Main.java

```
package j1;
import org.opencv.core.Mat;
import org.opencv.videoio.VideoCapture;
import utils.CameraUtils;
public class Main {
    public static void main(String[] args) {
        // Initialize camera and video processor
        VideoCapture camera = CameraUtils.initCamera(0);
        VideoProcessor processor = new VideoProcessor();
        if (camera != null) {
            while (true) {
                Mat frame = CameraUtils.captureFrame(camera);
                if (frame != null) {
                    // Face detection
                    Mat processedFrame = processor.detectFaces(frame);
                    // Object detection
                    processedFrame = processor.detectObjects(processedFrame);
                    // Motion tracking
                    processedFrame = processor.trackMotion(processedFrame);
                    // Display the processed frame (implementation of display method
needed)
                } else {
                    System.out.println("No frame captured.");
                    break;
                }
            }
            camera.release();
        }
    }
}
```

VideoProcessor.java

```
package j1;
import org.opencv.core.Mat;
import org.opencv.core.MatOfPoint;
```

```
import org.opencv.core.MatOfRect;
import org.opencv.core.Point;
import org.opencv.core.Rect;
import org.opencv.core.Scalar;
import org.opencv.imgproc.Imgproc;
import org.opencv.objdetect.CascadeClassifier;
import org.opencv.video.BackgroundSubtractorMOG2;
import org.opencv.video.Video;
import java.util.ArrayList;
import java.util.List;
public class VideoProcessor {
  private CascadeClassifier faceDetector;
  private BackgroundSubtractorMOG2 backgroundSubtractor;
  private List<Point> previousCenters;
  public VideoProcessor() {
    // Load the classifier from the resources folder
    String xmlFile =
getClass().getResource("src/main/resources/haarcascade_frontalface_alt.xml").getPath();
    faceDetector = new CascadeClassifier(xmlFile);
    // Initialize background subtractor for object detection
    backgroundSubtractor = Video.createBackgroundSubtractorMOG2();
    previousCenters = new ArrayList<>();
  }
```

```
public Mat detectFaces(Mat frame) {
    MatOfRect faceDetections = new MatOfRect();
    faceDetector.detectMultiScale(frame, faceDetections);
    // Draw rectangles around detected faces
    for (Rect rect : faceDetections.toArray()) {
      Imgproc.rectangle(
        frame,
        new Point(rect.x, rect.y),
        new Point(rect.x + rect.width, rect.y + rect.height),
        new Scalar(0, 255, 0),
        3
      );
    }
    return frame;
  }
  public Mat detectObjects(Mat frame) {
    Mat foregroundMask = new Mat();
    backgroundSubtractor.apply(frame, foregroundMask);
    // Find contours of moving objects
    List<MatOfPoint> contours = new ArrayList<>();
    Imgproc.findContours(foregroundMask, contours, new Mat(), Imgproc.RETR_EXTERNAL,
Imgproc.CHAIN APPROX SIMPLE);
```

```
for (int i = 0; i < contours.size(); i++) {
      Rect boundingRect = Imgproc.boundingRect(contours.get(i));
      if (boundingRect.area() > 500) { // Filter small objects
        Imgproc.rectangle(
          frame,
          new Point(boundingRect.x, boundingRect.y),
          new Point(boundingRect.x + boundingRect.y +
boundingRect.height),
          new Scalar(255, 0, 0),
          2
        );
      }
    }
    return frame;
 }
  public Mat trackMotion(Mat frame) {
    MatOfRect faceDetections = new MatOfRect();
    faceDetector.detectMultiScale(frame, faceDetections);
    List<Point> currentCenters = new ArrayList<>();
    for (Rect rect : faceDetections.toArray()) {
      Point center = new Point(rect.x + rect.width / 2, rect.y + rect.height / 2);
      currentCenters.add(center);
    }
```

```
if (!previousCenters.isEmpty()) {
      for (int i = 0; i < Math.min(previousCenters.size(), currentCenters.size()); i++) {
        Point prev = previousCenters.get(i);
        Point curr = currentCenters.get(i);
        Imgproc.line(frame, prev, curr, new Scalar(0, 0, 255), 2);
      }
    }
    previousCenters = currentCenters;
    return frame;
  }
}
CameraUtils.java
package utils;
import org.opencv.core.Core;
import org.opencv.core.Mat;
import org.opencv.videoio.VideoCapture;
public class CameraUtils {
    static {
        System.loadLibrary(Core.NATIVE_LIBRARY_NAME);
    }
    public static VideoCapture initCamera(int cameraIndex) {
        VideoCapture camera = new VideoCapture(cameraIndex);
        if (!camera.isOpened()) {
             System.out.println("Error: Could not open camera.");
             return null;
        return camera;
    }
```

```
public static Mat captureFrame(VideoCapture camera) {
    Mat frame = new Mat();
    if (camera.read(frame)) {
        return frame;
    }
    return null;
}
```

VideoStream.js

```
import React, { useEffect, useState } from 'react';
const VideoStream = () => {
    const [imageSrc, setImageSrc] = useState('');
    useEffect(() => {
        const fetchVideoStream = () => {
            fetch('http://localhost:8080/video-stream')
                .then(response => response.blob())
                .then(blob => {
                    const imageObjectURL = URL.createObjectURL(blob);
                    setImageSrc(imageObjectURL);
                })
                .catch(error => console.error('Error fetching video stream:',
error));
        };
        // Fetch a new frame every 100ms (10 frames per second)
        const intervalId = setInterval(fetchVideoStream, 100);
        return () => clearInterval(intervalId); // Cleanup interval on component
    }, []);
    return (
        <div>
            <h1>Real-Time Video Stream</h1>
            <img src={imageSrc} alt="Video Stream" style={{ width: '100%',</pre>
maxHeight: '500px' }} />
        </div>
    );
};
```

```
export default VideoStream;
```

App.js