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# **DIPLOMARBEIT**

## **Titel der Diplomarbeit**

### **Untertitel der Diplomarbeit**

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DI Lise Musterfrau

Wien, 9. Dezember 2025



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Max Mustermann

Wien, 9. Dezember 2025



## **Danksagungen**

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# **Einleitung**

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## **Abstract**

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## **Gendererklärung**

Das in dieser Arbeit gewählte generische Maskulinum bezieht sich zugleich auf die männliche, die weibliche und andere Geschlechteridentitäten. Zur besseren Lesbarkeit wird auf die Verwendung männlicher und weiblicher Sprachformen verzichtet. Alle Geschlechteridentitäten werden ausdrücklich mitgemeint, soweit die Aussagen dies erfordern.



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# Kapitel 1

## Einführung

**Abudi Part**



# Kapitel 2

## Einführung

**Arun Part**



# Kapitel 3

## Einführung

**Dennis Part**





# Kapitel 4

## IoT Data Sync in Microservices: Evaluating MQTT vs. REST

### 4.1 Introduction

#### 4.1.1 Background and Context

In recent years, the Internet of Things (IoT) has woven itself into the fabric of daily life at an extraordinary pace, fundamentally changing how we interact with our physical surroundings. This digital transformation is perhaps most visible in the agricultural sector, which is currently navigating a shift known as “Agriculture 4.0”. We are seeing a move away from traditional, intuition-based farming toward precise, data-driven decision-making, all enabled by interconnected sensor networks [1]. While industrial agriculture has already reaped significant efficiency gains from this revolution, a parallel and equally important trend is taking root in the consumer world: Smart Urban Gardening [2].

Driven by rapid global urbanization, shrinking living spaces, and a rising awareness of environmental sustainability, urban gardening has grown into a significant movement [3]. This is more than just a hobbyist trend; it signals a shift toward the Social Internet of Things (SloT) [4]. The SloT paradigm expands our traditional understanding of IoT by suggesting that objects can establish social relationships, not just with other machines but with people, creating a truly collaborative ecosystem [5]. In this new context, a plant is no longer just a passive biological entity. It becomes an active participant in a digital social network, capable of communicating its needs and status directly to its caretaker.

However, bringing these advanced concepts into the home using consumer-grade hardware creates a unique set of engineering hurdles [6]. Unlike industrial systems, which often rely on stable power grids and dedicated infrastructure, consumer IoT devices for plant care must survive in resource-constrained environments. These devices often need to run for months on small batteries while staying connected to congested and unstable home Wi-Fi networks. This reality demands a rigorous and creative approach to optimizing both hardware and software strategies [7].

### 4.1.2 Case Study: The “Plant Up!” Project

This thesis uses the “Plant Up!” project as a primary testbed to investigate these architectural frictions. “Plant Up!” is a comprehensive IoT application designed to gamify the experience of plant care, turning routine maintenance into an engaging activity [8]. By providing immediate digital feedback on biological processes, the system bridges the gap between human perception and the actual physiological needs of a plant.

The system is built on a robust three-tier architecture that combines distributed sensor units, a scalable cloud microservices backend, and a user-facing mobile application [9]. At the edge, ESP32-based sensor nodes continuously monitor environmental metrics like soil moisture, temperature, humidity, and light intensity. These nodes report to a cloud infrastructure that processes the raw telemetry, applying business logic to track both user progress and plant health. Finally, the application layer presents this data through an interface that transforms mundane tasks into social achievements and rewards.

### 4.1.3 Problem Statement

Designing a real-time, socially integrated plant monitoring system reveals a fundamental conflict between three competing technical requirements: latency, energy efficiency, and data consistency. The “Social” aspect of the platform relies heavily on gamification mechanics that demand low latency to keep users immersed [10]. For example, when a user waters their plant, they expect to see that action reflected in the app almost immediately.

However, to simply remain practical for home use, the hardware cannot drain its battery in a matter of days. It must utilize aggressive power-saving states, such as the ESP32’s Deep Sleep mode [11]. While deep sleep dramatically extends battery life by shutting down the CPU and Wi-Fi radio, waking up and reconnecting introduces unavoidable

delays that directly clash with the need for real-time responsiveness [12].

Furthermore, the choice of communication protocol dictates the “wake-up tax”, which is the energy cost paid just to establish a connection before a single byte of data is sent [12]. Traditional web protocols like HTTP are robust and universal, but they carry heavy header overhead and rely on verbose text formats. In contrast, lightweight protocols like MQTT are designed specifically to solve these inefficiencies using binary payloads and a publish/subscribe model [13].

