) \right].$$

Summing over all the above inequality when $i=1,2,\ldots,I$, the following inequality can be obtained as below.

$$\begin{split} &\frac{1}{2} \sum_{i=1}^{I} [G_i(t+1)^2 - G_i(t)^2] \\ &\leq \frac{1}{2} \sum_{i=1}^{I} \left[\left(\sum_{t=0}^{T-1} D_{i,b}(t) \right)^2 + \epsilon^2 + 2G_i(t) \left(\sum_{t=0}^{T-1} D_{i,b}(t) - \epsilon \right) \right]. \end{split}$$

According to the definition of Lyapunov drift function, we can get the expression below.

$$L(\Theta(t)) = \frac{1}{2} \left((H(t))^2 + \sum_{i=1}^{I} (G_i(t))^2 \right),$$

$$\triangle L(t) = E[L(\Theta(t+1)) - L(\Theta(t))].$$

Then, we can get a bound on $\triangle L(t)$.

$$\Delta L(t) \leq B + \left[H(t) \left(Q(t) - \omega \right) + \sum_{i=1}^{I} G_i(t) \left(\sum_{t=0}^{T-1} D_{i,b}(t) - \epsilon \right) \right],$$

where B is upper bounded by the expression as below.

$$\begin{split} B &\geq \frac{1}{2} E\left[\left(Q(t)\right)^2 + \omega^2\right] \\ &+ \frac{1}{2} \sum_{i=1}^I E\left[\left(\frac{1}{T} \sum_{t=0}^{T-1} D_{i,b}(t)\right)^2 + \epsilon^2\right]. \end{split}$$

APPENDIX B PROOF OF LEMMA 2

Lemma 2. The BER $\Omega_{i,b}(t)$ between TaV i and the edge cloud and the BER $\Omega_{i,j}(t)$ between TaV i and SeV j under Rayleigh fading conditions have the approximation as below.

$$\begin{split} \Omega_{i,b}(t) &\approx \\ &\frac{\left(e^{R_{i,b}(t)} - 1\right) \left(\sum_{k=i+1}^{I} \left|h_{k,b}(t)\right|^{2} \alpha_{i}^{n}(t) p_{k,b}(t) + \sigma^{2}\right)}{p_{i,b}(t) \left|h_{i,b}(t)\right|^{2}} \\ &\Omega_{i,j}(t) &\approx \frac{\left(e^{\frac{K_{i,j}}{L_{i,j}}} - 1\right) \sigma^{2}}{p_{i,j}(t) \left|h_{i,j}(t)\right|^{2}}. \end{split}$$

Proof. According to Taylor's Expanded Form, we can get the approximations of (7) and (8) as below.

$$\Omega_{i,b}(t) \approx 1 - k_1 \gamma_{i,b}(t) \left(1 + \frac{k_2}{\gamma_{i,b}(t)} + \frac{k_2^2}{2\gamma_{i,b}^2(t)} - 1 - \frac{k_3}{\gamma_{i,b}(t)} - \frac{k_3^2}{2\gamma_{i,b}^2(t)} \right),$$

where
$$k_1 = \sqrt{\frac{L_{i,b}}{2\pi(e^{2\frac{K_{i,b}}{L_{i,b}}}-1)}}$$
, $k_2 = 1 - e^{\frac{K_{i,b}}{L_{i,b}}} + \sqrt{\frac{\pi(e^{2\frac{K_{i,b}}{L_{i,b}}-1)}}{2L_{i,b}}}$, and $k_3 = 1 - e^{\frac{K_{i,b}}{L_{i,b}}} - \sqrt{\frac{\pi(e^{2\frac{K_{i,b}}{L_{i,b}}-1)}}{2L_{i,b}}}$.

$$\begin{split} \Omega_{i,j}(t) \approx & 1 - g_1 \gamma_{i,j}(t) \left(1 + \frac{g_2}{\gamma_{i,j}(t)} + \frac{g_2^2}{2\gamma_{i,j}^2(t)} \right. \\ & \left. - 1 - \frac{g_3}{\gamma_{i,j}(t)} - \frac{g_3^2}{2\gamma_{i,j}^2(t)} \right), \end{split}$$

where
$$g_1 = \sqrt{\frac{L_{i,j}}{2\pi(e^{2\frac{K_{i,j}}{L_{i,j}}}-1)}}$$
, $g_2 = 1 - e^{\frac{K_{i,j}}{L_{i,j}}} + \sqrt{\frac{\pi(e^{2\frac{K_{i,j}}{L_{i,j}}-1)}}{2L_{i,j}}}$, and $g_3 = 1 - e^{\frac{K_{i,j}}{L_{i,j}}} - \sqrt{\frac{\pi(e^{2\frac{K_{i,j}}{L_{i,j}}-1)}}{2L_{i,j}}}$.

