

Machine Learning

Trees, Bagging and Random forests

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Part II : Model averaging - Bagging and random forests

Introduction: model averaging

Bagging

Random forests

Algorithm

Out-Of-Bag sample

Variable importance

Motivation: Decision trees can be simple, but often produce unstable models with weak performance compared to other supervised methods.

→ Use decision trees as building blocks to construct more powerful prediction models → Model averaging.

Motivation: Decision trees can be simple, but often produce unstable models with weak performance compared to other supervised methods.

→ Use decision trees as building blocks to construct more powerful prediction models → Model averaging.

Model averaging

- **Bagging** [Breiman, 1996]: fit many large trees to bootstrap-resampled versions of the train set, and average the predictions.
- **Random forests** [Breiman, 2001]: a fancier version of bagging that uses features sampling.
- **Boosting** [Freund et al., 1996]: fit many large or small trees to reweighted versions of the train set (no bootstrap resampling) and use a weighted average of the predictions.

Some remarks:

- In general (in terms of performance), **Boosting** \succ **Random forests** \succ **Bagging** \succ **single decision tree**.
- Synonym of model averaging: ensemble learning.
- Here, we will only focus on **bagging** and **random forests**.

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What is bagging ?

Principle: Bagging or **Bootstrap Aggregating** averages a given procedure over many samples.

→ *Example: build lots of large and unpruned CART trees to bootstrap resampled versions of a data set.*

Two steps: (1) bootstrapping, (2) aggregation.

Motivations:

- To improve model stability and so model accuracy.
- To avoid overfitting.
 - ⚠ Important since we use large and unpruned trees¹.

¹Reminder: very large trees = trees that fit almost perfectly the data, i.e. trees with almost no bias but large variance.

Data available: only one data set $\mathcal{D}_n = \{(\mathbf{X}_1, Y_1), \dots (\mathbf{X}_n, Y_n)\}$ to train the model.

⚠ We need many samples and we cannot create and/or get additional data.

Solution: use bootstrapping = generate "new" data sets by randomly drawing observations (with or without replacement) into the original data set \mathcal{D}_n .

→ We say that we generate bootstrap samples.

Bootstrap algorithm

- **Input:** one data set \mathcal{D}_n with 8 observations.

\mathcal{D}_n	obs 1	obs 2	obs 3	obs 4	obs 5	obs 6	obs 7	obs 8
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- **Do bootstrapping:** repeat independently the following procedure B times: draw randomly and with replacement observations into \mathcal{D}_n .

\mathcal{D}_n^1	obs 2	obs 6	obs 5	obs 5	obs 2	obs 4	obs 8	obs 7
\mathcal{D}_n^2	obs 6	obs 8	obs 2	obs 4	obs 2	obs 7	obs 8	obs 1
				\vdots				
\mathcal{D}_n^B	obs 7	obs 8	obs 3	obs 7	obs 2	obs 3	obs 3	obs 1

- **Output:** B bootstrap-resampled versions of the original data set $\mathcal{D}_n \Leftrightarrow B$ "new" data sets made up of observations from \mathcal{D}_n :

$$\mathcal{D}_n^1, \dots, \mathcal{D}_n^B.$$

Important: the B bootstrap samples are drawn **independently**.

Two sampling strategies:

1. Draw with replacement $a_n = n$ observations into \mathcal{D}_n , (n = size of \mathcal{D}_n).
2. Draw without replacement $a_n \leq n$ observations into \mathcal{D}_n (also called subsampling).

Reminder: Bagging = bootstrapping + aggregation.

Bagging algorithm

Inputs:

- An original sample \mathcal{D}_n .
- A learning method/algorithm: here CART algorithm.
- Bagging parameters: B , a_n .

For $b = 1$ to B , repeat INDEPENDENTLY the two following steps:

1. Draw a bootstrap sample \mathcal{D}_n^b of size a_n .
2. Build a large and unpruned CART tree using \mathcal{D}_n^b and call it T_n^b .

end.

