

Chapter 3 Simulation of Stochastic Processes (v.17.1)

In this section we will review the mathematical foundations that are the basis for the valuation of derivative securities and the Black-Scholes pricing framework. We will focus only on the main concepts and provide the intuitions behind them, rather than attempting to give a full and rigorous coverage of the material.

In this section we will cover the basics of the stochastic processes, the popular models of stock prices and their properties.

In most models of Asset Pricing, the dynamics of the underlying security follow a continuous time stochastic process. To model the dynamics of asset prices we use Stochastic Differential equations (SDEs). In the Black-Scholes framework, the price of the asset under consideration S_t at time t follows a Geometric Brownian Motion (GBM). That is, the price dynamics (of a non-dividend paying stock) are given by the following SDE:

$$dS_t = \mu S_t dt + \sigma S_t dW_t$$

where μ is the drift, and σ is the volatility of the stock price movements. It follows that the instantaneous return of the stock

$$\frac{dS_t}{S_t} = \mu dt + \sigma dW_t$$

is given by two terms: the deterministic term - μdt , and the stochastic term - σdW_t .

W_t is Standard Brownian Motion process, thus, $dW_t \sim N(0, dt)$ and, therefore, $\mu dt + \sigma dW_t \sim N(\mu dt, \sigma^2 dt)$. That is, based on the above dynamics, the return of the stock is normally distributed.

In order to better understand the dynamics of the price-process above and study its properties and the Black-Scholes option pricing formula, we will study SDEs in a slightly more general context.

3.1 The Brownian Motion Process

A stochastic process $\{X_t: 0 \leq t \leq T\}$ defined on a probability space (Ω, \mathcal{A}, P) is called a Brownian Motion Process with a drift μ and variance σ^2 , if it satisfies the following properties:

1. $X_0 = 0$,
2. X_t is almost surely continuous in time t ,
3. $X_t - X_s$ is independent of $X_s - X_u$ for any $0 \leq u < s < t \leq T$.
4. $X_t - X_s \sim N(\mu(t - s), \sigma^2(t - s))$

A special case of this is the Standard Brownian Motion Process, in which $\mu = 0, \sigma^2 = 1$. This process is also referred to as the Wiener Process, and W_t is used for its notation.

Some properties of Wiener Processes

The Wiener Process $\{W_t: 0 \leq t \leq T\}$ has the following properties:

1. $E W_t = 0$ and $Var W_t = t$ for any $0 \leq t \leq T$,
2. $\lim_{t \rightarrow \infty} \frac{W_t}{t} = 0$
3. $E (W_t - W_s | \mathcal{A}_s) = 0$, where $\mathcal{A}_s = \sigma\{W_u, u \leq s\}$ is the σ -algebra (or the information set) generated by the Wiener process up to time s .
4. Define the following stopping time: $T_a = \inf\{t \geq 0, W_t = a\}$. Then for $a > 0, P(T_a < t) = 2 P(W_t > a)$ (this follows from the reflection principle).
5. Compute $P(T_a < \infty)$ and ET_a .

Brownian Bridge Process

A useful modification of the Standard Brownian Motion Process yields a process that is “tied” on both ends of the time interval and behaves like the Brownian Motion Process in the interval.

Assume $\{W_t: 0 \leq t \leq T\}$ is a Wiener Process. Define on $0 \leq t \leq T$

$$B_t = a + W_t - \frac{t}{T} [W_T - b + a]$$

Then B_t is a Brownian Bridge Process for which $B_0 = a, B_T = b$. This process (by its construction) is a Gaussian Process and is determined by its first and second moments.

The generation of the Wiener process

Assume $\{W_t: 0 \leq t \leq T\}$ is a Wiener Process. Since we know that $W_s \sim N(0, s)$, then for a Standard Normally distributed random variable $Z \sim N(0, 1)$, $\sqrt{T}Z \sim W_T$. That is, W_T has the same distribution as $\sqrt{T}Z$. Therefore, the generation of W_T is straightforward since we have methods to generate Z .

Method 1. Generate $Z \sim N(0, 1)$, by one of the two methods learned. Then take $\sqrt{T}Z = W_T$.

Method 2. Notice, that we can write

$$W_T = W_0 + \left(W_{\frac{T}{n}} - W_0\right) + \left(W_{\frac{2T}{n}} - W_{\frac{T}{n}}\right) + \cdots + \left(W_T - W_{\frac{(n-1)T}{n}}\right)$$

Since all the consecutive increments of a Wiener Process above are independent and normally

distributed $\left(W_{\frac{kT}{n}} - W_{\frac{(k-1)T}{n}}\right) \sim N\left(0, \frac{T}{n}\right)$, for any $k = 1, \dots, n$, then we can generate the entire

path of the process (actually, it is the discretized version of the process at n pre-specified times).

STEP 1. Generate $\{Z_i\}_{i=1}^n \sim iid N(0, 1)$,

STEP 2. Take $W_T = \sqrt{T/n} \sum_{i=1}^n Z_i$.

Obviously, the first method is much easier and computationally not-expensive to implement than the second method for generation of realizations of a Wiener Process at a fixed time T . However, the second method will prove to be more useful as it allows us to generate the entire path of the Wiener Process, not only its terminal value at time T .

3.2 Pricing Options – the First Steps

In the Black-Scholes framework, the price of the asset under consideration S_t at time t follows a Geometric Brownian Motion (GBM). That is, the price dynamics (of a non-dividend paying stock) are given by the following SDE:

$$dS_t = \mu S_t dt + \sigma S_t dW_t$$

In the Risk-Neutral World (or under the risk-neutral measure), the price dynamics are as follows:

$$dS_t = r S_t dt + \sigma S_t dW_t$$

The explicit formula for S_T is given by $S_T = S_0 e^{\left(\left(r - \frac{\sigma^2}{2}\right)T + \sigma W_T\right)}$, which shows that S_T is Log-Normally distributed (why?).

