

# Ass3 Solutions

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## 1 Solutions

### 1.1 Prob 4.3

Because  $\nabla f(x) = \frac{1}{2}(P + P^T)x + q$ ,

$$\begin{aligned}\nabla f(x^*) &= \frac{1}{2} \left( \begin{bmatrix} 13 & 12 & -2 \\ 12 & 17 & 6 \\ -2 & 6 & 12 \end{bmatrix} + \begin{bmatrix} 13 & 12 & -2 \\ 12 & 17 & 6 \\ -2 & 6 & 12 \end{bmatrix} \right) \begin{bmatrix} 1 \\ \frac{1}{2} \\ -1 \end{bmatrix} + \begin{bmatrix} -22 \\ -14.5 \\ 13 \end{bmatrix} \\ &= \begin{bmatrix} 13 & 12 & -2 \\ 12 & 17 & 6 \\ -2 & 6 & 12 \end{bmatrix} \begin{bmatrix} 1 \\ \frac{1}{2} \\ -1 \end{bmatrix} + \begin{bmatrix} -22 \\ -14.5 \\ 13 \end{bmatrix} \\ &= \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}\end{aligned}$$

According to equation (4.21)[?], because for all  $y$  satisfying  $y_i \in [-1, 1]$ ,  $i = 1, 2, 3$ , the optimality condition holds:

$$\begin{aligned}\nabla f(x^*)^T(y - x^*) &= \begin{bmatrix} -1 & 0 & 2 \end{bmatrix} \begin{bmatrix} y_1 - 1 \\ y_2 - 1/2 \\ y_3 + 1 \end{bmatrix} \\ &= -1(y_1 - 1) + 2(y_3 + 1) \geq 0\end{aligned}$$

therefore,  $x^*$  is optimal for  $f(x)$ .

### 1.2 Prob 4.8

#### 1.2.1 a

The Lagrangian of the primal problem is:

$$\begin{aligned}L(x, v) &= c^T x + v^T (Ax - b) \\ &= -b^T v + (c + A^T v)x\end{aligned}$$

$L$  is bounded below if and only if  $c + A^T v = 0$ . Therefore, the primal problem's optimal value  $p^* = -b^T v$  for some  $v$  satisfying  $c + A^T v = 0$ . The primal problem is unbounded otherwise.

### 1.2.2 b

The problem is always feasible. The Lagrangian of the primal problem is:

$$\begin{aligned} L(x, v) &= c^T x + \lambda(a^T x - b) \\ &= -b\lambda + (c + a^T \lambda)x \end{aligned}$$

$L$  is bounded below if and only if  $c + a^T \lambda = 0$  and  $\lambda \geq 0$ . Therefore, the primal problem has optimal value  $p^* = -b\lambda$  for some  $\lambda$  satisfying  $c + a^T \lambda = 0$  and  $\lambda \geq 0$ . Otherwise the primal problem is unbounded below.

### 1.2.3 c

The objective function can be written as  $\sum_{i=1}^n c_i x_i$ . Therefore, the objective function reaches minimal when each of component  $c_i x_i$  is minimized subject to  $l_i \leq x_i \leq u_i$ .

Therefore, for all indices such that  $c_i > 0$  we have  $x_i = l_i$  and for all indices such that  $c_i < 0$  we have  $x_i = u_i$ . When  $c_i = 0$ ,  $x_i$  can be any value in the domain of the problem namely  $l_i \leq x_i \leq u_i$ .

### 1.2.4 d

The Lagrangian of the primal problem is:

$$\begin{aligned} L(x, v, \lambda) &= c^T x + v(1^T x - 1) - \lambda^T x \\ &= -v + (c^T + v - \lambda^T)x \end{aligned}$$

$L$  is bounded below if and only if  $c^T + v - \lambda^T = 0$  and  $\lambda \geq 0$ , namely  $-v < c_i \forall i$ . Therefore, the primal problem has optimal value  $p^* \geq -v$  for some  $\lambda$  satisfying  $\lambda \geq 0$  and for some  $v$  satisfying  $-v < c_i \forall i$ . Suppose  $c$  has minimal values  $c_{min}$  at indexes  $i, j, k, \dots$ , we can always get the optimal solution by setting  $x_i, x_j, x_k, \dots$  to  $\sum_{m=i, j, k, \dots} x_m = 1$  at those indexes and 0 at anywhere else. Therefore, we have  $p^* = c_{min}$ . Otherwise the primal problem is unbounded below.

