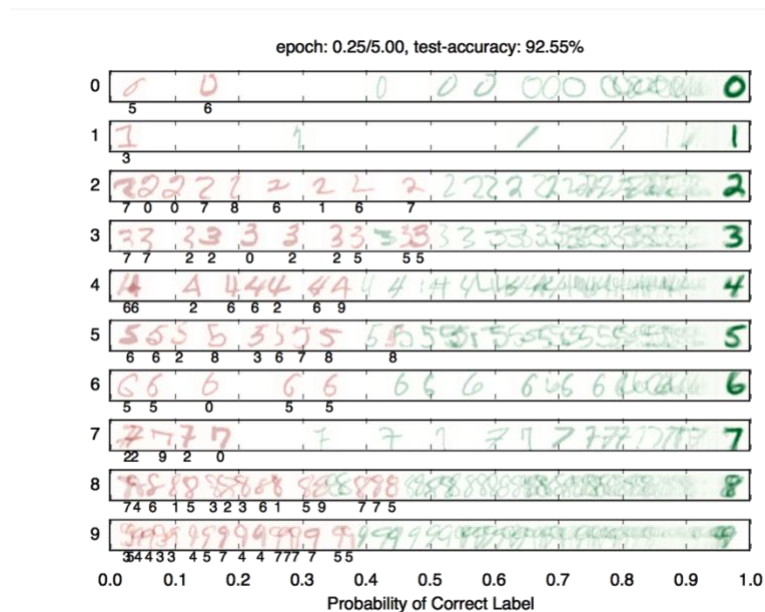


Project 5: Machine Learning (Due on Sunday December 5th at noon)

(Thanks to John DeNero and Dan Klein!)



In this project you will build a neural network to classify digits, and more!

Introduction

This project will be an introduction to machine learning. The code for this project contains the following files, available on blackboard and can be downloaded from [here](#).

Files you'll edit:

models.py	Perceptron and neural network models for a variety of applications
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Files you should NOT edit:

nn.py	Neural network mini-library
autograder.py	Project autograder
backend.py	Backend code for various machine learning tasks
data	Datasets for digit classification and language identification

What to submit:

You will fill in portions of models.py during the assignment. You should submit this file with your code and comments to blackboard. Please do not change the other files in this distribution or submit any of our original files other than multiAgents.py. **If you work with a partner, please write their name in a file named partner.txt.**

Evaluation: Your code will be autograded for technical correctness. Please do not change the names of any provided functions or classes within the code, or you will wreak havoc on the autograder. If your code works correctly on one or two of the provided examples but doesn't get full credit from the autograder, you most likely have a subtle bug that breaks one of our more thorough test cases; you will need to debug more fully by reasoning about your code and trying small examples of your own. That said, bugs in the autograder are not impossible, so please do contact the staff if you believe that there has been an error in the grading.

Academic Integrity: We will be checking your code against other submissions in the class for logical redundancy. If you copy someone else's code and submit it with minor changes, we will know. These cheat detectors are quite hard to fool, so please don't try. We trust you all to submit your own work only; please don't let us down. If you do, we will pursue the strongest consequences available to us.

Proper Dataset Use: Part of your score for this project will depend on how well the models you train perform on the test set included with the autograder. We do not provide any APIs for you to access the test set directly. Any attempts to bypass this separation or to use the testing data during training will be considered cheating.

Getting Help: You are not alone! If you find yourself stuck on something, contact the course staff for help. Office hours, section, and Piazza are there for your support; please use them. If you can't make our office hours, let us know and we will schedule more. We want these projects to be rewarding and instructional, not frustrating and demoralizing. But, we don't know when or how to help unless you ask.

