

## Clustering

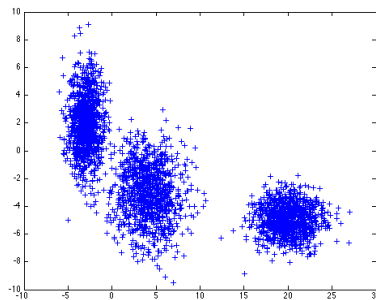
Automatic set grouping of objects (clusters)

September 2021

Thomas Corpetti



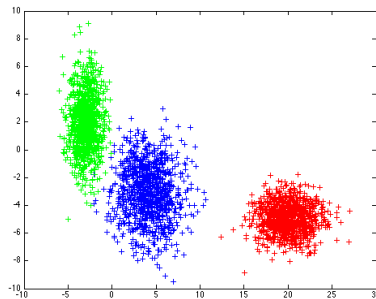
# What is clustering ?



From a dataset : group homogeneous sets of data : **clusters**

- Group them by their **similarity** with respect to a model (**generative methods**)
- Separate them with respect to their **dissimilarity** (**discriminative methods**)

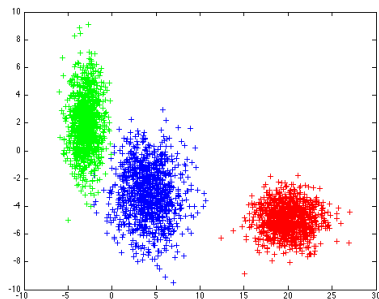
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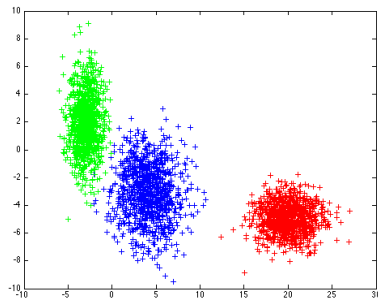
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## What is a good grouping ?



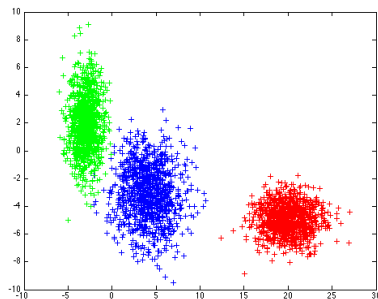
■ Inside a cluster :

## What is a good grouping ?



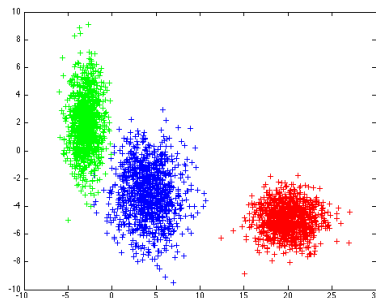
- Inside a cluster : **high similarity**

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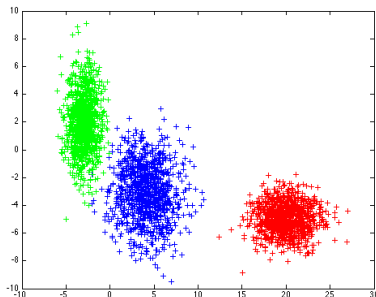
- Inside a cluster : high similarity
- Between clusters :

## What is a good grouping ?



- Inside a cluster : high similarity
- Between clusters : low similarity (high dissimilarity)

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- Inside a cluster : high similarity
- Between clusters : low similarity (high dissimilarity)

⇒ Distance/metric of prime importance



## Applications

### Large range of applications

- [Web](#) : similar web-pages
- [Social-networks](#) : group of users
- [Bio-informatics](#) : identify species
- [Marketing](#) : types of clients
- [Climatology](#) : types of weather
- [Image processing](#) : homogeneous areas
- ...

