

MODULE 1: BASIC STRUCTURE OF COMPUTERS

BASIC CONCEPTS

- **Computer Architecture (CA)** is concerned with the structure and behaviour of the computer.
- CA includes the information formats, the instruction set and techniques for addressing memory.
- In general covers, CA covers 3 aspects of computer-design namely: 1) Computer Hardware, 2) Instruction set Architecture and 3) Computer Organization.

1. Computer Hardware

- It consists of electronic circuits, displays, magnetic and optical storage media and communication facilities.

2. Instruction Set Architecture

- It is programmer visible machine interface such as instruction set, registers, memory organization and exception handling.
- Two main approaches are 1) CISC and 2) RISC.
(CISC→Complex Instruction Set Computer, RISC→Reduced Instruction Set Computer)

3. Computer Organization

- It includes the high level aspects of a design, such as
 - memory-system
 - bus-structure &
 - design of the internal CPU.
- It refers to the operational units and their interconnections that realize the architectural specifications.
- It describes the function of and design of the various units of digital computer that store and process information.

Q. With a neat diagram describe the functional units of a computer. Give few examples for I/O devices (6 M)

Q.Explain the operation of computer with neat block diagram (10 M)

FUNCTIONAL UNITS

- A computer consists of 5 functionally independent main parts:

- 1) Input
- 2) Memory
- 3) ALU
- 4) Output &
- 5) Control units.

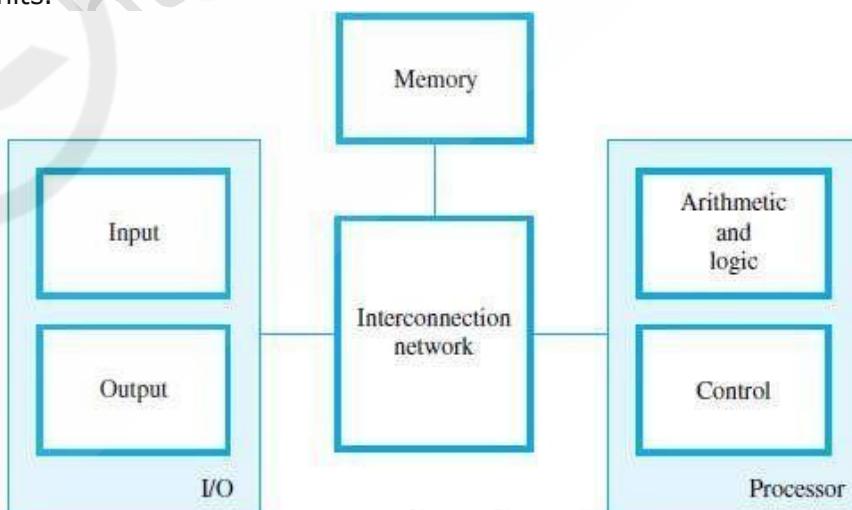


Figure 1.1 Basic functional units of a computer.

Input unit:- Computers accept coded information through input units, which read the data. Whenever a key is pressed, corresponding character or number is translated into its equivalent binary code over a cable & fed either to memory or processor.
Ex: Keyboard, Joysticks, trackballs, mouse, scanners etc are other input devices.

Output unit:- Its basic function is to send the processed results to the outside world.
Examples:- Printer, speakers, monitor etc.

Memory unit: - Its function is to store programs and data. It is basically of two types
1. Primary memory 2. Secondary memory

1. **Primary memory:** - The programs which has to be executed must be stored in this memory. Each memory location stores data in it. Each memory location is identified by its address.
Examples:- RAM, ROM, CACHE etc..

2 **Secondary memory:** - It is used where large amounts of data & programs have to be stored, particularly information that is accessed infrequently.
Examples: - Magnetic disks & tapes, optical disks (ie CD-ROM's), floppies etc.,

Arithmetic logic unit (ALU):- This unit performs arithmetic operations like addition, subtraction, division, multiplication and logical operations like not, and, or, xor etc. on the operands(data) that are brought into the ALU from memory. Then according to the instructions the operation is performed in the required sequence.

Control unit:- The actual timing signals that govern the transfer of data between input unit, processor, memory and output unit are generated by the control unit.

BASIC OPERATIONAL CONCEPTS

- An Instruction consists of 2 parts, 1) Operation code (Opcode) and 2) Operands.

OPCODE	OPERANDS
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- The data/operands are stored in memory.
- The individual instruction are brought from the memory to the processor.
- Then, the processor performs the specified operation.
- Let us see a typical instruction
ADD LOCA, R0
- This instruction is an addition operation. The following are the steps to execute the instruction:
Step 1: Fetch the instruction from main-memory into the processor.
Step 2: Fetch the operand at location LOCA from main-memory into the processor.
Step 3: Add the memory operand (i.e. fetched contents of LOCA) to the contents of register R0. Step 4: Store the result (sum) in R0.
- The same instruction can be realized using 2 instructions as:
Load LOCA, R1
Add R1, R0
- The following are the steps to execute the instruction:
Step 1: Fetch the instruction from main-memory into the processor.
Step 2: Fetch the operand at location LOCA from main-memory into the register R1. Step 3: Add the content of Register R1 and the contents of register R0.
Step 4: Store the result (sum) in R0.

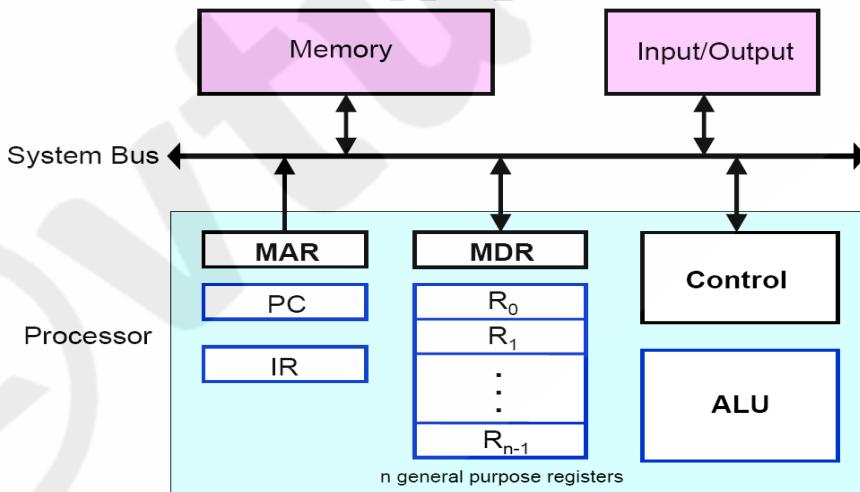
Q. With a neat diagram, discuss the operational concepts in a computer highlight the role of PC, MAR, MDR and IR – (08 M)

Various Processor Registers

- The processor contains ALU, control-circuitry and many registers.
- The processor has ‘n’ general-purpose registers R_0 through R_{n-1} .
- The IR (Instruction Register) holds the instruction that is currently being executed.
- The control-unit generates the timing-signals that determine when a given action is to take place.
- The PC (Program Counter) contains the memory-address of the next-instruction to be fetched & executed.
- During the execution of an instruction, the contents of PC are updated to point to next instruction.
- The MAR (Memory Address Register) holds the address of the memory-location to be accessed.
- The MDR (Memory Data Register) contains the data to be written into or read out of the addressed location.