Installation

For this project, you will need to install the following two libraries:

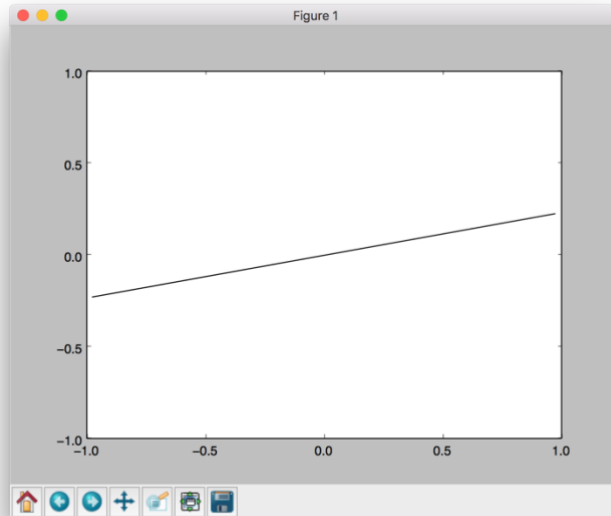
- numpy, which provides support for large multi-dimensional arrays - [installation instructions](#)
- matplotlib, a 2D plotting library - [installation instructions](#)

You will not be using these libraries directly, but they are required in order to run the provided code and autograder. Note that you will get a segmentation fault if any of them is not installed properly.

To test that everything has been installed, run:

```
python autograder.py --check-dependencies
```

If numpy and matplotlib are installed correctly, you should see a window pop up where a line segment spins in a circle:



Provided Code (Part I)

For this project, you have been provided with a neural network mini-library (**nn.py**) and a collection of datasets (**backend.py**).

The library in **nn.py** defines a collection of node objects. Each node represents a real number or a matrix of real numbers. Operations on node objects are optimized to work faster than using Python's built-in types (such as lists).

Here are a few of the provided node types:

- **nn.Constant** represents a matrix (2D array) of floating point numbers. It is typically used to represent input features or target outputs/labels. Instances of this type will be provided to you by other functions in the API; you will not need to construct them directly.
- **nn.Parameter** represents a trainable parameter of a perceptron or neural network.
- **nn.DotProduct** computes a dot product between its inputs.

Additional provided functions:

- **nn.as_scalar** can extract a Python floating-point number from a node.

When training a perceptron or neural network, you will be passed a *dataset* object. You can retrieve batches of training examples by calling `dataset.iterate_once(batch_size)`:

```
for x, y in dataset.iterate_once(batch_size):  
    ...
```

For example, let's extract a batch of size 1 (i.e., a single training example) from the perceptron training data:

```
>>> batch_size = 1  
>>> for x, y in dataset.iterate_once(batch_size):  
...     print(x)  
...     print(y)  
...     break  
...  
<Constant shape=1x3 at 0x11a8856a0>  
<Constant shape=1x1 at 0x11a89efd0>
```

The input features *x* and the correct label *y* are provided in the form of `nn.Constant` nodes. The shape of *x* will be `batch_size x num_features`, and the shape of *y* is `batch_size x num_outputs`. Here is an example of computing a dot product of *x* with itself, first as a node and then as a Python number.

```
>>> nn.DotProduct(x, x)  
<DotProduct shape=1x1 at 0x11a89edd8>  
  
>>> nn.as_scalar(nn.DotProduct(x, x))  
1.9756581717465536
```

Question 1 (6 points): Perceptron

Before starting this part, be sure you have `numpy` and `matplotlib` installed!

In this part, you will implement a binary perceptron. Your task will be to complete the implementation of the *PerceptronModel* class in `models.py`.

For the perceptron, the output labels will be either 1 or -1, meaning that data points (*x*, *y*) from the dataset will have *y* be a `nn.Constant` node that contains either 1 or -1 as its entries.

We have already initialized the perceptron weights *self.w* to be a `1×dimensions` parameter node. The provided code will include a bias feature inside *x* when needed, so you will not need a separate parameter for the bias.

Your tasks are to:

- Implement the `run(self, x)` method. This should compute the dot product of the stored weight vector and the given input, returning an `nn.DotProduct` object.
- Implement `get_prediction(self, x)`, which should return 1 if the dot product is non-negative or -1 otherwise. You should use `nn.as_scalar` to convert a scalar `Node` into a Python floating-point number.
- Write the `train(self)` method. This should repeatedly loop over the data set and make updates on examples that are misclassified. Use the `update` method of the `nn.Parameter` class to update the weights. When an entire pass over the data set is completed without making any mistakes, 100% training accuracy has been achieved, and training can terminate.