## General ideas

## Main families of clustering

- **Centroid** : create several clusters and evaluate their quality depending on some centroids (k-means, k-medoids, PAM, ...)
- **Hierarchical** : group in a hierarchical way data (AGNES, DIANA, ...)
- **Density** : rely on the adequacy of data with respect to a certain density (DBSCAN)
- **Model-based** : one model for each cluster
- **Spectral** : based on a graph-representation of data

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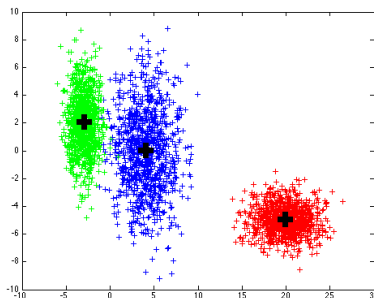
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# Outline

- 1 Introduction
- 2 Partitioning
  - K-means
  - Evaluation / Computations / Characterisation of clusters
  - K-medoids
- 3 Hierarchical Clustering
  - Principes
  - Agglomerative
  - Divisive
- 4 Density based clustering
  - Principles
- 5 Model based clustering
  - Principles
- 6 Spectral clustering (graph-based)
  - Principles

## Centroid

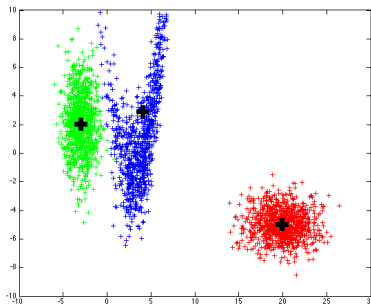
- Construct  $k$  clusters from  $n$  objects
- Many criteria
  - k-means (MacQueen'67) : rely on the **center** to create clusters





## Centroid

- Construct  $k$  clusters from  $n$  objects
- Many criteria
  - k-means (MacQueen'67) : rely on the **center** to create clusters
  - k-medoids or PAM (Partition around medoids) : rely on specific **data** to create clusters



## K-means

### Main idea

- Create **k-partitions** : each data is associated with the closest center of partition
  - Also called quantification algorithm of Lloyd-Max
- 
- We start from a **data matrix**  $X$  of dimension  $N \times P$  ( $N$  points of dimension  $P$ )
  - Le number of clusters  $k$  is a *hyperparameter*, supposed to be known

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## K-means

- Formalisation : find the **partition**  $\mathcal{S}^* = \{S_1, \dots, S_k\}$  such that

$$\mathcal{S}^* = \arg \min_{\mathcal{S}} \sum_{i=1}^k \sum_{x_j \in S_i} \|x_j - \mu_i\|^2$$

with  $\mu_i$  the average of points in  $S_i$

- $\Rightarrow$  Tricky optimization problem

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## K-means

## Standard algorithm

- 1** Iteration  $p = 0$  : find  $k$  initial means  $\mu_i^p, \forall i = 1 \dots k$  (usually randomly)
- 2** For each iteration  $p$ , until convergence
  - 1** Each point  $x_j$  is assigned to partition  $S_i^p$  if its distance with center  $\mu_i^p$  is minimal :

$$S_i^p = \left\{ x_j : \|x_j - \mu_i^p\| \leq \|x_j - \mu_{i^*}^p\|, \forall i^* = 1 \dots k \right\}$$

- 2** Update the mean of each partition

$$\mu_{i^*}^{p+1} = \frac{1}{\text{card}(S_i^p)} \sum_{x_j \in S_i^p} x_j$$

- 3**  $p = p + 1$

Note : the convergence can be low  $\implies$  find some heuristics

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## K-means : some notes

### Pros

- Cost-function always decreasing along iterations
- Simple and efficient

### Coins

- Discontinuous data (what is a “centroid” in this case) ?
- How to fix the number of clusters ?

