



Computer Vision

Lecture 3: (Gray) Mathematical Morphology

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Binary Morphology (reminder)

In short:

- local analysis in a neighbourhood (a.k.a. the structuring element)
- two basic (dual) operations: erosion and dilation
- combined to form more complex operators: opening/closing, gradient, residue, etc.
- scale-space with a series of structuring elements

Grayscale Morphology

Extending operators from set theory to complete lattices

- translation $f_x(z) = f(z - x)$
- shift $(f + y)(z) = f(z) + y$
- morphological translation $(f_x + y)(z) = f(z - x) + y$
- negative: $f^c(x) = -f(x)$
- reflection: $f(x) = f(-x)$
- g is below f if $D[g] \subset D[f]$ and $g(x) \leq f(x) \quad \forall x \in D[g]$
- minimum: $(f \wedge g)(x) = \min(f(x), g(x))$
- maximum: $(f \vee g)(x) = \max(f(x), g(x))$

Erosion

$$\varepsilon_g(f)(x) = (f \ominus g)(x) = \max(y : y + g_x \leq f) = \min(f(z) - g_x(z) : z \in D[g_x])$$

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$$\delta_g(f)(x) = (f \oplus \breve{g})(x) = \min(y : y - \breve{g}_x \geq f) = \max(f(z) + \breve{g}_x(z) : z \in D[\breve{g}_x])$$

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Structuring elements can be non-flat (a.k.a. structuring functions) or flat.

Using **flat SEs** leads to simpler definitions:

- $\varepsilon_B(f)(x) = \min_{z \in B}(f(x + z))$
- $\delta_B(f)(x) = \max_{z \in \breve{B}}(f(x + z))$

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Reflection may be omitted if symmetric structuring elements/functions are used.

All other operators extend to greyscale:

- opening
- closing
- alternate sequential filtering (for image smoothing)
- morphological gradient (for edge detection)
- top-hat
- morphological reconstruction, by replacing \cup by \vee and \cap by \wedge
- granulometry (with v the image volume, i.e. the sum of pixel values)
- etc.

Some examples follow...

a b
c d

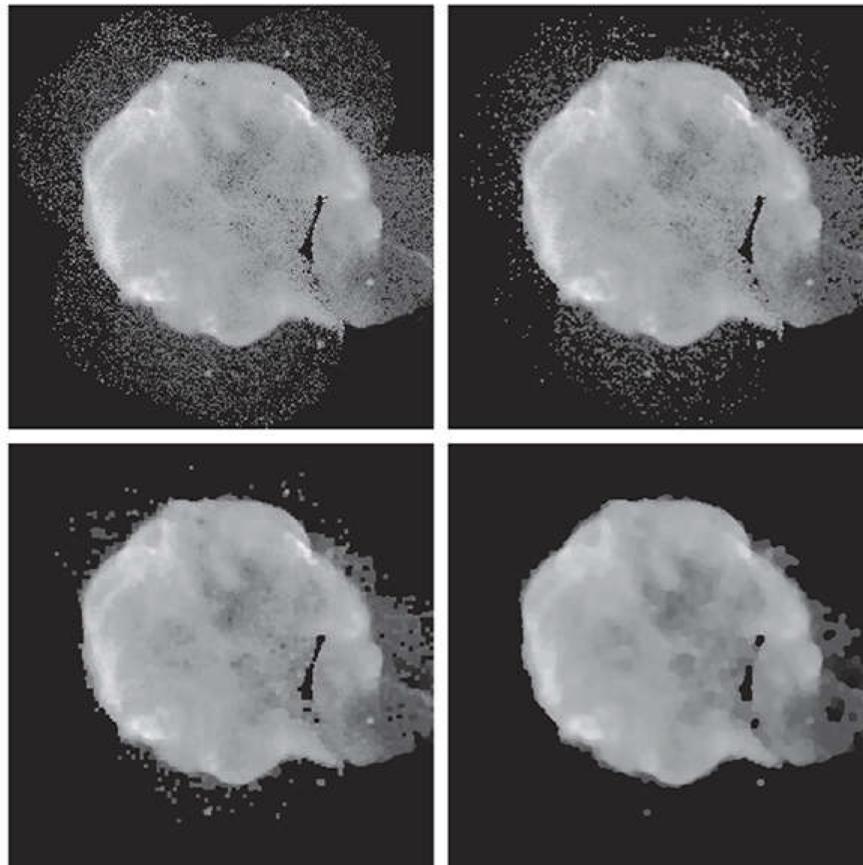


FIGURE 9.40

(a) 566×566 image of the Cygnus Loop supernova, taken in the X-ray band by NASA's Hubble Telescope. (b)–(d) Results of performing opening and closing sequences on the original image with disk structuring elements of radii, 1, 3, and 5, respectively.