In this project, the only way to change the value of a parameter is by calling `parameter.update(direction, multiplier)`, which will perform the update to the weights:

$$weights \leftarrow weights + direction \cdot multiplier$$

The direction argument is a `Node` with the same shape as the parameter, and the multiplier argument is a Python scalar.

To test your implementation, run the autograder:

```
python autograder.py -q q1
```

Note: the autograder should take at most 20 seconds or so to run for a correct implementation. If the autograder is taking forever to run, your code probably has a bug.

Neural Network Tips

In the remaining parts of the project, you will implement the following models:

- Q2: Regression
- Q3: Handwritten Digit Classification
- Q4: Language Identification

Building Neural Nets

Throughout the applications portion of the project, you'll use the framework provided in `nn.py` to create neural networks to solve a variety of machine learning problems. A simple neural network has layers, where each layer performs a linear operation (just like perceptron). Layers are separated by a non-linearity, which allows the network to approximate general functions. We'll use the ReLU operation for our non-linearity, defined as $\text{relu}(x) = \max(x, 0)$. For example, a simple two-layer neural network for mapping an input row vector x to an output vector $f(x)$ would be given by the function:

$$f(x) = \text{relu}(x \cdot W_1 + b_1) \cdot W_2 + b_2$$

where we have parameter matrices W_1 and W_2 and parameter vectors b_1 and b_2 to learn during gradient descent. W_1 will be an $i \times h$ matrix, where i is the dimension of our input vectors x , and h is the hidden layer size. b_1 will be a size h vector. We are free to choose any value we want for the hidden size (we will just need to make sure the dimensions of the other matrices and vectors agree so that we can perform the operations). Using a larger hidden size will usually make the network more powerful (able to fit more training data), but can make the network harder to train (since it adds more parameters to all the matrices and vectors we need to learn), or can lead to overfitting on the training data.

We can also create deeper networks by adding more layers, for example a three-layer net:

$$f(x) = \text{relu}(\text{relu}(x \cdot W_1 + b_1) \cdot W_2 + b_2) \cdot W_3 + b_3$$

Note on Batching

For efficiency, you will be required to process whole batches of data at once rather than a single example at a time. This means that instead of a single input row vector x with size i , you will be presented with a batch of b inputs represented as a $b \times i$ matrix X . We provide an example for linear regression to demonstrate how a linear layer can be implemented in the batched setting.

Note on Randomness

The parameters of your neural network will be randomly initialized, and data in some tasks will be presented in shuffled order. Due to this randomness, it's possible that you will still occasionally

fail some tasks even with a strong architecture – this is the problem of local optima! This should happen very rarely, though – if when testing your code you fail the autograder twice in a row for a question, you should explore other architectures.

Practical tips

Designing neural nets can take some trial and error. Here are some tips to help you along the way:

- Be systematic. Keep a log of every architecture you've tried, what the hyperparameters (layer sizes, learning rate, etc.) were, and what the resulting performance was. As you try more things, you can start seeing patterns about which parameters matter. If you find a bug in your code, be sure to cross out past results that are invalid due to the bug.
- Start with a shallow network (just two layers, i.e. one non-linearity). Deeper networks have exponentially more hyperparameter combinations, and getting even a single one wrong can ruin your performance. Use the small network to find a good learning rate and layer size; afterwards you can consider adding more layers of similar size.
- If your learning rate is wrong, none of your other hyperparameter choices matter. You can take a state-of-the-art model from a research paper, and change the learning rate such that it performs no better than random. A learning rate too low will result in the model learning too slowly, and a learning rate too high may cause loss to diverge to infinity. Begin by trying different learning rates while looking at how the loss decreases over time.
- Smaller batches require lower learning rates. When experimenting with different batch sizes, be aware that the best learning rate may be different depending on the batch size.
- Refrain from making the network too wide (hidden layer sizes too large) If you keep making the network wider accuracy will gradually decline, and computation time will increase quadratically in the layer size – you're likely to give up due to excessive slowness long before the accuracy falls too much. The full autograder for all parts of the project takes 2-12 minutes to run with staff solutions; if your code is taking much longer you should check it for efficiency.
- If your model is returning Infinity or NaN, your learning rate is probably too high for your current architecture.
- Recommended values for your hyperparameters:

- Hidden layer sizes: between 10 and 400.
- Batch size: between 1 and the size of the dataset. For Q2 and Q3, we require that total size of the dataset be evenly divisible by the batch size.
- Learning rate: between 0.001 and 1.0.
- Number of hidden layers: between 1 and 3.

