

# 1 Two Data Augmentations

Suppose we have a joint distribution  $p(X, \theta) = p(X | \theta)p(\theta)$  specified by a likelihood and a prior. Bayesian statistics frames inferences about the unknown quantity  $\theta$  in terms of calculations involving the posterior  $p(\theta | X)$  given the observations. In many cases, it is helpful to work with an augmented model containing intermediate latent variables  $\mu$ . In general we have the *hierarchical factorization*

$$p(X, \mu, \theta) = p(X | \mu, \theta)p(\mu | \theta)p(\theta). \quad (1)$$

In a *sufficient augmentation* (SA), the new variables  $\mu$  are sufficient for  $\theta$ , so the factorization

$$p(X, \mu, \theta) = p(X | \mu)p(\mu | \theta)p(\theta) \quad (2)$$

holds. In an *ancillary augmentation* (AA), the new variables—denoted  $\nu$  for contrast—are independent of  $\theta$  a priori, so the joint distribution factorizes as

$$p(X, \nu, \theta) = p(X | \nu, \theta)p(\nu)p(\theta). \quad (3)$$

**Example.** In location families, for example, there are natural sufficient and ancillary augmentations. One important example is the normal-normal model. In the sufficient augmentation,

$$\mu | \theta \sim \mathcal{N}(\theta, V) \quad (4)$$

$$X | \mu, \theta \sim \mathcal{N}(\mu, 1) \quad (5)$$

with a flat prior on  $\theta$ , the posterior is  $\mathcal{N}(X, 1 + V)$ . In the ancillary augmentation,

$$\nu | \theta \sim \mathcal{N}(0, V) \quad (6)$$

$$X | \nu, \theta \sim \mathcal{N}(\nu + \theta, 1) \quad (7)$$

There is a one-to-one relationship  $\nu = \mu - \theta$  between the two augmentation schemes, but the performance of approximate posterior inference methods can differ depending on the choice of augmentation.

# 2 Variational Inference

*Mean-field variational inference* finds the factorized distribution over the latent which is closest in KL-divergence to the posterior. In the context of the previous example, our objective is

$$\min_{q(\mu), q(\theta)} D\left(q(\mu)q(\theta) \parallel p(\mu, \theta | X)\right), \quad (8)$$

and similarly for the ancillary augmentation. This is easily shown to be equivalent to maximizing the evidence lower bound (ELBO)

$$\max_{q=q(\mu)q(\theta)} \underbrace{\mathbb{E}_q \left[ \log \frac{p(X, \mu, \theta)}{q(\mu)q(\theta)} \right]}_{\mathcal{L}(q)}, \quad (9)$$

It is also easily shown that maximizing one variational factor  $q(\mu)$  with the other  $q(\theta)$  held fixed and vice versa is given in closed form by

$$q(\mu) \propto \exp \left\{ \mathbb{E}_{q(\theta)} [\log p(X, \mu, \theta)] \right\} \quad (10)$$

$$q(\theta) \propto \exp \left\{ \mathbb{E}_{q(\mu)} [\log p(X, \mu, \theta)] \right\} \quad (11)$$

Alternating (10) and (11) gives a coordinate ascent algorithm (called *CAVI*) for maximizing (9).

**Example.** (SA) Returning to the sufficient augmentation version of the normal-normal model above,

$$q(\mu) \triangleq \mathcal{N}(\hat{\mu}, \hat{\sigma}_\mu^2) \quad (12)$$

$$q(\theta) \triangleq \mathcal{N}(\hat{\theta}_S, \hat{\sigma}_{\theta_S}^2) \quad (13)$$

