

# Ass2 Solutions

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## 1 Solutions

### 1.1 Prob 2.12

Prove convexity of halfspaces

#### 1.1.1 Prob a

This set is convex. Let  $B = \{x \in R^n | a^T x \geq \alpha\}$ ,  $C = \{x \in R^n | a^T x \leq \beta\}$ . Then the slab  $S = B \cap C = \{x \in R^n | \alpha \leq a^T x \leq \beta\}$ . Because  $B$  and  $C$  are both halfspaces hence convex and the intersection operation preserves convexity. Therefore slab  $S$  is convex.

#### 1.1.2 Prob b

This set is convex. Let  $S = \{x \in R^n | \alpha_i \leq x \leq \beta_i, i = 1, \dots, n\}$  can be written as the intersection of a finite number of slabs

$$S = \cap_{i=1, \dots, n} \{x \in R^n | \alpha_i \leq x \leq \beta_i\}$$

From Prob a we know that slab is convex. Since the intersection operation preserves convexity, the set  $S$  is also convex.

#### 1.1.3 Prob c

This set is convex. Let  $S = \{x \in R^n | a_1^T x \leq b_1, a_2^T x \leq b_2\}$ ,  $A = \{x \in R^n | a_1^T x \leq b_1\}$  and  $B = \{x \in R^n | a_2^T x \leq b_2\}$ . Therefore,  $S = A \cap B$ . Since  $A$  and  $B$  are halfspaces hence convex, and the intersection operation preserves convexity, the set  $S$  is also convex.

#### 1.1.4 Prob d

This set is convex. Let  $A = \{\|x - x_0\|_2 \leq \|x - y\|_2 \text{ for all } y \in S\}$ , then  $A$  can be written as the intersection of a finite number of sets:

$$A = \cap_{y \in S} \{\|x - x_0\|_2 \leq \|x - y\|_2\}$$

When  $y$  is fixed, let  $B = \{\|x - x_0\|_2 \leq \|x - y\|_2\}$ . We have,

$$\begin{aligned}\|x - x_0\|_2 \leq \|x - y\|_2 &\iff (x - x_0)^T(x - x_0) \leq (x - y)^T(x - y) \\ &\iff x^T x - 2x_0^T x + x_0^T x_0 \leq x^T x - 2y^T x + y^T y \\ &\iff 2(y - x_0)^T x \leq y^T y - x_0^T x_0 \\ &\iff Ax \preceq b\end{aligned}$$

where,

$$A = 2 \begin{bmatrix} y_1 - x_0 \\ y_2 - x_0 \\ \dots \\ y_n - x_0 \end{bmatrix}$$

$$b = \begin{bmatrix} y_1^T y_1 - x_0^T x_0 \\ y_2^T y_2 - x_0^T x_0 \\ \dots \\ y_n^T y_n - x_0^T x_0 \end{bmatrix}$$

Therefore, for every  $y \in S$ ,  $B$  is a halfspace which is convex. Since the intersection operation preserves convexity and  $A$  can be written as the intersection of a finite number of halfspaces,  $A$  is also convex.

#### 1.1.5 Prob e

In general this set is not convex. As an example, suppose  $x \in R$ ,  $S = \{-a, a\}$ ,  $T = \{0\}$  and  $a \in R^+$ . Then we have,

$$A = \{x | \text{dist}(x, S) \leq \text{dist}(x, T)\} = \{x \in R | x \leq -\frac{a}{2} \text{ or } x \geq \frac{a}{2}\}$$

where  $c = -\frac{a}{2} \in A$  and  $b = \frac{a}{2} \in A$ . However,  $0 = \frac{1}{2}c + (1 - \frac{1}{2})b \notin A$ . Therefore,  $A$  is not convex. So in general the set  $\{x | \text{dist}(x, S) \leq \text{dist}(x, T)\}$  is not convex.