Provided Code (Part II)

Here is a full list of nodes available in `nn.py`. You will make use of these in the remaining parts of the assignment:

- `nn.Constant` represents a matrix (2D array) of floating point numbers. It is typically used to represent input features or target outputs/labels. Instances of this type will be provided to you by other functions in the API; you will not need to construct them directly.
- `nn.Parameter` represents a trainable parameter of a perceptron or neural network. All parameters must be 2-dimensional. Usage: `nn.Parameter(n, m)` constructs a parameter with shape $n \times m$.
- `nn.Add` adds matrices element-wise.
 - Usage: `nn.Add(x, y)` accepts two nodes of shape $\text{batch_size} \times \text{num_features}$ and constructs a node that also has shape $\text{batch_size} \times \text{num_features}$.
- `nn.AddBias` adds a bias vector to each feature vector.
 - Usage: `nn.AddBias(features, bias)` accepts features of shape $\text{batch_size} \times \text{num_features}$ and bias of shape $1 \times \text{num_features}$, and constructs a node that has shape $\text{batch_size} \times \text{num_features}$.
- `nn.Linear` applies a linear transformation (matrix multiplication) to the input.
 - Usage: `nn.Linear(features, weights)` accepts features of shape $\text{batch_size} \times \text{num_input_features}$ and weights of shape $\text{num_input_features} \times \text{num_output_features}$, and constructs a node that has shape $\text{batch_size} \times \text{num_output_features}$.
- `nn.ReLU` applies the element-wise Rectified Linear Unit
- nonlinearity $\text{relu}(x) = \max(x, 0)$. This nonlinearity replaces all negative entries in its input with zeros.

- Usage: `nn.ReLU(features)`, which returns a node with the same shape as the input.
- `nn.SquareLoss` computes a batched square loss, used for regression problems
 - Usage: `nn.SquareLoss(a, b)`, where `a` and `b` both have shape `batch_size×num_outputs`.
- `nn.SoftmaxLoss` computes a batched softmax loss, used for classification problems.
 - Usage: `nn.SoftmaxLoss(logits, labels)`, where `logits` and `labels` both have shape `batch_size×num_classes`. The term “logits” refers to scores produced by a model, where each entry can be an arbitrary real number. The labels, however, must be non-negative and have each row sum to 1. Be sure not to swap the order of the arguments!
- Do not use `nn.DotProduct` for any model other than the perceptron.

The following methods are available in `nn.py`:

- `nn.gradients` computes gradients of a loss with respect to provided parameters.
 - Usage: `nn.gradients(loss, [parameter_1, parameter_2, ..., parameter_n])` will return a list `[gradient_1, gradient_2, ..., gradient_n]`, where each element is an `nn.Constant` containing the gradient of the loss with respect to a parameter.
- `nn.as_scalar` can extract a Python floating-point number from a loss node. This can be useful to determine when to stop training.
 - Usage: `nn.as_scalar(node)`, where `node` is either a loss node or has shape `(1,1)`.

The datasets provided also have two additional methods:

- `dataset.iterate_forever(batch_size)` yields an infinite sequences of batches of examples.
- `dataset.get_validation_accuracy()` returns the accuracy of your model on the validation set. This can be useful to determine when to stop training.