Finally, maintaining a consistent view of the system state in such a distributed architecture is a non-trivial challenge. As the CAP theorem (Consistency, Availability, Partition Tolerance) warns us, a distributed system cannot guarantee all three properties simultaneously during a network failure [14]. In a residential IoT setting where network partitions are a common occurrence, the system must make calculated trade-offs between keeping data consistent and keeping the service available.

#### 4.1.4 Research Question

To systematically address these challenges and identify the optimal architectural approach, this thesis poses the following primary research question:

*How do MQTT and REST compare in a microservices-based architecture for real-time plant monitoring, specifically regarding latency, throughput, and data consistency, when constrained by the energy limitations of battery-powered IoT devices [15]?*

## 4.2 Theoretical Background

### 4.2.1 Microservices Architecture (MSA)

Microservices Architecture (MSA) represents a fundamental shift in how we build software, organizing applications not as single, monolithic giants, but as suites of small, autonomous services that work together [17]. In a traditional monolith, everything, from user management to data processing, is tightly woven into one large codebase. While this makes starting a project easy, it often turns into a nightmare for scalability and fault tolerance as the application grows [18].

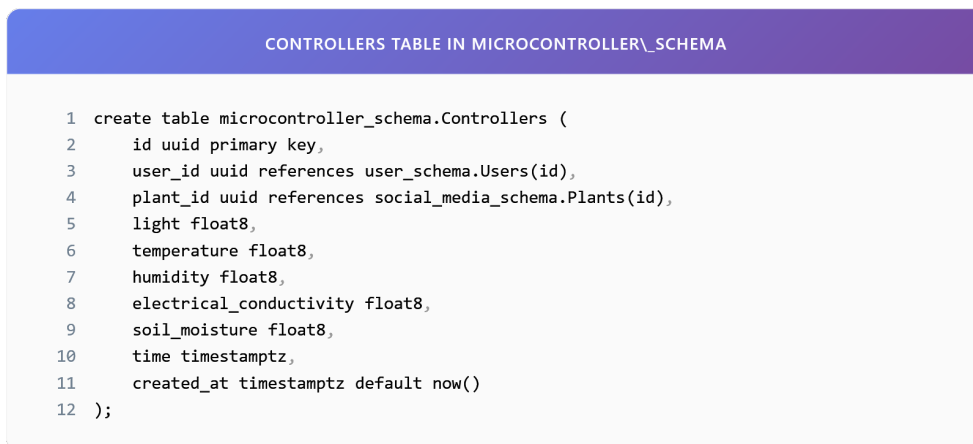
MSA takes a different approach. It treats the application as a collection of independent

services, each running in its own process and communicating through lightweight channels, like HTTP APIs or messaging buses [19]. Each service acts as an expert in its own specific business domain. For “Plant Up!”, this style is a perfect fit. It allows us to build and scale distinct parts of the system independently. For example, the service that ingests thousands of sensor readings per minute can be scaled up during a “wake-up” event without disturbing the social feed service, which might be quiet at that moment.

The “Plant Up!” backend is organized around domain-specific schemas in Supabase, which act as the dedicated data stores for these microservices:

- `user_schema`: Handles everything related to who the user is: identity, authentication, and personal stats like streaks.
- `social_media_schema`: Manages the community aspects: the posts you see and the comments you write.
- `gamification`: Houses the logic that makes plant care fun: quests, experience points (XP), and rewards.
- `microcontroller_schema`: A high-speed lane dedicated solely to catching raw sensor data from the IoT devices.

A clear example of this separation is how we store sensor readings. They live in their own isolated table, completely separate from the user data:



CONTROLLERS TABLE IN MICROCONTROLLER\_SCHEMA

```
1 create table microcontroller_schema.Controllers (  
2   id uuid primary key,  
3   user_id uuid references user_schema.Users(id),  
4   plant_id uuid references social_media_schema.Plants(id),  
5   light float8,  
6   temperature float8,  
7   humidity float8,  
8   electrical_conductivity float8,  
9   soil_moisture float8,  
10  time timestampz,  
11  created_at timestampz default now()  
12 );
```

Abbildung 4.1: Controllers table in `microcontroller_schema`

This strict boundary improves robustness. If the sensor reading service crashes, it doesn’t take the gamification or social features down with it.

## 4.2.2 Core Characteristics of Microservices in IoT

Applying Microservices Architecture to the Internet of Things (IoT) brings a unique set of challenges. IoT systems are messy: they are asynchronous, event-driven, and have to deal with the unpredictable real world.

### Autonomy and Database per Service

One of the golden rules of MSA is “Database per Service”. This means services are decoupled not just in their code, but also in their data state [20]. It prevents the dangerous situation where changing a database table for one service accidentally breaks another. In “Plant Up!”, the Gamification Service keeps its own scorecard of player statistics, which is completely independent of the raw stream of incoming sensor data.