Since we are optimizing the variational parameters (denoted by  $\hat{\cdot}$ ), we include superscripts  $\hat{\mu}^{(t)}$  for the iteration number. Writing out the ELBO

$$\begin{aligned} \mathcal{L}(q) &= \mathbb{E}_q \left[ \log \frac{p(X, \mu, \theta)}{q(\mu)q(\theta)} \right] \\ &= \mathbb{E}_q \left[ \log p(X | \mu) \right] - \mathbb{E}_q \left[ \log \frac{q(\mu)}{p(\mu | \theta)} \right] - \mathbb{E}_q \left[ \log \frac{q(\theta)}{p(\theta)} \right] \\ &= \frac{2X\hat{\mu} - \hat{\sigma}_\mu^2 - \hat{\mu}^2}{2} + \log \hat{\sigma}_\mu - \frac{\hat{\sigma}_\mu^2 + \hat{\sigma}_{\theta_S}^2 + (\hat{\mu} - \hat{\theta})^2}{2V} + \log \hat{\sigma}_{\theta_S} + \text{const.} \end{aligned}$$

The coordinate ascent updates are

$$\hat{\mu}^{(t+1)} = \frac{VX + \hat{\theta}^{(t)}}{1 + V} \quad (14)$$

$$\hat{\sigma}_\mu^{2(t+1)} = \frac{V}{1 + V} \quad (15)$$

$$\hat{\theta}^{(t+1)} = \hat{\mu}^{(t+1)} \quad (16)$$

$$\hat{\sigma}_{\theta_S}^{2(t+1)} = V \quad (17)$$

Thus the variational parameter for the posterior variance of  $\theta$  given  $X$ ,  $\hat{\sigma}_{\theta_S}^{2(t+1)} = V$  underestimates the true posterior variance  $1 + V$  (this is a common property of variational Bayes). The variational parameter for the posterior mean of  $\theta$  given  $X$  satisfies

$$\left| \hat{\theta}^{(t+1)} - X \right| = \left| \frac{VX + \hat{\theta}^{(t)}}{1 + V} - X \right| = \frac{1}{1 + V} \left| \hat{\theta}^{(t)} - X \right|, \quad (18)$$

this parameter converges geometrically with rate  $\frac{1}{1+V}$ .

**Example.** (AA) For the ancillary augmentation, let

$$\tilde{q}(\nu) \triangleq \mathcal{N}(\hat{\nu}, \hat{\sigma}_\nu^2) \quad (19)$$

$$\tilde{q}(\theta) \triangleq \mathcal{N}(\hat{\theta}_A, \hat{\sigma}_{\theta_A}^2). \quad (20)$$

Again writing out the ELBO,

$$\begin{aligned} \mathcal{L}(\tilde{q}) &= \mathbb{E}_{\tilde{q}} \left[ \log \frac{p(X, \nu, \theta)}{\tilde{q}(\nu) \tilde{q}(\theta)} \right] \\ &= \mathbb{E}_{\tilde{q}} \left[ \log p(X \mid \nu, \theta) \right] - \mathbb{E}_{\tilde{q}} \left[ \log \frac{\tilde{q}(\nu)}{p(\nu)} \right] - \mathbb{E}_{\tilde{q}} \left[ \log \frac{\tilde{q}(\theta)}{p(\theta)} \right] \\ &= \frac{2X\hat{\nu} + 2X\hat{\theta} - 2\hat{\nu}\hat{\theta} - \hat{\sigma}_\nu^2 - \hat{\nu}^2 - \hat{\sigma}_{\theta_A}^2 - \hat{\theta}^2}{2} + \log \hat{\sigma}_\nu - \frac{\hat{\sigma}_\nu^2 + \hat{\nu}^2}{2V} + \log \hat{\sigma}_{\theta_A} + \text{const.} \end{aligned}$$

The coordinate ascent updates are

$$\hat{\nu}^{(t+1)} = \frac{V(X - \hat{\theta}^{(t)})}{1 + V} \quad (21)$$

$$\hat{\sigma}_\nu^{2(t+1)} = \frac{V}{1 + V} \quad (22)$$

$$\hat{\theta}^{(t+1)} = X - \hat{\nu}^{(t+1)} \quad (23)$$

$$\hat{\sigma}_{\theta_A}^{2(t+1)} = 1 \quad (24)$$

The variational parameter for the posterior mean of  $\theta$  given  $X$  satisfies

$$\left| \hat{\theta}^{(t+1)} - X \right| = \left| \hat{\nu}^{(t+1)} \right| = \frac{V}{1 + V} \left| X - \hat{\theta}^{(t)} \right|, \quad (25)$$

this parameter converges geometrically with rate  $\frac{V}{1+V}$ .