Output: For an observation \mathbf{x} , the bagging prediction = aggregation of the predictions obtained with the B trees.

Bagging prediction

For an observation \mathbf{x} , the bagging prediction is:

- *In regression*: the prediction average over the B trees

$$f_n^B(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^B f_n^b(\mathbf{x}),$$

where $f_n^b(\mathbf{x})$ is the prediction of the b th tree T_n^b for observation \mathbf{x} .

- *In classification*: the majority class over the B trees

$$f_n^B(\mathbf{x}) = \text{majority vote}\{\hat{C}_b(\mathbf{x})\}_1^B,$$

where $\hat{C}_b(\mathbf{x})$ is the class prediction of the b th tree T_n^b for observation \mathbf{x} .

- The B bootstrap samples are **independent** and the B trees are built **independently**.
- Choose B as large as possible, often around 500.
 - ➔ Larger B is, more stable bagging predictions are.
- **Bagging does not impact the bias**: suppose all trees have the same bias θ then the bias of the bagging model will still equal θ .
- **Bagging reduces model variance and so model stability** (bagging properties).

Variance reduction with bagging

Idea: suppose we have B regression trees with same variance σ^2 and a positive pairwise correlation ρ . Then the variance of the tree average (= variance of bagging for regression) is

$$V_{\text{bagging}} = \rho\sigma^2 + \frac{1-\rho}{B}\sigma^2.$$

As B increases, the second term disappears and so we have

$$V_{\text{bagging}} \approx \rho\sigma^2.$$

Since $0 < \rho < 1$, we obtain

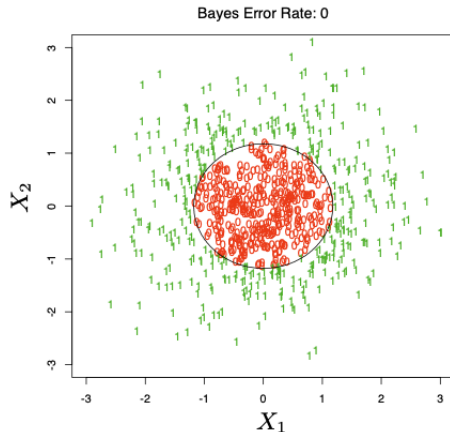
$$V_{\text{bagging}} < \sigma^2.$$

→ **Conclusion:** the bagging variance is (generally) lower than the variance of a single tree:

$$V_{\text{bagging}} < V_{\text{single tree}}.$$

Illustration with a toy example (1/5)

- A simple deterministic problem.
- No noise: Bayes error=0.



→ We will compare performance of a single CART tree and bagging.

Example drawn from <https://web.stanford.edu/hastie/TALKS/boost.pdf>

Illustration with a toy example (2/5)

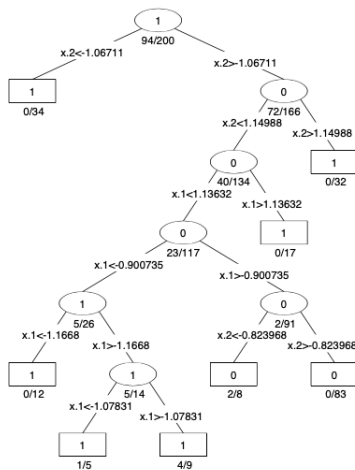


Figure 1: The single CART tree based on a train set of size 200.

Illustration: a toy example (3/5)

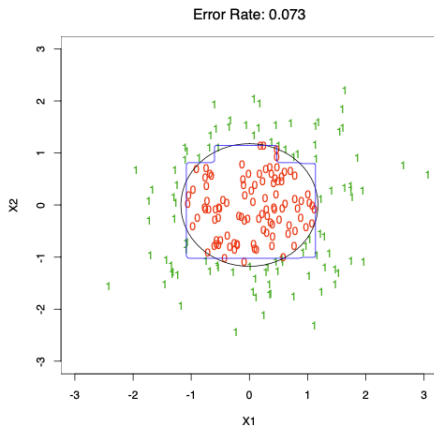


Figure 2: The partition associated with the previous single CART tree.

