



# Using an iterative Markov Chain process to develop driving cycles based on large-scale GPS data: a case study in Beijing

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## Introduction

- Typical Driving Cycles are important in evaluation of vehicle fuel consumption, emission and environmental impacts.
- Researches have shown that previous regulatory driving cycles (e.g., NEDC) fail to represent real-world traffic effects on vehicle emissions.
- Second-by-second vehicle trajectory data collected from various road types, traffic conditions and individual vehicles (e.g., 459 vehicles in this study) are fundamental to develop representative driving cycles under various circumstances of concerns.
- We have developed representative driving cycles of passenger cars in Beijing by using a Markov Chain stochastic method.

## Theory and Method

- Markov Chain Process.** The shift between two consecutive quasi-instantaneous (typically 2 – 3 seconds) driving status can be simulated by the Markov Chain method. The driving status of the next moment is in association with the present status by probability.

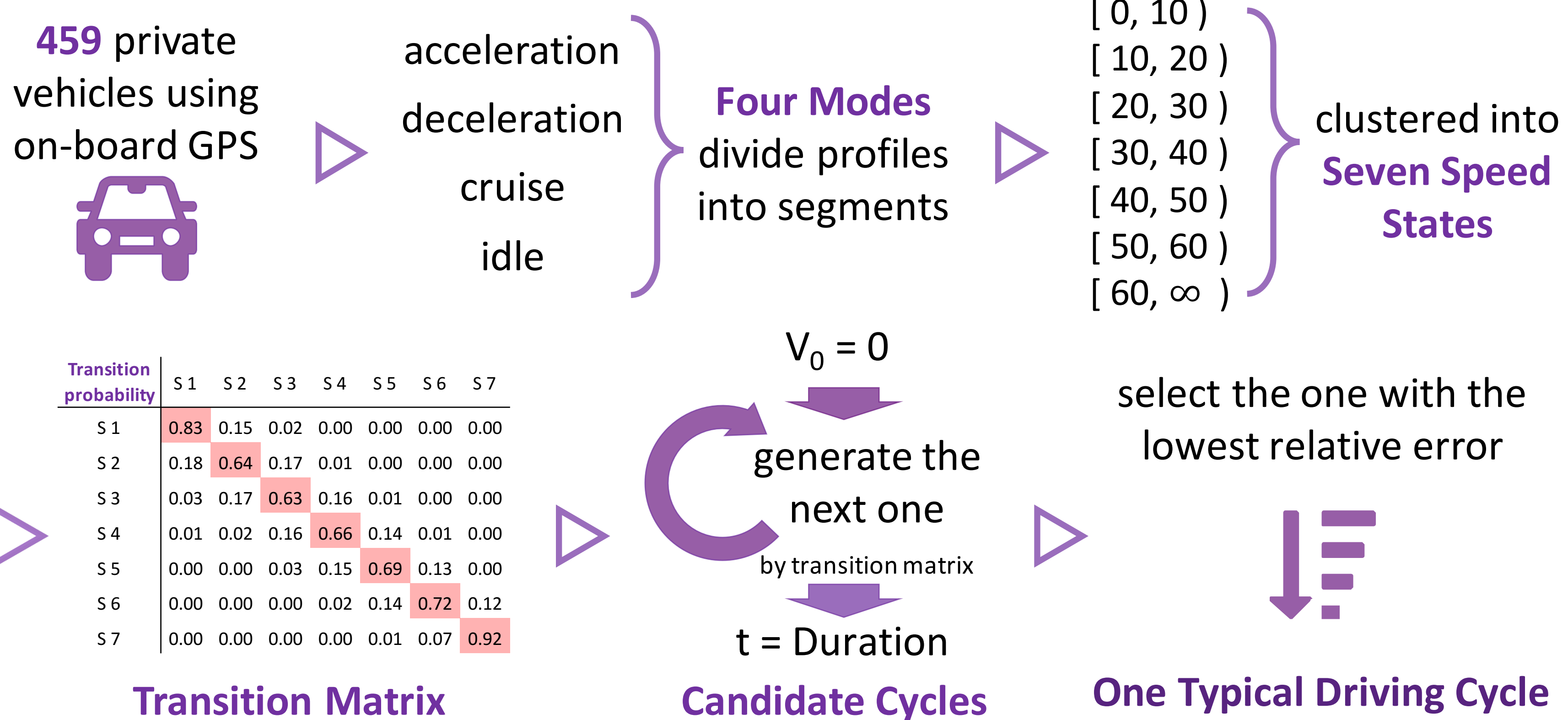
$$P\{X_{n+1} = j | X_0 = i_0, X_1 = i_1, \dots, X_n = i\} =$$

$$P\{X_{n+1} = j | X_n = i\}$$

One-step transition probability matrix:

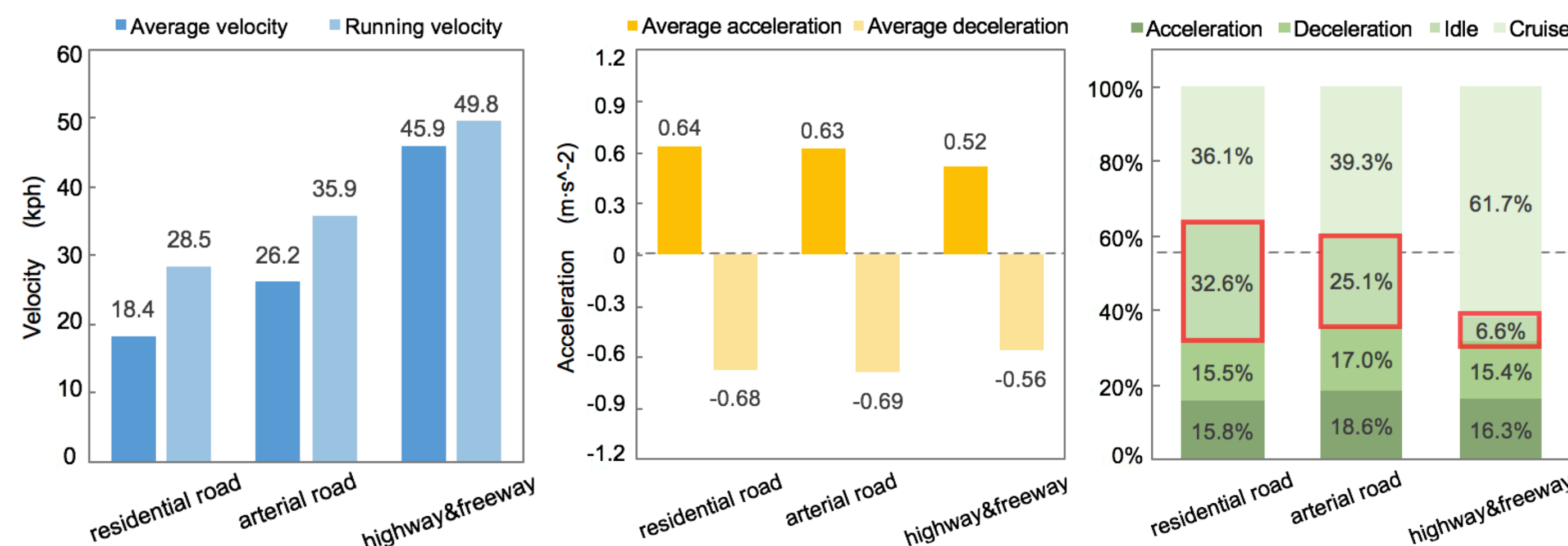
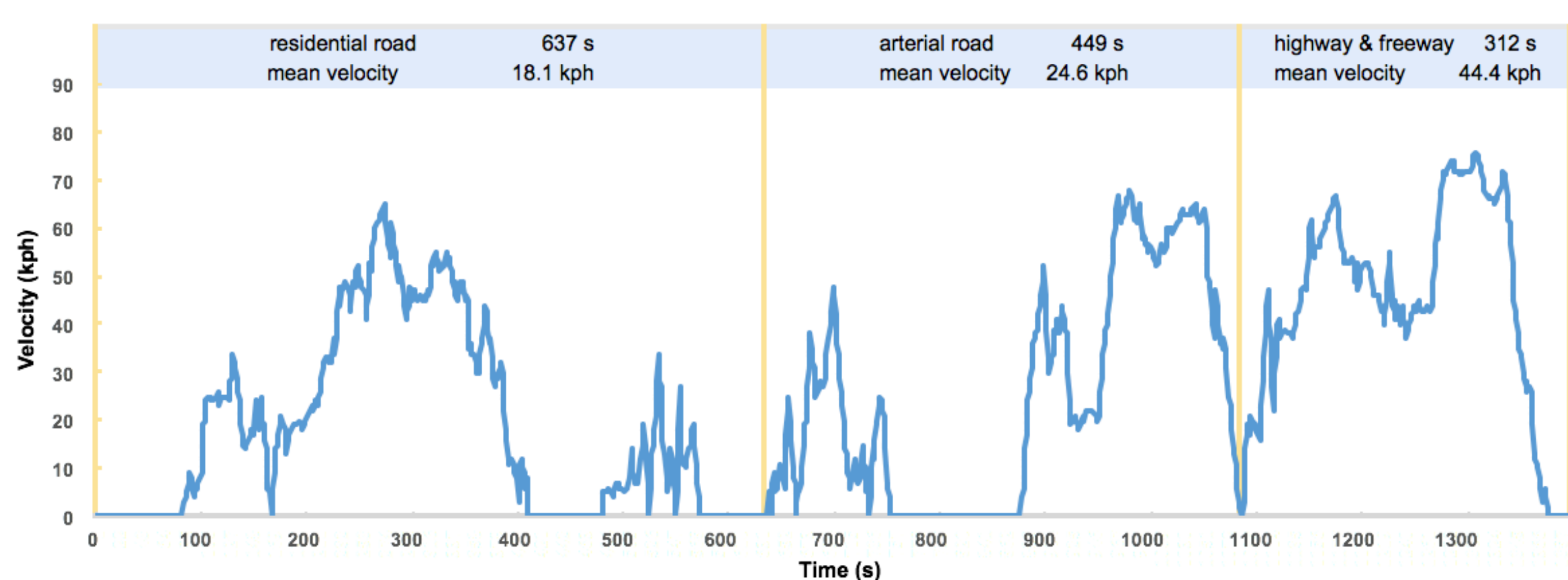
$$P = (p_{ij}) = \begin{pmatrix} p_{00} & p_{01} & p_{02} & p_{03} & \cdots \\ p_{10} & p_{11} & p_{12} & p_{13} & \cdots \\ p_{20} & p_{21} & p_{22} & p_{23} & \cdots \\ p_{30} & p_{31} & p_{32} & p_{33} & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