#### 1.1.6 Prob f

This set is convex. Let  $S = \{x | x + S_2 \subseteq S_1\}$ . We have,

$$S = \{x | x + S_2 \subseteq S_1\} = \cap_{\text{for all } y \in S_2} \{x | x + y \subseteq S_1\} = \cap_{\text{for all } y \in S_2} (S_1 - y)$$

Since  $S_1$  is convex,  $S_1 - y$  is also convex. This is because for all  $z \in S_1 - y$ , let  $m \in S_1$ . Because  $y$  is fixed, if  $z_1 = x_1 - y \in S_1 - y$  and  $z_2 = x_2 - y \in S_1 - y$ , then  $\theta z_1 + (1 - \theta)z_2 = (\theta x_1 + (1 - \theta)x_2) - y$ . Because  $S_1$  is convex, let  $x_3 = (\theta x_1 + (1 - \theta)x_2) \in S_1$ . Then  $\theta z_1 + (1 - \theta)z_2 = x_3 - y \in S_1 - y$ .

Therefore,  $S$  is convex because it can be written as the intersection of convex sets.

#### 1.1.7 Prob g

This set is convex. Let  $S = \{x | \|x - a\|_2 \leq \theta \|x - b\|_2\}$ , where  $0 \leq \theta \leq 1$ .

$$\begin{aligned}\|x - a\|_2 \leq \theta \|x - b\|_2 &\iff (x - a)^T(x - a) \leq \theta^2(x - b)^T(x - b) \\ &\iff x^T x - 2a^T x + a^T a \leq \theta^2(x^T x - 2b^T x + b^T b) \\ &\iff (1 - \theta^2)x^T x - 2(a - \theta^2 b)^T x + (a^T a - \theta^2 b^T b) \leq 0\end{aligned}$$

Because  $0 \leq \theta \leq 1$ , when  $\theta = 1$ ,  $S = \{x | -2(a - b)^T x \leq -(a^T a - b^T b)\}$ . Therefore,  $S$  is a halfspace hence convex.

When  $\theta < 1$

$$S = \{x | (x - \frac{a - \theta^2 b}{1 - \theta^2})^T (x - \frac{a - \theta^2 b}{1 - \theta^2}) \leq (\frac{\theta^2 b^T b - a^T a}{1 - \theta^2} - (\frac{a - \theta^2 b}{1 - \theta^2})^T (\frac{a - \theta^2 b}{1 - \theta^2}))\}$$

Therefore,  $S$  is a ball hence convex.

## 1.2 Prob 2.15

Let  $P = \{p | \mathbf{1}^T p = 1, p \succeq 0\}$ . Because  $\mathbf{1}^T p = 1$  defines a hyperplane and  $p \succeq 0$  define halfspaces,  $P$  is an intersection of a hyperplane and halfspaces. Therefore,  $P$  is a polyhedron hence convex.

### 1.2.1 a

This is convex constraint. The constraint can be written as:

$$Ef(x) \leq \beta \iff \sum_{i=1}^n p_i f(a_i) \leq \beta \quad (1)$$

$$Ef(x) \geq \alpha \iff \sum_{i=1}^n p_i f(a_i) \geq \alpha \quad (2)$$

Therefore, both constraints 1 and 2 are halfspaces hence are convex. Since  $P$  is convex and the intersection operation preserves convexity, the intersection of  $P$  and two halfspaces:  $P^* = \{p | \mathbf{1}^T p = 1, p \succeq 0, \alpha \leq \mathbf{E}f(x) \leq \beta\}$  is also convex.

### 1.2.2 b

This is convex constraint. Because  $a$  is in ascent order, let  $i^*$  equals the minimum index satisfies  $a_i \geq \alpha$ . The constraint can be written as:

$$\text{prob}(x \geq \alpha) = \sum_{i^*}^n p_i = \begin{bmatrix} 0 \\ 0 \\ \dots \\ 1 \\ 1 \\ \dots \\ 1 \end{bmatrix}^T \begin{bmatrix} p_1 \\ p_2 \\ \dots \\ p_i^* \\ p_{i^*+1} \\ \dots \\ p_n \end{bmatrix} = v^T p \leq \beta$$

Where the first  $i^* - 1$  elements of  $v$  are zeros and all ones after  $i^*$ . Therefore the constraint defines a halfspace hence convex. Since  $P$  is convex and the intersection operation preserves convexity, the intersection of  $P$  and halfspace:  $P^* = \{p | \mathbf{1}^T p = 1, p \succeq 0, \text{prob}(x \geq \alpha)\}$  is also convex.