Illustration: a toy example (4/5)

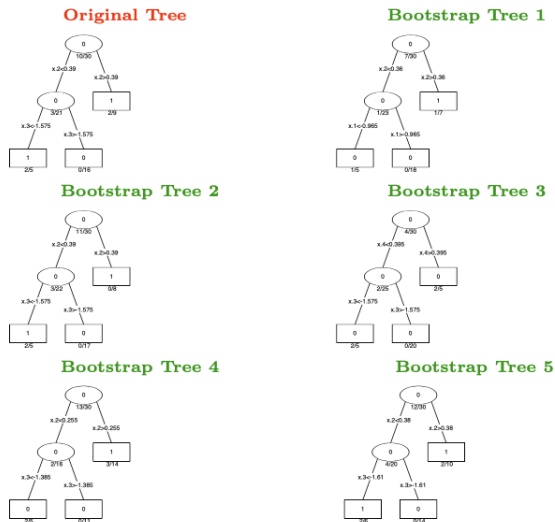


Figure 3: Single tree vs. Bagging.

Illustration: a toy example (5/5)

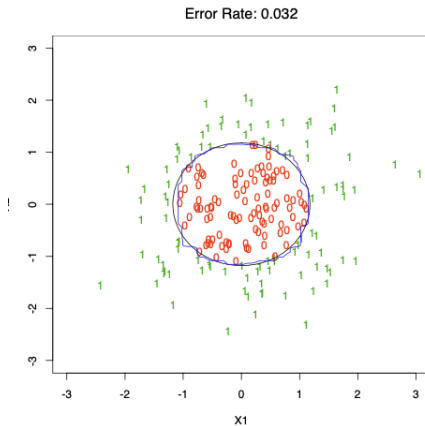


Figure 4: The partition obtained with bagging.

Illustration: a toy example (5/5)

- The decision boundaries are **smoother** (consequence of aggregation).
- Bagging error is lower.

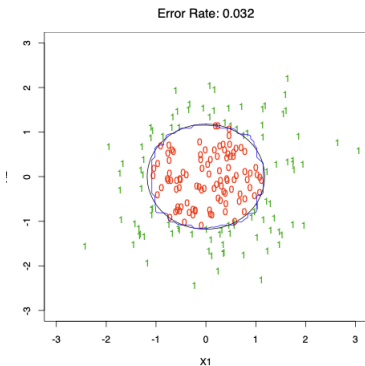


Figure 4: The partition obtained with bagging.

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What is random forests ?



Author: Phill Cutler

Principle: Random forest = bagging + features sampling.

Motivations:

- Same as bagging: performance improvement (by reducing variance) and no overfitting.
- Additional motivation: **greater variance reduction than bagging.**
 - ➔ **Strategy:** encouraging diversity among trees by using random features sampling.

Variance reduction with random forests

Idea: suppose we have B regression trees with same variance σ^2 and a positive pairwise correlation ρ . Then the variance of the tree average (= variance of bagging for regression) is

$$V_{\text{bagging}} = \rho\sigma^2 + \frac{1-\rho}{B}\sigma^2.$$

As B increases, the 2nd term disappears (= *gagging benefit*) and so we have

$$V_{\text{bagging}} \approx \rho\sigma^2.$$

→ **Random forests idea:** use features sampling to reduce the tree correlation ρ :

$$\begin{aligned}\rho_{\text{rf}}\sigma^2 &< \rho\sigma^2 \\ V_{\text{rf}} &< V_{\text{bagging}}\end{aligned}$$

with $\rho_{\text{rf}} < \rho$ denoting the tree correlation after using features sampling.