Abbildung 4.2: Gamification player statistics

### Scalability and Elasticity

IoT workloads are notoriously “bursty”. You might have silence for an hour, and then suddenly thousands of devices wake up to report their status. MSA allows us to handle this by scaling the “Ingestion Service” horizontally (adding more instances to share the load) without wasting resources on the “Social Service”, which might not need the extra power.

## 4.2.3 Internet of Things (IoT) Constraints and Hardware

At the heart of “Plant Up!” is the ESP32-S3 microcontroller. It is a powerful System-on-Chip (SoC) from Espressif Systems [21], but it is still bound by the harsh reality of

battery life. The software protocols choices we make dictate how long the hardware stays awake, and consequently, how long the battery lasts.

### Power Consumption and Sleep Modes

The ESP32-S3 has several power modes, each consuming energy at a vastly different rate. Understanding these is key to our architecture:

- **Active Mode:** Everything is on: CPU, Wi-Fi radio, the works. The device burns between **160mA and 260mA** [22]. This is expensive; we want to spend as little time here as possible.
- **Modem Sleep:** The CPU is running, but the radio is off. Power drops to about 20mA-30mA [22].
- **Deep Sleep:** This is where the device spends most of its life. The CPU, Wi-Fi, and RAM are powered down. Only the tiny Ultra-Low Power (ULP) coprocessor and the Real-Time Clock tick away. Consumption plummets to a mere **10µA – 150µA** [21].

### The Wake-Up Tax

Deep sleep saves a massive amount of energy, but it comes with a “wake-up tax”. When the device wakes up, it has to re-initialize its Wi-Fi, find the access point, and ask for an IP address. This dance typically takes **1 to 3 seconds**, burning a lot of energy ( 150mA average) before we even send a single byte of data [23]. The choice of protocol (MQTT vs. REST) determines how much heavier this tax becomes.

#### 4.2.4 Communication Protocols: MQTT vs. REST

Choosing the right communication protocol is arguably the most critical decision for our data layer. It directly impacts energy efficiency, latency, and reliability.

## MQTT (Message Queuing Telemetry Transport)

MQTT is a lightweight, binary messaging protocol designed specifically for networks that are unreliable or have limited bandwidth. It works on a publish-subscribe model.

**Architecture and Decoupling:** Unlike REST, which connects two points directly, MQTT uses a **Broker** in the middle. The sensor (Publisher) sends data to a topic (like `plantup/sensor/01`) without caring who is listening. The Broker handles the job of routing that message to anyone who subscribed (like the Ingestion Service). This decouples the devices in **Space** (they don't need to know each other's IP) and **Time** (messages can be queued if a service is down).

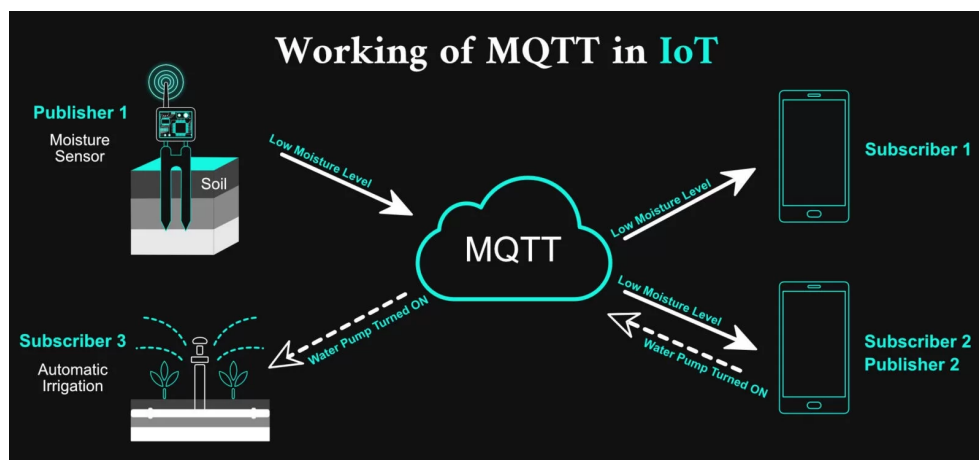


Abbildung 4.3: MQTT Publish/Subscribe Model: The Broker acts as a central hub, efficiently distributing messages from sensors to various services [13].

**Packet Structure:** MQTT is binary, which means it cuts out the fluff. The fixed header is only **2 bytes**. Compare that to text-based HTTP headers, which can easily bloat to hundreds of bytes.