### 1.2.3 e

This is convex constraint. The constraint can be written as:

$$\mathbf{E}x^2 = \sum_{i=1}^n p_i a_i^2 \geq \alpha$$

which defines a halfspace hence convex. Since  $P$  is convex and the intersection operation preserves convexity, the intersection of  $P$  and halfspace:  $P^* = \{p | \mathbf{1}^T p = 1, p \succeq 0, \mathbf{E}x^2\}$  is also convex.

#### 1.2.4 f

In general this is not a convex constraint. The constraint can be written as:

$$\text{var}(x) = \mathbf{E}x^2 - (\mathbf{E}x)^2 = \sum_{i=1}^n p_i a_i^2 - \left(\sum_{i=1}^n p_i a_i\right)^2 \leq \alpha$$

Let  $n = 2$ ,  $\alpha = 0.1$ ,  $a_1 = 1$  and  $a_2 = 2$ . Let  $p_1 = (1, 0)$  and  $p_2 = (0, 1)$ . We have  $\text{var}(p_1) = 0 \leq \alpha$  and  $\text{var}(p_2) = 0 \leq \alpha$ . However, the convex combination  $p_3 = \frac{1}{2}p_1 + \frac{1}{2}p_2 = (\frac{1}{2}, \frac{1}{2})$  doesn't satisfy the constraint  $\text{var}(p_3) = 0.25 > \alpha$ . Therefore, in general it is not a convex constraint.

### 1.3 Prob 3.14

#### 1.3.1 a

Since  $f(x, z)$  is second-order differentiable. Because for each fixed  $x$ ,  $f(x, z)$  is a concave function of  $z$ , we have  $\nabla_{zz}^2 f(x, z) \preceq 0$ . Because for each fixed  $x$ ,  $f(x, z)$  is a convex function of  $x$ , we have  $\nabla_{xx}^2 f(x, z) \succeq 0$ . Therefore, in the Hessian matrix

$$\nabla^2 f(x, z) = \begin{bmatrix} \nabla_{xx}^2 f(x, z) & \nabla_{xz}^2 f(x, z) \\ \nabla_{xz}^2 f(x, z) & \nabla_{zz}^2 f(x, z) \end{bmatrix}$$

The element  $\nabla_{xx}^2 f(x, z) \succeq 0$  and the element  $\nabla_{zz}^2 f(x, z) \preceq 0$ .

#### 1.3.2 b

Because for each fixed  $\tilde{x}$ ,  $f(\tilde{x}, z)$  is a concave function of  $z$ , we also know that  $\nabla f(\tilde{x}, \tilde{z}) = 0$ , therefore  $\tilde{z}$  maximizes  $f(\tilde{x}, z)$  over  $z$ . Therefore, we have  $f(\tilde{x}, z) \leq f(\tilde{x}, \tilde{z})$ , namely  $\inf_x \sup_z f(x, z) \leq \sup_z f(\tilde{x}, z) \leq f(\tilde{x}, \tilde{z})$ .

For similar reason, because for each fixed  $\tilde{z}$ ,  $f(x, \tilde{z})$  is a convex function of  $x$ , we also know that  $\nabla f(\tilde{x}, \tilde{z}) = 0$ , therefore  $\tilde{x}$  minimizes  $f(x, \tilde{z})$  over  $x$ . Therefore, we have  $f(\tilde{x}, \tilde{z}) \leq f(x, \tilde{z})$ , namely  $f(\tilde{x}, \tilde{z}) \leq \inf_x f(x, \tilde{z}) \leq \sup_z \inf_x f(x, z)$ .