The price of a European Call option (under the risk neutral measure) is given by

$$c = e^{-(rT)} \mathbb{E}^*(S_T - X)^+ = e^{-(rT)} \mathbb{E}^* \left(S_0 e^{\left(\left(r - \frac{\sigma^2}{2}\right)T + \sigma W_T\right)} - X \right)^+ = \mathbb{E}^* f(W_T)$$

To estimate c by simulation, we will use the LLN and Monte Carlo simulations to write

$$c = \mathbb{E}^* f(W_T) \approx \frac{1}{n} \sum_{i=1}^n f(W_T^i),$$

where W_T^i is the i^{th} realization of W_T .

3.2.1 The Black-Scholes Formula

In a risk-neutral world, the price of a security (a call option in this case) is simply the discounted (at a risk-free rate) payoff of the security. In case of a European call option, the price c will be

$$c = e^{-rT} \mathbb{E}^*(S_T - X)^+$$

In case of a European put option, the price p would be computed as follows:

$$p = e^{-rT} \mathbb{E}^*(X - S_T)^+$$

In both cases, under the risk-neutral measure, the price dynamics are given by

$$S_T = S_0 e^{\left(\left(r - \frac{\sigma^2}{2}\right)T + \sigma W_T\right)}$$

The explicit formulas for prices of European call and put options are given by

$$c = S_0 N(d_1) - X e^{-rT} N(d_2), \text{ and } p = X e^{-rT} N(-d_2) - S_0 N(-d_1)$$

where

$$d_1 = \frac{\ln\left(\frac{S_0}{X}\right) + \left(r + \frac{1}{2}\sigma^2\right)T}{\sigma\sqrt{T}}, \quad d_2 = d_1 - \sigma\sqrt{T}$$

There is also a relationship between the prices of European call and put options on the same stock, with the same strike price and maturity – the Put-Call Parity:

$$c + X e^{-rT} = p + S_0$$

Comments:

1. When the stock pays dividends at a continuous rate δ , then the above pricing formulas hold true with a minor modification: replace S_0 by $\bar{S}_0 = S_0 e^{-\delta T}$.
2. When the stock pays discrete dividends, then the above pricing formulas hold true with a minor modification: replace S_0 by $\bar{S}_0 = S_0 - \text{PV of Dividends paid during the life of the option}$.

3.2.2 The Greeks of the Black-Scholes Formula

To manage the risk of the options and be able to replicate their payoffs, one needs to know the sensitivities of the options prices with respect to various parameters of the model – the Greeks.

Table 3: *The Formulas for European Call/Put Option Greeks.*

Greek	Sensitivity	For a call option	For a put option
Delta	$\frac{\partial Price}{\partial S_0}$	$N(d_1)$	$N(d_1) - 1$
Gamma	$\frac{\partial^2 Price}{\partial S_0^2}$	$\frac{1}{S_0 \sigma \sqrt{T}} n(d_1)$	$\frac{1}{S_0 \sigma \sqrt{T}} n(d_1)$
Theta	$\frac{\partial Price}{\partial T}$	$\frac{-S_0 \sigma n(d_1)}{2\sqrt{T}} - rX e^{-rT} N(d_2)$	$\frac{-S_0 \sigma n(d_1)}{2\sqrt{T}} + rX e^{-rT} N(-d_2)$
Vega	$\frac{\partial Price}{\partial \sigma}$	$S_0 \sqrt{T} n(d_1)$	$S_0 \sqrt{T} n(d_1)$
Rho	$\frac{\partial Price}{\partial r}$	$X T e^{-rT} N(d_2)$	$-X T e^{-rT} N(-d_2)$

where $n(t) = \frac{1}{\sqrt{2\pi}} e^{-t^2/2}$, $N(t) = \int_{-\infty}^t \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du$

3.2.3. The Simulation of Black- Scholes Greeks

To estimate the Greeks of the option prices, we would use the following method of estimating differentials: Let Δ_c be the delta of a European call option: $\Delta_c = \frac{\partial c}{\partial S_0}$. From the definition of the derivative we know that

$$\Delta_c = \lim_{h \rightarrow 0} \frac{C(S + h, t) - C(S, t)}{h}$$

A natural choice for approximating the derivative is to use a forward-difference scheme:

$$\frac{C(S + \epsilon, t) - C(S, t)}{\epsilon},$$

This, however, is not the only available method for approximating the delta. We can also approximate delta by a backward-difference

$$\frac{C(S, t) - C(S - \epsilon, t)}{\epsilon},$$

or, by a central difference

$$\frac{C(S + \epsilon, t) - C(S - \epsilon, t)}{2\epsilon}.$$

Which scheme is better? A Taylor expansion of the option price about the point (S, t) shows that

$$C(S + \epsilon, t) = C(S, t) + \epsilon \frac{\partial C(S, t)}{\partial S} + \frac{1}{2} \epsilon^2 \frac{\partial^2 C(S, t)}{\partial S^2} + O(\epsilon^3).$$

$O(\epsilon^3)$, called “big O notation”, means that the remainder of this expansion is smaller in absolute value than $|\epsilon^3|$ times a constant. Similarly we get,

$$C(S - \epsilon, t) = C(S, t) - \epsilon \frac{\partial C(S, t)}{\partial S} + \frac{1}{2} \epsilon^2 \frac{\partial^2 C(S, t)}{\partial S^2} + O(\epsilon^3).$$

Thus, we conclude that

$$\frac{\partial C(S, t)}{\partial S} = \frac{C(S + \epsilon, t) - C(S - \epsilon, t)}{2\epsilon} + O(\epsilon^2)$$

The error of the central difference scheme is therefore of size $O(\epsilon^2)$. From the above equations, it follows immediately that the error of the forward and backward difference schemes are of size $O(\epsilon)$. Therefore, the central difference scheme provides greater accuracy, but there are reasons (e.g. stability) for using the forward and backward difference. In some situations, it might even not be possible to use the central difference scheme because we do not know $C(S + \epsilon, t)$ or $C(S - \epsilon, t)$. Such a case is the case where S is close to zero. It is possible to derive forward and

backward schemes with greater accuracy by using three points instead of two (see the problems below).

