1 Array Based on Tree

An Array Based on Tree (ABT) is a data structure that represents an array in the form of a self-balancing binary tree that maintains a balance between the size of its left and right subtrees. Unlike binary search tree that sort nodes based on their key values, ABT maintains the insertion order of elements. ABT not only has the ability of random access but also has the ability of dynamic editing. The time complexity of its random access, insertion, and deletion operations is O(log n).

1.1 Applicability

Array and list are two common data structures. Array allow random access to elements in O(1) time, while list allow insertion and deletion of elements in O(1) time. However, sometimes we need a data structure that combines the advantages of both array and list. As a result, the concept of an Array Based on Tree was invented. ABT balances the performance of random access, insertion, and deletion operations well, making it suitable for application scenarios that require both random access and dynamic editing.

1.2 Properties

An Array Based on Tree is a data structure based on a non-sorted binary tree and has the following properties:

- (1) The size of the left child node is not less than the sizes of its two nephew nodes.
- (2) The size of the right child node is not less than the sizes of its two nephew nodes.
- (3) Both left and right subtrees are ABTs.

Consider the following example where T is the node of ABT, L and R are its child nodes, A, B, C, and D are subtrees that also satisfy the above properties of ABT.

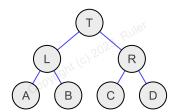


Figure 1.2 Array Based on Tree

According to the properties of ABT, the node T must satisfy:

- (1) size(L) > = max(size(C), size(D))
- (2) size(R) >= max(size(A), size(B))

1.3 Node

The node of ABT include a parent node, two child nodes, and the size of nodes in the subtree

where the node is located.

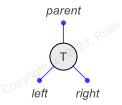


Figure 1.3 Node

The C++code for node definition is as follows:

```
template <class T>
   struct ab_tree_node
2.
3.
4.
      using node_type
                               = ab_tree_node<T>;
      using node_pointer
5.
                               = node_type*;
6.
      using const_node_pointer = const node_type*;
      using node_reference = node_type&;
7.
8.
      using const_node_reference = const node_type&;
9.
10.
      node_pointer
                                parent;
11.
      node_pointer
                                left;
12.
      node_pointer
                                right;
13.
      size_t
                                size;
14.
      Т
                                data;
15. };
```

1.4 Rotations

Like other self-balancing binary search trees, rotation operations are necessary to restore balance when inserting or deleting nodes causes the Size-Balanced Tree to become unbalanced.

Common rotation operations include left rotation and right rotation, which can be achieved by exchanging the position of nodes and subtrees. The following describes the operation process of left and right rotation.

1.4.1 Left rotation

The left rotation is used to make the right child node R of node T become its parent node and make the left child node A of its right child node R become its right child node. This operation makes the original node T become the left child node of its right child node R, thereby maintaining the balance of the binary tree.

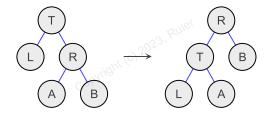


Figure 1.4.1 Left rotation

The C++ code for left rotation is as follows:

```
1.
    node_pointer left_rotate(node_pointer t)
2.
3.
      node_pointer r = t->right;
4.
      t->right = r->left;
5.
      if (r->left)
           r->left->parent = t;
6.
7.
      r->parent = t->parent;
8.
      if (t == header->parent)
           header->parent = r;
9.
10.
      else if (t == t->parent->left)
11.
           t->parent->left = r;
12.
      else
13.
           t->parent->right = r;
14.
      r\rightarrow left = t;
      r->size = t->size;
15.
16.
      t->parent = r;
      t->size = (t->left ? t->left->size : 0) + (t->right ? t->right->size : 0) + 1;
17.
18.
      return r;
19. }
```

1.4.2 Right rotation

The right rotation is similar to the left rotation but in the opposite direction. The right rotation is used to make the left child node L of node T become its parent node and make the right child node B of its left child node L become its left child node. This operation makes the original node T become the right child node of its left child node L, thereby maintaining the balance of the binary tree.