STEPS TO EXECUTE AN INSTRUCTION between processor and memory

- 1) The address of first instruction (to be executed) gets loaded into PC.
- 2) The contents of PC (i.e. address) are transferred to the MAR & control-unit issues Read signal to memory.
- 3) After certain amount of elapsed time, the first instruction is read out of memory and placed into MDR.
- 4) Next, the contents of MDR are transferred to IR. At this point, the instruction can be decoded & executed.
- 5) To fetch an operand, its address is placed into MAR & control-unit issues Read signal. As a result, the operand is transferred from memory into MDR, and then it is transferred from MDR to ALU.
- 6) Likewise required number of operands is fetched into processor.
- 7) Finally, ALU performs the desired operation.
- 8) If the result of this operation is to be stored in the memory, then the result is sent to the MDR.
- 9) The address of the location where the result is to be stored is sent to the MAR and a Write cycle is initiated.
- 10) At some point during execution, contents of PC are incremented to point to next instruction in the program.



Q. Explain single bus and multiple bus structure in computer (06 M)

BUS STRUCTURE

- A bus is a group of lines that serves as a connecting path for several devices.
- A bus may be lines or wires.
- The lines carry data or address or control signal.
- There are 2 types of Bus structures: 1) Single Bus Structure and 2) Multiple Bus Structure.

1) Single Bus Structure

- Because the bus can be used for only one transfer at a time, only 2 units can actively use the bus at any given time.
- Bus control lines are used to arbitrate multiple requests for use of the bus.

➤ **Advantages:**

- 1) Low cost &
- 2) Flexibility for attaching peripheral devices.

2) Multiple Bus Structure

➤ Systems that contain multiple buses achieve more concurrency in operations.

➤ Two or more transfers can be carried out at the same time.

➤ **Advantage:** Better performance.

➤ **Disadvantage:** Increased cost.

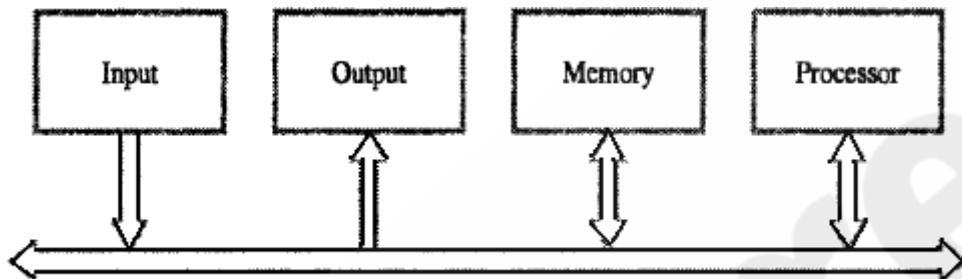


Figure 1.3 Single-bus structure.

- The devices connected to a bus vary widely in their speed of operation.
- To synchronize their operational-speed, buffer-registers can be used.

• **Buffer Registers**

→ are included with the devices to hold the information during transfers.

→ prevent a high-speed processor from being locked to a slow I/O device during data transfers.

Memory mapped I/O

It is an usual assumption that the addresses issued by the processor to access instructions and operands always refer to memory locations. Many computers use an arrangement called memory mapped I/O in which some memory address values are used to refer to peripheral device buffer registers, such as DATAIN and DATAOUT. Thus no special instructions are needed to access the contents of these registers; data can be transferred between these registers and the processor using instructions such as Move, Load or Store. For Example, the contents of the keyboard character buffer DATAIN can be transferred to register R1 in the processor by the instruction

MoveByte DATAIN,R1

Similarly, the contents of register R1 can be transferred to DATAOUT by the instruction

MoveByte R1, DATAOUT

The status flags SIN and SOUT are automatically cleared when the buffer registers DATAIN and DATAOUT are referenced, respectively. The MoveByte operation code signifies that the operand size is a byte, to distinguish it from the operation code Move that has been used for word operands.

Q. Explain system Software functions in computer(06M).

- In order for a user to enter and run an application program, the computer must already contain some system software in its memory.
- System software is a collection of programs that are executed as needed to perform functions such as
 - Receiving and interpreting user commands
 - Running standard application programs such as word processors, etc, or games
 - Managing the storage and retrieval of files in secondary storage devices
 - Controlling I/O units to receive input information and produce output results
 - Translating programs from source form prepared by the user into object form consisting of machine instructions
 - Linking and running user-written application programs with existing standard library routines, such as numerical computation packages

- System software is thus responsible for the coordination of all activities in a computing system

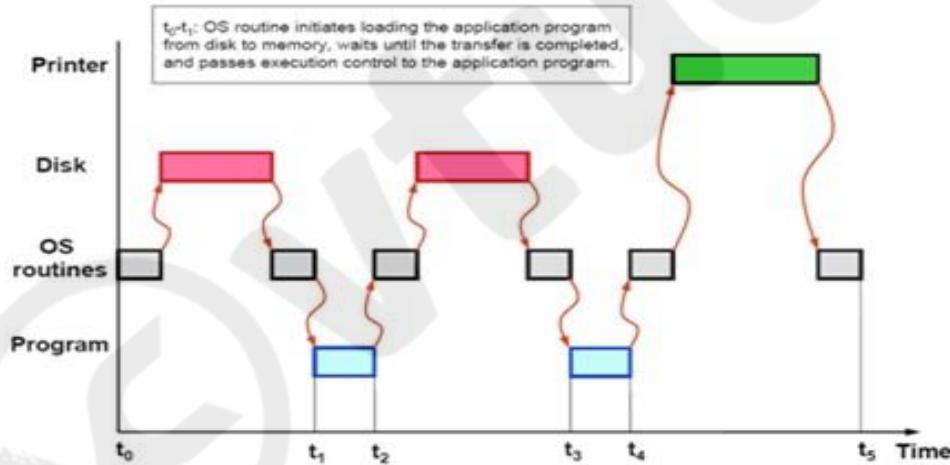
Q. What is operating system? Explain user program and OS routine sharing the processor (08 M).