We can estimate the other Greeks by simulation in a very similar fashion: perturb the initial parameter under consideration, and estimate the price of the option under the new parameter. Then approximate the differentials by the finite differences.

Problems

1. Show that the delta of a stock option can also be approximated by

$$\frac{-3C(S, t) + 4C(S + \epsilon, t) - C(S + 2\epsilon, t)}{2\epsilon}.$$

Show that this approximation is of order $O(\epsilon^2)$.

2. Derive a backward scheme which is based on the points (S, t) , $(S - \epsilon, t)$ and $(S - 2\epsilon, t)$ and is of the order $O(\epsilon^2)$.
3. Approximate the Gamma and the Theta.

3.2.4 The Black-Scholes PDE

The following differential equation is the Black-Scholes PDE to price a European call option:

$$\frac{\partial c}{\partial t} + rS \frac{\partial c}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 c}{\partial S^2} - rc = 0$$

3.3 Multidimensional Normal Generation

Definition: A random vector $X = (X_1, X_2, \dots, X_n)$ is said to have a n-dimensional Normal Distribution with a mean vector $\mu = (\mu_1, \mu_2, \dots, \mu_n)$, and a variance-covariance matrix $\Sigma = (\sigma_{i,j})_{i,j=1,\dots,n}$ if the density function of X is given by

$$\phi(x) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)' \Sigma^{-1} (x - \mu)\right)$$

To generate a realization of an n -variate Normal vector, we will follow these steps:

1. Use Cholesky decomposition of matrix Σ to write $\Sigma = L L'$, where L is an $n \times n$ lower-diagonal matrix, and L' is its transpose matrix.
2. Generate a vector $Z = (Z_1, Z_2, \dots, Z_n)$ of independent standard normally distributed variates,
3. Take $X = \mu + L Z$. Then, for this vector, $X \sim N(\mu, \Sigma)$.

To prove the statement of Step 3, note that

- (a) $X = \mu + L Z$ is a linear combination of normals, so it is a normal variate,
- (b) $EX = \mu + L EZ = \mu$,
- (c) $Var(X) = Var(\mu + L Z) = Var(L Z) = L Var(ZZ') L' = L L' = \Sigma$.

Since normal variates are determined by their first two moments, then the statements of normality are proved.

Comment:

When $n = 2$, then a Bivariate Normal $X = (X_1, X_2)$ is generated as follows:

Assume $\Sigma = \begin{pmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \rho \\ \sigma_1 \sigma_2 \rho & \sigma_2^2 \end{pmatrix}$, then we can take $L = \begin{pmatrix} \sigma_1 & 0 \\ \sigma_2 \rho & \sqrt{1 - \rho^2} \sigma_2 \end{pmatrix}$, and the generation of

the two normal variates is given by the following algorithm:

$$\begin{cases} X_1 = \mu_1 + \sigma_1 Z_1 \\ X_2 = \mu_2 + \sigma_2 \rho Z_1 + \sigma_2 \sqrt{1 - \rho^2} Z_2 \end{cases}$$

It is easy to see that the means and variance-covariances of the pair are as desired.

Suggested Exercise: Derive the matrix L for $n=3$ case.

3.4 Simulation of Stochastic Differential Equation (SDE)

Consider a general (not the most general) Ito Stochastic Process given by:

$$X_t = x_0 + \int_0^t a(X_s)ds + \int_0^t b(X_s)dW_s$$

An SDE for of the above integral equation is given by the following:

$$dX_t = a(X_t)dt + b(X_t)dW_t, \text{ and } X_0 = x_0.$$

First, we will provide a result that will allow us to write an SDE for a function of a stochastic process, for which an SDE is known.

3.4.1 Ito's Formula

Suppose the stochastic process $\{X_t, t \geq 0\}$ is an Ito Process; that is, it can be written in the following form:

$$X_t = x_0 + \int_0^t a(X_s, s)ds + \int_0^t b(X_s, s)dW_s$$

The SDE of the above integral equation is given by

$$dX_t = a(X_t, t)dt + b(X_t, t)dW_t, \text{ and } X_0 = x_0.$$

We would like to be able to write the dynamics of a function $f(\cdot)$ of the process $\{X_t, t \geq 0\}$ in SDE form. The next result will help to answer this question.