After simplification, we can obtain the below expressions.

$$\Omega_{i,b}(t) \approx \frac{(e^{\frac{K_{i,b}}{L_{i,b}}} - 1) \left(\sum_{k=i+1}^{I} \left| h_{k,b}(t) \right|^2 p_{k,b}(t) + \sigma^2 \right)}{p_{i,b}(t) \left| h_{i,b}(t) \right|^2},$$

$$\Omega_{i,j}(t) \approx \frac{\left(e^{\frac{K_{i,j}}{L_{i,j}}} - 1\right)\sigma^2}{p_{i,j}(t)\left|h_{i,j}(t)\right|^2}$$

APPENDIX C PROOF OF LEMMA 3

Lemma 3. The expected service reliability incurred by PA-TRLF could achieve the effect that has a gap with the maximal service reliability, which can be described below.

$$\lim_{T \to \infty} \frac{1}{T} \sum_{t=0}^{T-1} E\{\Upsilon(t)|\Theta(t)\} \le \Upsilon^{\sup}(t) - \frac{B}{V},$$

where $\Upsilon^{\sup}(t)$ is the supremum of the average service reliability achieved by any joint strategy under the required constraints, and B is mentioned in **Lemma 1**.

Proof. From Lemma 2, we can get the below expression.

$$\begin{split} \Delta L(t) - VE\{\Upsilon(t)|\Theta(t)\} &\leq B - VE\{\Upsilon(t)|\Theta(t)\} \\ &+ \sum_{i}^{I} G_i(t)E\{\frac{1}{T}\sum_{t=0}^{T-1} D_{i,b}(t) - \epsilon|\Theta(t)\} \\ &+ H(t)E\{Q(t) - \omega|\Theta(t)\}. \end{split}$$

B is the upper bound, which follows the below inequality.

$$B \ge \frac{1}{2} E \left[(Q(t))^2 + \omega^2 \right] + \frac{1}{2} \sum_{i=1}^{I} E \left[\left(\frac{1}{T} \sum_{t=0}^{T-1} D_{i,b}(t) \right)^2 + \epsilon^2 \right].$$

From **Section 3.1.4** in the study [16], we have the following inequality.

$$B - V \Upsilon^{\sup}(t) < \triangle L(t) - V E \{\Upsilon(t) | \Theta(t)\}.$$

By adding $t = 0, 1, \dots, T - 1$ cumulatively, we get:

$$\begin{split} TB - TV\Upsilon^{\sup}(t) &\leq E\left\{L(\Theta(t)) - L(\Theta(0))\right\} \\ &- V\sum_{t=0}^{T-1} E\left\{\Upsilon(t)|\Theta(t)\right\}. \end{split}$$

Since $L(\Theta(t)) \ge 0$, $L(\Theta(0)) = 0$, both sides divide by the same -TV, when $t \to +\infty$, we can obtain that:

$$\lim \sup_{t \to +\infty} \frac{1}{t} \sum_{t=0}^{T-1} E\left\{\Upsilon(t)\right\} \le \Upsilon^{\sup}(t) - \frac{B}{V}.$$

With Jensen's inequality, we can get:

$$\lim_{T \to \infty} \frac{1}{T} \sum_{t=0}^{T-1} E(\Upsilon(t)) \le \Upsilon^{\sup}(t) - \frac{B}{V}.$$

APPENDIX D PROOF OF LEMMA 4

Lemma 4. The virtual task queue in the edge cloud and the virtual delay queue for all TaVs in NOMA-enabled VEC are stable, which can be presented as follows.

$$\begin{split} &\lim_{T \to \infty} \frac{1}{T} \sum_{t=0}^{T-1} \left(E\{H(t)\} + \sum_{i=1}^{I} E\{G_i(t)\} \right) \\ &\leq \frac{V(\hat{\Upsilon}(t) - \check{\Upsilon}(t)) - B}{\varsigma}, \end{split}$$

where $\hat{\Upsilon}(t)$ and $\check{\Upsilon}(t)$ are defined as the maximum and minimum service reliability among all strategies. B is mentioned in **Lemma 1**.

