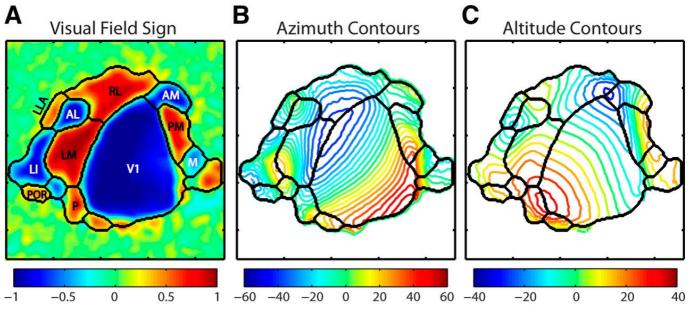
# autoRM: an Automatic Retinotopic Mapping Tool for Mice

version 1.0

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**autoRM** provides a fully automatic tool for mice retinotopic mapping. It can help you to locate the primary and several higher-order visual cortex of mice with calcium or optical imaging (figure from ref [1]).



# What you need to use autoRM

- 1. **Psychopy3** (>=2020.1.3) to present visual stimulus
- 2. NI-DAQ USB-6501 digital I/O Device and NI-DAQmx driver for synchronization
- 3. MATLAB (>=2019a) with image processing toolbox

## The content of autoRM

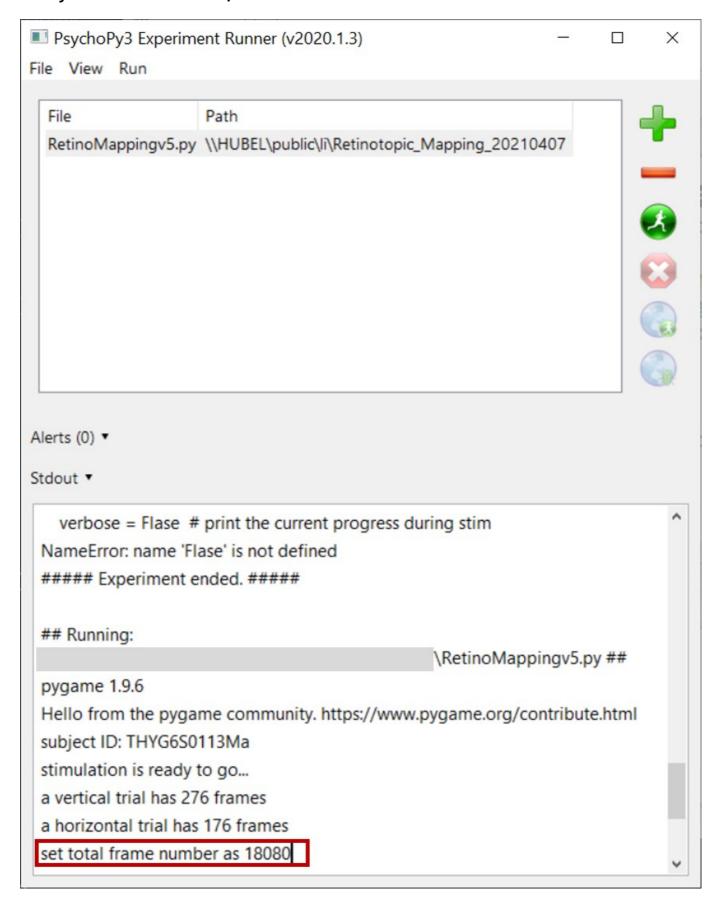
- RetinotopicMappingv5.py is a Python script to present visual stimulus for retinotopic mapping, a typical experiment last about 30 minutes.
- RMDegMap.m is a MATLAB function to calculate visual degree, naming azimuth and elevation.
- RMSetParam.m is a MATLAB app helps you to determine parameters used in RMAreaMAp.m.
- RMAreaMap.m is a MATLAB function to identify visual areas, see ref [2] for details.
- autoRM.m is *the MATLAB function you use*, it calls RMDegMap RMSetParam and RMAreaMap, usually you don't need to use other functions.

#### How to use

1. MATLAB image processing toolbox is required.

2. Run RetinotopicMappingv5.py with psychopy3 before start recording. Recommend using a NI-DAQ digital I/O device to synchronize your camera with the visual stimulus.