Lemma (Itô) Assume $f(\cdot, \cdot) \in C^2(R \times R^+)$ and the process $\{X_t, t \geq 0\}$ satisfies

$$dX_t = a(X_t, t)dt + b(X_t, t)dW_t, \text{ and } X_0 = x_0.$$

Then, the SDE for $\{f(X_t, t), t \geq 0\}$ will be given by

$$\begin{aligned}
df(X_t, t) &= \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dX + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (dX)^2 \\
&= \left(\frac{\partial f}{\partial t} + \frac{\partial f}{\partial x} a(X_t, t) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} b(X_t, t)^2 \right) dt + \frac{\partial f}{\partial x} b(X_t, t) dW_t
\end{aligned}$$

Comment: In Ito's calculus, we will use the following products when dealing with terms like $(dX_t)^2$:

$$dt \, dt = dt \, dW_t = dW_t \, dt = 0, \text{ and } dW_t \, dW_t = dt$$

Example: $f(W_t, t) = \frac{1}{2} W_t^2$. Then

$$df(W_t, t) = d\left(\frac{1}{2} W_t^2\right) = 0dt + \frac{1}{2} 2W_t dW_t + \frac{1}{2} \left(\frac{1}{2} 2 \cdot 1\right) dt = W_t dW_t + \frac{1}{2} dt.$$

Integrating both sides will result in

$$\int_0^s W_t dW_t = \frac{1}{2} W_s^2 - \frac{1}{2} s$$

3.4.2 Higher Dimensional Ito's Formula

Assume the n-dimensional stochastic vector process $\{X_t, t \geq 0\}$ satisfies

$$dX_t = a(X_t, t)dt + b(X_t, t)dW_t, \text{ and } X_0 = x_0.$$

where

$$\begin{aligned}
X_t &= \begin{pmatrix} X_t^1 \\ X_t^2 \\ \vdots \\ X_t^n \end{pmatrix}, \quad a(X_t, t) = \begin{pmatrix} a^1(X_t, t) \\ a^2(X_t, t) \\ \vdots \\ a^n(X_t, t) \end{pmatrix}, \\
b(X_t, t) &= \begin{pmatrix} b^{11}(X_t, t), \dots, b^{1m}(X_t, t) \\ b^{21}(X_t, t), \dots, b^{2m}(X_t, t) \\ \vdots \\ b^{n1}(X_t, t), \dots, b^{nm}(X_t, t) \end{pmatrix}, \quad dW_t = \begin{pmatrix} dW_t^1 \\ dW_t^2 \\ \vdots \\ dW_t^m \end{pmatrix}
\end{aligned}$$

Let $f(t, x) = (f_1(t, x), \dots, f_k(t, x))$ be $C^2(R^+ \times R^n) \rightarrow R^k$.

Then, the SDE for $\{f(t, X_t), t \geq 0\}$ will be given by

$$df_i(t, X_t) = \frac{\partial f_i}{\partial t} dt + \sum_{j=1, \dots, n} \frac{\partial f_i}{\partial x_j} dX_j + \frac{1}{2} \sum_{j, l=1, \dots, n} \frac{\partial^2 f_i}{\partial x_j \partial x_l} (dX_j dX_l)$$

where, we use the following properties

$$dt dt = dt dW_t^i = dW_t^i dt = 0, \quad \text{and } dW_t^i dW_t^i = dt,$$

$$dW_t^i dW_t^j = 0 \text{ for any } i, j = 1, \dots, n, \text{ and } i \neq j.$$

Example:

$$dX_t = (a - X_t)dt + \sqrt{X_t}dW_t^1 + bY_t dW_t^2$$

$$dY_t = (cX_t Y_t)dt + (Y_t + 1)dW_t^1 + edW_t^2$$

and $X_0 = 1, Y_0 = 1/2$.

Define $f(t, x, y) = (f_1(t, x, y), f_2(t, x, y), f_3(t, x, y))$ to be $C^2(R^+ \times R^2) \rightarrow R^3$ as follows:

$$f_1(t, x, y) = txy, \quad f_2(t, x, y) = x + y, \quad f_3(t, x, y) = e^{x+y}.$$

Then,

$$\begin{aligned} df_1(t, X_t, Y_t) &= X_t Y_t dt + tX_t dY_t + tY_t dX_t + (t[(\sqrt{X_t})(Y_t + 1) + bY_t])dW_t^1 \\ &+ (X_t Y_t + ctX_t^2 Y_t + tY_t(a - X_t) + (t[(\sqrt{X_t})(Y_t + 1) + bY_t]))dW_t^2 \\ &+ ((tX_t(Y_t + 1) + tY_t)\sqrt{X_t})dW_t^1 + (tX_t e + tY_t^2)dW_t^2. \end{aligned}$$

Similarly we can express $df_2(t, X_t, Y_t)$ and $df_3(t, X_t, Y_t)$ in an SDE form.

3.5 DISCRETIZATION OF SDEs

Consider a general (not the most general) Ito Stochastic Process given by:

$$X_t = x_0 + \int_0^t a(X_s)ds + \int_0^t b(X_s)dW_s$$

An SDE for of the above integral equation is given by the following:

$$dX_t = a(X_t)dt + b(X_t)dW_t, \text{ and } X_0 = x_0.$$

The above integral equation or the SDE do not always have an explicit solution, so there is a need for numerical algorithms for solving the equations numerically. The basic idea is explained below. Discretize the $[0, T]$ interval by $0 = t_0 < t_1 < \dots < t_N = T$. Denote $\Delta = \frac{T}{N}$. There are a few discrete approximations to the SDE above, for simulation of its paths and for numerical calculations. We will consider the Euler's and Milshtein's discretization schemes here.

First, we will approximate the solutions of SDE by considering discrete time approximations that are derived from the stochastic Taylor expansions.

