Please use this README file (or a new one) to provide the following documentation for this project:

- \* Your name and student id-
- Rupak Khatri, 920605878
- \* General description of the project (a few sentences).
  - Program to send the get the list of user and send and receive the message. Moreover we also use UDP protocal to send the message and use CDMA protocal to broadcast the message.
- \* If you used external Python modules/libraries. Provide a requirements.txt file in this repository **No external libraries other than discussed**.
- \* Python version and compatibility issues (if any). Your project must be run exactly as in the running instructions

described below in this file

python above 2

\* Attach screenshots or videos to this file to illustrate how your program works for all the options in the menu. This

is your proof that the project was working on your side. Server side

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TO. OUT THE ROOTING TABLE OF THIS OCTOR WITH LINK OTALE FIOLOGO

- 11. Get the Routing Table of this network with Distance Vector Protocol
- 12. Turn web proxy server on (extra-credit)
- 13. Disconnect from server

Your option <enter a number>: 12

\*\*\*\*\* TCP/UDP Network \*\*\*\*\*

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## Options Available:

- 1. Get users list
- 2. Send a message
- 3. Get my messages
- 4. Send a direct message with UDP protocol
- 5. Broadcast a message with CDMA protocol
- 6. Create a secure channel to chat with your friends using PGP protocol
- 7. Join an existing channel
- 8. Create a Bot to manage a future channel
- 9. Map the network
- 10. Get the Routing Table of this client with Link State Protocol
- 11. Get the Routing Table of this network with Distance Vector Protocol
- 12. Turn web proxy server on (extra-credit)
- 13. Disconnect from server

Your option <enter a number>: 11

Routing table requested! Waiting for response....

## Network Map:

	rupak	rumpum	robot	roos
rupak	0	1	2	3
rumpum	1	0	4	5
robot	2	4	0	6
roos	3	5	6	e

Routing table for roos (id: 55371) computed with Distance Vector Protocol:

	rupak	rumpum	robot	roos
rupak	Θ	1	2	3
rumpum	1	0	4	5
robot	2	4	0	6
roos	3	5	6	0

Your option <enter a number>: 10

Routing table requested! Waiting for response....

Network Map:

	rupak	rumpum	robot	roos
rupak	0	1	2	3
rumpum	1	0	4	5
robot	2	4	0	6
roos	3	5	6	0

Routing table for roos (id: 55371) computed with Link State Protocol:

destination	Path	Cost
rupak	<pre>(rupak,rumpum,robot,)</pre>	14
rumpum	(rupak,rumpum,)	8
robot	(rupak,)	3

Your option <enter a number>: 9

Routing table requested! Waiting for response....

Network Map:

	rupak	rumpum	robot	roos
rupak	0	1	2	3
rumpum	1	0	4	5
robot	2	4	0	6
roos	3	5	6	0

our option <enter a number>: 13

venv) Rupaks-MacBook-Pro:client rupakkhatri\$

## 3. \* A few sentences about all the challenges you found during the implementation of this project and how you overcame them. Please be honest here.

For options I created method for them and added those methods to a list and when use requests them we will be calling them as the in1. for sending the menu class I first read the menu.py file as a string and then send it and change it to actual python format using exec method.

2. For connecting between classes and objects I created public variables that works outside the objectdex.

For the connection I used a class for binding, listening and accepting clients For sending and receving data's I used a dictionary that make the work more efficent for seeing unread messages. I added a separate method that have its own thread and works actively and store the result in unread message list