When we use inequality constraint to replace the equality constraint, the optimal value is equal to  $p^* = \min\{0, c_{min}\}$ . This is because we can assign  $x$  as above if  $c_{min} < 0$  and  $x = 0$  otherwise.

### 1.2.5 e

Suppose the components of  $c$  are sorted in increasing order as:

$$c_1 \leq c_2 \leq \dots \leq c_\alpha \leq \dots \leq c_n$$

When  $\alpha$  is an integer, the primal problem has optimal value  $p^* = \sum_{i=1}^\alpha c_i$ , namely the smallest  $\alpha$  elements of  $c$  if and only if  $x_i = 1$  for  $i \leq \alpha$  and  $x_i = 0$  for  $i > \alpha$ .

If  $\alpha$  is not an integer, let  $[\alpha]$  denotes the nearest integer less than or equal to  $\alpha$ , the optimal value is

$$p^* = \sum_{i=1}^{[\alpha]} c_i + c_{1+[\alpha]}(\alpha - [\alpha])$$

by setting  $x_i = 1$  for  $i \leq [\alpha]$ ,  $x_{1+[\alpha]} = \alpha - [\alpha]$  and  $x_i = 0$  for  $i > 1 + [\alpha]$ .

If change the equality constraint to inequality constraint  $1^T x \leq \alpha$ , then the optimal value is

$$p^* = \begin{cases} \sum_{i=1}^{[\alpha]} c_i + c_{1+[\alpha]}(\alpha - [\alpha]) & \text{if } c_{1+[\alpha]} < 0 \\ \sum_{i=1}^j c_i & \text{if } c_j + 1 \geq 0 \text{ and } j < 1 + [\alpha] \\ 0 & \text{if } c_1 > 0 \end{cases}$$

We can always get this by setting:

$$x_i = \begin{cases} 0 & c_i \geq 0 \\ 1 & c_i < 0 \end{cases} \text{ for } i \leq [\alpha]$$

$$x_{1+[\alpha]} = \begin{cases} \alpha - [\alpha] & \text{if } c_{1+[\alpha]} < 0 \\ 0 & \text{otherwise} \end{cases}$$

and  $x_i = 0$  for  $i > [\alpha] + 1$ .

### 1.2.6 f

Let  $y_i = d_i x_i$  for  $i = 1, \dots, n$  and use  $y$  to substitute  $x$  in the original problem. Then we have:

$$\begin{aligned} & \text{minimize } \sum_{i=1}^n \frac{c_i}{d_i} y_i \\ & \text{s.t. } 1^T y = \alpha, \quad 0 \preceq y \preceq d. \end{aligned}$$

This formulation is similar to section 1.2.5. Suppose the components of  $\frac{c_i}{d_i}$  are sorted in increasing order as:

$$\frac{c_1}{d_1} \leq \dots \leq \frac{c_\alpha}{d_\alpha} \leq \dots \leq \frac{c_n}{d_n}$$

Let  $k^* = \operatorname{argmax}_k d_1 + \dots + d_k \leq \alpha$ , the primal problem reaches optimal value  $p^* = \sum_{i=1}^{k^*} c_i + \frac{c_{k^*+1}}{d_{k^*+1}}(\alpha - (d_1 + \dots + d_{k^*}))$  by setting  $y_i = d_i$  for  $i \leq k^*$ ,  $y_{k^*+1} = \alpha - (d_1 + \dots + d_{k^*})$  and  $y_i = 0$  for  $i > k^* + 1$ .

Namely by setting  $x_i = 1$  for  $i \leq k^*$ ,  $x_{k^*+1} = \frac{\alpha - (d_1 + \dots + d_{k^*})}{d_{k^*+1}}$  and  $x_i = 0$  for  $i > k^* + 1$ .

### 1.3 Prob 4.9

### 1.4 Prob 4.47

### 1.5 Prob 5.12

### 1.6 Prob 5.31