Assume the SDE for X_t is given by:

$$dX_t = a(X_t)dt + b(X_t)dW_t, \text{ and } X_0 = x_0.$$

The SDE can be written in an equivalent integral form:

$$X_t = x_0 + \int_0^t a(X_s)ds + \int_0^t b(X_s)dW_s$$

Now, applying the Ito's formula on $a(X_t)$ and, on $b(X_t)$, we will get:

$$\begin{aligned} da(X_t) &= a'(X_t)dX_t + \frac{1}{2}a''(X_t)(dX_t)^2 \\ &= \left(a'(X_t)a(X_t) + \frac{1}{2}a''(X_t)b(X_t)^2 \right) dt + a'(X_t) b(X_t)dW_t \end{aligned}$$

$$\begin{aligned}
db(X_t) &= b'(X_t)dX_t + \frac{1}{2}b''(X_t)(dX_t)^2 \\
&= \left(b'(X_t)a(X_t) + \frac{1}{2}b''(X_t)b(X_t)^2 \right) dt + b'(X_t) b(X_t)dW_t
\end{aligned}$$

which can be written as integral equations as follows:

$$\begin{aligned}
a(X_s) &= a(x_0) + \int_0^s \left(a'(X_u)a(X_u) + \frac{1}{2}a''(X_u)b(X_u)^2 \right) du + \int_0^s a'(X_u)b(X_u)dW_u \\
b(X_s) &= b(x_0) + \int_0^s \left(b'(X_u)a(X_u) + \frac{1}{2}b''(X_u)b(X_u)^2 \right) du + \int_0^s b'(X_u)b(X_u)dW_u
\end{aligned}$$

Replace $a(X_s)$ and $b(X_s)$ in the integral equation $X_t = x_0 + \int_0^t a(X_s)ds + \int_0^t b(X_s)dW_s$ by their expressions above to get:

$$\begin{aligned}
X_t &= x_0 + \\
&\int_0^t \left\{ a(x_0) + \int_0^s \left(a'(X_u)a(X_u) + \frac{1}{2}a''(X_u)b(X_u)^2 \right) du + \int_0^s a'(X_u)b(X_u)dW_u \right\} ds + \\
&\int_0^t \left\{ b(x_0) + \int_0^s \left(b'(X_u)a(X_u) + \frac{1}{2}b''(X_u)b(X_u)^2 \right) du + \int_0^s b'(X_u)b(X_u)dW_u \right\} dW_s
\end{aligned}$$

This will lead to the Ito-Taylor expansion of X_t . All Numerical algorithms for generating paths of the process X_t are based on the above formula. We will consider a few of those algorithms.

3.5.1 Euler Approximation

We can use the above integral equation and approximate the X_t process by taking a few terms on the right hand side.

$$\begin{aligned}
X_t &= x_0 + \int_0^t \{a(x_0)\} ds + \int_0^t \{b(x_0)\} dW_s + \\
&\int_0^t \left\{ \int_0^s \left(a'(X_u)a(X_u) + \frac{1}{2}a''(X_u)b(X_u)^2 \right) du + \int_0^s a'(X_u)b(X_u)dW_u \right\} ds +
\end{aligned}$$

$$\int_0^t \left\{ \int_0^s \left(b'(X_u)a(X_u) + \frac{1}{2} b''(X_u)b(X_u)^2 \right) du + \int_0^s b'(X_u)b(X_u)dW_u \right\} dW_s$$

If we only take the first three terms of the right hand side, then we will get this approximate discrete version of the above SDE:

$$\tilde{X}_t = \tilde{X}_0 + a(\tilde{X}_0)t + b(\tilde{X}_0)W_t$$

The general term can be written by

$$\tilde{X}_{t_{k+1}} - \tilde{X}_{t_k} = a(\tilde{X}_{t_k})\Delta + b(\tilde{X}_{t_k})\Delta W_{t_k}, \text{ and } \tilde{X}_0 = x_0.$$

Here $\Delta W_{t_k} = W_{t_{k+1}} - W_{t_k}$.

We know that for a Wiener process W_t , ΔW_{t_k} , $k = 0, \dots, N - 1$ are independent increments and are normally distributed $\Delta W_{t_k} \sim N(0, \Delta)$.

Theorem: Under certain regularity conditions (Lipschitz and bounded growth), the discrete version of the simulated \tilde{X}_N converges in a strong sense with order $1/2$ to the continuous-time version of X_T as $N \rightarrow \infty$:

$$\mathbb{E}(|\tilde{X}_N - X_T|) \leq K \left(\frac{T}{N} \right)^{1/2}$$

That is, the convergence of the Euler scheme is $N^{-1/2}$. There are other schemes that result in better convergence rates and we will consider one of them – the Milshtein's scheme.

Comment: The Euler scheme evaluates the process at discrete times: $t_0 < t_1 < \dots < t_N$. If needed, one can also approximate the values of the process at times that are in between the discretization times, say at time t so that $t_k < t < t_{k+1}$. One can use a simple linear interpolation to write:

$$\tilde{X}_t = \tilde{X}_{t_k} + \frac{t - t_k}{t_{k+1} - t_k} (\tilde{X}_{t_{k+1}} - \tilde{X}_{t_k})$$

3.5.2 The Milshtein's Scheme

Another discretized version of the above SDE that uses more terms in the Ito-Taylor expansion is given by the Milshtein's scheme:

$$\tilde{X}_{t_{k+1}} - \tilde{X}_{t_k} = a(\tilde{X}_{t_k})\Delta + b(\tilde{X}_{t_k})\Delta W_{t_k} + \frac{1}{2}b(\tilde{X}_{t_k})b'(\tilde{X}_{t_k})\{\Delta W_{t_k}^2 - \Delta\}, \text{ and } X_0 = x_0.$$

Here, $\Delta W_{t_k} = W_{t_{k+1}} - W_{t_k}$.