(Original image courtesy of NASA.)

a b
c d

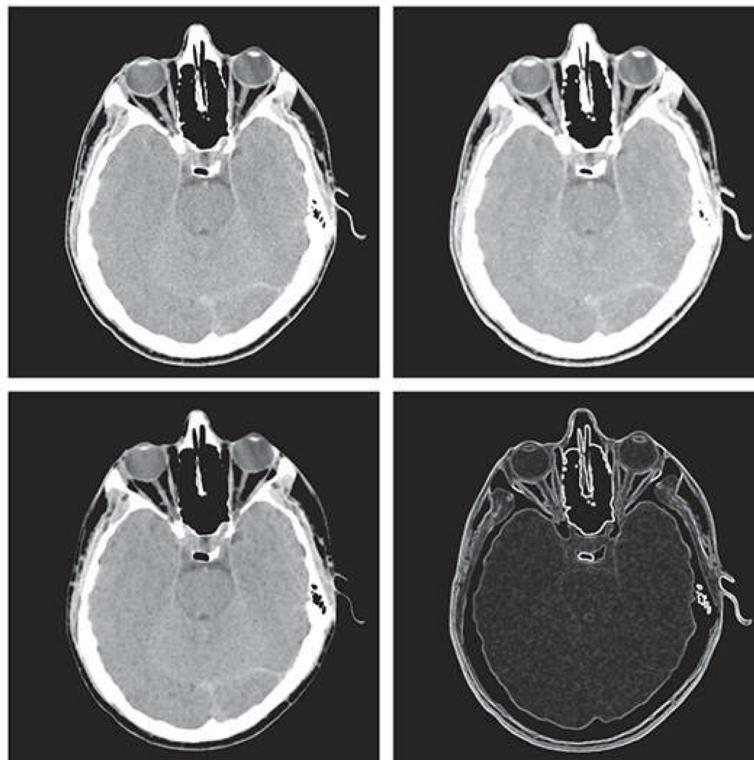


FIGURE 9.41

(a) 512×512 image of a head CT scan. (b) Dilation. (c) Erosion. (d) Morphological gradient, computed as the difference between (b) and (c).

(Original image courtesy of Dr. David R. Pickens, Vanderbilt University.)

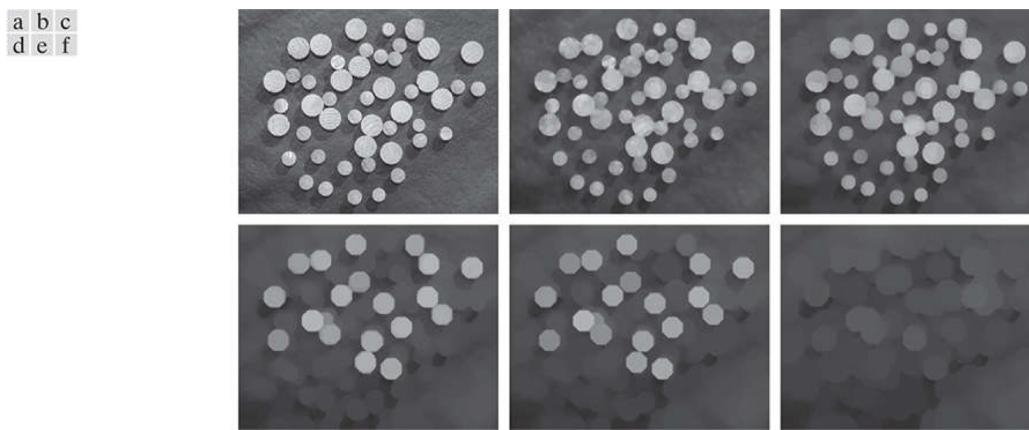


FIGURE 9.43

(a) 531×675 image of wood dowels. (b) Smoothed image. (c)–(f) Openings of (b) with disks of radii equal to 10, 20, 25, and 30 pixels, respectively.

(Original image courtesy of Dr. Steve Eddins, MathWorks, Inc.)

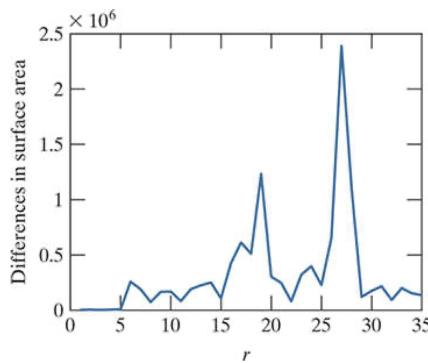


FIGURE 9.44

Differences in surface area as a function of SE disk radius, r . The two peaks indicate that there are two dominant particle sizes in the image.