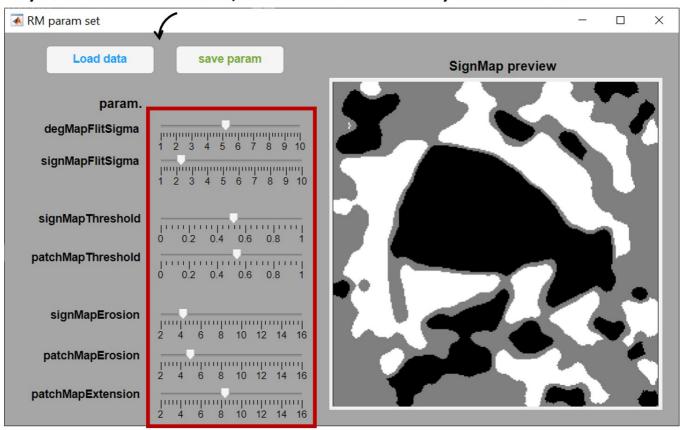
3. The Python program will return the frame number required for recording. **Set the frame number in your camera control interface.** 



4. After stimulus finish, RetinotopicMappingv5.py will save a txt log file and a json configuration file. *The json file is required in the following steps.* 

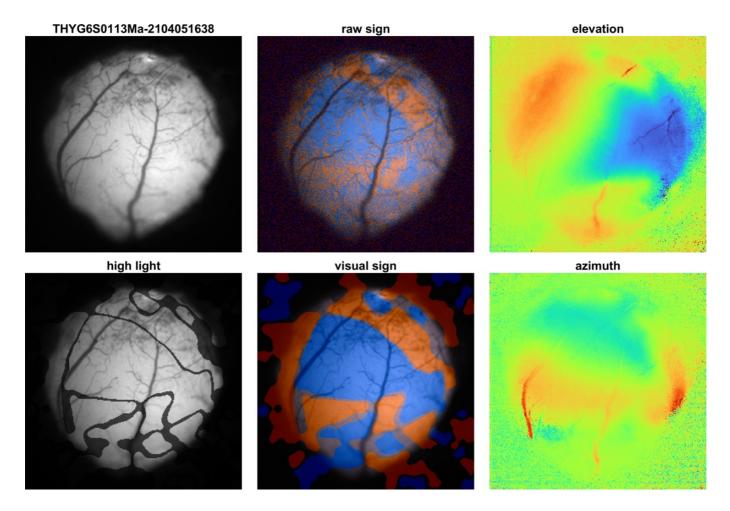
- 5. Convert your recording data into .mat data.
- 6. Add RMDegMap.m, RMSetParam.m and RMAreaMap.m to your MATLAB path, then call autoRM in MATLAB command window and follow the instructions to select recording data .mat file and .json configration files.
- 7. A GUI will pop-up for you to adjust parameters.

## If you use autoRM function, data will be automatically loaded and saved



Adjust parameters by looking at the figure. Close the window when finished.

8. autoRM will create a figure for you at the path of .json config file. This figure can be used as retinotopic mapping reference for your subsequential experiments.



# Inputs and outputs

autoRM need the following input to work

- XYT image data: the image data for analysis
- configuration json file: the json file generated by RetinotopicMappingv5.py, which contains
  experiment configurations for data process.

## autoRM save the following data

#### degMap mat file contains the following data

- FOV: a image of field of view
- dataL2R, dataR2L: trial average data of left to right and right to left
- dataD2U, dataU2D: trial average data of down to up and up to down
- phaseMaps: phase maps of trial average data obtained from FFT.
- degMaps: degree maps connect visual areas with visual field.
- degMapAzi: azimuth map. Here assume the azimuth at front of mouse is 0. Azimuth usually ranges from 0 to 120 degree.
- degMapElv: elevation map. Here assume the elevation at front of mouse is 0. Elevation ususally ranges from -40 to 40 degree.

#### areaMap mat file contains the following data

- rSignMap: raw sign map calculated from degMapAzi and degMapElv
- signMap: sign map after image process to reduce noise and artifacts.
- areaMap: a bit map indicate visal areas.
- signFOV: align sign map to FOV.
- hltFOV: high light visual areas in FOV.

## autoRM save 2 figures

# **Endnote**

#### References:

- [1] Marshel, James H., et al. "Functional specialization of seven mouse visual cortical areas." Neuron 72.6 (2011): 1040-1054.
- [2] Juavinett, Ashley L., et al. "Automated identification of mouse visual areas with intrinsic signal imaging." Nature protocols 12.1 (2017): 32.
- [3] Zhuang, Jun, et al. "An extended retinotopic map of mouse cortex." Elife 6 (2017): e18372.