→ **Conclusion:** Random forests achieves (generally) greater variance reduction than bagging.

Features sampling in random forests

- Modification of the CART algorithm.
- Features sampling performed during the tree building process and specifically when splitting a node:
 - (1) Random selection of $\text{max_features} < d$ features among the d features.
 - (2) Selection of the best split by using only this subset.

Remarks: we can say that RF use rCART trees with a 'r' for random.

Reminder: Random forests = Bagging + Features sampling.

RF algorithm

Inputs:

- An original sample \mathcal{D}_n .
- A learning method/algorithm: CART algorithm.
- RF parameters: B , a_n , `max_features`, `nodesize` .

For $b = 1$ to B , repeat INDEPENDENTLY the two following steps:

1. Draw a bootstrap sample \mathcal{D}_n^b of size a_n .
2. Build a large and unpruned rCART tree T_n^b using \mathcal{D}_n^b by repeating the following steps on each terminal node until reaching the minimum node size (`nodesize`):
To split a node,
 - a) Draw randomly `max_features` features.
 - b) Select the best split based only on the `max_features` selected features.

end.

Output: For an observation \mathbf{x} , the RF prediction = aggregation of the predictions obtained with the B trees.

RF prediction

For an observation \mathbf{x} , the RF prediction is:

- *In regression*: the prediction average over the B trees

$$f_n^{RF}(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^B f_n^b(\mathbf{x}),$$

where $f_n^b(\mathbf{x})$ is the prediction of the b th tree T_n^b for observation \mathbf{x} .

- *In classification*: the majority class over the B trees

$$f_n^{RF}(\mathbf{x}) = \text{majority vote}\{\hat{C}_b(\mathbf{x})\}_1^B,$$

where $\hat{C}_b(\mathbf{x})$ is the class prediction of the b th tree T_n^b for observation \mathbf{x} .

Parameters in random forests

- B = the number of trees in the forest.
→ Take B large (default value: $B = 500$) to obtain stable/robust estimate.
- $a_n \leq n$ = the size of each bootstrap sample and the bootstrap strategie.
→ Two usual bagging strategies:
 - (1) Choose $a_n = n$ and draw with replacement,
 - (2) Choose $a_n \leq n$ and draw without replacement.
- `nodesize` = the minimum number of observations required to split a node
.
→ Take `nodesize` small to obtain trees with **small bias** and **large variance**.
- `max_features` = the number of features randomly selected when splitting a node.
→ **Almost the most important parameter to be tuned.**

What value for `max_features` ?

Parameter `max_features`: "*slightly controls*" the bias-variance tradeoff for the forest.

Explanation:

- **Smaller `max_features`:** more different and less correlated trees (smaller $|\rho|$) but tree that do not fit well the data (larger bias).
- **Larger `max_features`:** trees that fit correctly the data (= smaller bias) but tree more similar and so more correlated (larger $|\rho|$).

Default values: `max_features` = $d/3$ in regression and `max_features` = \sqrt{d} in classification.

→ Often reported to be good choices.

→ Yet, optimal value for `max_features` depends mainly on the data: use of the out-of-bag samples to tune this parameter.

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As for other machine learning algorithms, we need a **criterion to measure performances of a random forest**.

Common criteria (reminder):

- The quadratic loss for regression: $\frac{1}{n} \sum_{i=1}^n (y_i - f_n^{RF}(\mathbf{x}))^2$.
- The misclassification error for classification: $\frac{1}{n} \sum_{i=1}^n \mathbb{1}_{y_i \neq f_n^{RF}(\mathbf{x})}$.