### 3 ASIS-CAVI

Consider the following algorithm for *ancillary sufficient interweaving scheme-coordinate ascent variational inference*, as inspired by Yu and Meng (2011).

1. Update  $q(\mu)$  using the CAVI update in the SA model,
2. Update  $q(\theta)$  using the CAVI update in the SA model,
3. Reparametrize: choose  $\tilde{q}(\nu)$ ,  $\tilde{q}(\theta)$  to minimize

$$\min_{\tilde{q}(\nu), \tilde{q}(\theta)} D\left(\tilde{q}(\nu)\tilde{q}(\theta) \parallel q(\nu + \theta)q(\theta)\right)$$

4. Update  $\tilde{q}(\nu)$  using the CAVI update in the AA model,
5. Update  $\tilde{q}(\theta)$  using the CAVI update in the AA model,
6. Reparametrize: choose  $q(\mu)$ ,  $q(\theta)$  to minimize

$$\min_{q(\mu), q(\theta)} D\left(q(\mu)q(\theta) \parallel \tilde{q}(\mu - \theta)\tilde{q}(\theta)\right)$$

7. Repeat 1 through 6 until convergence.

**Example.** Returning to the normal-normal model, we need to solve the reparametrization steps.

$$D\left(\tilde{q}(\nu)\tilde{q}(\theta) \parallel q(\nu + \theta)q(\theta)\right) = \mathbb{E}_{\tilde{q}}[\log q(\nu + \theta)q(\theta)] - H(\tilde{q}) \quad (26)$$

$$= \mathbb{E}_{\tilde{q}} \left[ \log \frac{1}{\sqrt{2\pi\hat{\sigma}_\mu^2}} \exp\left(-\frac{(\nu + \theta - \hat{\mu})^2}{2\hat{\sigma}_\mu^2}\right) \frac{1}{\sqrt{2\pi\hat{\sigma}_{\theta_S}^2}} \exp\left(-\frac{(\theta - \hat{\theta}_S)^2}{2\hat{\sigma}_{\theta_S}^2}\right) \right] - H(\tilde{q}) \quad (27)$$

$$= \text{const.} + \mathbb{E}_{\tilde{q}} \left[ -\frac{(\nu + \theta - \hat{\mu})^2}{2\hat{\sigma}_\mu^2} - \frac{(\theta - \hat{\theta}_S)^2}{2\hat{\sigma}_{\theta_S}^2} \right] + \log(2\pi e \hat{\sigma}_\nu \hat{\sigma}_{\theta_A}) \quad (28)$$

$$= \text{const.} - \frac{\hat{\nu}^2 + \hat{\sigma}_\nu^2 + \hat{\theta}_A^2 + \hat{\sigma}_{\theta_A}^2 + \hat{\mu}^2 - 2\hat{\nu}\hat{\mu} - 2\hat{\theta}_A\hat{\mu} + 2\hat{\nu}\hat{\theta}_A}{2\hat{\sigma}_\mu^2} \quad (29)$$

$$- \frac{\hat{\theta}_A^2 + \hat{\sigma}_{\theta_A}^2 + \hat{\theta}_S^2 - 2\hat{\theta}_S\hat{\theta}_A}{2\hat{\sigma}_{\theta_S}^2} + \log(2\pi e \hat{\sigma}_\nu \hat{\sigma}_{\theta_A}) \quad (30)$$