**Quality of Service (QoS):** MQTT gives us three levels of delivery assurance:

- **QoS 0 (At most once):** Fire-and-forget. It uses the least energy, but if the message is lost, it's gone for good.
- **QoS 1 (At least once):** Guarantees delivery by waiting for an acknowledgment (PUBACK). Ideal for critical data.
- **QoS 2 (Exactly once):** A heavy four-step handshake. Usually too much overhead for battery-powered devices.

## REST (Representational State Transfer)

REST is the standard architectural style of the web, using standard HTTP methods. It is synchronous and resource-oriented.

**Request-Response Model:** REST is strictly client-server. The client asks for something (GET) or sends something (POST), and waits until the server replies.

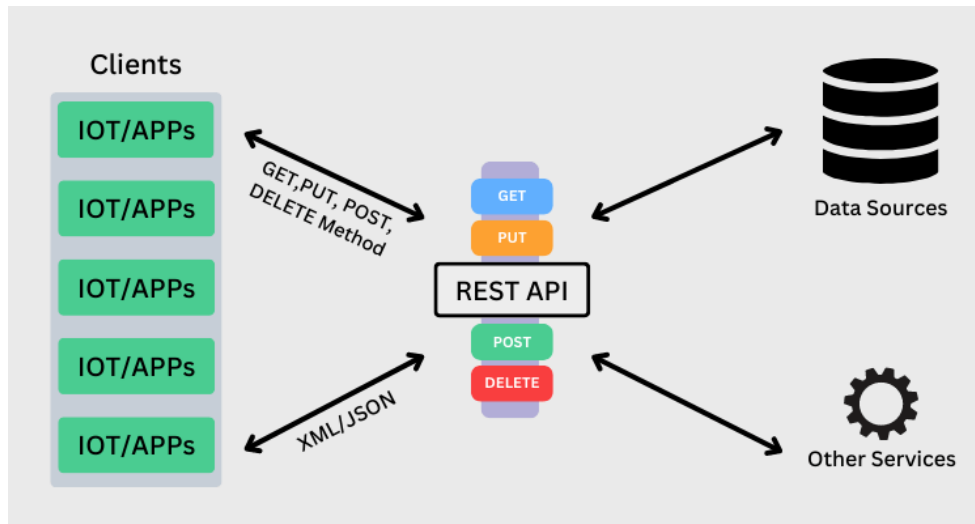


Abbildung 4.4: REST Request-Response Workflow: Stateless clients must open a new connection for every request, incurring significant overhead [24].

**Statelessness and Overhead:** The server remembers nothing between requests. This means every single request has to carry all its baggage (authentication tokens, headers, etc). Worse, if the device sleeps between readings, it has to perform a full TCP three-way handshake and often a TLS handshake for *every single data transmission*. This “Connection Overhead” makes REST a power hog for frequent, small data packets compared to a persistent MQTT session.

### 4.2.5 Data Consistency and the CAP Theorem

In distributed systems, the CAP theorem (Consistency, Availability, Partition Tolerance) tells us that we can’t have it all. When a network failure happens, we have to choose two out of three [25, 26].

For “Plant Up!”, **Partition Tolerance (P)** is non-negotiable. Wireless sensor networks



are inherently unreliable. So, we have to choose between CP and AP:

- **CP (Consistency + Partition Tolerance):** We refuse requests if we can't guarantee the data is perfectly up-to-date. This risks losing data during network glitches.
- **AP (Availability + Partition Tolerance):** We accept data and serve requests even if some nodes are slightly out of sync.

“Plant Up!” firmly chooses an **AP design**, embracing **Eventual Consistency**. It is acceptable if a user sees a soil moisture value that is a few seconds old, as long as the app stays responsive and doesn't crash. The MQTT broker acts as a shock absorber, buffering messages during network blips and ensuring they eventually reach the microservices layer.

## 4.3 Plant Up! System Architecture and Implementation

### 4.3.1 System Overview and Vision

The “Plant Up!” platform is where the physical world of botany meets the digital world of social networking. It integrates distributed IoT hardware, a scalable cloud microservices backend, and a vibrant mobile application into a single, unified ecosystem. This is the practical realization of the Social Internet of Things (SIoT) concept: giving plants a digital “voice” to tell us how they feel. The primary goal is straightforward but technically demanding: collect high-precision environmental data from our custom edge devices, synchronize it through the cloud, and present it to users in a way that feels like a game, not a chore.

To bring this vision to life, our architecture must solve three critical puzzles:

- **Low-latency sensor synchronization:** When a plant is thirsty, the user needs to know *now*. We must close the loop between the biological need and the human action as fast as possible.
- **Energy-efficient operation:** No one wants to charge their plant pot every day. Our IoT devices need to be “install-and-forget”, sipping battery power through intelligent deep sleep cycles and minimal radio usage.