We know that the X_t can be written as follows:

$$\begin{aligned} X_t = x_0 &+ \int_0^t \{a(x_0)\} ds + \int_0^t \{b(x_0)\} dW_s + \\ &\int_0^t \left\{ \int_0^s \left(a'(X_u)a(X_u) + \frac{1}{2}a''(X_u)b(X_u)^2 \right) du + \int_0^s a'(X_u)b(X_u)dW_u \right\} ds + \\ &\int_0^t \left\{ \int_0^s \left(b'(X_u)a(X_u) + \frac{1}{2}b''(X_u)b(X_u)^2 \right) du + \int_0^s b'(X_u)b(X_u)dW_u \right\} dW_s \end{aligned}$$

We will rewrite the above equation as follows:

$$\begin{aligned} X_t = x_0 &+ \int_0^t \{a(x_0)\} ds + \int_0^t \{b(x_0)\} dW_s + \int_0^t \int_0^s b'(X_u)b(X_u)dW_u dW_s + \\ &\int_0^t \left\{ \int_0^s \left(a'(X_u)a(X_u) + \frac{1}{2}a''(X_u)b(X_u)^2 \right) du + \int_0^s a'(X_u)b(X_u)dW_u \right\} ds + \\ &\int_0^t \left\{ \int_0^s \left(b'(X_u)a(X_u) + \frac{1}{2}b''(X_u)b(X_u)^2 \right) du \right\} dW_s \end{aligned}$$

We will use the first three terms and only a part of the forth term of the right-side of the above expression to derive the Milshtein's scheme. To derive the scheme, we apply the Ito's lemma on the function $f(X_u) = b'(X_u)b(X_u)$ and replace the integrand in the integral

$\int_0^t \int_0^s b'(X_u)b(X_u)dW_u dW_s$ above by that expression. Then we will take only the first term of that integral's expansion and add to the other terms that determined the Euler's scheme to get the following:

$$X_t = x_0 + \int_0^t \{a(x_0)\} ds + \int_0^t \{b(x_0)\} dW_s + b'(x_0)b(x_0) \int_0^t \int_0^s dW_u dW_s +$$

(Higher Order Terms for $b'(X_u)b(X_u)$ expansion)+

$$\int_0^t \left\{ \int_0^s \left(a'(X_u)a(X_u) + \frac{1}{2}a''(X_u)b(X_u)^2 \right) du + \int_0^s a'(X_u)b(X_u)dW_u \right\} ds +$$

$$\int_0^t \left\{ \int_0^s \left(b'(X_u)a(X_u) + \frac{1}{2}b''(X_u)b(X_u)^2 \right) du \right\} dW_s$$

Use the fact that $\int_s^T W_t dW_t = \frac{1}{2}(W_T - W_s)^2 - \frac{1}{2}(T - S)$, to get the Milshtein's scheme:

$$\tilde{X}_{t_{k+1}} - \tilde{X}_{t_k} = a(\tilde{X}_{t_k})\Delta + b(\tilde{X}_{t_k})\Delta W_{t_k} + \frac{1}{2}b(\tilde{X}_{t_k})b'(\tilde{X}_{t_k})\{(\Delta W_{t_k})^2 - \Delta\}, \text{ and } X_0 = x_0$$

The following result justifies the use of the Milshtein's scheme in approximating SDE solutions.

Theorem: Under certain regularity conditions (Lipschitz and bounded growth), the discrete version of the simulated process \tilde{X}_N converges in a strong sense with order 1 to the continuous-time version of X_T as $N \rightarrow \infty$:

$$\mathbb{E}(|\tilde{X}_N - X_T|) \leq K \left(\frac{T}{N} \right)^1$$

That is, the rate of strong convergence of the Milshtein's scheme is N^{-1} . This is a significant improvement in the convergence rate, though it comes at the expense of adding an extra term. At the end, it will be a numerical exercise to compare the cost and benefits of adding that extra term and using the Milshtein's scheme, versus the Euler's one.

Note: The rate of weak convergence is the same here – it is 1.

How do we simulate the path of the stochastic process $\{X_t, 0 \leq t \leq T\}$?

In case of the Euler scheme we can use the following algorithm:

STEP 1: Set $\tilde{X}_{t_0} = x_0$,

STEP 2: Generate a sequence of $Z_1, Z_2, \dots, Z_N \sim iid N(0,1)$,

STEP 3: Define $\tilde{X}_{t_{k+1}} = \tilde{X}_{t_k} + a(\tilde{X}_{t_k})\Delta + b(\tilde{X}_{t_k})\sqrt{\Delta} Z_{k+1}$.

Thus, we have a simulated a path $\{\tilde{X}_{t_k}, k = 0, 1, \dots, N\}$ of the stochastic process $\{X_t, 0 \leq t \leq T\}$ at discrete times $0 = t_0 < t_1 < \dots < t_N = T$.

The Milshtein's scheme will be implemented in exact the same way.

3.6 The Heston Model

Consider the following 2-factor model for stock prices with stochastic volatility:

$$\begin{cases} dS_t = rS_t dt + \sqrt{V_t} S_t dW_t^1 \\ dV_t = \alpha(\beta - V_t)dt + \sigma\sqrt{V_t} dW_t^2 \end{cases}$$

where the Brownian Motion processes above are correlated: $dW_t^1 dW_t^2 = \rho dt$, where the correlation ρ is a constant in $[-1,1]$.

This model is referred to as the Heston Model.

Many practical applications of models with Heston-dynamics involve the pricing and hedging of path-dependent securities, which, in turn, nearly always requires the introduction of Monte Carlo methods.

Remark: Taking $V_0 > 0$ and $2\alpha\beta \geq \sigma^2$ guarantees that the process for V_t can never reach zero.

