```
File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/gradients_impl.py", line 158, in gradients
     unconnected_gradients)
   File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/gradients_util.py", line 731, in _GradientsHelper
      lambda: grad_fn(op, *out_grads))
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/gradients_util.py", line 403, in _MaybeCompile
      return grad_fn() # Exit early
   File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/gradients_util.py", line 731, in <lambda>
     lambda: grad_fn(op, *out_grads))
  File \ "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/math\_grad.py", \ line \ 142, \ in \ \_MeanGrad.py = 1.00 \ and 1
     output_shape = array_ops.shape(op.outputs[0])
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/array_ops.py", line 330, in shape
     return shape_internal(input, name, optimize=True, out_type=out_type)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/ops/array_ops.py", line 357, in shape_internal
     return constant(input_shape.as_list(), out_type, name=name)
   File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/framework/constant_op.py", line 246, in constant
     allow broadcast=True)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/framework/constant op.py". line 290, in constant impl
     name=name).outputs[0]
   File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/util/deprecation.py", line 507, in new_func
     return func(*args, **kwargs)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/framework/ops.py", line 3616, in create_op
     op def=op def)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/framework/ops.py", line 2040, in __init__
     self._graph._add_op(self) # pylint: disable=protected-access
   File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/framework/ops.py", line 3240, in _add_op
     with self._lock:
KeyboardInterrupt
Process Process-1:
Traceback (most recent call last):
  File "/home/ubuntu/anaconda3/lib/python3.7/multiprocessing/process.py", line 297, in _bootstrap
   File "/home/ubuntu/anaconda3/lib/python3.7/multiprocessing/process.py", line 99, in run
     self._target(*self._args, **self._kwargs)
   File "/home/ubuntu/_uti_basic.py", line 70, in fun
     q_out.put((i, f(x)))
  File "/home/ubuntu/simu_funs.py", line 84, in once
      inner_parallel = inner_parallel)
  File "/home/ubuntu/simu_funs.py", line 252, in simu_once
     inner_parallel = inner_parallel)
  File "/home/ubuntu/main.py", line 158, in V_DR
      r = arr([getOneRegionValue(i) for i in range(N)])
  File "/home/ubuntu/main.py", line 158, in <listcomp>
     r = arr([getOneRegionValue(i) for i in range(N)])
  File "/home/ubuntu/main.py", line 114, in getOneRegionValue
     spatial = False)
  File "/home/ubuntu/main.py", line 262, in getWeight
  epsilon = epsilon, spatial = spatial, mean_field = mean_field)
File "/home/ubuntu/weight.py", line 301, in train
     self.policy_ratio2: policy_ratio2
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/client/session.py", line 950, in run
      run metadata ptr)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/client/session.py", line 1173, in _run
  feed_dict_tensor, options, run_metadata)
File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/client/session.py", line 1350, in _do_run
  run_metadata)
File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/client/session.py", line 1356, in _do_call
     return fn(*args)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/client/session.py", line 1341, in _run_fn
     options, feed dict, fetch list, target list, run metadata)
  File "/home/ubuntu/.local/lib/python3.7/site-packages/tensorflow/python/client/session.py", line 1429, in _call_tf_sessionrun
     run metadata)
KeyboardInterrupt
ubuntu@ip-172-31-6-10:~$ export openblas_num_threads=1; export OMP_NUM_THREADS=1; python EC2.py
13:40, 04/13; num of cores:96
sd_u_0_30
Basic setting: [rep_times, sd_0, sd_D, sd_u_0, w_0, w_A, u_0_u_D, t_func] = [16, None, None, 40, 0.5, 1.5, 0, None]
[thre_range, sd_R_range, day_range, penalty_range]: [[95, 100, 110, 120, 125, 140], [0, 20, 40], [7], [[0.0001, 5e-05], [0.0001, 5e-05]
11
[pattern_seed, day, sd_R] = [2, 7, 0]
max(u_0) = 191.7
0_{threshold} = 95
means of Order:
83.3 97.7 14.6 165.6 28.3
66.3 120.1 50.2 57.7 63.6
122.1 191.7 101.7 55.3 121.6
76.2 99.2 147.0 70.1 100.4
64.9 93.7 110.3 60.4 86.4
target policy:
```

```
0 1 0 1 0
0 1 0 0 0
1 1 1 0 1
 01101
0 0 1 0 0
 number of reward locations: 11
 0_{threshold} = 100
 number of reward locations: 9
 0_{threshold} = 110
 number of reward locations: 7
 0_{threshold} = 120
 number of reward locations: 6
 0_{threshold} = 125
 number of reward locations: 3
 0_{threshold} = 140
 number of reward locations: 3
 target 1 in 1 DONE!