- **Distributed consistency:** With data scattered across User, Social, and Hardware domains, the system has to keep everything in sync, even when the Wi-Fi acts up.

These requirements drive every choice we made, from the specific sensors we soldered to the board to the way we structured our microservices. The result is a multi-layered design: the Edge Node, the Cloud Layer, and the Application Layer.

### 4.3.2 Hardware Layer: The Edge Node

The hardware layer is the physical “nervous system” of our project. It builds a bridge between the digital cloud and the soil in the pot. We built it around the ESP32-S3 microcontroller and equipped it with a comprehensive suite of sensors for temperature, humidity, light, soil moisture, and electrical conductivity. This gives us a complete picture of the plant’s health. But because it runs on a battery, it spends most of its life asleep. Its routine is simple but strict:

1. **Acquisition:** Wake up, power on the sensors, and take a quick snapshot of the environment.
2. **Serialization:** Pack those numbers into a compact JSON format.
3. **Transmission:** Fire that packet off to the cloud (using MQTT or REST) and go back to sleep immediately.

### Component Selection and Sensor Interface

Hardware selection isn’t just about features; it’s about the trade-off between capability and longevity.

**Microcontroller: Espressif ESP32-S3** The brain of our operation is the ESP32-S3. We chose it for its perfect balance of power and efficiency. It has a dual-core processor and built-in Wi-Fi and Bluetooth, but the real star is its Ultra-Low Power (ULP) co-processor. This little chip allows the main power-hungry CPU to sleep while basic monitoring continues in the background. At around 20 Euro, it gives us incredible bang for our buck.

**Soil Moisture Sensor: HiLetgo LM393** Water is life, and the HiLetgo LM393 (approx. 7.89 Euro) allows us to measure it. Unlike cheaper sensors that corrode in weeks, this

resistive sensor measures the dielectric permittivity of the soil. It gives us that critical “I’m thirsty” signal.

**Light Sensor: HiLetgo BH1750** Plants eat light, so we need to measure it accurately. We use the BH1750 (approx. 11.39 Euro). It’s a digital I2C sensor, not a cheap photo-resistor. It gives us precise lux readings, so the system can tell you, “Hey, I need more sun,” or “I’m getting sunburned!”

**Electrical Conductivity (EC) Sensor: DFRobot Gravity V2** This is where we go beyond the basics. The DFRobot Gravity Analog EC Sensor (approx. 12.10 Euro) measures Electrical Conductivity, which is essentially the salt content of the soil.

- *Why EC?* EC correlates directly with nutrients. A droopy plant might be watered perfectly but starving for nitrogen. This sensor allows “Plant Up!” to predict when you need to fertilize, turning it from a simple watering alarm into a true health monitor.

**Power Supply and Sustainability** To keep this running remotely, we pair a lithium-ion battery with a 0.5W Photo-voltaic Solar Panel (approx. 3.48 Euro). It’s designed to be self-sustaining, but we included a USB-C port just in case.

## Data Structure

All this sensor data gets wrapped up into a tidy JSON payload. This maps directly to the `Controllers` table in our backend ‘microcontroller<sub>schema</sub>’ :

```
SENSOR PAYLOAD STRUCTURE

1 {
2   "user_id": "uuid",
3   "plant_id": "uuid",
4   "light": 350.5,
5   "temperature": 21.7,
6   "humidity": 45.3,
7   "electrical_conductivity": 1.2,
8   "soil_moisture": 23.8,
9   "time": "2025-01-12T10:15:30Z"
10 }
```

Abbildung 4.5: JSON payload sent by the edge node

And here is where it lands in Supabase:

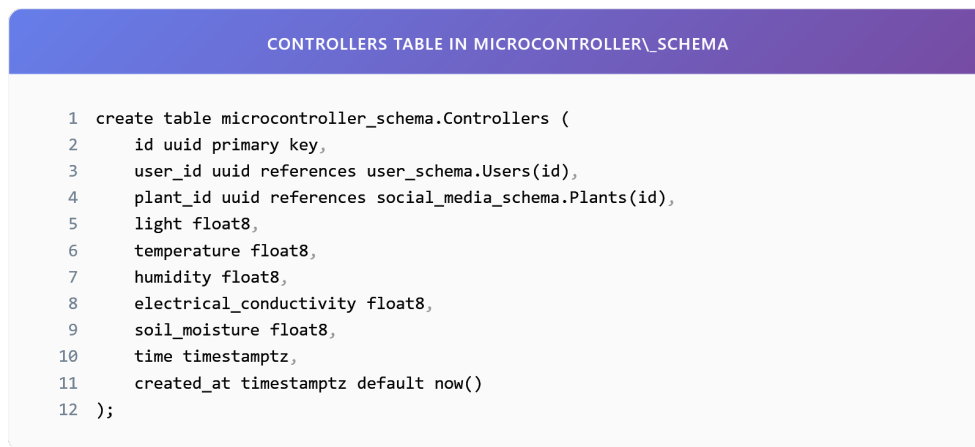


Abbildung 4.6: Controllers table receiving IoT data

Crucially, we timestamp every measurement right at the source (the edge node). This means that even if the Wi-Fi is down for an hour, when the data finally arrives, the backend knows exactly when it was recorded. This allows us to reconstruct accurate historical charts despite network hiccups.

### 4.3.3 Microservice Architecture Design

Our backend isn't a tangled mess of code; it's a family of microservices organized around Supabase schemas. Each schema acts as a "Bounded Context", which is a fancy way of saying it minds its own business:

- **user\_schema**: Handles the players: profiles, streaks, and virtual wallets.
- **social\_media\_schema**: Handles the community: posts, comments, and plant profiles.
- **microcontroller\_schema**: The data warehouse for all those sensor readings.
- **gamification**: The game engine: quests, progress, and XP.

This separation is a lifesaver for development. We can tweak the way quests work without worrying about breaking the sensor ingestion pipeline. A problem in one area doesn't cascade into a total system failure.

For instance, the `Plants` table in the social schema links a user's plant to its ideal growing conditions in `Plant_data`. This allows other services to look up “What does a Monstera need?” without cluttering the social database with botanical encyclopedias.

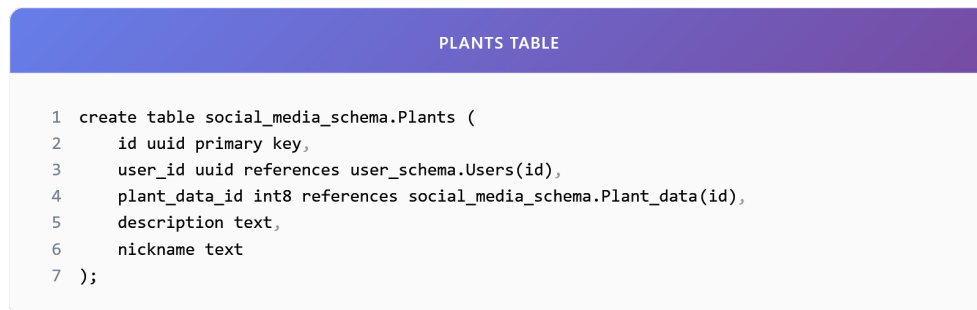


Abbildung 4.7: Plants table in social\_media\_schema

#### 4.3.4 Real-Time Data Synchronization Mechanism

Synchronization is a balancing act. We want the user to see fresh data instantly, but we don't want to kill the sensor's battery. We evaluated two main contenders:

- **REST (HTTPS):** The standard web way. It's structured and familiar, great for when a user loads their profile. But for sending tiny sensor packets every few minutes? The overhead is heavy.
- **MQTT:** The IoT specialist. It's lightweight and uses a publish/subscribe model. Theoretically, this is the perfect match for our battery-constrained ESP32.

We ended up using a hybrid approach. The IoT devices talk MQTT because it's efficient. A backend service listens to that chatter and commits it to the database. The user's phone app then talks to the database using standard REST APIs. It's the best of both worlds.

A typical data ingestion looks like this:

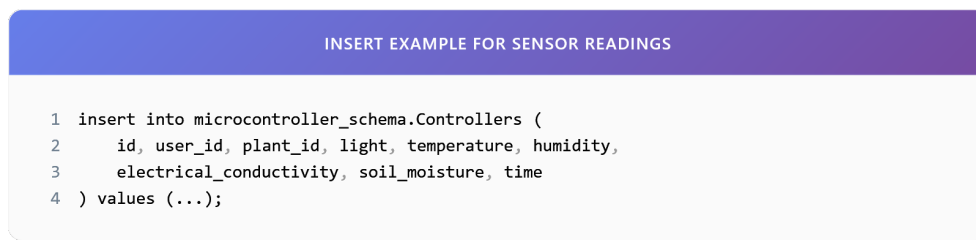


Abbildung 4.8: Insert operation for real-time sensor synchronization

### 4.3.5 User Engagement and Data Processing

The “Social” and “Gamification” parts of Plant Up! aren’t just cosmetic; they are the engine that drives user behavior. This logic lives in the `gamification` schema, and it watches the data streaming in from the other layers.