Setting derivatives equal to zero and finding fixed points,

$$\hat{\nu} = \hat{\mu} - \hat{\theta}_S \quad (31)$$

$$\hat{\theta}_A = \hat{\theta}_S \quad (32)$$

$$\sigma_\nu^2 = \hat{\sigma}_\mu^2 = \frac{V}{V+1} \quad (33)$$

$$\hat{\sigma}_{\theta_A}^2 = \left( \frac{1}{\hat{\sigma}_\mu^2} + \frac{1}{\hat{\sigma}_{\theta_S}^2} \right)^{-1} = \frac{V}{V+2} \quad (34)$$

Similarly deriving step (6),

$$\hat{\mu} = \hat{\nu} + \hat{\theta}_A \quad (35)$$

$$\hat{\theta}_S = \hat{\theta}_A \quad (36)$$

## 4 Alternate ASIS-CAVI

Consider the following algorithm for *ancillary sufficient interweaving scheme-coordinate ascent variational inference*, as inspired by Yu and Meng (2011).

1. Update  $q_\mu(\mu)$  using the CAVI update in the SA model,
2. Update  $q_\theta(\theta)$  using the CAVI update in the SA model,
3. Reparametrize: choose  $\tilde{q}_\nu(\nu)$  to minimize

$$\min_{\tilde{q}_\nu(\nu)} D\left(q_\mu(\mu) \parallel \tilde{q}_\nu(\mu - \theta)\right)$$

4. Update  $\tilde{q}_\theta(\theta)$  using the CAVI update in the AA model,
5. Repeat 1 through 4 until convergence.

**Example.** Returning to the normal-normal model, the only step we have yet to solve is (3)

$$D\left(q_\mu(\mu) \parallel \tilde{q}_\nu(\mu - \theta)\right) = \mathbb{E}_q \left[ \log \frac{q_\mu(\mu)}{\tilde{q}_\nu(\mu - \theta)} \right] \quad (37)$$

$$= \text{const.} - \mathbb{E}_q [\log \tilde{q}_\nu(\mu - \theta)] \quad (38)$$

$$= \text{const.} - \mathbb{E}_q \left[ \log \frac{1}{\sqrt{2\pi\hat{\sigma}_\nu^2}} \exp \left\{ -\frac{(\mu - \theta - \hat{\nu})^2}{2\hat{\sigma}_\nu^2} \right\} \right] \quad (39)$$

$$= \text{const.} + \log \hat{\sigma}_\nu + \frac{\hat{\nu}^2 - 2\hat{\mu}\hat{\nu} + 2\hat{\theta}\hat{\nu} + \hat{\mu}^2 + \hat{\sigma}_\mu^2 + \hat{\theta}^2 + \hat{\sigma}_{\theta_s}^2 - 2\hat{\mu}\hat{\theta}}{2\hat{\sigma}_\nu^2} \quad (40)$$

this yields

$$\hat{\nu}^{(t)} = \hat{\mu}^{(t)} - \hat{\theta}^{(t)} \quad (41)$$

$$\hat{\sigma}_\nu^{2(t)} = \hat{\sigma}_\mu^{2(t)} + \hat{\sigma}_{\theta_s}^{2(t)} = \frac{V+2}{V+1}V. \quad (42)$$

So the whole algorithm listed above is

$$\hat{\mu}^{(t+1)} = \frac{VX + \hat{\theta}^{(t)}}{1+V} \quad (43)$$

$$\hat{\sigma}_\mu^{2(t+1)} = \frac{V}{1+V} \quad (44)$$

$$\hat{\theta}^{(t+1)} = \hat{\mu}^{(t+1)} \quad (45)$$

$$\hat{\sigma}_\theta^{2(t+1)} = V \quad (46)$$

$$\hat{\nu}^{(t+1)} = \hat{\mu}^{(t+1)} - \hat{\theta}^{(t+1)} = 0 \quad (47)$$

$$\hat{\sigma}_\nu^{2(t+1)} = \frac{V+2}{V+1}V \quad (48)$$

$$\hat{\theta}^{(t+1)} = X - \hat{\nu}^{(t+1)} = X \quad (49)$$

$$\sigma_\theta^{2(t+1)} = 1 \quad (50)$$

The algorithm converges in one iteration.