 Value of Behaviour policy:50.343
 0_{threshold} = 95
 MC for this TARGET: [62.565, 0.076]
[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias: [[-0.25, -0.48, -1.6]] [[-0.78, -62.56, -12.22]]
std: [[0.42, 0.42, 0.35]] [[0.3, 0.0, 0.3]]
MSE: [[0.49, 0.64, 1.64]] [[0.84, 62.56, 12.22]]
MSE(-DR): [[0.0, 0.15, 1.15]] [[0.35, 62.07, 11.73]]
 ___
 0_threshold = 100
MC for this TARGET:[61.987, 0.078]

[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-1.19, -1.39, -2.28]][[-2.67, -61.99, -11.64]]
std:[[0.59, 0.6, 0.44]][[0.33, 0.0, 0.3]]
MSE:[[1.33, 1.51, 2.32]][[2.69, 61.99, 11.64]]
MSE(-DR):[[0.0, 0.18, 0.99]][[1.36, 60.66, 10.31]]
 ***
=========
 0_threshold = 110
0_threshold = 110
MC for this TARGET:[61.518, 0.077]
    [DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-3.08, -3.25, -4.27]][[-5.17, -61.52, -11.17]]
std:[[0.59, 0.63, 0.39]][[0.31, 0.0, 0.3]]
MSE:[[3.14, 3.31, 4.29]][[5.18, 61.52, 11.17]]
MSE(-DR):[[0.0, 0.17, 1.15]][[2.04, 58.38, 8.03]]
 ***
 <del>---</del>-----
 0_{threshold} = 120
 MC for this TARGET: [59.981, 0.073]
[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias: [[-2.95, -3.09, -3.82]][[-5.85, -59.98, -9.64]]
std: [[0.62, 0.62, 0.47]][[0.32, 0.0, 0.3]]
MSE: [[3.01, 3.15, 3.85]][[5.86, 59.98, 9.64]]
MSE(-DR): [[0.0, 0.14, 0.84]][[2.85, 56.97, 6.63]]
 0_{threshold} = 125
MC for this TARGET: [60.214, 0.078]

[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]

bias: [[-7.25, -7.31, -7.3]] [[-12.62, -60.21, -9.87]]
 std:[[1.01, 1.04, 0.45]][[0.33, 0.0, 0.3]]
 MSE:[[7.32, 7.38, 7.31]][[12.62, 60.21, 9.87]]
 MSE(-DR):[[0.0, 0.06, -0.01]][[5.3, 52.89, 2.55]]
 0_{threshold} = 140
 MC for this TARGET: [60.214, 0.078]
[DR_VO/VIS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-7.26, -7.31, -7.35]][[-12.63, -60.21, -9.87]]
std:[[1.02, 1.04, 0.44]][[0.33, 0.0, 0.3]]
MSE:[[7.33, 7.38, 7.36]][[12.63, 60.21, 9.87]]
 MSE(-DR):[[0.0, 0.05, 0.03]][[5.3, 52.88, 2.54]]
 ***
 ____
 [[ 0.49  0.64  1.64  0.84  62.56  12.22]
  [ 1.33 1.51 2.32 2.69 61.99 11.64]
[ 3.14 3.31 4.29 5.18 61.52 11.17]
  [ 3.01 3.15 3.85 5.86 59.98 9.64]
```

```
[ 7.32 7.38 7.31 12.62 60.21 9.87]
[ 7.33 7.38 7.36 12.63 60.21 9.87]]
time spent until now: 17.0 mins
13:57. 04/13
[pattern_seed, day, sd_R] = [2, 7, 20]
max(u_0) = 191.7
O_threshold = 95
means of Order:
83.3 97.7 14.6 165.6 28.3
66.3 120.1 50.2 57.7 63.6
122.1 191.7 101.7 55.3 121.6
76.2 99.2 147.0 70.1 100.4
64.9 93.7 110.3 60.4 86.4
target policy:
0 1 0 1 0
0 1 0 0 0
1 1 1 0 1
0 1 1 0 1
0 0 1 0 0
number of reward locations: 11
0_{threshold} = 100
number of reward locations: 9
0_{threshold} = 110
number of reward locations: 7
0 \text{ threshold} = 120
number of reward locations: 6
0 \text{ threshold} = 125
number of reward locations: 3
0_threshold = 140
number of reward locations: 3
target 1 in 1 DONE!