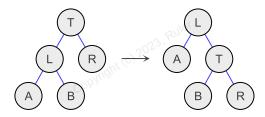


Figure 1.4.2 Right rotation

The C++ code for right rotation is as follows:

```
node_pointer right_rotate(node_pointer t)
    {
2.
      node pointer 1 = t->left;
3.
4.
      t->left = 1->right;
5.
      if (1->right)
           1->right->parent = t;
6.
      1->parent = t->parent;
7.
8.
      if (t == header->parent)
           header->parent = 1;
9.
      else if (t == t->parent->right)
10.
           t->parent->right = 1;
11.
12.
      else
13.
           t->parent->left = 1;
14.
      1-right = t;
      1->size = t->size;
15.
16.
      t->parent = 1;
      t->size = (t->left ? t->left->size : 0) + (t->right ? t->right->size : 0) + 1;
17.
18.
      return 1;
19. }
```

1.5 Rebalancing

After insertion or deletion in ABT, the properties of ABT may be violated, and it is necessary to rebalance the ABT rooted at node T. The prerequisite is that the child nodes of T are already ABTs themselves. There are four cases to consider when rebalancing:

(1) size(T.left) < size(T.right.left)

It may occur when inserting a node into the right child of T or deleting a node from the left child of T. First, perform a right rotation on the right child node of T, and then perform a left rotation on T. Now, the subtrees A, B, D, E, F, and L still satisfy the properties of ABT, while the left subtree T and the right subtree R may violate the properties of ABT. For the left subtree T, due to the decrease in nodes of its right subtree, it may occur that size(T.right) < size(T.left.child), which requires rebalancing. For the right subtree R, due to the decrease in nodes of its left subtree, it may occur that size(R.left) < size(R.right.child), which requires rebalancing. Finally, rebalance node C and its ancestor nodes one by one until reaching the root node.

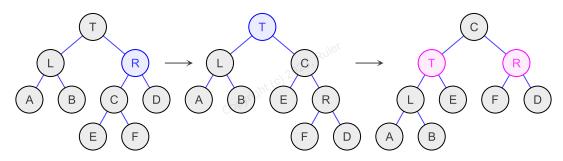


Figure 1.5-1 Case 1

(2) size(T.left) < size(T.right.right)

It may occur when inserting a node into the right child of T or deleting a node from the left child of T. After performing a left rotation on T, the subtree A, B, C, D, E, F, and L still satisfy the properties of ABT. However, due to the decrease in nodes of the right subtree of T, it may occur that size(T.right) < size(T.left.child), which requires rebalancing. Finally, rebalance node R and its ancestor nodes one by one until reaching the root node.

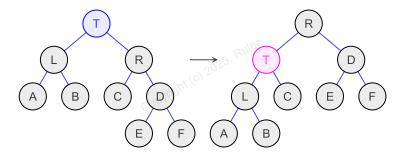


Figure 1.5-2 Case 2

(3) size(T.right) < size(T.left.right)

It may occur when inserting a node into the left child of T or deleting a node from the right child of T. First, perform a left rotation on the left child node of T, and then perform a right rotation on T. Now, the subtrees A, C, D, E, F, and R still satisfy the properties of ABT, while the left subtree L and the right subtree T may violate the properties of ABT. For the left subtree L, due to the decrease in nodes of its right subtree, it may occur that size(L.right) < size(L.left.child), which requires rebalancing. For the right subtree T, due to the decrease in nodes of its left subtree, it may occur that size(T.left) < size(T.right.child), which requires rebalancing. Finally, rebalance node B and its ancestor nodes one by one until reaching the root node.

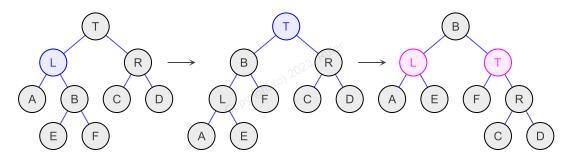


Figure 1.5-3 Case 3

(4) size(T.right) < size(T.left.left)

It may occur when inserting a node into the left child of T or deleting a node from the right child of T. After performing a right rotation on T, the subtrees A, B, C, D, E, F, and R still satisfy the properties of ABT. However, due to the decrease in nodes of the left subtree of T, it may occur that size(T.left) < size(T.right.child), which requires rebalancing. Finally, rebalance node L and its

ancestor nodes one by one until reaching the root node.