### Variations, alternative approaches

- Monte-Carlo
- Fix  $k$  with cross validation

In each case : centers are not guarantee to be part of the dataset

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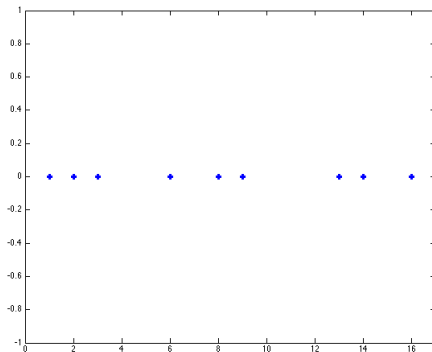
## K-means : exercice

Apply a k-mean with 3 clusters for the 1D dataset :

$$P = \{1, 2, 3, 6, 8, 9, 13, 14, 16\}$$

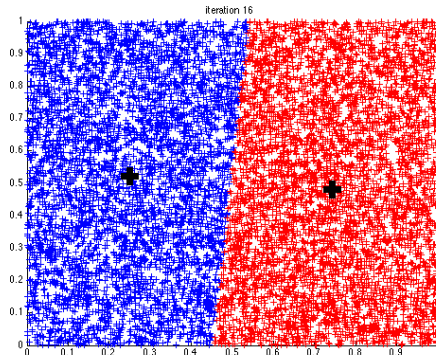
With initial means

$$\mu_1^0 = 1, \mu_2^0 = 2, \mu_3^0 = 3$$



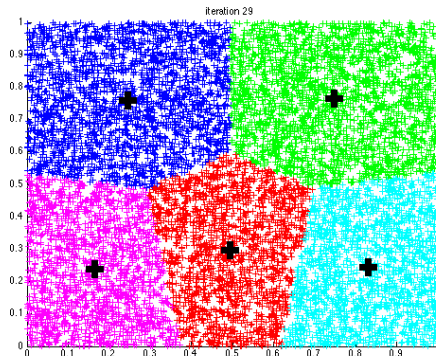
## K-means : illustrations

Uniform random set : 2 partitions



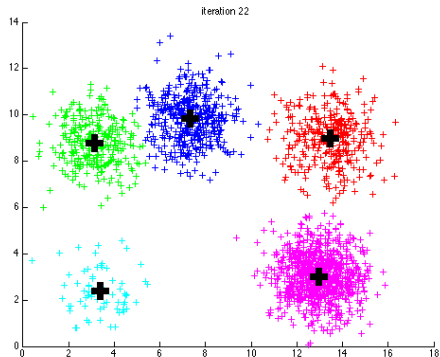
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Uniform random set : 5 partitions



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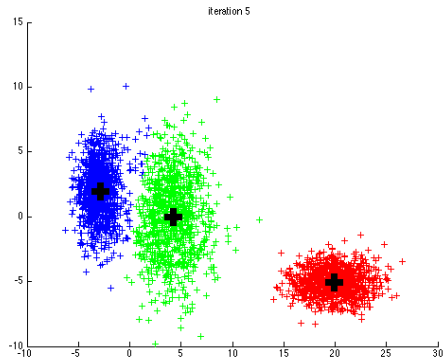
Point cloud with 5 clusters





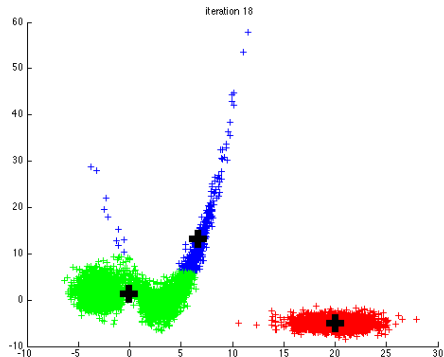
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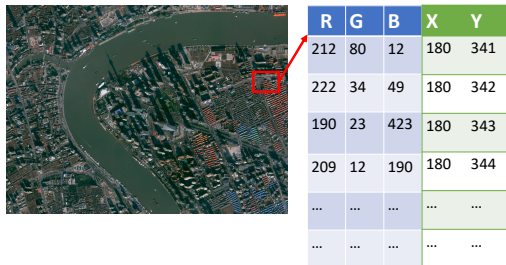
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## What about images

create a point cloud with  $R, G, B$  coef, and may be spatial coordinates

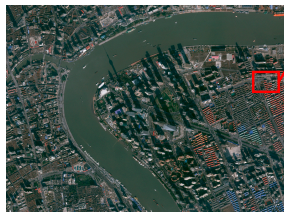


To impose spatial consistency

- one can add  $X, Y$  coordinates ;
- one can also filter images

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R	G	B	X	Y
212	80	12	180	341
222	34	49	180	342
190	23	423	180	343
209	12	190	180	344
...	...	...	...	...
...	...	...	...	...