So we have  $f(\tilde{x}, z) \leq f(\tilde{x}, \tilde{z}) \leq f(x, \tilde{z})$ .

We also have:

$$\inf_x \sup_z f(x, z) \leq \sup_z f(\tilde{x}, z) \leq f(\tilde{x}, \tilde{z}) \leq \inf_x f(x, \tilde{z}) \leq \sup_z \inf_x f(x, z)$$

However, according to equation 5.46 in Boyd's book[1]. The following condition always hold:

$$\sup_z \inf_x f(x, z) \leq \inf_x \sup_z f(x, z)$$

Therefore, we have  $\sup_z \inf_x f(x, z) = \inf_x \sup_z f(x, z) = f(\tilde{x}, \tilde{z})$ .

### 1.3.3 c

For all  $x$ , because the following holds  $f(\tilde{x}, \tilde{z}) \leq f(x, \tilde{z})$ . Therefore  $\tilde{x}$  minimizes  $f(x, \tilde{z})$  over all  $x$ . Therefore  $\nabla f_x(\tilde{x}, \tilde{z}) = 0$ .

For all  $z$ , because the following holds  $f(\tilde{x}, z) \leq f(\tilde{x}, \tilde{z})$ . Therefore  $\tilde{z}$  maximizes  $f(\tilde{x}, z)$  over all  $z$ . Therefore  $\nabla f_z(\tilde{x}, \tilde{z}) = 0$ .

Therefore,  $\nabla f(\tilde{x}, \tilde{z}) = 0$ .

## 1.4 Prob 3.16

### 1.4.1 a

This is both convex and quasiconvex and quasiconcave but not concave. This is because:

$$\nabla^2 f(x) = e^x > 0, \text{ for all } x \in R$$

Therefore  $f(x)$  is both convex and quasiconvex.

For its superlevel sets:

$$S_\alpha = \{x | e^x - 1 \geq \alpha\}$$

is also convex. Let  $x_1 \leq x_2$ ,  $e^{x_1} - 1 \geq \alpha$  and  $e^{x_2} - 1 \geq \alpha$ , then  $x_1 \leq \theta x_1 + (1-\theta)x_2$  for  $\theta \geq 0$ . Therefore,  $e^{\theta x_1 + (1-\theta)x_2} - 1 \geq e^{x_1} - 1 \geq \alpha$  because  $\nabla(e^x) = e^x > 0$  which is increasing.

### 1.4.2 b

This is quasiconcave, but not convex, concave or quasiconvex. This is because

$$\nabla^2 f(x) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

Therefore, the Hessian matrix of  $f$  is neither positive semidefinite nor negative semidefinite. Therefore, it is neither convex nor concave.

However, it is quasiconcave, since the superlevel sets

$$\{x \in R_{++}^2 | x_1 x_2 \geq \alpha\}$$

are convex sets for all  $\alpha$ .

### 1.4.3 c

This is convex and quasiconvex, but not concave or quasiconcave. This is because,

$$\nabla^2 f(x) = \frac{1}{x_1 x_2} \begin{bmatrix} \frac{2}{x_1^2} & \frac{1}{x_1 x_2} \\ \frac{1}{x_1 x_2} & \frac{2}{x_2^2} \end{bmatrix} \succeq 0$$

Therefore,  $f(x)$  is convex and hence quasiconvex.

#### 1.4.4 d

This is both quasiconvex and quasiconcave, but not convex or concave. This is because,

$$\nabla^2 f(x) = \begin{bmatrix} 0 & -\frac{1}{x_2^2} \\ -\frac{1}{x_2^2} & 2\frac{x_1}{x_2^3} \end{bmatrix}$$

Therefore, the Hessian matrix of  $f$  is neither positive semidefinite nor negative semidefinite. Therefore, it is neither convex nor concave.