- Operating system (OS)
 - This is a large collection of routines, that controls the sharing and interaction among various computer units as they perform application programs
- The OS routines perform the tasks required to assign computer resource to individual application programs
 - These tasks include assigning memory and magnetic disk space to program and data files, moving data between memory and disk units, and handling I/O operations
- In the diagram, a system with one processor, one disk, and one printer is given to explain the basics of OS
 - Assume that part of the program's task involves reading a data file from the disk into the memory, performing some computation on the data, and printing the results.

In the diagram shown, the above procedure as per to the time slots is explained.

- i) In the time period $t_0 - t_1$, **Operating system loads the application program from disk to memory.**
- ii) In the time period $t_1 - t_2$ **program is executed**
- iii) t_2-t_3 **program accesses disk**
- iv) $t_3 - t_4$ **program executes some more**
- v) t_4-t_5 **program accesses printer**
- vi) At t_5 **program terminates**

User Program and OS Routine Sharing



PERFORMANCE

- The most important measure of performance of a computer is how quickly it can execute programs.
- The speed of a computer is affected by the design of
 - 1) Instruction-set.
 - 2) Hardware & the technology in which the hardware is implemented.
 - 3) Software including the operating system.
- Because programs are usually written in a HLL(HLL→ High Level Language), performance is also affected by the compiler that translates programs into machine language.

- For best performance, it is necessary to design the compiler, machine instruction set and hardware in a co-ordinated way.

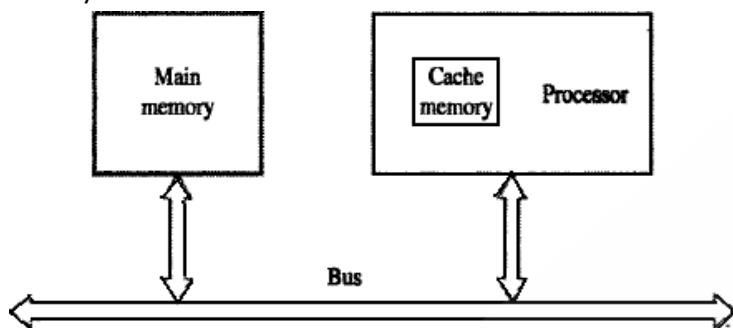


Figure 1.5 The processor cache.

- Let us examine the flow of program instructions and data between the memory & the processor.
- At the start of execution, all program instructions are stored in the main-memory.
- As execution proceeds, instructions are fetched into the processor, and a copy is placed in the cache.
- Later, if the same instruction is needed a second time, it is read directly from the cache.

Q. Explain in brief different types of key parameters that affect the processor performance (05 M)

Factors for improving or affecting the performance

1. PROCESSOR CLOCK

- Processor circuits are controlled by a timing signal called a **Clock**.
 - The clock defines regular time intervals called **Clock Cycles**.
 - To execute a machine instruction, the processor divides the action to be performed into a sequence of basic steps such that each step can be completed in one clock cycle.
 - Let P = Length of one clock cycle R = Clock rate.
 - Relation between P and R is given by
- $$R = \frac{1}{P}$$
- R is measured in cycles per second.
 - Cycles per second is also called Hertz (Hz)

2. BASIC PERFORMANCE EQUATION (Q. Explain computer basic performance equation -04 M)

- Let T = Processor time required to execute a program.
 - N = Actual number of instruction executions.
 - S = Average number of basic steps needed to execute one machine instruction.
 - R = Clock rate in cycles per second.
 - The program execution time is given by
- $$T = \frac{N \times S}{R} \quad \text{-----(1)}$$
- Equ1 is referred to as the basic performance equation.
 - To achieve high performance, the computer designer must reduce the value of T , which means reducing N and S , and increasing R .
 - The value of N is reduced if source program is compiled into fewer machine instructions.
 - The value of S is reduced if instructions have a smaller number of basic steps to perform.
 - The value of R can be increased by using a higher frequency clock.
 - Care has to be taken while modifying values since changes in one parameter may affect the other.

3. CLOCK RATE

- There are 2 possibilities for increasing the clock rate R:
 - 1) Improving the IC technology makes logic-circuits faster.
 - 2) Reducing the amount of processing done in one basic step also reduces the clock period P.

4. Compiler:

- A compiler translates a high-level language program into a sequence of machine instructions.
- To reduce N, we need a suitable machine instruction set and a compiler that makes good use of it.
- Goal is to reduce $N \times S$
 - N= is the actual number of instruction execution
 - S= is the total number of basic steps needed to execute one machine cycle instruction.

5. Pipelining and superscalar operation.

- Pipelining: by overlapping the execution of successive instructions
- Superscalar: different instructions are concurrently executed with multiple instruction pipelines. This means that multiple functional units are needed. This means that multiple functional units are used creating parallel paths through which different instructions can be executed in parallel with such an arrangement, it becomes possible to start the execution of several instructions in every clock cycle. This mode of operation is called superscalar execution.

6. CISC and RISC

- It is much easier to implement efficient pipelining in processor with simple instruction sets
- Reduced Instruction Set Computers (RISC)
- Complex Instruction Set Computers (CISC)

INSTRUCTION SET: CISC AND RISC

RISC	CISC
Simple instructions taking one cycle.	Complex instructions taking multiple cycle.
Instructions are executed by hardwired control unit.	Instructions are executed by microprogrammed control unit.
Few instructions.	Many instructions.
Fixed format instructions.	Variable format instructions.
Few addressing modes, and most instructions have register to register addressing mode.	Many addressing modes.
Multiple register set.	Single register set.
Highly pipelined.	No pipelined or less pipelined.

Problem 1:

List the steps needed to execute the machine instruction:

Add R2, LOCA

in terms of transfers between the components of processor and some simple control commands.
Assume that the address of the memory-location containing this instruction is initially in register PC.

Solution:

1. Transfer the contents of register PC (address of this instruction) to register MAR.
2. Issue a Read command to memory.
And, then wait until the instruction is transferred into register MDR.