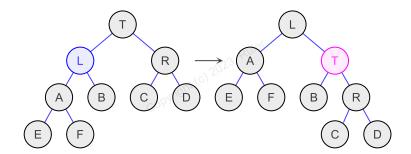


Figure 1.5-4 Case 4

The C++ code for rebalancing after inserting a node into the child node of T is as follows:

```
1.
    node_pointer insert_rebalance(node_pointer t, bool flag)
2.
    {
      if (flag)
3.
4.
5.
           if (t->right)
6.
           {
               size_type left_size = t->left ? t->left->size : 0;
7.
8.
               // case 1: size(T.left) < size(T.right.left)</pre>
               if (t->right->left && left_size < t->right->left->size)
9.
10.
               {
                    t->right = right_rotate(t->right);
11.
12.
                    t = left_rotate(t);
                    t->left = insert_rebalance(t->left, false);
13.
                    t->right = insert rebalance(t->right, true);
14.
                    t = insert_rebalance(t, true);
15.
16.
               }
               // case 2. size(T.left) < size(T.right.right)</pre>
17.
               else if (t->right->right && left_size < t->right->right->size)
18.
19.
               {
20.
                    t = left_rotate(t);
                    t->left = insert rebalance(t->left, false);
21.
22.
                    t = insert_rebalance(t, true);
23.
               }
24.
           }
25.
      }
26.
      else
27.
      {
28.
           if (t->left)
29.
30.
               size_type right_size = t->right ? t->right->size : 0;
31.
               // case 3. size(T.right) < size(T.left.right)</pre>
               if (t->left->right && right size < t->left->right->size)
32.
33.
34.
                    t->left = left_rotate(t->left);
35.
                    t = right_rotate(t);
```

```
36.
                    t->left = insert_rebalance(t->left, false);
                    t->right = insert rebalance(t->right, true);
37.
                    t = insert_rebalance(t, false);
38.
39.
               }
               // case 4. size(T.right) < size(T.left.left)</pre>
40.
               else if (t->left->left && right_size < t->left->left->size)
41.
42.
               {
43.
                    t = right_rotate(t);
                    t->right = insert rebalance(t->right, true);
44.
45
                    t = insert_rebalance(t, false);
46.
               }
           }
47.
48.
      }
49.
      return t;
50. }
```

The C++ code for rebalancing after deleting a node from the child node of T is as follows:

```
1.
    node_pointer erase_rebalance(node_pointer t, bool flag)
2.
    {
3.
      if (!flag)
4.
      {
           if (t->right)
5.
6.
7.
               size_type left_size = t->left ? t->left->size : 0;
8.
               // case 1: size(T.left) < size(T.right.left)</pre>
               if (t->right->left && left_size < t->right->left->size)
9.
10.
11.
                    t->right = right_rotate(t->right);
                    t = left rotate(t);
12.
13.
                    t->left = erase_rebalance(t->left, true);
14.
                    t->right = erase_rebalance(t->right, false);
                    t = erase_rebalance(t, false);
15.
16.
               // case 2. size(T.left) < size(T.right.right)</pre>
17.
18.
               else if (t->right->right && left_size < t->right->right->size)
19.
20.
                    t = left_rotate(t);
                    t->left = erase_rebalance(t->left, true);
21.
                    t = erase_rebalance(t, false);
22.
23.
               }
           }
25.
      }
26.
      else
27.
           if (t->left)
28.
29.
               size_type right_size = t->right ? t->right->size : 0;
30.
31.
               // case 3. size(T.right) < size(T.left.right)</pre>
               if (t->left->right && right_size < t->left->right->size)
```

```
33.
               {
34.
                    t->left = left_rotate(t->left);
35.
                    t = right_rotate(t);
                    t->left = erase_rebalance(t->left, true);
36.
                    t->right = erase_rebalance(t->right, false);
37.
38.
                    t = erase_rebalance(t, true);
39.
               }
               // case 4. size(T.right) < size(T.left.left)</pre>
40.
               else if (t->left->left && right size < t->left->left->size)
41.
42.
43.
                    t = right_rotate(t);
                    t->right = erase_rebalance(t->right, false);
44.
45.
                    t = erase_rebalance(t, true);
46.
               }
47.
           }
48.
      }
49.
      return t;
50. }
```

1.6 Insertion

If the ABT is empty, directly add the node as the root node. Otherwise, it can be divided into the following two cases based on the situation of inserting child nodes of node T:

(1) Node T does not have a left child node.