To impose spatial consistency

- one can add  $X, Y$  coordinates ;
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## Computation on clusters

How to characterise a cluster? How to compare partitions?

- Characterisation :

- Inertia inside a cluster  $S_i$  composed of points  $x_1, \dots, x_M$  of  $M$  :

$$\mathcal{I}_i = \sum_{k=1}^M p(x_k) d(x_k, \mu_i)$$

with

- $d(.,.)$  : a distance function ;
- $\mu_i$  : center of the cluster ;
- $p(x_k)$  : probability of point  $x_k$

Note : If all points have similar probability,  $p(x_k) = 1/M$

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- “Intra-class” inertia (of all clusters
- $S$
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$$Intra = \sum_{k=1}^{|S|} \mathcal{I}_k$$

⇒ sum of all cluster inertia

- “Inter-class” inertia (between all clusters
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$$Inter = \sum_{k=1}^{|S|} \frac{1}{|\text{card}(S_k)|} d(\mu_k, \mu)$$

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- $\mu$
- : global average of points

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## How to compare partitions

- Let's take **all pair of points**  $(x_m, x_n)$  and let's have a look of their partitions with two methods. Four possibilities :

Class with method 2 \ Class with method 1		same	different
		a	b
same	a	b	
different	c	d	

- Rand index** :

$$R = \frac{a + d}{a + b + c + d} = \frac{a + d}{C_2^N}$$

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## Exercise

- We have a set of 5 points  $\{x_1, x_2, x_3, x_4, x_5\}$ , and 2 clustering methods gave the following partitions :
  - $S_1 = \{1, 1, 2, 2, 2\}$
  - $S_2 = \{1, 2, 2, 1, 2\}$
- What is the **Rand index** ?

## K-medoids

### General ideas

- Find most **representative centroids** (medoids) in the cluster
- Principle : iteratively replace medoids if the global distance is reduced
- More robust with respect to outliers

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Note : exactly the same than k-means

- 2** For each class  $i$ , choose randomly some non-medoids (or all)  $\mu_j^p$ 
  - Compute the replace cost of  $\mu_i^p$  by  $\mu_j^p$
  - ⇒ If the cost is lower,  $\mu_i^p$  is replaced by  $\mu_j^p$

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## K-medoids : some notes

### Pros

- Cost-function always decreasing along iterations
- Simple and efficient
- The cluster centroids (medoids) are interpretable

### Coins

- How to fix the number of clusters ?

### Variations, alternative approaches

- Monte-Carlo
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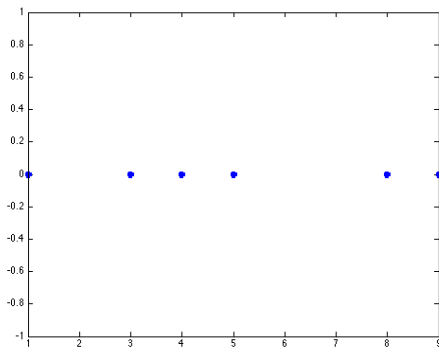
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Apply the K-medoids method with 2 clusters on the 1D dataset :

$$P = \{1, 3, 4, 5, 8, 9\}$$

With initial medoids

$$\mu_1^0 = 1, \mu_2^0 = 8$$



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  - Principles
  - Agglomerative
  - Divisive
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## Hierarchical Clustering

Two main types :

- 1 Clustering **agglomerative (bottom-up)** : all points are in distincts clusters that are merged based on some criteria
- 2 Clustering **divisive** : all points are in a single cluster which is split depending on some criteria

⇒ **Important question** : what is the distance between two clusters. Is it :

- The smallest distance between points of each clusters
- The largest distance between points of each clusters
- The distance between the mean of each cluster
- The average between all pairwise distances
- ...