- Driving Cycle Development**

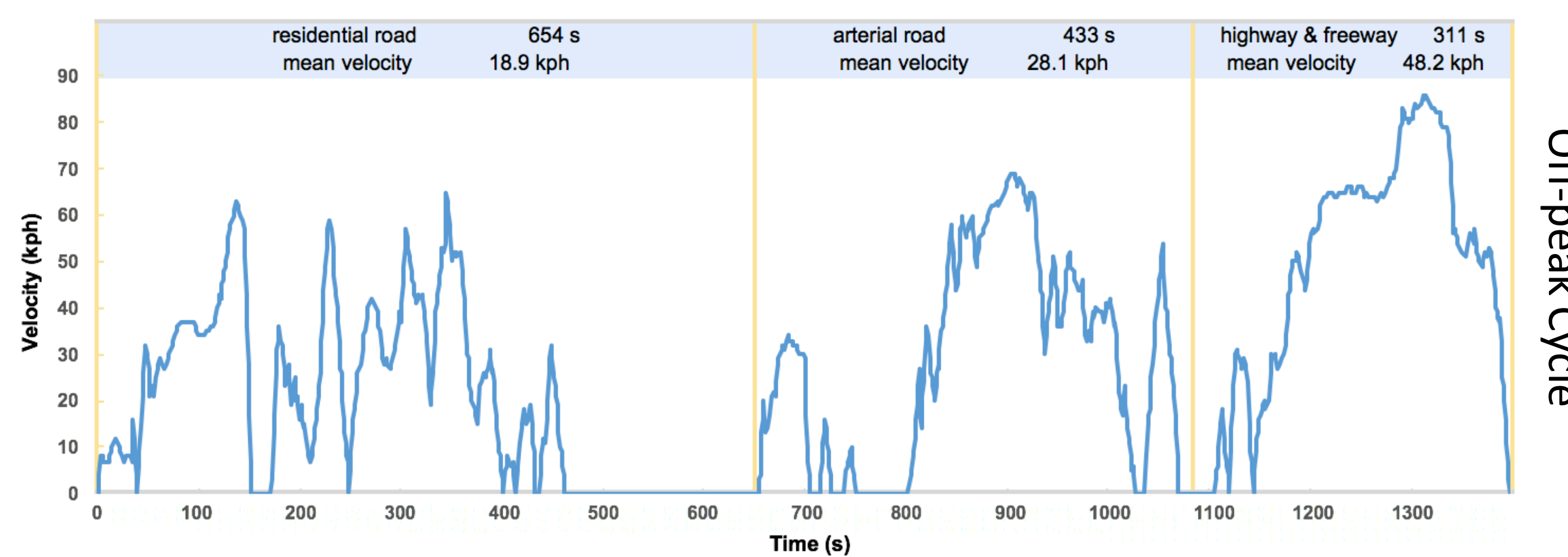
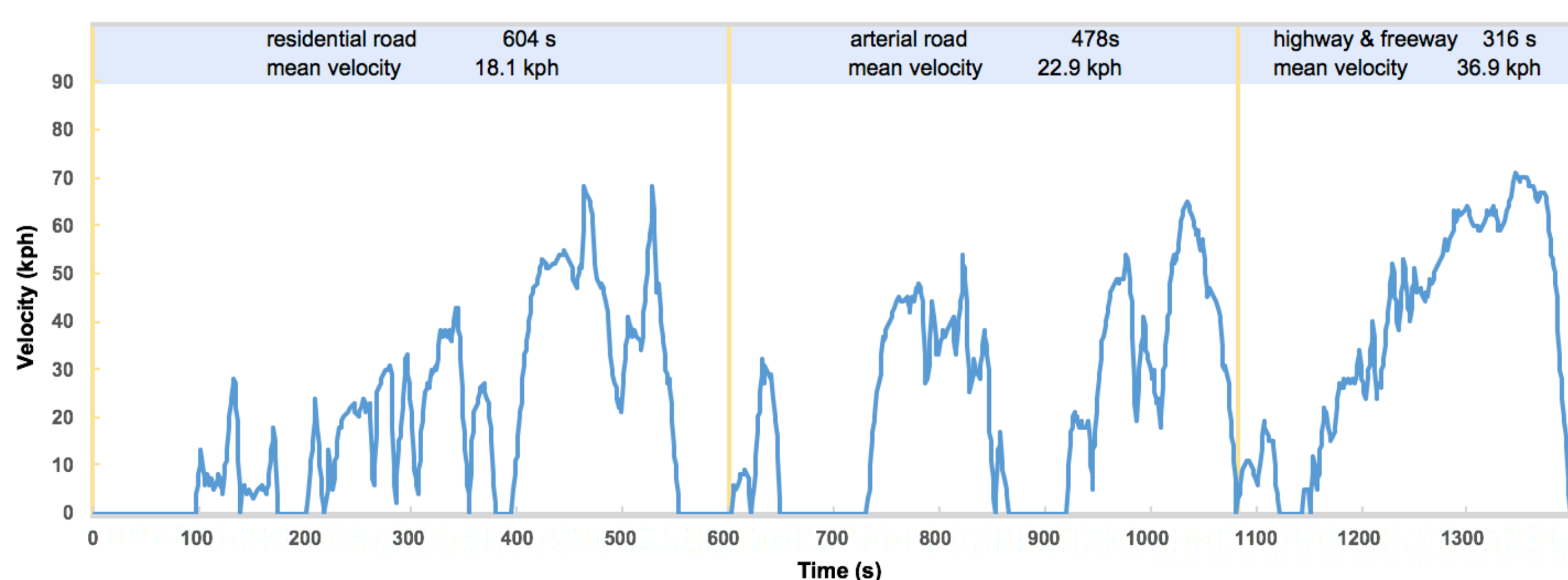