In this case, insert the node directly into the left subtree of node T. The node counts of its ancestor nodes should all be incremented by 1. The above-mentioned case 3 or case 4 may occur, so it is necessary to rebalance node T.

(2) Node T has a left child node.

In this case, select the last node in its left subtree as the actual insertion node X. Insert into the right subtree of node X, and the node counts of its ancestor nodes should all be incremented by 1. The above-mentioned case 1 or case 2 may occur, so it is necessary to rebalance node X.

The C++ code for the insertion operation is as follows:

```
template<class ...Args>
2.
   node_pointer insert_node(node_pointer t, Args&&... args)
3.
4.
      // creates a new node
5.
      node_pointer n = this->create_node(std::forward<Args>(args)...);
6.
      n->left = nullptr;
7.
      n->right = nullptr;
8.
      n \rightarrow size = 1;
9.
      if (t == header)
10.
11.
           // if the tree is empty
12.
           if (!header->parent)
```

```
13.
           {
14.
               // inserts the node
15.
               n->parent = t;
               header->parent = n;
16.
17.
               header->left = n;
18.
               header->right = n;
19.
          }
          else
20.
21.
          {
22.
               t = header->right;
23.
               // inserts the node
24.
               n->parent = t;
25.
               t->right = n;
26.
               header->right = n;
               // increases the size of nodes
27.
28.
               for (node_pointer p = t; p != header; p = p->parent)
29.
                   ++p->size;
30.
               do
31.
               {
                   // rebalance after insertion
32.
33.
                   t = insert_rebalance(t->parent, t == t->parent->right);
34.
               } while (t->parent != header);
35.
          }
      }
36.
      else if (t->left)
37.
38.
39.
          t = t->left;
40.
          while (t->right)
41.
               t = t->right;
42.
          // inserts the node
43.
          n->parent = t;
44.
          t->right = n;
45.
          // increases the size of nodes
46.
          for (node_pointer p = t; p != header; p = p->parent)
47.
               ++p->size;
48.
          do
49.
           {
               // rebalance after insertion
50.
               t = insert_rebalance(t->parent, t == t->parent->right);
51.
52.
          } while (t->parent != header);
      }
53.
      else
54.
55.
      {
56.
          // inserts the node
          n->parent = t;
57.
          t->left = n;
58.
59.
          if (t == header->left)
60.
               header->left = n;
          // increases the size of nodes
61.
```

```
62.
           for (node_pointer p = t; p != header; p = p->parent)
63.
               ++p->size;
           do
64.
65.
           {
               // rebalance after insertion
66.
               t = insert rebalance(t->parent, t == t->parent->right);
67.
68.
           } while (t->parent != header);
      }
69.
      return n;
70.
71. }
```

1.7 Deletion

Assuming the node to be deleted is T, it can be divided into the following two cases based on the number of child nodes of node T:

(1) Node T has at most one child node.

In this case, the node T can be deleted directly. The number of nodes of its ancestor nodes should be reduced by 1. If node T has a child node L or R, replace node T with its child node. Finally, rebalance the parent node of node T.

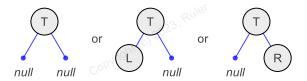


Figure 1.7-1 Case 1

(2) Node T has two child nodes.

In this case, the node T cannot be deleted directly, otherwise the entire tree will be destroyed. When the number of nodes in the left subtree of node T is less than the number of nodes in the right subtree, select the node with the minimum value in its right subtree as the actual deletion node X; otherwise, select the node with the maximum value in its left subtree as the actual deletion node X. Then swap the positions of node T and node X, and it is completely the same as the first case.