3. Transfer the instruction from MDR into IR(Instruction Register) and decode it.
4. Transfer the address LOCA from IR to MAR.
5. Issue a Read command and wait until MDR is loaded with data present at LOCA address.
6. Transfer contents of MDR to the ALU.
7. Transfer contents of R2 to the ALU.
8. Perform addition of the two operands in the ALU and transfer result at location LOCA.
9. Transfer contents of PC to ALU.
10. Add 1 to operand in ALU and transfer incremented address to PC.

Problem 2:

List the steps needed to execute the machine instruction:

Add R4, R2, R3

in terms of transfers between the components of processor and some simple control commands.

Assume that the address of the memory-location containing this instruction is initially in register PC.

Solution:

1. Transfer the contents of register PC to register MAR.
2. Issue a Read command to memory.
And, then wait until the instruction is transferred into register MDR.
3. Transfer the instruction from MDR into IR and decode it.
4. Transfer contents of R1 and R2 to the ALU.
5. Perform addition of two operands in the ALU and transfer answer into R3.
6. Transfer contents of PC to ALU.
7. Add 1 to operand in ALU and transfer incremented address to PC.

Problem 3:

(a) Given a short sequence of machine instructions for the task "Add the contents of memory-location A to those of location B, and place the answer in location C". Instructions:

Load LOC, Ri and
Store Ri, LOC

are the only instructions available to transfer data between memory and the general purpose registers. Add instructions do not change contents of either location A or B.

(b) Suppose that Move and Add instructions are available with the formats:

Move Location1, Location2 and
Add Location1, Location2

These instructions move or add a copy of the operand at the second location to the first location, overwriting the original operand at the first location. Either or both of the operands can be in the memory or the general-purpose registers. Is it possible to use fewer instructions of these types to accomplish the task in part (a)? If yes, give the sequence.

Solution:

(a)

Load A, R0
Load B, R1
Add R0, R1
Store R1, C

(b) Yes;

Move B, C
Add A, C

Problem 4:

A program contains 1000 instructions. Out of that 25% instructions requires 4 clock cycles, 40% instructions requires 5 clock cycles and remaining require 3 clock cycles for execution. Find the total time required to execute the program running in a 1 GHz machine.

Solution:

$$N = 1000$$

25% of N= 250 instructions require 4 clock cycles.

40% of N =400 instructions require 5 clock cycles. 35% of N=350 instructions require 3 clock cycles.

$$T = (N \times S) / R = (250 \times 4 + 400 \times 5 + 350 \times 3) / 1 \times 10^9 = (1000 + 2000 + 1050) / 1 \times 10^9 = 4.05 \mu\text{s}$$

Problem 5:

For the following processor, obtain the performance.

Clock rate = 800 MHz

No. of instructions executed = 1000

Average no of steps needed / machine instruction = 20

Solution:

$$T = \frac{N \times S}{R} = \frac{(1000 \times 20)}{800 \times 10^6} = 25 \text{ micro sec or } 25 \times 10^{-6} \text{ sec}$$

MODULE 1 (CONT.): MACHINE INSTRUCTIONS & PROGRAMS

Computers are built using logic circuits that operate on information in the form of binary digit whose values are 0 and 1. The most natural way to represent a number in a computer system is by a string of bits, called a binary number. A text character can also be represented by a string of bits called a character code.

Numeric Data Representation

Fixed Point	Decimal	Binary	Octal	Hexadecimal
	00	0000	00	0
	01	0001	01	1
	02	0010	02	2
	03	0011	03	3
	04	0100	04	4
	05	0101	05	5
	06	0110	06	6
	07	0111	07	7
	08	1000	10	8
	09	1001	11	9
	10	1010	12	A
	11	1011	13	B
	12	1100	14	C
	13	1101	15	D
	14	1110	16	E
	15	1111	17	F

Representation:

It's the representation for integers only where the decimal point is always fixed. i.e at the end of rightmost point. it can be again represented in two ways.

1. Sign and Magnitude Representation:

In this system, the most significant (leftmost) bit in the word as a sign bit. If the sign bit is 0, the number is positive; if the sign bit is 1, the number is negative.

The simplest form of representing sign bit is the sign magnitude representation.

One of the draw back for sign magnitude number is addition and subtraction need to consider both sign of the numbers and their relative magnitude.

Another drawback is there are two representation for 0(Zero) i.e +0 and -0.

2. One's Complement (1's) Representation:

In this representation negative values are obtained by complementing each bit of the corresponding positive number.

COMPUTER ORGANIZATION

For example 1s complement of 0101 is 1010 . The process of forming the 1s complement of a given number is equivalent to subtracting that number from $2^n - 1$ i.e from 1111 for 4 bit number.

Two's Complement (2's) Representation Forming the 2's complement of a number is done by subtracting that number from 2^n . So 2's complement of a number is obtained by adding 1 to 1s complement of that number.

Ex: 2's complement of 0101 is $1010 + 1 = 1011$

NOTE: In all systems, the leftmost bit is 0 for positive number and 1 for negative number.



Signed integer represented in three ways.

Represent +12 and -12 in the following ways.

1. Sign and Magnitude Representation:

Sign bit	True Magnitude (actual binary bits)
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Ex: a. +12 is 01100 [4 bits are for representing number 12 and 1 bit is for sign. Hence]
b. -12 is 11100 [it is signed 5 bit number representation]

2. One's Complement (1's) Representation:

Sign bit	1's complement of actual binary bits
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Ex: a. +12 is 01100 and b. -12 is 10011

3. Two's Complement (2's) Representation :

Sign bit	2's complement of actual binary bits
----------	--------------------------------------

Ex: a. +12 is 01100 and b. -12 is 10100

Note: unsigned (+ve) number representation remains in same manner in all three ways.



Addition and Subtraction – 2's Complement

Any subtraction operation is performed by means of 2's complement addition.

Hence the operation is addition and subtraction

Perform following operation in 2's complement system in signed 4 bit representation.

1. (4) + (3)
2. (-4) - (3)
3. (4) + (-3)
4. (-4) + (3)

Solution: 1. (4) + (3)

$$\begin{array}{r} 4 \\ + 3 \\ \hline 7 \end{array}$$

2. (-4) + (-3)

$$\begin{array}{r} -4 \\ + (-3) \\ \hline -7 \end{array}$$

$$\begin{array}{r} +4 \ 0100 \\ +3 \ 0011 \\ \hline -4 \ 1011 \end{array}$$

$$\begin{array}{r} -4 \ 1011 \\ +1 \\ \hline 1100 \end{array}$$

$$\begin{array}{r} -3 \ 1100 \\ +1 \\ \hline 1101 \end{array}$$

3. (4) + (-3)

$$\begin{array}{r} 4 \\ -3 \\ \hline 1 \end{array}$$

$$\begin{array}{r} 4 \\ -4 \\ \hline -1 \end{array}$$

$$\begin{array}{r} 0100 \\ +1 \\ \hline 0111 \end{array}$$

4. (-4) + (3)

$$\begin{array}{r} -4 \\ +3 \\ \hline -1 \end{array}$$

$$\begin{array}{r} 1100 \\ +3 \\ \hline 1111 \end{array}$$

$$\begin{array}{r} 0000 \\ +1 \\ \hline 0001 \end{array}$$

Floating-point representation:

Floating-point numbers are so called as the decimal or binary point floats over the base depending on the exponent value. It consists two components.