## Results

- Spatial Analysis**

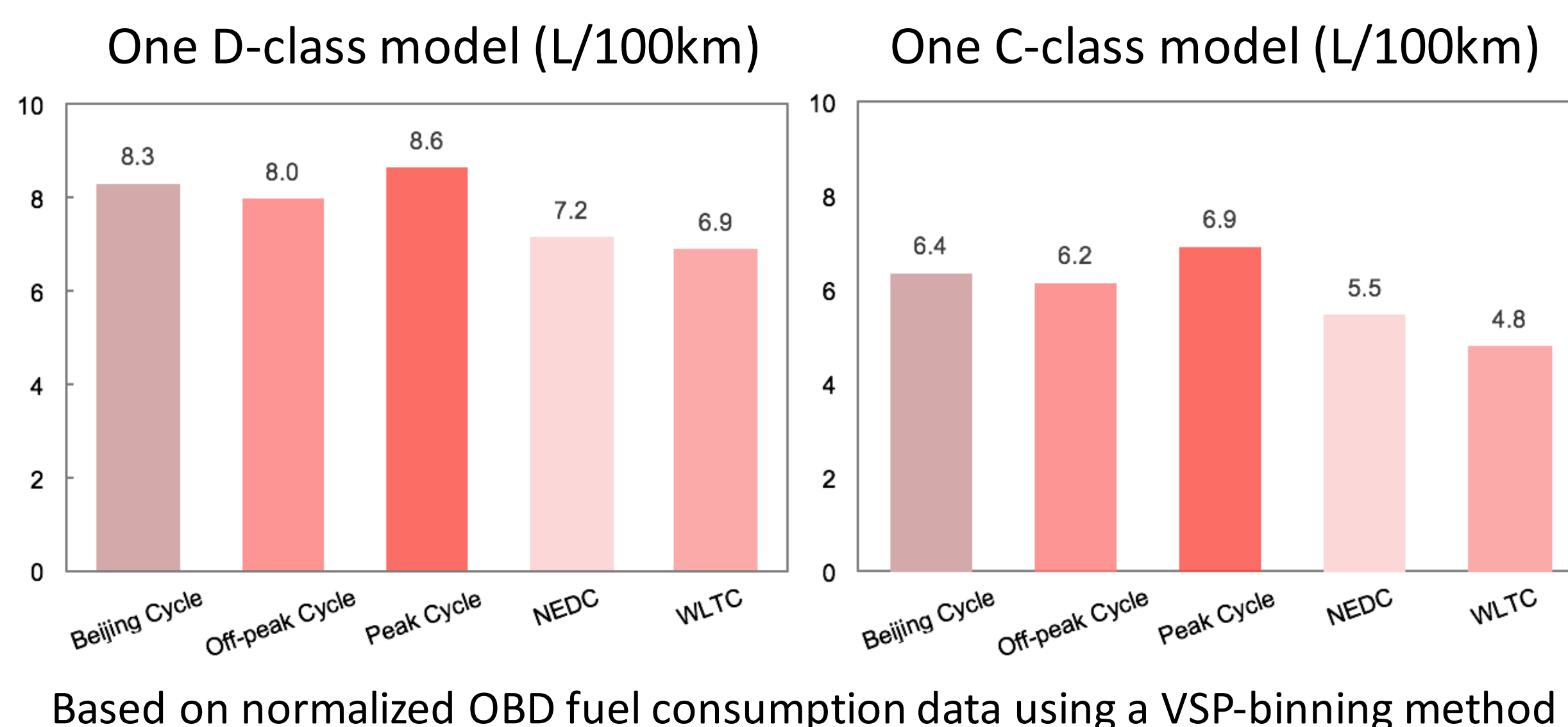


- Temporal Analysis**



- Model Application on Fuel Consumption Estimation**

- Fuel consumption under real-world driving could be higher than NEDC and WLTC by up to 30%.
- Fuel consumption during peak period is approximately 10% higher than off-peak period.
- Weighted average of Peak Cycle and Off-peak Cycle results are 8.15 and 6.37 L/100km for two models respectively, which shows highly self-consistent with results under Beijing Cycle (8.31 and 6.37 L/100km).



Based on normalized OBD fuel consumption data using a VSP-binning method

## Conclusion

- This research used an iterative Markov method to develop driving cycles based on large-scale GPS data, providing a scientific approach for urban driving cycle development.
- The research developed driving cycles for various spatial and temporal dimensions, providing an improved basis for emission estimation and fuel consumption simulation.
- Fuel consumption simulation results confirmed that Beijing real-world driving has higher fuel consumption than NEDC and WLTC.