ECC2025: Simulation Parameters

1

Ruixuan Zhao, Guitao Yang, Thomas Parisini, and Boli Chen

This is a supplementary document for the conference paper "Distributed Unknown Input Observer Design with Relaxed Conditions" published in European Control Conference 2025.

	$oldsymbol{f 0}_{3 imes 1}$	$0_{3\times 1}$	$0_{3\times}$	1 <b>0</b> <sub>3&gt;</sub>	$0_{3\times 1}$	$0_{3\times 1}$	$0_{3\times 1}$	$0_{3  imes 1}$	$0_{3 imes 1}$
$W_{g,1}^* =$	0	0	0	-	1 0	0	0	0	0
	0	0.0350	0	0	0	0	0	0.9994	0
	0	-0.999	4 0	0	0	0	0	0.0350	0
	0	0	0	0	0	1	0	0	0
	0	0	0.035	50 0	0	0	-0.9994	0	0
	0	0	-0.99	994 0	0	0	-0.0350	0	0
	0	0	0	0	1	0	0	0	0
	0.0350	0	0	0	0	0	0	0	0.9994
	[-0.9994]	0	0	0	0	0	0	0	0.0350
	_								٦
$W_{g,2}^* = 1$	0	0	0	0.0030	-0.0008	-1	0	0	0
	0	0	0.0350	0	0	0	0.9988	0.0096	0.0333
	0	0	-0.9994	0	0	0	0.0350	0.0003	0.0012
	$0_{3 imes 1}$	$0_{3\times1}$	$0_{3\times 1}$	$0_{3\times 1}$	$0_{3\times 1}$	$0_{3\times1}$	$0_{3\times 1}$	$0_{3\times 1}$	$0_{3 imes 1}$
	0	0	0	0.0705	0.9975	-0.0000	6 0	0	0
	0	-0.0350	0	0	0	0	-0.0347	0.2764	0.9598
	0.0006	0.9994	0	0	0	0	-0.0012	0.0097	0.0336
	0	0	0	0.9975	-0.0705	6 0.0030	0	0	0
	-0.0350	0	0	0	0	0	0	-0.9604	1 0.2766
	0.9994	-0.0006	0	0	0	0	0	-0.0337	7 0.0097

October 31, 2024 DRAFT

October 31, 2024 DRAFT

 $L_4^{\top} = \begin{bmatrix} \mathbf{0}_{1 \times 9} & -5.9980 & -0.7597 & 6.1126 \\ \mathbf{0}_{1 \times 9} & -1.0108 & 2.2837 & -67.6448 \end{bmatrix}.$