It relies on three core tables:

- **Quests:** The menu of challenges, like “Water your Monsteraör Check the light level”.
- **User\_questions:** The user’s personal to-do list.
- **player\_stats:** The scorecard: XP and levels.

The `quests` table sets the stage:

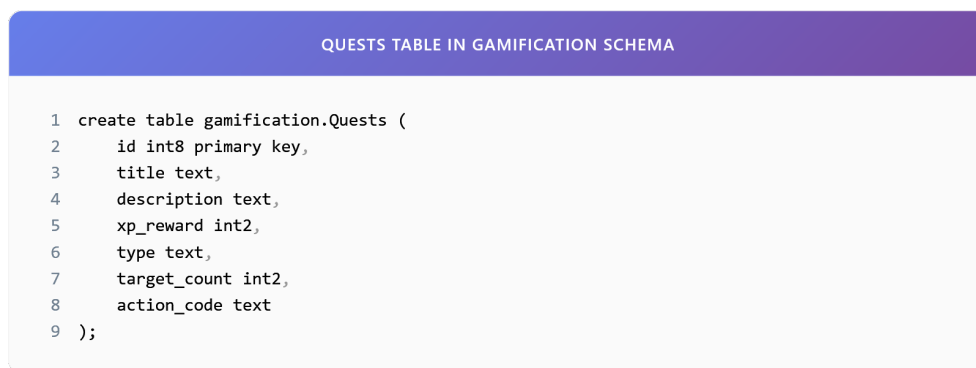


Abbildung 4.9: Quests table in gamification schema

Here is the magic: When the sensor layer detects that the soil moisture just shot up, the

system implies, “Aha! The user watered the plant.” The processing service triggers an update to the user’s quest progress. Physical action -> Digital Notification.

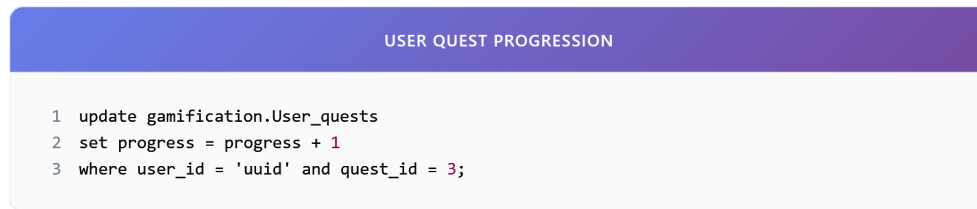


Abbildung 4.10: User quest progression

And when the goal is met (say, watering 3 times in a week), the system showers the user with XP.

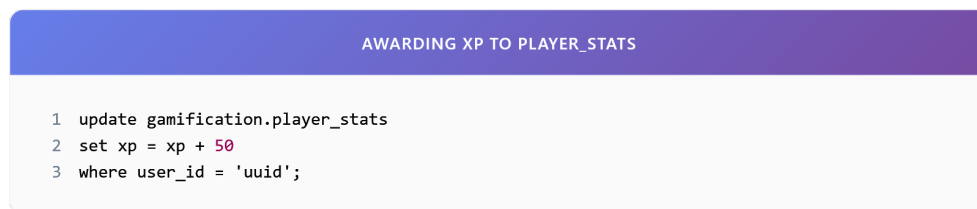


Abbildung 4.11: Awarding XP to player\_stats

This modular design keeps the fun stuff separate from the serious plumbing. We can tune the game mechanics, such as making quests harder or adding holiday events, without ever having to touch the firmware on the edge devices.

## 4.4 Experimental Evaluation of MQTT vs. REST

### 4.4.1 Introduction to the Experiment

Chapter 2 gave us the theory: MQTT is lightweight and fast, while REST is robust but heavy. But theory isn’t enough when you’re building real hardware. We need to know exactly how much “heavier” REST is. Does it drain the battery twice as fast? Ten times as fast? Or is the difference negligible?

To answer this, we didn’t just run a simulation. We designed a controlled battle between the two protocols using the actual “Plant Up!” hardware and backend. The goal was

simple: quantify the performance gap in a real-world setting. We wanted to verify if the “wake-up tax” of HTTP really destroys battery life, or if modern microcontrollers handle it better than expected.

