

EDUCATION

Australia National University , Canberra, ACT, Australia	Jul. 2016 – Present
Master of Computing (Advanced), Artificial Intelligence	GPA: 6.875/7.0
<i>Advisor: Marine-Andrei Rizoïu</i>	
– Core courses: Statistical Machine Learning, Document Analysis, Computer Vision, Algorithms, Research Project	
Purdue University , West Lafayette, IN, US	Aug. 2015 – Dec. 2015
Exchange Student	GPA: 4.0/4.0
– Anticipated courses: Introduction To Discrete Mathematics, Numerical Analysis, International GEARE Project, Fundamentals Of Wind Energy	
Shanghai Jiao Tong University , Shanghai, China	Sept. 2012 – Jul. 2016
Bachelor of Engineering , Mechanical Engineering	GPA: 3.7/4.3
<i>Advisor: Chenkun Qi</i>	
– Core courses: Robotics, Theoretical Mechanics, Mathematical Methods in Physics, Probability and Statistics, Mechanics of Material, Engineering Thermodynamics, Engineering Fluid Mechanics, Heat Transfer	

SKILLS

Programming Languages – C++, Python, Java, R, MATLAB, JavaScript

RESEARCH EXPERIENCE

Graduate Research Assistant , <i>Computational Media Lab (ANU)</i>	Jun. 2017 – Present
<i>Advisor: Marine-Andrei Rizoïu (ANU)</i>	
Learning Non-parametric Triggering Kernels of Hawkes Point Processes	
– <i>Point Process</i> : Using non-parametric models, including Neural Network and Gaussian Process, as the triggering kernel of Hawkes Point Process to improve its fitting capacity.	
Graduate Research Assistant , <i>Computational Media Lab (ANU)</i>	Sept. 2016 – Present
<i>Advisor: Marine-Andrei Rizoïu (ANU)</i>	
Uncovering Social Links through Stochastic Point Processes	
– <i>Point Process</i> : Combine EM algorithm with Hawkes Point Processes to establish the probabilistic social network	
Undergraduate Research Assistant , <i>Mechanism and Robotic Equipment Institute (SJTU)</i>	Aug. 2015 – Jun. 2016
<i>Advisor: Chenkun Qi (SJTU)</i>	
Distortion Compensation for a Ground-based Semi-physical Simulation System for Space Collision	
– <i>System Modelling and Simulation</i> : Model semi-physical simulation system and design compensation algorithm.	
Undergraduate Research Assistant , <i>Biomechatronics and Biorobotics Laboratory(SJTU)</i>	Sept. 2014 – Apr. 2015
<i>Advisor: Dingguo Zhang (SJTU)</i>	
Controlled a Cockroach to Move Right or Left by Microstimulation of its Antenna Nerves.	
– <i>Bio-robot</i> : Use the existing chip to connect the human brain with a cockroach to control the motion of the latter	

PROFESSIONAL EXPERIENCE

Robot Motion Planning and Control Intern	Apr. 2015 – Aug. 2015
<i>Mechanism and Robotic Equipment Institute (SJTU)</i>	
Did kinematic and dynamic analysis of four-legged robots and simulated their running gaits by MATLAB.	

HONORS

Outstanding Graduate of Shanghai Jiao Tong University	2016
<i>by Shanghai Jiao Tong University</i>	
Dean's List & Semester Honors	2016
<i>by College of Engineering, Purdue</i>	
Excellent Undergraduate International Exchange Program Scholarship	2015
<i>by China Scholarship Council</i>	
Academic Excellence Scholarship (Second-Class) of Shanghai Jiao Tong University	2014
<i>by Shanghai Jiao Tong University</i>	
Academic Excellence Scholarship (Third-Class) of Shanghai Jiao Tong University	2013
<i>by Shanghai Jiao Tong University</i>	

PATENT

Rui Zhang; Fenghe Tang; Jianqiu Huang; Guilong Li; Yihan Fu. **Simple Waste Gel Ink Pen Refill Treatment Machine**, 2016, National Invention Patent. China Patent No. CN104325811B.