Proof. We now prove that Q(t) and $G_i(t)$ are mean rate stable under Algorithm 3.

Denote $\Phi(t)TV\{\hat{\Upsilon}(t)\} - V\sum_{t=0}^{T-1} E\left\{\Upsilon(\bar{t})|\Theta(t)\right\} - TB + E\left\{L(\Theta(0))\right\}.$

Based on **Lemma 3**, we can get $E\{L(\Theta(t))\} \leq \Phi(t)$, i.e., $E\{H(t)^2\} \leq 2\Phi(t)$ and $E\{\sum_{i=1}^I G_i(t)^2\} \leq 2\Phi(t)$. Thus, we have the following inequality.

$$0 \le E\{H(t)\} \le \sqrt{2\Phi(t)}.$$

 $0 \le \sum_{i=1}^{I} E\{G_i(t)\} \le \sqrt{2\Phi(t)}.$

Since $\lim_{T\to\infty} \frac{\sqrt{2\Phi(t)}}{T}=0$, we can also acknowledge that

$$\lim_{T \to \infty} \frac{E\{H(t)\}}{T} = 0.$$

$$\lim_{T \to \infty} \sum_{i=1}^{I} \frac{E\{G_i(t)\}}{T} = 0.$$

To find the upper bound of the average sum queue length of $E\{H(t)\}$ and $\sum_{i=1}^{I} E\{G_i(t)\}$, we can obtain the below expression in the proof of **Lemma 3**,

$$L(\Theta(t+1)) - L(\Theta(t)) - VE\{\Upsilon(t)|\Theta(t)\} \ge \left[\sum_{i=1}^{I} G_i(t) \left(\frac{1}{T}\sum_{t=0}^{T-1} D_{i,b}(t) - \epsilon\right) + H(t) \left(Q(t) - \omega\right)\right] + B - V\Upsilon^{\sup}(t),$$

where $\Upsilon^{\text{sup}}(t)$ is the supremum of the average service reliability achieved by any joint strategy under the required constraints.

Then, summing over $t \in \{0, 1, 2, \dots, T-1\}$, we can obtain the expression below.

$$\begin{split} L(\Theta(T)) - L(\Theta(0)) - \sum_{t=0}^{T-1} VE\{\Upsilon(t)|\Theta(t)\} \geq \\ TB - TV\Upsilon^{\sup}(t) + \varsigma \left(E\{H(t)\} + \sum_{i=1}^{I} E\{G_i(t)\}\right), \end{split}$$

where $\varsigma > 0$.

After dividing T and ς by both sides of the above inequality, we can finally get.

$$\begin{split} &\frac{1}{T} \left(E\{H(t)\} + \sum_{i=1}^{I} E\{G_i(t)\} \right) \leq \frac{E(L(T))}{\varsigma T} - \frac{E(L(0))}{\varsigma T} \\ &- \frac{B - V \Upsilon^{\text{sup}}(t) + \frac{1}{T} \sum_{t=0}^{T-1} V E\{\Upsilon(t) | \Theta(t)\}}{\varsigma}, \end{split}$$

$$\Upsilon^{\sup}(t) - \frac{1}{T} \sum_{t=0}^{T-1} E\{\Upsilon(t)|\Theta(t)\} \leq \hat{\Upsilon}(t) - \check{\Upsilon}(t).$$

From the predefined value L(0), we can get the conclusion.

$$\lim_{T \to \infty} \frac{1}{T} \sum_{t=0}^{T-1} \left(E\{H(t)\} + \sum_{i=1}^{I} E\{G_i(t)\} \right)$$
$$\leq \frac{V(\hat{\Upsilon}(t) - \check{\Upsilon}(t)) - B}{\varsigma}.$$