Value of Behaviour policy:50.315
0_{threshold} = 95
MC for this TARGET: [62.596, 0.239]

[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias: [[-0.14, -0.41, -1.5]] [[-0.92, -62.6, -12.28]]
std:[[0.98, 0.96, 0.6]][[0.66, 0.0, 0.28]]
MSE:[[0.99, 1.04, 1.62]][[1.13, 62.6, 12.28]]
MSE(-DR):[[0.0, 0.05, 0.63]][[0.14, 61.61, 11.29]]
***
0_threshold = 100
MC for this TARGET: [62.018, 0.241]
    [DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-0.95, -1.16, -2.21]][[-2.75, -62.02, -11.7]]
std:[[0.98, 0.98, 0.47]][[0.62, 0.0, 0.28]]
MSE:[[1.36, 1.52, 2.26]][[2.82, 62.02, 11.7]]
MSE(-DR):[[0.0, 0.16, 0.9]][[1.46, 60.66, 10.34]]
0_threshold = 110
MC for this TARGET:[61.549, 0.239]
[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-3.11, -3.36, -4.13]][[-5.18, -61.55, -11.23]]
std:[[1.14, 1.18, 0.55]][[0.52, 0.0, 0.28]]
MSE:[[3.31, 3.56, 4.17]][[5.21, 61.55, 11.23]]
MSE(-DR):[[0.0, 0.25, 0.86]][[1.9, 58.24, 7.92]]
=========
0_{threshold} = 120
MC for this TARGET: [60.013, 0.24]
[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-3.01, -3.2, -3.8]][[-5.94, -60.01, -9.7]]
std:[[1.12, 1.16, 0.66]][[0.48, 0.0, 0.28]]
```

```
MSE:[[3.21, 3.4, 3.86]][[5.96, 60.01, 9.7]]
MSE(-DR):[[0.0, 0.19, 0.65]][[2.75, 56.8, 6.49]]
=========
0_threshold = 125
MC for this TARGET: [60.246, 0.241]
[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-7.76, -7.81, -7.51]][[-12.72, -60.25, -9.93]]
std:[[1.58, 1.66, 0.66]][[0.5, 0.0, 0.28]]
MSE:[[7.92, 7.98, 7.54]][[12.73, 60.25, 9.93]]
MSE(-DR):[[0.0, 0.06, -0.38]][[4.81, 52.33, 2.01]]
**
_____
0 \text{ threshold} = 140
MC for this TARGET: [60.246, 0.241]
[DR/QV/IS]; [DR_NO_MARL, DR_NO_MF, V_behav]
bias:[[-7.77, -7.81, -7.54]][[-12.72, -60.25, -9.93]]
std:[[1.53, 1.66, 0.71]][[0.52, 0.0, 0.28]]
MSE:[[7.92, 7.98, 7.57]][[12.73, 60.25, 9.93]]
MSE(-DR):[[0.0, 0.06, -0.35]][[4.81, 52.33, 2.01]]
**
[[ 0.49  0.64  1.64  0.84  62.56  12.22]
 [ 1.33 1.51 2.32 2.69 61.99 11.64]
[ 3.14 3.31 4.29 5.18 61.52 11.17]
  [ 3.01 3.15 3.85 5.86 59.98 9.64]
 [ 7.32 7.38 7.31 12.62 60.21 9.87]
[ 7.33 7.38 7.36 12.63 60.21 9.87]
[[ 0.99 1.04 1.62 1.13 62.6 12.28]
 [ 1.36  1.52  2.26  2.82 62.02 11.7 ]
[ 3.31  3.56  4.17  5.21 61.55 11.23]
 [ 3.21 3.4 3.86 5.96 60.01 9.7 ]
[ 7.92 7.98 7.54 12.73 60.25 9.93]
 [ 7.92 7.98 7.57 12.73 60.25 9.93]]
time spent until now: 34.2 mins
14:14, 04/13
[pattern_seed, day, sd_R] = [2, 7, 40]
max(u_0) = 191.7
0 \text{ threshold} = 95
means of Order:
83.3 97.7 14.6 165.6 28.3
66.3 120.1 50.2 57.7 63.6
122.1 191.7 101.7 55.3 121.6
76.2 99.2 147.0 70.1 100.4
64.9 93.7 110.3 60.4 86.4
target policy:
0 1 0 1 0
0 1 0 0 0
1 1 1 0 1
0 1 1 0 1
0 0 1 0 0
number of reward locations: 11
0_threshold = 100
number of reward locations: 9
0_{threshold} = 110
number of reward locations: 7
0_{threshold} = 120
number of reward locations: 6
0_{threshold} = 125
number of reward locations: 3
0_{threshold} = 140
number of reward locations: 3
```