However, the superlevel is:

$$\{x \in R_{++}^2 \mid \frac{x_1}{x_2} \geq \alpha\} = \{x \in R_{++}^2 \mid x_1 - \alpha x_2 \geq 0\}$$

the sublevel is:

$$\{x \in R_{++}^2 \mid \frac{x_1}{x_2} \leq \alpha\} = \{x \in R_{++}^2 \mid x_1 - \alpha x_2 \leq 0\}$$

Since they are all halfspaces therefore convex. Therefore,  $f(x)$  is both quasiconvex and quasiconcave.

#### 1.4.5 e

This is convex and quasiconvex, but not concave or quasiconcave. This is because:

$$\nabla^2 f(x) = \frac{2}{x_2} \begin{bmatrix} 1 & -\frac{x_1}{x_1 x_2} \\ -\frac{x_1}{x_1 x_2} & \frac{x_1}{x_2^2} \end{bmatrix} = \frac{2}{x_2} \begin{bmatrix} 1 \\ -\frac{x_1}{x_2} \end{bmatrix} \begin{bmatrix} 1 \\ -\frac{x_1}{x_2} \end{bmatrix}^T \succeq 0$$

Therefore,  $f(x)$  is convex and hence quasiconvex.

#### 1.4.6 f

This is concave and quasiconcave, but not convex or quasiconvex. This is because:

$$\begin{aligned} \nabla^2 f(x) &= \alpha(\alpha - 1)x_1^\alpha x_2^{1-\alpha} \begin{bmatrix} \frac{1}{x_1^2} & -\frac{1}{x_1 x_2} \\ -\frac{1}{x_1 x_2} & \frac{1}{x_2^2} \end{bmatrix} \\ &= \alpha(\alpha - 1)x_1^\alpha x_2^{1-\alpha} \begin{bmatrix} \frac{1}{x_1} \\ -\frac{1}{x_2} \end{bmatrix} \begin{bmatrix} \frac{1}{x_1} \\ -\frac{1}{x_2} \end{bmatrix}^T \preceq 0 \end{aligned}$$

Therefore,  $f(x)$  is concave and hence quasiconcave.

### 1.5 Prob 3.16

#### 1.5.1 a

We first determine the domain for  $y$  of the conjugate function.

$$f^*(y) = \sup_{x \in \text{dom} f} (y^T x - \max_{i=1, \dots, n} x_i) \quad (3)$$

First, let  $y \prec 0$ . Suppose  $x_j = -t$ ,  $x_i = 0$  for  $i \neq k$  and let  $t$  go to infinity, so that:

$$y^T x - \max_{i=1, \dots, n} x_i = -ty_j \rightarrow \infty$$

Therefore,  $y \prec 0$  is not in the domain  $\text{dom} f^*$ .

Let  $y \succeq 0$ . Let  $x = t\mathbf{1}$  and  $t$  go to infinity, we have,

$$y^T x - \max_{i=1, \dots, n} x_i = t\mathbf{1}^T y - t = (\mathbf{1}^T y - 1)t$$

Therefore, when  $\mathbf{1}^T y \neq 1$ , we always have  $y^T x - \max_{i=1, \dots, n} x_i \rightarrow \infty$  (Let  $x = -t\mathbf{1}$  when  $\mathbf{1}^T y < 1$ ). When  $\mathbf{1}^T y = 1$ , so that:

$$y^T x - \max_{i=1, \dots, n} x_i \leq 0 \text{ for all } x$$

When  $x = 0$ ,  $y^T x - \max_{i=1, \dots, n} x_i = 0$ . Therefore, we have

$$f^*(y) = \begin{cases} 0 & \text{if } y \succeq 0, \mathbf{1}^T y = 1 \\ \infty & \text{otherwise} \end{cases}$$

### 1.5.2 b

We first determine the domain for  $y$  of the conjugate function.

$$f^*(y) = \sup_{x \in \text{dom} f} (y^T x - \sum_{i=1}^r x_{[i]}) \quad (4)$$

First, let  $y \prec 0$ . Suppose  $x_j = -t$ ,  $x_i = 0$  for  $i \neq k$  and let  $t$  go to infinity, so that:

$$y^T x - \sum_{i=1}^r x_{[i]} = -ty_j \rightarrow \infty$$

Therefore,  $y \prec 0$  is not in the domain  $\text{dom} f^*$ .