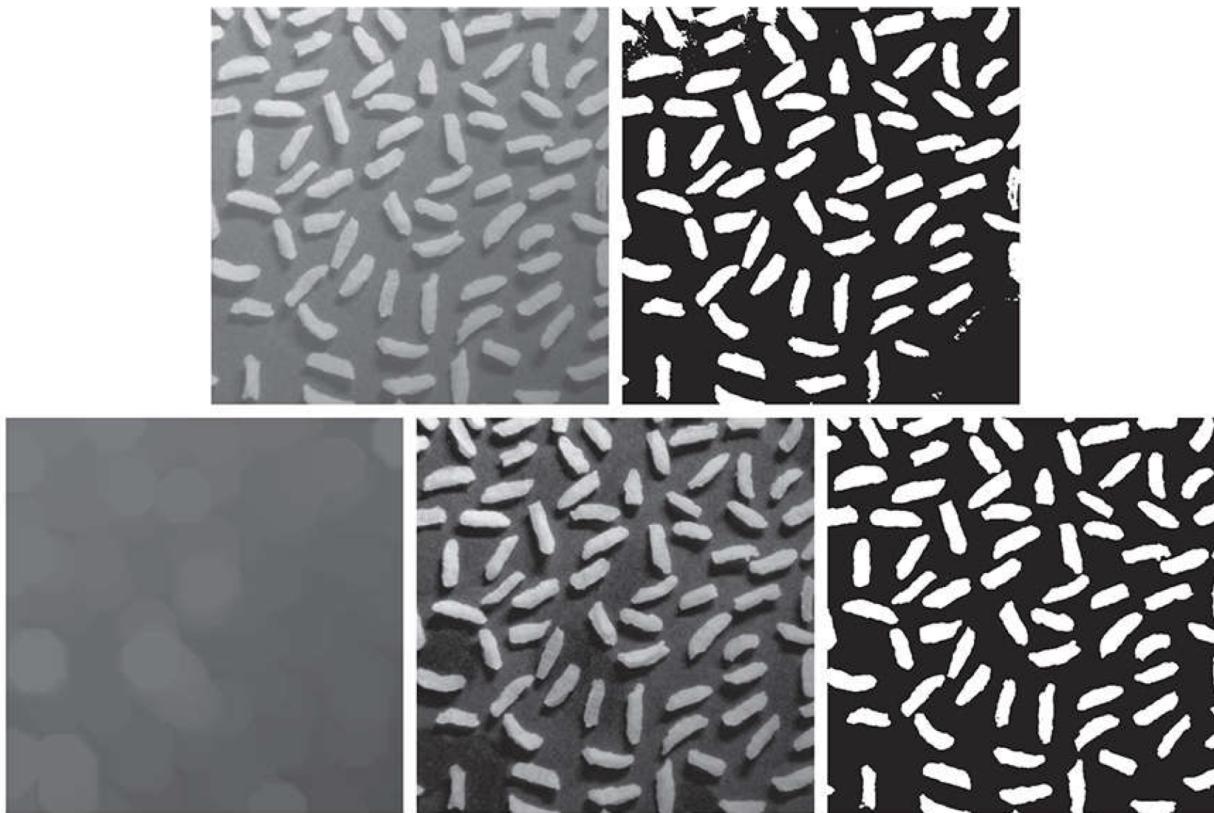


FIGURE 9.42

Using the top-hat transformation for *shading correction*. (a) Original image of size 600×600 pixels. (b) Thresholded image. (c) Image opened using a disk SE of radius 40. (d) Top-hat transformation (the image minus its opening). (e) Thresholded top-hat image.



FIGURE 9.46

(a) Original image of size 1134×1360 pixels. (b) Opening by reconstruction of (a), using a structuring element consisting of a horizontal line 71 pixels long in the erosion. (c) Opening of (a) using the same SE. (d) Top-hat by reconstruction. (e) Result of applying just a top-hat transformation. (f) Opening by reconstruction of (d), using a horizontal line 11 pixels long. (g) Dilation of (f) using a horizontal line 21 pixels long. (h) Minimum of (d) and (g). (i) Final reconstruction result.

(Images courtesy of Dr. Steve Eddins, MathWorks, Inc.)

Other morphological-based tools

The [Watershed Transform](#), together with its Marker-based version, is a very popular morphological segmentation technique ([see Image Analysis lecture on segmentation](#)).

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For more details, see MM-related references

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- Pesaresi and Benediktsson (2001) A new approach for the morphological segmentation of high-resolution satellite imagery
- Soille and Pesaresi (2002) Advances in mathematical morphology applied to geoscience and remote sensing
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A still active topic, with regular special issues,
e.g. IJGI in 2016, JSTARS in 2021.

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Let us consider the series of openings (by reconstruction).

Not only global measures, but also local features can be derived...

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or Differential Morphological Profiles:

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Both are very popular structural features in remote sensing.

Assignment

1. Select one paper (old or recent) dealing with MM+RS
(e.g. from GoogleScholar)
2. Implement the morphological pipeline
3. Discuss the pros and cons of the method

Deadline: October 3, 2021

Practice 1

Let us consider the image below.



Design a morphological processing chain to extract the airport.



Practice 2

Compute and plot the DMP of pixels belonging to different land cover classes.

Discuss the characterization power of the DMP.