- Exponent
- Mantissa

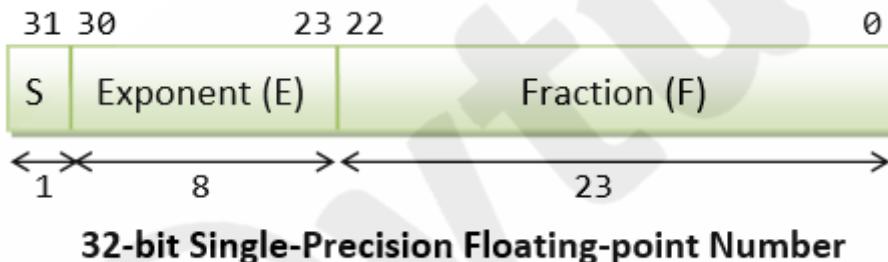
Table - 1 Precision Representation

Precision	Base	Sign	Exponent	Significand
Single precision	2	1	8	23+1
Double precision	2	1	11	52+1

IEEE-754 32-bit Single-Precision Floating-Point Numbers

In 32-bit single-precision floating-point representation:

- The most significant bit is the *sign bit* (S), with 0 for positive numbers and 1 for negative numbers.
- The following 8 bits represent *exponent* (E).
- The remaining 23 bits represents *fraction* (F).



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Example 1: Convert $(3.5)_{10}$ to IEEE 32 bit floating point format

Solution:

1. Convert the given decimal number into its equivalent binary.

$$\begin{aligned} 0.5 \times 2 &= 1.0 & 1 \\ 0.0 \times 2 &= 0 & 0 \text{ [not required to multiply with 0]} \\ (3.5)_{10} &= (11.1)_2 \end{aligned}$$

2. Normalize the number [$1.M \times 2^{E'}$ format is used]

$$1.11 \times 2^1 \text{ (here } E' = 1, \text{ the power of 2)}$$

3. M = Mantissa = 110 0000 0000 0000 0000 0000 [extra bits as mantissa is of 23 bits]

4. Exponent E = E' + 127
= 1 + 127 = $(128)_{10} = (1000\ 0000)_2$

5. Sign bit S = 0 \Rightarrow positive number

6. 0 1000 0000 110 0000 0000 0000 0000 sign, exponent and mantissa

Example 1: Suppose that IEEE-754 32-bit floating-point representation pattern is

0 1000 0000 110 0000 0000 0000 0000.

obtain its normalized form.

Sign bit S = 0 \Rightarrow positive number

$$E = 1000\ 0000_B = 128D$$

Use the format $1.M$ and convert binary to decimal.

Fraction is $1.11B$ (with an implicit leading 1)

$$= 1 + 1 \times 2^{-1} + 1 \times 2^{-2} = 1.75D$$

Since the E is > 127 hence use the formula $E' = E - 127$

The number is $+1.75 \times 2^{(128-127)} = +3.5D$

Example 2: Suppose that IEEE-754 32-bit floating-point representation pattern is 10111110 100 0000 0000 0000 0000 0000. obtain its normalized form.

Sign bit S = 1 \Rightarrow negative number

$$E = 0111\ 1110_B = 126D \text{ (in normalized form)}$$

Fraction is $1.1B$ (with an implicit leading 1) = $1 + 2^{-1} = 1.5D$

The number is $-1.5 \times 2^{(126-127)} = -0.75D$

Binary, Signed-Integer Representations

B	Values represented		
$b_3 b_2 b_1 b_0$	Sign and magnitude	1's complement	2's complement
0 1 1 1	+ 7	+ 7	+ 7
0 1 1 0	+ 6	+ 6	+ 6
0 1 0 1	+ 5	+ 5	+ 5
0 1 0 0	+ 4	+ 4	+ 4
0 0 1 1	+ 3	+ 3	+ 3
0 0 1 0	+ 2	+ 2	+ 2
0 0 0 1	+ 1	+ 1	+ 1
0 0 0 0	+ 0	+ 0	+ 0
1 0 0 0	- 0	- 7	- 8
1 0 0 1	- 1	- 6	- 7
1 0 1 0	- 2	- 5	- 6
1 0 1 1	- 3	- 4	- 5
1 1 0 0	- 4	- 3	- 4
1 1 0 1	- 5	- 2	- 3
1 1 1 0	- 6	- 1	- 2
1 1 1 1	- 7	- 0	- 1

Figure 2.1. Binary, signed-integer representations.