Let  $y \succeq 0$ . Let  $x = t\mathbf{1}$  and  $t$  go to infinity, we have,

$$y^T x - \sum_{i=1}^r x_{[i]} = t\mathbf{1}^T y - tr = (\mathbf{1}^T y - r)t$$

Therefore, when  $\mathbf{1}^T y \neq r$ , we always have  $y^T x - \sum_{i=1}^r x_{[i]} \rightarrow \infty$  (Let  $x = -t\mathbf{1}$  when  $\mathbf{1}^T y < r$ ). When  $\mathbf{1}^T y = r$ , so that:

$$y^T x - \sum_{i=1}^r x_{[i]} \leq 0 \text{ for all } x$$

When  $x = 0$ ,  $y^T x - \sum_{i=1}^r x_{[i]} = 0$ . Therefore, we have

$$f^*(y) = \begin{cases} 0 & \text{if } y \succeq 0, \mathbf{1}^T y = r \\ \infty & \text{otherwise} \end{cases}$$

### 1.5.3 e

We first determine the domain for  $y$  of the conjugate function.

$$f^*(y) = \sup_{x \in \text{dom} f} (y^T x - (-\prod x_i)^{1/n}) \quad (5)$$

First, let  $y \succ 0$ . Suppose  $x_j = t$ ,  $x_i = 1$  for  $i \neq k$  and let  $t$  go to infinity, so that:

$$y^T x - (-\prod x_i)^{1/n} = ty_j + \sum_{i \neq j} y_i + t^{1/n} \rightarrow \infty$$

Therefore,  $y \succ 0$  is not in the domain  $\text{dom} f^*$ .

Let  $y \preceq 0$ . Let  $x_i = -\frac{t}{y_i}$  and  $t$  go to infinity, we have,

$$y^T x - (-\prod x_i)^{1/n} = -tn - t(-\prod (-\frac{1}{y_i}))^{1/n} = ((\prod (-\frac{1}{y_i}))^{1/n} - n)t$$

Therefore, when  $\prod (-y_i)^{1/n} \leq \frac{1}{n}$ , we always have  $y^T x - (-\prod x_i)^{1/n} \rightarrow \infty$ . When  $\prod (-y_i)^{1/n} \geq \frac{1}{n}$ , because  $x \in R_{++}^n$ , according to arithmetic-geometric mean inequality we have that:

$$-\frac{y^T x}{n} \geq (\prod_i (-y_i x_i))^{1/n} \geq \frac{1}{n} (\prod_i x_i)^{1/n}$$

Namely,  $y^T x - f(x) \leq 0$ . When  $x_i = -\frac{t}{y_i}$ ,  $y^T x - (-\prod x_i)^{1/n} = 0$ . Therefore, we have

$$f^*(y) = \begin{cases} 0 & \text{if } y \preceq 0, \prod (-y_i)^{1/n} \geq \frac{1}{n} \\ \infty & \text{otherwise} \end{cases}$$

## 1.6 Polyhedron

Let  $S = \{A, B, C, D, E, F\} = \{(-1, 2), (0, 3), (2, 0), (2, -2), (0, 0), (-1, 0)\}$ . According to Quickhull algorithm[2], ultimate points are  $A, B, C, D$  and  $F$ . So the polyhedron can be expressed as:

$$\begin{bmatrix} -1 & 1 \\ 3 & 2 \\ -2 & -3 \\ 1 & 0 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \preceq \begin{bmatrix} 3 \\ 6 \\ 2 \\ 2 \\ 1 \end{bmatrix}$$

## Bibliography

- [1] S. Boyd and L. Vandenberghe, *Convex optimization*. Cambridge university press, 2004.
- [2] Wikipedia, "Quickhull — wikipedia, the free encyclopedia," 2016. [Online; accessed 14-August-2016].