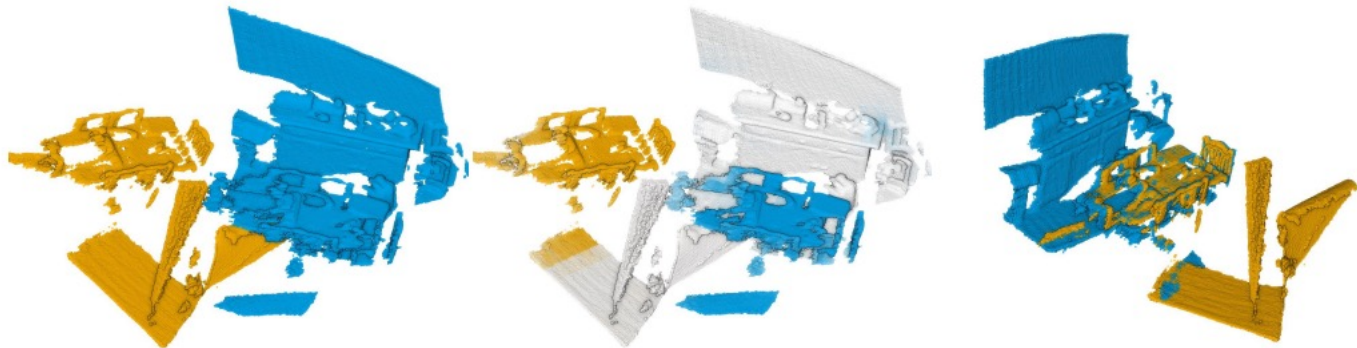


3DMatch



ModelNet40



odometryKITTI



(a) 输入点云

(b) 推理重叠区域

(c) 配准结果