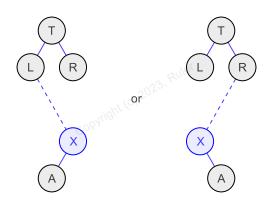


Figure 1.7-2 Case 2

The C++ code for the deletion operation is as follows:

```
    void erase_node(node_pointer t)

2. {
3.
      bool flag;
4.
      node_pointer x;
5.
      node pointer parent;
      // case 1. has one child node at most
6.
7.
      if (!t->left || !t->right)
8.
9.
          x = t \rightarrow left ? t \rightarrow left : t \rightarrow right;
10.
          // the rebalance flag
11.
          flag = (t == t->parent->right);
12.
          // removes t node
13.
          if (x)
14.
               x->parent = t->parent;
15.
          if (t == header->parent)
16.
               header->parent = x;
17.
           else if (t == t->parent->left)
18.
               t->parent->left = x;
19.
           else
20.
               t->parent->right = x;
21.
           if (t == header->left)
               header->left = x ? leftmost(x) : t->parent;
22.
23.
          if (t == header->right)
24.
               header->right = x ? rightmost(x) : t->parent;
          // reduces the number of nodes
25.
          for (node pointer p = t->parent; p != header; p = p->parent)
26.
27.
               --p->size;
           // rebalance after deletion
28.
29.
          if (t != header)
30.
               node_pointer p = erase_rebalance(t->parent, flag);
31.
               while (p != header)
32.
                    p = erase rebalance(p->parent, p == p->parent->right);
33.
34.
           }
35.
      // case 2. has two child nodes
36.
37.
      else
38.
39.
           if (t->left->size < t->right->size)
40.
           {
41.
               x = leftmost(t->right);
42.
               // the rebalance flag
43.
               flag = (x == x->parent->right);
44.
               // reduces the number of nodes
45.
               for (node pointer p = x->parent; p != header; p = p->parent)
                    --p->size;
```

```
47.
               // replaces t node with x node and removes t node
48.
               t->left->parent = x;
49.
               x->left = t->left;
               if (x != t->right)
50.
51.
52.
                   x->parent->left = x->right;
53.
                   if (x->right)
54.
                        x->right->parent = x->parent;
55.
                   t->right->parent = x;
56.
                   x->right = t->right;
57.
                   parent = x->parent;
58.
               }
59.
               else
60.
                   parent = x;
61.
               if (t == header->parent)
                   header->parent = x;
62.
63.
               else if (t == t->parent->left)
64.
                   t->parent->left = x;
65.
               else
66.
                   t->parent->right = x;
67.
               x->parent = t->parent;
68.
               x->size = t->size;
69.
           }
70.
          else
71.
          {
72.
               x = rightmost(t->left);
73.
               // the rebalance flag
74.
               flag = (x == x->parent->right);
75.
               // reduces the number of nodes
76.
               for (node_pointer p = x->parent; p != header; p = p->parent)
77.
                    --p->size;
78.
               // replaces t node with x node and removes t node
79.
               t->right->parent = x;
80.
               x->right = t->right;
81.
               if (x != t->left)
82.
83.
                   x->parent->right = x->left;
84.
                   if (x->left)
85.
                        x->left->parent = x->parent;
86.
                   t->left->parent = x;
                   x->left = t->left;
87.
88.
                   parent = x->parent;
89.
               }
90.
               else
91.
                   parent = x;
92.
               if (t == header->parent)
93.
                   header->parent = x;
94.
               else if (t == t->parent->left)
                   t->parent->left = x;
95.
```

```
96.
              else
97.
                   t->parent->right = x;
98.
              x->parent = t->parent;
99.
              x->size = t->size;
100.
          }
101.
          // rebalance after deletion
          node_pointer p = erase_rebalance(parent, flag);
102.
103.
          while (p != header)
              p = erase_rebalance(p->parent, p == p->parent->right);
104.
105. }
106. // destroy node
107. destroy_node(t);
108.}
```

1.8 Selection

The select operation provides random access function in ABT.

The C++ code for the insertion operation is as follows:

```
1. node_pointer select_node(size_type k)
2. {
      node_pointer t = header->parent;
3.
      while (t)
4.
5.
6.
           size_type left_size = t->left ? t->left->size : 0;
7.
           if (left_size < k)</pre>
8.
           {
9.
               t = t->right;
               k -= (left_size + 1);
10.
11.
           }
12.
           else if (k < left_size)</pre>
13.
               t = t->left;
14.
           else
15.
               return t;
16.
      }
17.
      return header;
18. }
```