In typical applications, however, $2\alpha\beta$ is often significantly below σ^2 , so the chance of V_t hitting zero is significant. Also, in simulations often one faces the case of V_t turning negative, despite the choice of parameters that satisfy $2\alpha\beta \geq \sigma^2$.

To price securities one often needs to solve the above model numerically, using Monte Carlo simulations. Therefore a discretization scheme is used to simulate the dynamics of the price and volatility processes above. For demonstration purposes, we will use the Euler discretization method:

Let's consider a discretization scheme – the Euler scheme:

$$\hat{S}_{k+1} - \hat{S}_k = r\hat{S}_k \Delta + \sqrt{\hat{V}_k} \hat{S}_k \sqrt{\Delta} Z_{k+1}^1$$

$$\hat{V}_{k+1} - \hat{V}_k = \alpha(\beta - \hat{V}_k) \Delta + \sigma \sqrt{\hat{V}_k} \sqrt{\Delta} Z_{k+1}^2$$

Here, $\hat{V}_0 = V_0$ is given, $\hat{S}_0 = S_0$ is given. Also, Z_{k+1}^1 and Z_{k+1}^2 are standard normally distributed random variables with correlation ρ .

Since this is a finite discretization of a continuous process, it is possible to introduce *discretization errors* where V can become negative with non-zero probability, which in turn would make computation of $\sqrt{\hat{V}_k}$ impossible, and cause the scheme to fail.

To get around this problem, several remedies have been proposed in the literature; see the paper by Lord, R., R. Koekkoek and D. van Dijk (2006), “A Comparison of biased simulation schemes for stochastic volatility models” for a review of various “fixes”.

In order to handle negative values of V , we need to modify the above formula to include methods of eliminating negative values for subsequent iterations of the volatility path. Thus we introduce three new schemes, summarized below, by using three functions as defined below.

$$\hat{S}_{k+1} - \hat{S}_k = r\hat{S}_k \Delta + \sqrt{f_3(\hat{V}_k)} \hat{S}_k \sqrt{\Delta} Z_{k+1}^1$$

$$\hat{V}_{k+1} - f_1(\hat{V}_k) = \alpha(\beta - f_2(\hat{V}_k)) \Delta + \sigma \sqrt{f_3(\hat{V}_k)} \sqrt{\Delta} Z_{k+1}^2$$

Scheme	f_1	f_2	f_3
Reflection	$ x $	$ x $	$ x $
Partial Truncation	x	x	x^+
Full Truncation	x	x^+	x^+

The existing literature suggests that the Full Truncation method is the "best". Here is the method applied to the discretized Heston Model of Stock Price with Stochastic Volatility:

$$\hat{S}_{k+1} - \hat{S}_k = r\hat{S}_k \Delta + \sqrt{\hat{V}_k^+} \hat{S}_k \sqrt{\Delta} Z_{k+1}^1$$

$$\hat{V}_{k+1} - \hat{V}_k = \alpha(\beta - \hat{V}_k^+) \Delta + \sigma \sqrt{\hat{V}_k^+} \sqrt{\Delta} Z_{k+1}^2$$

where $\hat{V}_k^+ = \max(0, \hat{V}_k)$.

Remark: The main characteristic of this scheme is that the process for V is allowed to go below zero, at which point the process for V becomes deterministic with an upward drift of $\alpha\beta$.

3.7 Numerical Computation of $N(\cdot)$

The CDF of a standard normal distribution does not have a closed-form formula that can be used in computing the prices of options. Thus, it needs to be estimated numerically. Take

$$N(x) = \begin{cases} 1 - \frac{1}{2} (1 + d_1 x + d_2 x^2 + d_3 x^3 + d_4 x^4 + d_5 x^5 + d_6 x^6)^{-16}, & \text{if } x \geq 0 \\ 1 - N(-x), & \text{if } x < 0 \end{cases}$$

Then with the following choice of the parameters the method has an accuracy of 10^{-7} .

$$d_1 = 0.0498673470, \quad d_2 = 0.0211410061, \quad d_3 = 0.0032776263,$$

$$d_4 = 0.0000380036, \quad d_5 = 0.0000488906, \quad d_6 = 0.0000053830.$$

3.8 Exercises

1. Let S_t be a Geometric Brownian Motion process: .

$$S_t = S_0 e^{\left(\sigma W_t + \left(r - \frac{\sigma^2}{2}\right)t\right)}$$

where $r = 0.04$, $\sigma = 0.2$, $S_0 = 88$, and W_t is a Standard Brownian Motion process (Wiener process).

- (a) Estimate the price c of a European Call option on the stock with $T = 10$, $X = 100$ by using Monte Carlo simulation.
- (b) Now use the variance reduction techniques to compute the price in part (a) again. Did the accuracy improve? You may compute the exact value of the option c by the Black-Scholes formula, by using Excel. Now estimate c by crude Monte Carlo simulation, and then by using different variance reduction techniques to see if there is an improvement in convergence.

2. Simulate 4 paths of S_t for $0 \leq t \leq 10$ (defined in the Problem 4) by dividing up the interval $[0, 10]$ into 1,000 equal parts. Then, for each integer number n from 1 to 10, compute ES_n . Plot all of this in one graph.
3. Evaluate the following expected values and probabilities:

$$E\left(X_2^{\frac{1}{3}}\right), \quad E(Y_3), \quad E(X_2 Y_2 \mathbf{1}(X_2 > 1)), \quad P(Y_2 > 5).$$

where the Ito's processes X and Y evolve according to the following SDEs:

$$dX_t = \left(\frac{1}{5} - \frac{1}{2}X_t\right)dt + \frac{2}{3}dW_t, \quad X_0 = 1,$$

$$dY_t = \left(\left(\frac{2}{1+t}\right)Y_t + \frac{1+t^3}{3}\right)dt + \frac{1+t^3}{3}dZ_t, \quad Y_0 = \frac{3}{4}$$

W and Z are independent Wiener processes, and $\mathbf{1}(X_2 > 1) = 1$ if $X_2 > 1$, and 0 if $X_2 \leq 1$.