Example: Linear Regression

As an example of how the neural network framework works, let’s fit a line to a set of data points. We’ll start four points of training data constructed using the function $y=7x_0+8x_1+3$. In batched form, our data is:

$$\mathbf{X} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{Y} = \begin{bmatrix} 3 \\ 11 \\ 10 \\ 18 \end{bmatrix}$$

Suppose the data is provided to us in the form of `nn.Constant` nodes:

```
>>> x
<Constant shape=4x2 at 0x10a30fe80>
>>> y
<Constant shape=4x1 at 0x10a30fef0>
```

Let's construct and train a model of the form $f(x)=x_0 \cdot m_0 + x_1 \cdot m_1 + b$. If done correctly, we should be able to learn that $m_0=7$, $m_1=8$, and $b=3$.

First, we create our trainable parameters. In matrix form, these are:

$$\mathbf{M} = \begin{bmatrix} m_0 \\ m_1 \end{bmatrix} \quad \text{and} \quad \mathbf{B} = [b]$$

Which corresponds to the following code:

```
m = nn.Parameter(2, 1)
b = nn.Parameter(1, 1)
```

Printing them gives:

```
>>> m
<Parameter shape=2x1 at 0x112b8b208>
>>> b
<Parameter shape=1x1 at 0x112b8beb8>
```

Next, we compute our model's predictions for y:

```
xm = nn.Linear(x, m)
```

```
predicted_y = nn.AddBias(xm, b)
```

Our goal is to have the predicted y-values match the provided data. In linear regression we do this by minimizing the square loss:

$$\mathcal{L} = \frac{1}{2N} \sum_{(x,y)} (y - f(x))^2$$

We construct a loss node:

```
loss = nn.SquareLoss(predicted_y, y)
```

In our framework, we provide a method that will return the gradients of the loss with respect to the parameters:

```
grad_wrt_m, grad_wrt_b = nn.gradients(loss, [m, b])
```

Printing the nodes used gives:

```
>>> xm
<Linear shape=4x1 at 0x11a869588>
>>> predicted_y
<AddBias shape=4x1 at 0x11c23aa90>
>>> loss
<SquareLoss shape=() at 0x11c23a240>
>>> grad_wrt_m
<Constant shape=2x1 at 0x11a8cb160>
>>> grad_wrt_b
<Constant shape=1x1 at 0x11a8cb588>
```

We can then use the **update** method to update our parameters. Here is an update for m, assuming we have already initialized a multiplier variable based on a suitable learning rate of our choosing:

```
m.update(grad_wrt_m, multiplier)
```

If we also include an update for b and add a loop to repeatedly perform gradient updates, we will have the full training procedure for linear regression.

Question 2 (6 points): Non-linear Regression

For this question, you will train a neural network to approximate $\sin(x)$ over $[-2\pi, 2\pi]$.

You will need to complete the implementation of the `RegressionModel` class in `models.py`. For this problem, a relatively simple architecture should suffice (see Neural Network Tips for architecture tips.) Use `nn.SquareLoss` as your loss.

Your tasks are to:

- Implement `RegressionModel.__init__` with any needed initialization
- Implement `RegressionModel.run` to return a `batch_size×1batch_size×1` node that represents your model's prediction.
- Implement `RegressionModel.get_loss` to return a loss for given inputs and target outputs.
- Implement `RegressionModel.train`, which should train your model using gradient-based updates.

There is only a single dataset split for this task (i.e., there is only training data and no validation data or test set). Your implementation will receive full points if it gets a loss of 0.02 or better, averaged across all examples in the dataset. You may use the training loss to determine when to stop training (use `nn.as_scalar` to convert a loss node to a Python number). Note that it should take the model a few minutes to train.

```
python autograder.py -q q2
```

Question 3 (6 points): Digit Classification

For this question, you will train a network to classify handwritten digits from the MNIST dataset.

Each digit is of size 28×28 pixels, the values of which are stored in a 784-dimensional vector of floating point numbers. Each output we provide is a 10-dimensional vector which has zeros in all positions, except for a one in the position corresponding to the correct class of the digit.

Complete the implementation of the `DigitClassificationModel` class in `models.py`. The return value from `DigitClassificationModel.run()` should be a `batch_size×10` node containing scores, where higher scores indicate a higher probability of a digit belonging to a particular class (0-9). You should use `nn.SoftmaxLoss` as your loss. **Do not put a ReLU activation after the last layer of the network.**

For both this question and Q4, in addition to training data, there is also validation data and a test set. You can use `dataset.get_validation_accuracy()` to compute validation accuracy for your model, which can be useful when deciding whether to stop training. The test set will be used by the autograder.