2's-Complement Add and Subtract Operations

(a)	$\begin{array}{r} 0010 \\ + 0011 \\ \hline 0101 \end{array}$	$\begin{array}{l} (+2) \\ \{+3\} \end{array}$	(b)	$\begin{array}{r} 0100 \\ + 1010 \\ \hline 1110 \end{array}$	$\begin{array}{l} (+4) \\ (-6) \end{array}$
(c)	$\begin{array}{r} 1011 \\ + 1110 \\ \hline 1001 \end{array}$	$\begin{array}{l} (-5) \\ \{-2\} \end{array}$	(d)	$\begin{array}{r} 0111 \\ + 1101 \\ \hline 0100 \end{array}$	$\begin{array}{l} (+7) \\ (-3) \end{array}$
(e)	$\begin{array}{r} 1101 \\ - 1001 \\ \hline 1001 \end{array}$	$\begin{array}{l} (-3) \\ \{-7\} \end{array}$		$\begin{array}{r} 1101 \\ + 0111 \\ \hline 0100 \end{array}$	$\begin{array}{l} (+4) \end{array}$
(f)	$\begin{array}{r} 0010 \\ - 0100 \\ \hline 1110 \end{array}$	$\begin{array}{l} (+2) \\ (+4) \end{array}$		$\begin{array}{r} 0010 \\ + 1100 \\ \hline 1110 \end{array}$	$\begin{array}{l} (-2) \end{array}$
(g)	$\begin{array}{r} 0110 \\ - 0011 \\ \hline 0011 \end{array}$	$\begin{array}{l} (+6) \\ \{+3\} \end{array}$		$\begin{array}{r} 0110 \\ + 1101 \\ \hline 0011 \end{array}$	$\begin{array}{l} (+3) \end{array}$
(h)	$\begin{array}{r} 1001 \\ - 1011 \\ \hline 1110 \end{array}$	$\begin{array}{l} (-7) \\ \{-5\} \end{array}$		$\begin{array}{r} 1001 \\ + 0101 \\ \hline 1110 \end{array}$	$\begin{array}{l} (-2) \end{array}$
(i)	$\begin{array}{r} 1001 \\ - 0001 \\ \hline 1000 \end{array}$	$\begin{array}{l} (-7) \\ (+1) \end{array}$		$\begin{array}{r} 1001 \\ + 1111 \\ \hline 1000 \end{array}$	$\begin{array}{l} (-8) \end{array}$
(j)	$\begin{array}{r} 0010 \\ - 1101 \\ \hline 0101 \end{array}$	$\begin{array}{l} (+2) \\ \{(-3)\} \end{array}$		$\begin{array}{r} 0010 \\ + 0011 \\ \hline 0101 \end{array}$	$\begin{array}{l} (+5) \end{array}$

Figure 2.4. 2's-complement Add and Subtract operations.

Overflow Conditions

5	0111 0101	-7	1000 1001
3	0011	-2	1100
-8	1000	7	10111
Overflow		Overflow	
5	0000 0101	-3	1111 1101
2	0010	-5	1011
7	0111	-8	11000

No overflow

No overflow

Overflow when carry-in to the high-order bit does not equal carry out

Overflow occurs in following conditions:

1. when adding two numbers that have the same sign.
2. the carry out signal from the sign bit position is not a sufficient indicator of overflow when adding signed numbers.

A simple way to detect overflow is to examine the signs of the two summands X and Y and the sign of the result. When both operands X and Y have the same sign, an overflow occurs when the sign of S is not the same as the signs of X and Y.



Sign Extension Example

Decimal	Hexa decimal	Binary (8 bit)	Sign Extended Binary (16 bit)
8	8	0000 1000	0000 0000 0000 1000
161	A1	1010 0001	1111 1111 1010 0001
13	0D	0000 1101	0000 0000 0000 1101
236	EC	1110 1100	1111 1111 1110 1100

MEMORY-LOCATIONS & ADDRESSES

- **Memory** consists of many millions of storage cells (flip-flops).
- Each cell can store a bit of information i.e. 0 or 1 (Figure 2.1).
- Each group of n bits is referred to as a **word** of information, and n is called the **word length**.
- The word length can vary from 8 to 64 bits.
- A unit of 8 bits is called a **byte**.
- Accessing the memory to store or retrieve a single item of information (word/byte) requires distinct addresses for each item location. (It is customary to use numbers from 0 through $2^k - 1$ as the addresses of successive-locations in the memory).
- If $2^k = \text{no. of addressable locations}$;
then 2^k addresses constitute the address-space of the computer.

For example, a 24-bit address generates an address-space of 2^{24} locations (16 MB).

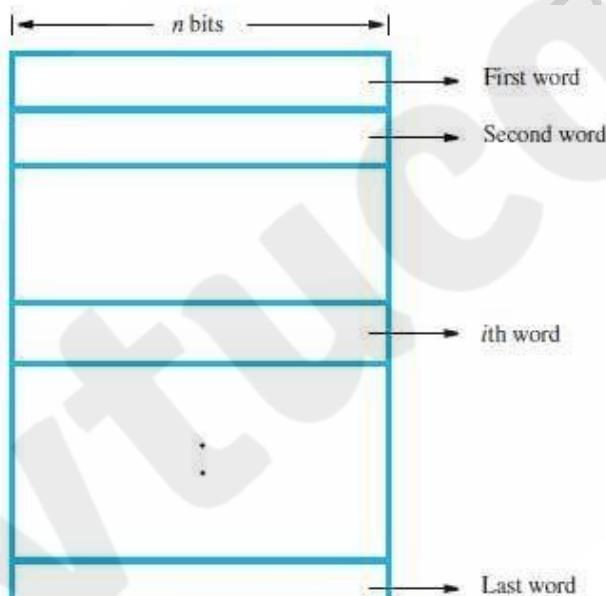
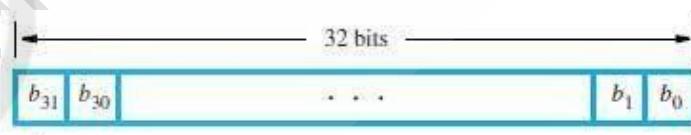
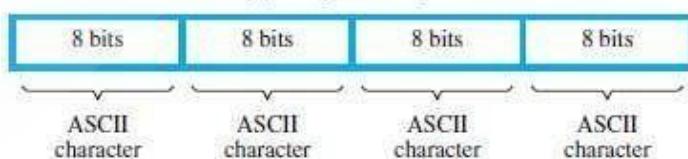


Figure 2.1 Memory words.



(a) A signed integer



(b) Four characters

Figure 2.2 Examples of encoded information in a 32-bit word.