4. Estimate the following expected values and compare:

$$E(1 + X_3)^{1/3}, \text{ and } E(1 + Y_3)^{1/3}$$

where

$$dX_t = \frac{1}{4}X_t dt + \frac{1}{3}X_t dW_t - \frac{3}{4}X_t dZ_t, \quad X_0 = 1$$

$$Y_t = e^{-0.08t + \frac{1}{3}W_t - \frac{3}{4}Z_t}$$

and W and Z are independent Wiener processes.

5. (a) Compute the price of a European Call option via Monte Carlo simulation. Use variance reduction techniques (e.g. antithetic variates). The code should be generic: for any input of the 5 parameters $- S_0, T, X, r, \sigma$, the output is the corresponding price of the call option.
- (b) Compute the price of a European Call option by using the Black-Scholes formula. (use the approximation of $N(\cdot)$ described in class). The code should be generic: for any input values of the 5 parameters $- S_0, T, X, r, \sigma$, it should compute and return the value of the option price.
- (c) Compute the hedging parameters of a Call option (all 5 of the Greeks) and graph them as a function of stock price: S_0 , where $S_0=20, X = 20, \sigma = 0.25, r = 0.04$ and $T = 0.5$ years. Use the range $[15:25]$ for S_0 with a step size 1.
6. Compute the probability (by simulation) that a European *put* option will expire in the money. Use these parameters: $S_0 = 20, X = 20, \sigma = 0.25, r = 0.04$ and $T = 0.5$ years.
7. Compare the pseudorandom sample with the quasi MC sample of $Uniform[0,1] \times [0,1]$:
 - a) Generate 100 vectors of $Uniform [0,1] \times [0,1]$ by using MATLAB (or the software you are using) random number generator.
 - b) Generate 100 points of the 2-dimentional Halton sequences, using bases 2 and 7.
 - c) Generate 100 points of the 2-dimentional Halton sequences, using bases 2 and 4. (4 is non-prime!).
 - d) Draw all on separate graphs and see if there are differences in the three (visual test only).
 - e) Use 2-dimensional Halton sequences and compute the following integral:
(use $N = 10,000$. Try different pairs of bases: $(2,4), (2,7), (5,7)$.)

$$\int_0^1 \int_0^1 e^{-xy} \left(\sin(6\pi x) + \cos^{\frac{1}{3}}(2\pi y) \right) dx dy$$

8. Consider the following 3-factor model for short term interest rate (Balduzzi et al. model):

$$\begin{cases} dr_t = k(\alpha_t - r_t)dt + \sqrt{v_t}dW_t^1 \\ d\alpha_t = a(b - \alpha_t)dt + cdW_t^2 \\ dv_t = u(x - v_t)dt + z\sqrt{v_t}dW_t^3 \end{cases}$$

where $dW_t^1 dW_t^2 = \rho_1 dt$, $dW_t^2 dW_t^3 = \rho_2 dt$, $dW_t^3 dW_t^1 = \rho_3 dt$. Compute $E(r_2)$ and

$E(e^{-\int_0^2 r_s ds})$ for $\rho_1 = 0.5$, $\rho_2 = 0.2$, $\rho_3 = 0.4$. Choose $k = 0.1027$, $r_0 = 0.035$, $\alpha_0 = 0.036$, $a = 0.089$, $b = 0.0377$, $c = 0.05$, $v_0 = 0.15$, $u = 0.092$, $x = 0.18$, $z = 0.067$.

9. Consider the following 2-factor model for stock prices with stochastic volatility:

$$\begin{cases} dS_t = rS_t dt + \sqrt{V_t} S_t dW_t^1 \\ dV_t = \alpha(\beta - V_t)dt + \sigma\sqrt{V_t} dW_t^2 \end{cases}$$

where the Brownian Motion processes above are correlated: $dW_t^1 dW_t^2 = \rho dt$, where the correlation ρ is a constant in $[-1, 1]$.

Compute the price of a European Call option (via Monte Carlo simulation) that has a Strike price of \$50 and matures in 1 year. Use the following parameters of the model: $\rho = -0.6$, $r = 0.03$, $S_0 = \$48$, $V_0 = 0.25$, $\sigma = 0.42$, $\alpha = 5.8$, $\beta = 0.12$.

Use the Full Truncation, Partial Truncation and Reflection methods, and compare the efficiencies of the tree methods.

10. X and Y are standard normally distributed random variables. Define another random variable Z as follows: flip a fair coin and if the outcome is a Tale, take $Z = X$, otherwise take $Z = Y$. Describe the distribution of Z. What are the mean and the variance of Z? Use explicit formulas to answer. Use simulations to answer.

11. What is the sum of all the integers from 1 to 100? You have 30 seconds to answer!
12. You hold two European Call options with similar characteristics, but one (the first) matures in 1 year and the other (the second) matures in 3 months. Which will have higher delta? Higher Gamma? Use explicit formulas to answer. Use simulations to answer.
13. Which is more expensive: an ATM European call or an ATM European put on the same stock with the same maturity? Use explicit formulas to answer. Use simulations to answer.
14. Which is higher: the Gamma of an ATM European call or an ATM European put on the same stock with the same maturity? What if they both are 10% ITM or 10% OTM? Use explicit formulas to answer. Use simulations to answer.