To receive points for this question, your model should achieve an accuracy of at least 97% on the test set. For reference, our staff implementation consistently achieves an accuracy of 98% on the validation data after training for around 5 epochs. Note that the test grades you on test accuracy, while you only have access to validation accuracy - so if your validation accuracy meets the 97%

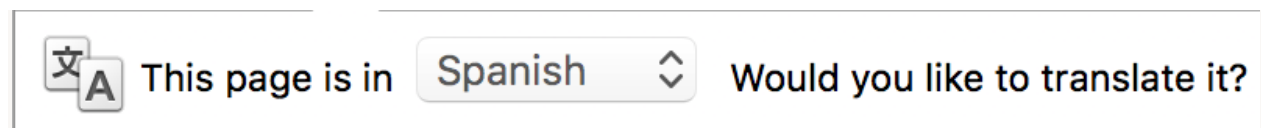
threshold, you may still fail the test if your test accuracy does not meet the threshold. Therefore, it may help to set a slightly higher stopping threshold on validation accuracy, such as 97.5% or 98%.

To test your implementation, run the autograder:

```
python autograder.py -q q3
```

Question 4 (7 points): Language Identification

Language identification is the task of figuring out, given a piece of text, what language the text is written in. For example, your browser might be able to detect if you've visited a page in a foreign language and offer to translate it for you. Here is an example from Chrome (which uses a neural network to implement this feature):



In this project, we're going to build a smaller neural network model that identifies language for one word at a time. Our dataset consists of words in five languages, such as the table below:

Word	Language
discussed	English
eternidad	Spanish
itseänne	Finnish
paleis	Dutch
mieszkać	Polish

Different words consist of different numbers of letters, so our model needs to have an architecture that can handle variable-length inputs. Instead of a single input x (like in the previous questions), we'll have a separate input for each character in the word: x_0, x_1, \dots, x_{L-1} where L is the length of the word. We'll start by applying a network f_{initial} that is just like the feed-forward networks in the previous problems. It accepts its input x_0 and computes an output vector h_1 of dimensionality d :

$$h_1 = f_{\text{initial}}(x_0)$$

Next, we'll combine the output of the previous step with the next letter in the word, generating a vector summary of the first two letters of the word. To do this, we'll apply a sub-network that accepts a letter and outputs a hidden state, but now also depends on the previous hidden state h_1 . We denote this sub-network as f .