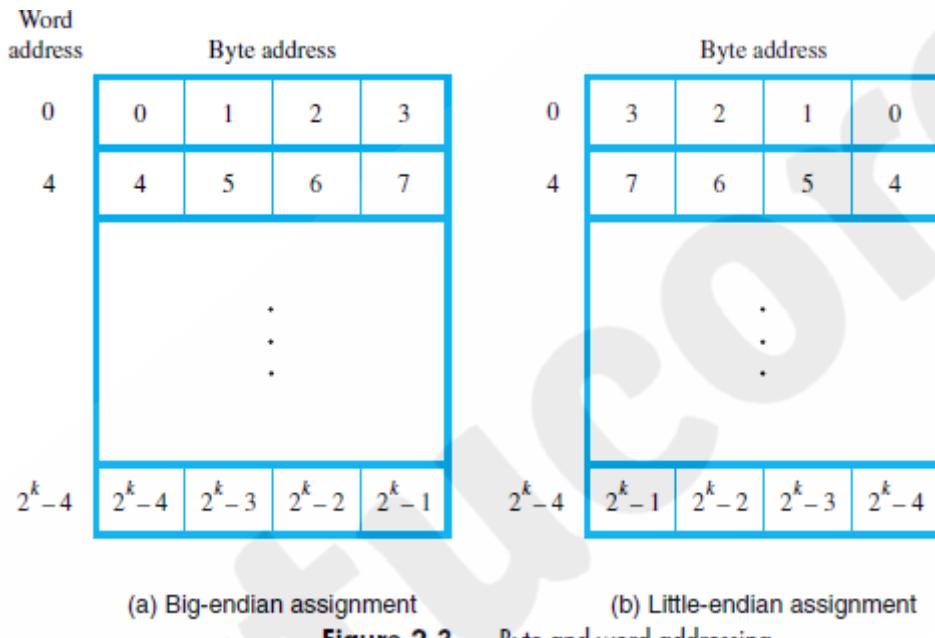
COMPUTER ORGANIZATION

BYTE-ADDRESSABILITY

- In byte-addressable memory, successive addresses refer to successive byte locations in the memory.
 - Byte locations have addresses 0, 1, 2. . . .
 - If the word-length is 32 bits, successive words are located at addresses 0, 4, 8. . with each word having 4 bytes.

BIG-ENDIAN & LITTLE-ENDIAN ASSIGNMENTS

- There are two ways in which byte-addresses are arranged (Figure 2.3).
 - 1) **Big-Endian:** Lower byte-addresses are used for the more significant bytes of the word.
 - 2) **Little-Endian:** Lower byte-addresses are used for the less significant bytes of the word
 - In both cases, byte-addresses 0, 4, 8.....are taken as the addresses of successive words in the memory.



- Consider a 32-bit integer (in hex): **0x12345678** which consists of 4 bytes: 12, 34, 56, and 78.
 - Hence this integer will occupy 4 bytes in memory.
 - Assume, we store it at memory address starting 1000.
 - On little-endian, memory will look like

Address	Value
1000	78
1001	56
1002	34
1003	12

- On big-endian, memory will look like

Address	Value
1000	12
1001	34
1002	56
1003	78

WORD ALIGNMENT

- Words are said to be **Aligned** in memory if they begin at a byte-address that is a multiple of the number of bytes in a word.
 - For example,
 - If the word length is 16(2 bytes), aligned words begin at byte-addresses 0, 2, 4
 - If the word length is 64(2 bytes), aligned words begin at byte-addresses 0, 8, 16
 - Words are said to have **Unaligned Addresses**, if they begin at an arbitrary byte-address.

COMPUTER ORGANIZATION

ACCESSING NUMBERS, CHARACTERS & CHARACTERS STRINGS

- A number usually occupies one word. It can be accessed in the memory by specifying its word address. Similarly, individual characters can be accessed by their byte-address.
- There are two ways to indicate the length of the string:
 - 1) A special control character with the meaning "end of string" can be used as the last character in the string.
 - 2) A separate memory word location or register can contain a number indicating the length of the string in bytes.

MEMORY OPERATIONS

- Two memory operations are:
 - 1) Load (Read/Fetch) &
 - 2) Store (Write).
- The **Load** operation transfers a copy of the contents of a specific memory-location to the processor. The memory contents remain unchanged.
- Steps for Load operation:
 - 1) Processor sends the address of the desired location to the memory.
 - 2) Processor issues „read“ signal to memory to fetch the data.
 - 3) Memory reads the data stored at that address.
 - 4) Memory sends the read data to the processor.
- The **Store** operation transfers the information from the register to the specified memory-location. This will destroy the original contents of that memory-location.
- Steps for Store operation are:
 - 1) Processor sends the address of the memory-location where it wants to store data.
 - 2) Processor issues „write“ signal to memory to store the data.
 - 3) Content of register(MDR) is written into the specified memory-location.

INSTRUCTIONS & INSTRUCTION SEQUENCING

- A computer must have instructions capable of performing 4 types of operations:
 - 1) Data transfers between the memory and the registers (MOV, PUSH, POP, XCHG).
 - 2) Arithmetic and logic operations on data (ADD, SUB, MUL, DIV, AND, OR, NOT).
 - 3) Program sequencing and control (CALL,RET, LOOP, INT).
 - 4) I/O transfers (IN, OUT).

COMPUTER ORGANIZATION

REGISTER TRANSFER NOTATION (RTN)

- The possible locations in which transfer of information occurs are: 1) Memory-location 2) Processor register & 3) Registers in I/O device.

Location	Hardware Binary Address	Example	Description
Memory	LOC, PLACE, NUM	R1 \leftarrow [LOC]	Contents of memory-location LOC are transferred into register R1.
Processor	R0, R1, R2	[R3] \leftarrow [R1]+[R2]	Add the contents of register R1 & R2 and places their sum into R3.
I/O Registers	DATAIN, DATAOUT	R1 \leftarrow DATAIN	Contents of I/O register DATAIN are transferred into register R1.

ASSEMBLY LANGUAGE NOTATION

- To represent machine instructions and programs, assembly language format is used.

Assembly Language Format	Description
Move LOC, R1	Transfer data from memory-location LOC to register R1. The contents of LOC are unchanged by the execution of this instruction, but the old contents of register R1 are overwritten.
Add R1, R2, R3	Add the contents of registers R1 and R2, and places their sum into register R3.

BASIC INSTRUCTION TYPES

Instruction Type	Syntax	Example	Description	Instructions for Operation C \leftarrow [A]+[B]
Three Address	Opcode Source1, Source2, Destination	Add A,B,C	Add the contents of memory-locations A & B. Then, place the result into location C.	
Two Address	Opcode Source, Destination	Add A,B	Add the contents of memory-locations A & B. Then, place the result into location B, replacing the original contents of this location. Operand B is both a source and a destination.	Move B, C Add A, C
One Address	Opcode Source/Destination	Load A	Copy contents of memory-location A into accumulator.	Load A Add B Store C
		Add B	Add contents of memory-location B to contents of accumulator register & place sum back into accumulator.	
		Store C	Copy the contents of the accumulator into location C.	
Zero Address	Opcode [no Source/Destination]	Push	Locations of all operands are defined implicitly. The operands are stored in a pushdown stack.	Not possible

- Access to data in the registers is much faster than to data stored in memory-locations.

- Let Ri represent a general-purpose register. The instructions:

Load A,Ri

Store Ri,A

Add A,Ri

are generalizations of the Load, Store and Add Instructions for the single-accumulator case, in which register Ri performs the function of the accumulator.