Reminder: to be a good proxy of the *true* error, these criteria must be **evaluated on a test set or by using cross validation, leave-one-out, etc.**

Bootstrapping-step asset: **performance criteria can be evaluated directly on the original dataset \mathcal{D}_n by using the Out of Bag samples (OOB).**

➔ With RF: no need for a test set or to use strategies such as cross validation or leave-one-out)

Bootstrapping step (reminder)

- **Input:** a data set \mathcal{D}_n with 8 observations

\mathcal{D}_n	obs 1	obs 2	obs 3	obs 4	obs 5	obs 6	obs 7	obs 8
-----------------	-------	-------	-------	-------	-------	-------	-------	-------

- **Do bootstrapping:** Draw observations randomly and with replacement into \mathcal{D}_n . Repeat independently this procedure B times.

\mathcal{D}_n^1	obs 2	obs 6	obs 5	obs 5	obs 2	obs 4	obs 8	obs 7
\mathcal{D}_n^2	obs 6	obs 8	obs 2	obs 4	obs 2	obs 7	obs 8	obs 1
				\vdots				
\mathcal{D}_n^B	obs 7	obs 8	obs 3	obs 7	obs 2	obs 3	obs 3	obs 1

➔ **Output:** B bootstrap-resampled versions of the original $\mathcal{D}_n \Leftrightarrow$ B "new" data sets made up of observations of \mathcal{D}_n

$$\mathcal{D}_n^1, \dots, \mathcal{D}_n^B.$$

Bootstrapping step

- Input: a data set \mathcal{D}_n with 8 observations

\mathcal{D}_n	obs 1	obs 2	obs 3	obs 4	obs 5	obs 6	obs 7	obs 8
-----------------	-------	-------	-------	-------	-------	-------	-------	-------

- Do bootstrapping: obtain B bootstrap samples

\mathcal{D}_n^1	obs 2	obs 6	obs 5	obs 5	obs 2	obs 4	obs 8	obs 7
\mathcal{D}_n^2	obs 6	obs 8	obs 2	obs 4	obs 2	obs 7	obs 8	obs 1
				\vdots				
\mathcal{D}_n^B	obs 7	obs 8	obs 3	obs 7	obs 2	obs 3	obs 3	obs 1

- B OOB samples: observations in \mathcal{D}_n that are not in the B bootstrap samples.

OOB^1 :	obs 1	obs 3	obs 6	obs 6	obs 6	obs 6	obs 6	ind 0
OOB^2 :	obs 2	obs 5	obs 6					
				\vdots				
OOB^B :	obs 4	obs 5	obs 7					

→ Use the OOB samples to estimate the error of a random forest.

Notations:

- $\mathcal{D}_n = \{(\mathbf{X}_1, Y_1), \dots, (\mathbf{X}_n, Y_n)\}$,
- f_n^{RF} : the prediction function of a RF fitted on \mathcal{D}_n .

OOB error

For each couple (\mathbf{X}_i, Y_i) in \mathcal{D}_n , compute its RF predictor by averaging only the trees associated to **bootstrap samples that do not included** (\mathbf{X}_i, Y_i) :

$$f_n^{RF}(\mathbf{x}_i) = \frac{1}{\#\mathcal{I}_i^B} \sum_{b \in \mathcal{I}_i^B} f_n^b(\mathbf{x}_i),$$

where \mathcal{I}_i^B denotes the set of indices for bootstrap samples for which (\mathbf{X}_i, Y_i) is out-of-bag.

In regression: $f_n^{RF}(\mathbf{x}_i) = \frac{1}{\#\mathcal{I}_i^B} \sum_{b \in \mathcal{I}_i^B} (Y_i - f_n^{RF}(\mathbf{x}_i))^2$.

In classification: $f_n^{RF}(\mathbf{x}_i) = \frac{1}{\#\mathcal{I}_i^B} \sum_{b \in \mathcal{I}_i^B} \mathbb{1}_{Y_i \neq f_n^{RF}(\mathbf{x}_i)}$.

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One major asset of the single trees: models highly interpretable.

A random forest = aggregation of several single trees.

→ Not directly interpretable.

Alternative with RF: introduction of an importance score that measures the prediction strength of each feature.