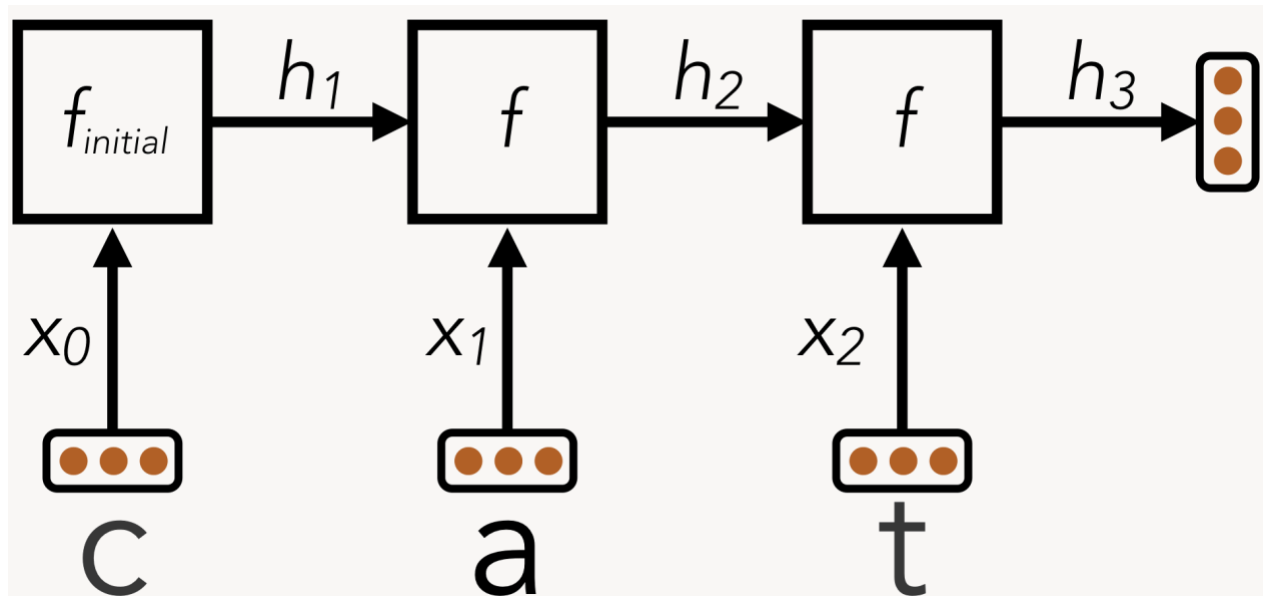
$$h_2 = f(h_1, x_1)$$

This pattern continues for all letters in the input word, where the hidden state at each step summarizes all the letters the network has processed thus far:

$$h_3 = f(h_2, x_2) \quad h_3 = f(h_2, x_2) ::$$

Throughout these computations, the function $f(\cdot, \cdot)$ is the same piece of neural network and uses the same trainable parameters; f_{initial} will also share some of the same parameters as $f(\cdot, \cdot)$. In this way, the parameters used when processing words of different length are all shared. You can implement this using a for loop over the provided inputs x_s , where each iteration of the loop computes either f_{initial} or ff .

The technique described above is called a Recurrent Neural Network (RNN). A schematic diagram of the RNN is shown below:



Here, an RNN is used to encode the word “cat” into a fixed-size vector h_3 .

After the RNN has processed the full length of the input, it has encoded the arbitrary-length input word into a fixed-size vector h_L , where L is the length of the word. This vector summary of the input word can now be fed through additional output layers to generate classification scores for the word’s language identity.

Batching

Although the above equations are in terms of a single word, in practice you must use batches of words for efficiency. For simplicity, our code in the project ensures that all words within a single batch have the same length. In batched form, a hidden state h_i is replaced with the matrix H_i of dimensionality $\text{batch_size} \times d$.

Design Tips

The design of the recurrent function $f(h, x)$ is the primary challenge for this task. Here are some tips:

- Start with a feed-forward architecture $f_{\text{initial}}(x)$ of your choice, as long as it has at least one non-linearity.
- You should use the following method of constructing $f(h,x)$ given $f_{\text{initial}}(x)$. The first layer of $f_{\text{initial}}(x)$ will begin by multiplying the vector x_0 by some weight matrix W to produce $z_0 = x_0 \cdot W$. For subsequent layers, you should replace this computation with $z_i = x_i W + h_i W_{\text{hidden}}$ using an *nn.Add* operation. In other words, you should replace a computation of the form $z = \text{nn.Linear}(x, W)$ with a computation of the form $z = \text{nn.Add}(\text{nn.Linear}(x, W), \text{nn.Linear}(h, W_{\text{hidden}}))$.
- If done correctly, the resulting function f will be non-linear in both x and h
- The hidden size dd should be sufficiently large
- Start with a shallow network for f , and figure out good values for the hidden size and learning rate before you make the network deeper. If you start with a deep network right away you will have exponentially more hyperparameter combinations, and getting any single hyperparameter wrong can cause your performance to suffer dramatically.

Your task

Complete the implementation of the *LanguageIDModel* class.

To receive full points on this problem, your architecture should be able to achieve an accuracy of at least 81% on the test set.

To test your implementation, run the autograder:

```
python autograder.py -q q4
```

Disclaimer: This dataset was generated using automated text processing. It may contain errors. It has also not been filtered for profanity. However, our reference implementation can still correctly classify over 85% of the validation set despite the limitations of the data. Our reference implementation takes 10-20 epochs to train.