- In processors, where arithmetic operations are allowed only on operands that are in registers, the task C \leftarrow [A]+[B] can be performed by the instruction sequence:

Move A,Ri

Move B,Rj

Add Ri,Rj

Move Rj,C

COMPUTER ORGANIZATION

INSTRUCTION EXECUTION & STRAIGHT LINE SEQUENCING

- The program is executed as follows:
 - 1) Initially, the address of the first instruction is loaded into PC (Figure 2.8).
 - 2) Then, the processor control circuits use the information in the PC to fetch and execute instructions, one at a time, in the order of increasing addresses. This is called *Straight-Line sequencing*.
 - 3) During the execution of each instruction, PC is incremented by 4 to point to next instruction.
- There are 2 phases for Instruction Execution:
 - 1) **Fetch Phase:** The instruction is fetched from the memory-location and placed in the IR.
 - 2) **Execute Phase:** The contents of IR is examined to determine which operation is to be performed. The specified-operation is then performed by the processor.

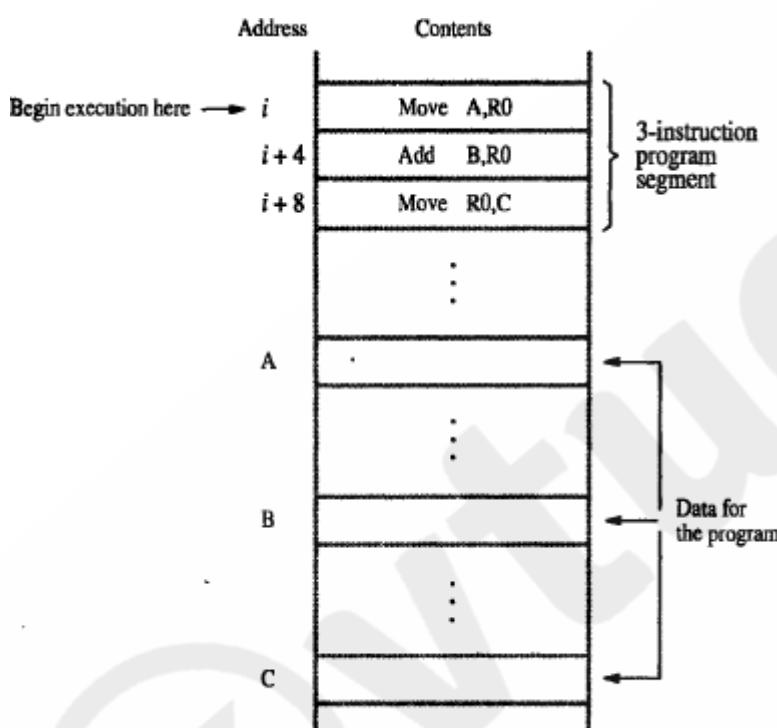


Figure 2.8 A program for $C \leftarrow [A] + [B]$.

i	Move NUM1,R0
$i+4$	Add NUM2,R0
$i+8$	Add NUM3,R0
\vdots	\vdots
$i+4n-4$	Add NUM n ,R0
$i+4n$	Move R0,SUM
\vdots	\vdots
SUM	
NUM1	
NUM2	
\vdots	\vdots
NUM n	

Figure 2.9 A straight-line program for adding n numbers.

Program Explanation

- Consider the program for adding a list of n numbers (Figure 2.9).
- The Address of the memory-locations containing the n numbers are symbolically given as NUM1, NUM2.....NUM n .
- Separate Add instruction is used to add each number to the contents of register R0.
- After all the numbers have been added, the result is placed in memory-location SUM.

BRANCHING

- Consider the task of adding a list of „n“ numbers (Figure 2.10).
- Number of entries in the list „n“ is stored in memory-location **N**.
- Register **R1** is used as a counter to determine the number of times the loop is executed.
- Content-location N is loaded into register R1 at the beginning of the program.
- The **Loop** is a straight line sequence of instructions executed as many times as needed. The loop starts at location LOOP and ends at the instruction Branch>0.
- During each pass,
 - address of the next list entry is determined and
 - that entry is fetched and added to R0.
- The instruction *Decrement R1* reduces the contents of R1 by 1 each time through the loop.
- Then **Branch Instruction** loads a new value into the program counter. As a result, the processor fetches and executes the instruction at this new address called the **Branch Target**.
- A **Conditional Branch Instruction** causes a branch only if a specified condition is satisfied. If the condition is not satisfied, the PC is incremented in the normal way, and the next instruction in sequential address order is fetched and executed.

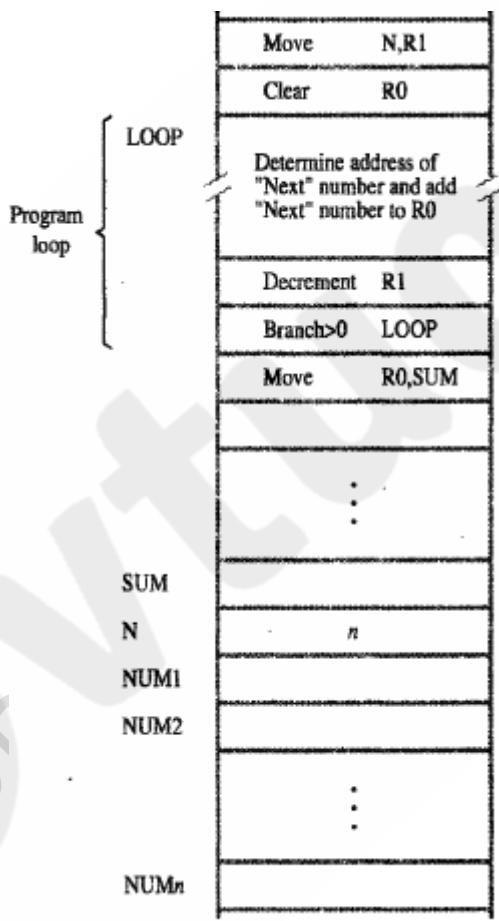


Figure 2.10 Using a loop to add n numbers.

CONDITION CODES

- The processor keeps track of information about the results of various operations. This is accomplished by recording the required information in individual bits, called **Condition Code Flags**.

• These flags are grouped together in a special processor-register called the condition code register (or statue register).

- Four commonly used flags are:

- 1) N (negative) set to 1 if the result is negative, otherwise cleared to 0.
- 2) Z (zero) set to 1 if the result is 0; otherwise, cleared to 0.
- 3) V (overflow) set to 1 if arithmetic overflow occurs; otherwise, cleared to 0.
- 4) C (carry) set to 1 if a carry-out results from the operation; otherwise cleared to 0.