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## Hierarchical Agglomerative Clustering

Starting point : distance matrix

- From a set of  $N$  points of dimension  $P$ , the (symmetric) distance matrix is :

$$M = \begin{bmatrix} 0 & D(1,2) & \cdot & D(1,N) \\ D(2,1) & 0 & \cdot & D(2,N) \\ \cdot & \cdot & 0 & \cdot \\ D(N,1) & D(N,2) & \cdot & 0 \end{bmatrix}$$

### Algorithm

- 1 Group all distances lower than a given threshold together
- 2 Recompute a distance matrix with the new dataset

Stop criteria to define

Main family : **AGNES** (AGglomerative NESTing)

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### Algorithm

- 1 Start from a large cluster that embeds all data
- 2 Divide it if not consistent

How to divide it?  $\Rightarrow$  Less used algorithm

Main family : **DIANA** (Divise ANAlysis)

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## Density based clustering

### Basic assumptions

- 1 A cluster is a “dense” area
- 2 Data are composed of various clusters separated by less-dense areas

### Principles

- 1 Two points are potentially in the same cluster if they are separated by a distance less than a **radius** fixed by the user
- 2 Each cluster has a minimal size

**Main problem** : in case of too much noise : all points in the same cluster

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- 1 A cluster is a “dense” area
- 2 Data are composed of various clusters separated by less-dense areas

### Principles

- 1 Two points are potentially in the same cluster if they are separated by a distance less than a **radius** fixed by the user
- 2 Each cluster has a minimal size

**Main problem** : in case of too much noise : all points in the same cluster

**Pros** : no need to compute means

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# Outline

- 1 Introduction
- 2 Partitioning
  - K-means
  - Evaluation / Computations / Characterisation of clusters
  - K-medoids
- 3 Hierarchical Clustering
  - Principes
  - Agglomerative
  - Divisive
- 4 Density based clustering
  - Principles
- 5 Model based clustering**
  - Principles
- 6 Spectral clustering (graph-based)
  - Principles

## Model based clustering

### Basic assumptions

- 1 We know the number  $k$  of clusters
- 2 Each  $x_i$  has a model

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- Each point is associated with the most likely model

Main difficulty : get such models

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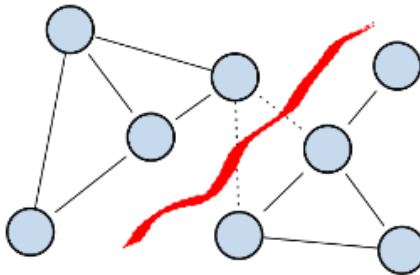
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## Spectral clustering

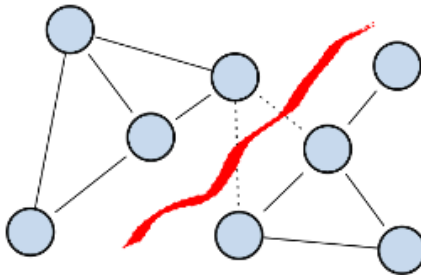
Data are represented on graphs



- The distance between each vertices is computed based on the similarity between points
- Perform “cut” on graphs

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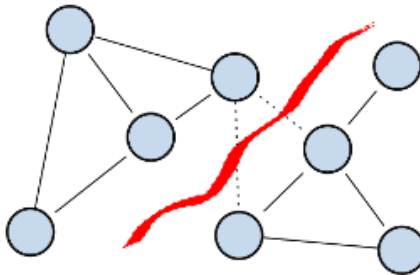
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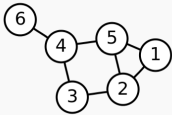


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## Graph theory

source : Wikipedia

Graphe	Représentation par une <a href="#">matrice d'adjacence</a>	Représentation par une <a href="#">matrice laplacienne</a> (non normalisée)
	$\begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{pmatrix}$

- Based on [Adjency](#) and [Laplacian](#) matrix, one can characterise the structure of data