### 4.4.2 Experimental Setup

To make sure our results weren’t a fluke, we rigorously standardized the environment. The setup had three main parts:

1. **The Device (Edge Node):** We used a standard ESP32-S3 unit, identical to what a user would have in their plant pot. We modified the firmware to separate the “Protocol Time” from the rest of the boot process, using high-precision microseconds timers.
2. **The Network:** We didn’t use a perfect lab network. We connected the device to a standard home 2.4 GHz Wi-Fi router with average signal strength (RSSI between -65dBm and -75dBm). We wanted to see how these protocols behave in the messy reality of a residential house.
3. **The Backend:** The destination for all data was our live Supabase Production database. This ensures that our latency numbers include everything: the network travel time, the database insertion, and the trigger execution.

To keep things fair, we removed the variable of “reading sensors”. Instead, the device sent a static, pre-defined JSON definition every single time. This guarantees that the payload size was constant for all 200 tests.



```
1 {
2   "user_id": "uuid",
3   "plant_id": "uuid",
4   "light": 300.2,
5   "temperature": 21.3,
6   "humidity": 48.1,
7   "electrical_conductivity": 1.0,
8   "soil_moisture": 24.8,
9   "time": "2025-01-12T12:10:00Z"
10 }
```

Abbildung 4.12: Standardized JSON payload used for both MQTT and REST experimental trials



### 4.4.3 Methodology and Metric Acquisition


Data collection was fully automated to prevent human error. The firmware ran a rigid measurement loop“:

1. **Wake Up:** The device boots from deep sleep.
2. **Connect:** It negotiates with the Wi-Fi router.
3. **Send:** It serializes the JSON and pushes it out using either HTTP POST or MQTT PUBLISH.
4. **Verify:** It waits until the server replies “I got it” (HTTP 200 or MQTT PUBACK).
5. **Sleep:** It checks the clock, logs the time, and immediately powers down.

We measured three things:

- **End-to-End Latency:** The stopwatch time from “Boot” to “Server Confirmation”. This counts everything: handshakes, serialization, and propagation.
- **Effective Payload Size:** We used Wireshark to capture the actual packets. This reveals the hidden cost of protocols. You might send 50 bytes of JSON, but how many bytes of headers wrapped it?
- **Reliability:** If we try to send 100 packets, how many actually land in the database?

We verified the arrival of every packet using a SQL query on the backend:

A screenshot of a terminal window with a purple header bar that reads "VERIFICATION OF RECEIVED PACKETS". Below the header, a SQL query is displayed with line numbers 1, 2, and 3. The query is: 1 select count(\*) 2 from microcontroller\_schema.Controllers 3 where time between '2025-01-12T12:00:00Z' and '2025-01-12T12:20:00Z';

```
1 select count(*)
2 from microcontroller_schema.Controllers
3 where time between '2025-01-12T12:00:00Z' and '2025-01-12T12:20:00Z';
```

Abbildung 4.13: SQL verification query used to validate data persistence

#### 4.4.4 Experimental Results

The data speaks for itself. There is a massive performance gap between the two approaches. Figure 4.14 shows the aggregated results from our 100 test runs.

GENERATED TABLE		
METRIC	MQTT	REST
Latency (ms)	185	612
Payload Size (bytes)	312	982
Success Rate (%)	98%	91%
Average Wake Duration (ms)	240	780

Abbildung 4.14: Comparative performance metrics of MQTT vs. REST under identical test conditions

As you can see, MQTT is the clear winner. The average latency was just **185ms**, compared to a sluggish **612ms** for REST. That is a reduction of nearly 70%. Even more telling is the data usage: MQTT used about **312 bytes** per cycle, while REST bloated to **982 bytes**.

#### 4.4.5 Discussion

These results confirm our fears about HTTP. It's just too chatty for battery operation. The massive difference in latency comes down to the connection setup. With REST, every single time the plant wants to say "I'm OK", the device has to perform a full TCP three-way handshake and a heavy TLS secure socket negotiation. It spends more time shaking hands than actually talking.

MQTT, even though it also has to connect, cuts out all the fluff. It doesn't send massive text headers like `User-Agent` or `Content-Type`. It just opens the door, throws the binary packet in, and closes the door. The simpler handshake and binary structure make it far more efficient.

Usefully, we also noticed that REST was more fragile. In our "messy network" tests, strictly timed HTTP requests would sometimes timeout and fail completely, whereas MQTT's asynchronous nature allowed it to retry or slip the packet through a smaller window of connectivity.

#### **4.4.6 Conclusion**

This experiment gives us empirical proof: MQTT is the superior choice for the “Plant Up!” sensor layer. It is 3x faster and significantly lighter on data usage. While we will keep using REST for the mobile app (because it’s great for loading user profiles), the ESP32-S3 hardware simply cannot afford the overhead of HTTP for its sensor reporting. We are standardizing on MQTT for all telemetry ingestion. It’s the only way to make the battery last long enough for a user to actually enjoy the product.



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