→ Importance score used OOB samples.

→ Importance score can be used to rank features and so to perform features selection.

1) Compute the OOB error of each tree.

- OOB_b = the OOB sample of the b -th tree T^b
- E_{OOB_b} = the OOB error of T^b on OOB_b .
 - In regression: $E_{OOB_b} = \frac{1}{\#OOB_b} \sum_{i \in OOB_b} (Y_i - f_n^b(\mathbf{X}_i))^2$ (quadratic loss),
 - In classification: $E_{OOB_b} = \frac{1}{\#OOB_b} \sum_{i \in OOB_b} \mathbf{1}_{f_n^b(\mathbf{x}_i) \neq Y_i}$ (misclassification error).

2) Permute randomly values of the j th feature and compute the OOB error on the permuted sample.

- OOB_b^j = the b th OOB sample with the j th feature permuted.
- \mathbf{X}_i^j = the i th observation in OOB_b^j with permuted value for input j .
- $E_{OOB_b^j}$ = the error of T^b on OOB_b^j .
 - In regression: $E_{OOB_b^j} = \frac{1}{\#OOB_b^j} \sum_{i \in OOB_b^j} (Y_i - f_n^b(\mathbf{X}_i^j))^2$ (quadratic loss),
 - In classification: $E_{OOB_b^j} = \frac{1}{\#OOB_b^j} \sum_{i \in OOB_b^j} \mathbf{1}_{f_n^b(\mathbf{x}_i^j) \neq Y_i}$ (misclassification error).

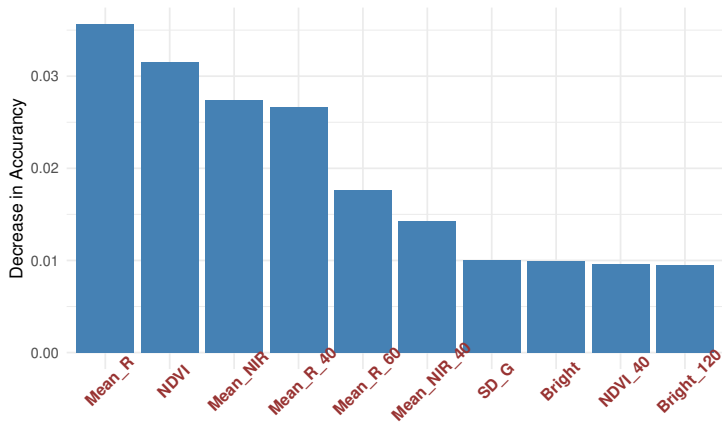
3). Compute the importance score for the j th feature

$$VI(\mathbf{X}^j) = \frac{1}{B} \sum_{b=1}^B (E_{OOB_b^j} - E_{OOB_b})$$

- **Meaning:** the importance score of the j th feature is defined as the average over the B trees of the difference between the OOB error and the permuted.
- **Explanation:** Permutations are used to mimics independence (no link) between \mathbf{X}^j and Y .
→ The feature \mathbf{X}^j is considered as important if by breaking the link between \mathbf{X}^j and Y , the error on the OOB samples increase.
- **Interpretation:** Large difference between the OOB error and the permuted OOB error \Rightarrow large $VI(\mathbf{X}^j) \Rightarrow \mathbf{X}^j$ is an important feature to predict Y .

Variable importance: example on the land cover data set

The 10 variables with the highest importance score (see TP2):



- Random Forest = an improvement over bagged CART trees.
- Algorithm with few parameters to tune.
- No overfitting problem compared to a single tree.
- Higher performances than a single CART tree or bagged CART trees.
- No need of test set: out-of-bag samples.
- Interpretation tool: variable importance score.
- Large applicability.



Breiman, L. (1996).

Bagging predictors.

Machine learning, 24(2):123–140.



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Experiments with a new boosting algorithm.

In *icml*, volume 96, pages 148–156. Citeseer.